

TECH BOOTCAMP
DAY 06

INTRODUCTION TO IMAGE PROCESSING AND TOOLS

01

INTRODUCTION TO OPENCY

OPEN SOURCE COMPUTER VISION LIBRARY

IMAGE PROCESSING LIBRARY

CRUCIAL IN COMPUTER VISION

MULTILINGUAL, CROSS-PLATFORM, EVOLVING

DETECTION, RECOGNITION, CALIBRATION

ACTIVE, RESOURCE-RICH COMMUNITY

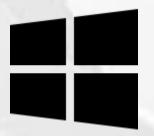
02

INSTALLATION

OFFICIAL WEBSITE

https://opencv.org/

AVAILABLE FOR







03

BASIC IMAGE OPERATIONS

LOAD IMAGE

cv2.imread('path_to_image.jpg')

DISPLAY IMAGE

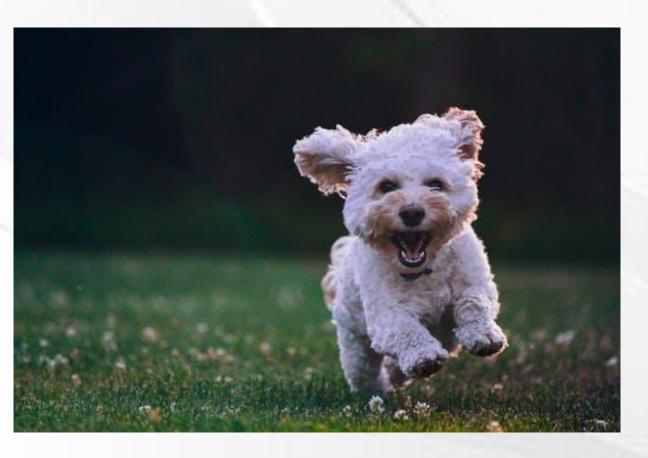
cv2.imshow('Loaded Image', image)

SAVE IMAGE

cv2.imwrite('saved_image.jpg', image)

IMAGE TO GREYSCALE

cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)



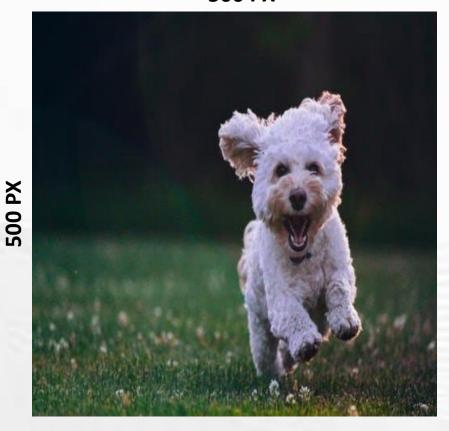


RESIZE IMAGE

cv2.resize(image, (500, 500))

640 PX

500 PX

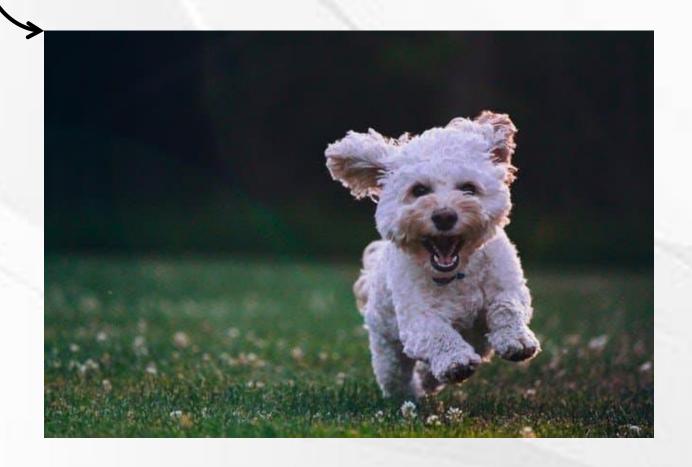


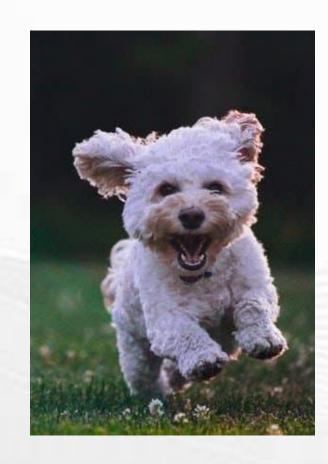
427 PX

CROP IMAGE

ORIGIN

image[y:y+h, x:x+w]





