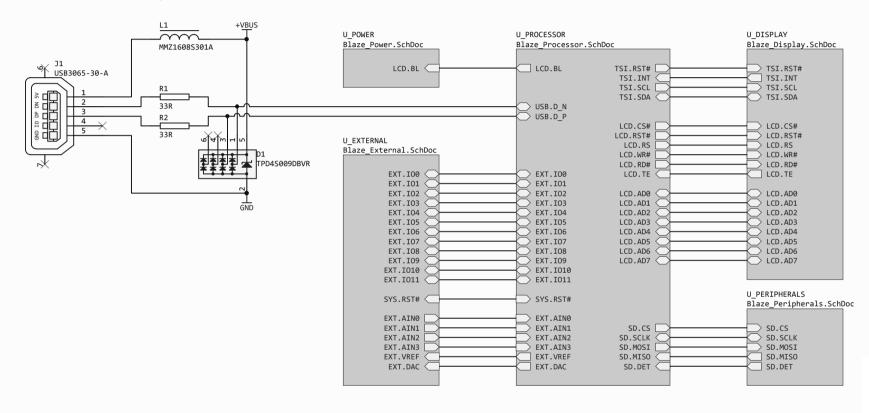
### USB Micro Receptacle



# M2 Mounting Holes

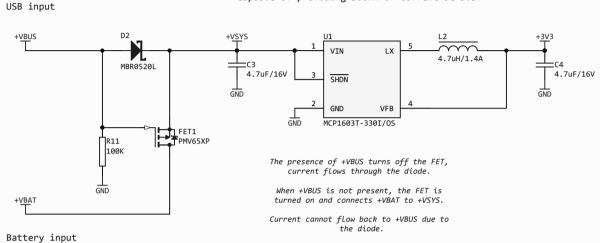




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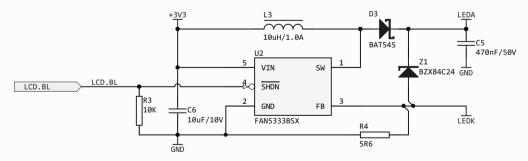
## **Voltage Regulator**

Capable of providing 500mA of current at 3.3V



# Backlight Regulator

Driving 3 LEDs in series (20mA each)

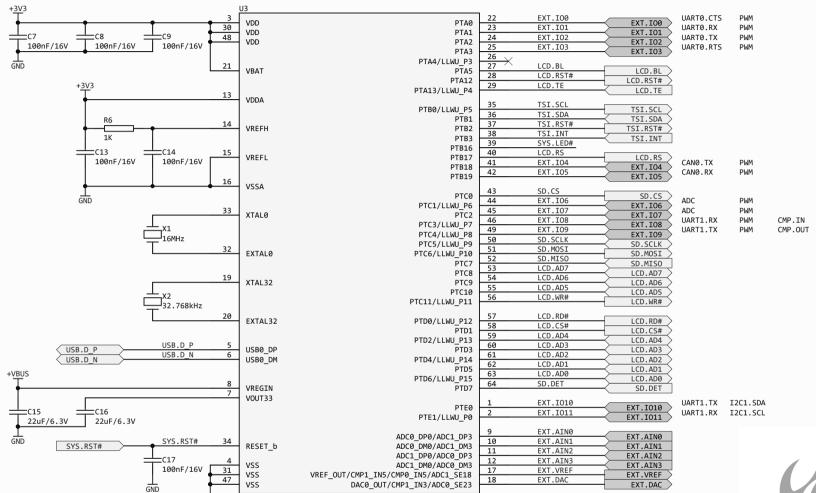


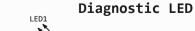
ILED = VFB/R R = 0.315/ILED R = 0.315/0.06 R = 5R25 (~5R6)



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#### Kinetis K22 120MHz Cortex-M4 Microcontroller







### JTAG TMS Pull-up

MK22FN1M0VLH12





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## 1.6" 240x240px Display

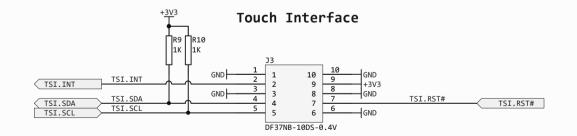
LCD.RST#	LCD.RST#	GND 1 2 GND 3 4	1 24 2 23 3 22	24 GND 23 LEDK 22 LEDA 21 CEDA		
LCD.AD7 LCD.AD6 LCD.AD5 LCD.AD4 LCD.AD3	LCD.AD7 LCD.AD6 LCD.AD5 LCD.AD4 LCD.AD3	5 6 7 8 9	4 21 5 20 6 19 7 18 8 17 9 16	GND 19 +3V3 17 +3V3	LCD.CS# LCD.RS	LCD.TE  LCD.CS#  LCD.RS
LCD.AD2 LCD.AD1 LCD.AD0	LCD.AD2 LCD.AD1 LCD.AD0	10 11 12	10 15 - 11 14 - 12 13 DF37NB-24DS-	15 14 13   GND 0.4V	LCD.RD#	LCD.WR# LCD.RD#

The display is driven entirely by the FlexBus peripheral in 8-bit mode, however the FlexBus must be configured for 32-bit mode. This is essential to allow the RS signal to work below.

The RS signal sits on bit 16 of the FlexBus AD port and is used to control whether data or a command is sent to the display.

When writing a command to the display, write to address 0x60000000.

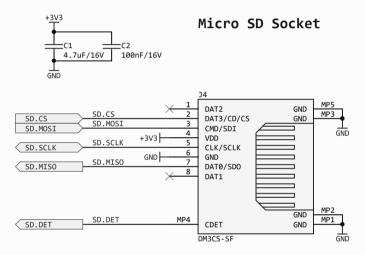
When writing data to the display, write to address 0x60010000 - note that bit 16 is set which tells the display that it is receiving a command.





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# V1 - Blaze

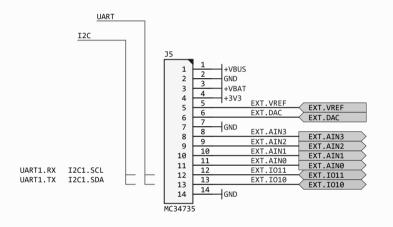


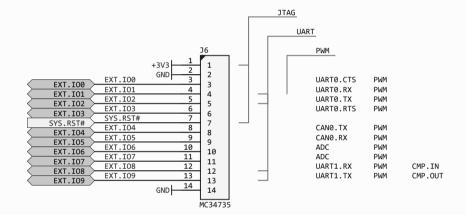


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#### External IO Headers

Pair of external IO headers for expansion







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