04

IMAGE FILTERING

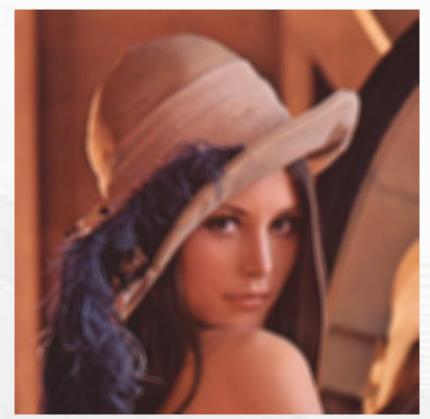
BLURRING

AVERAGE BLURRING GAUSSIAN BLURRING MEDIAN BLURRING

AVERAGE BLURRING

blurred_image = cv2.blur(image, (9, 9))

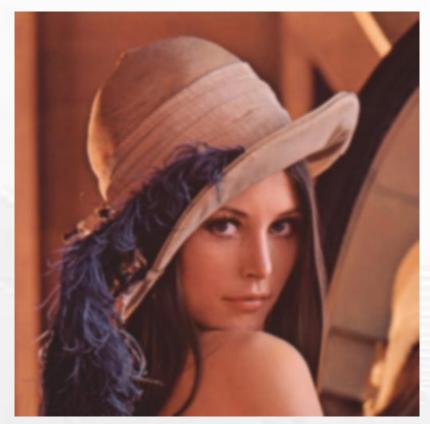




GAUSSIAN BLURRING

gaussian_blurred_image = cv2.GaussianBlur(image, (9, 9), 0)

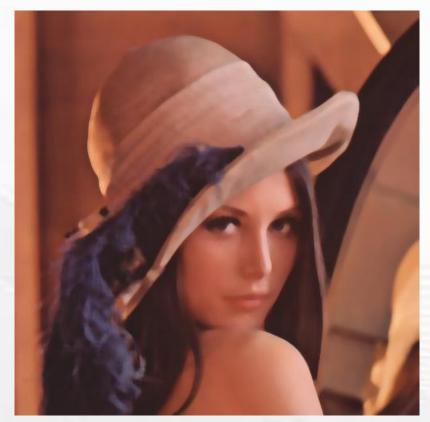




MEDIAN BLURRING

median_blurred_image = cv2.medianBlur(image, 9)

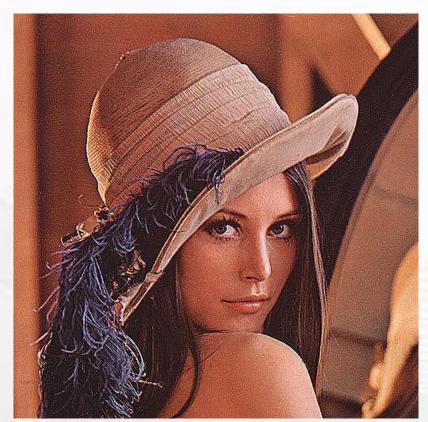




SHARPENING

cv2.filter2D(image, -1, kernel)





EDGE DETECTION

SOBEL EDGE DETECTION LAPLACIAN EDGE DETECTION CANNY EDGE DETECTION

SOBEL EDGE DETECTION

cv2.Sobel(image, cv2.CV_64F, 1, 0, ksize=5)





LAPLACIAN EDGE DETECTION

cv2.Laplacian(image, cv2.CV_64F)





CANNY EDGE DETECTION

cv2.Canny(image, 100, 200)





05

IMAGE TRANSFORMATIONS

RESIZING

cv2.resize(image, (image.shape[1] // 2, image.shape[0] // 2))





<u>ROTATING</u>

cv2.getRotationMatrix2D(center, angle, scale) cv2.warpAffine(image, rotation_matrix, (w, h))





<u>CROPPING</u>

image[y:y+h, x:x+w]



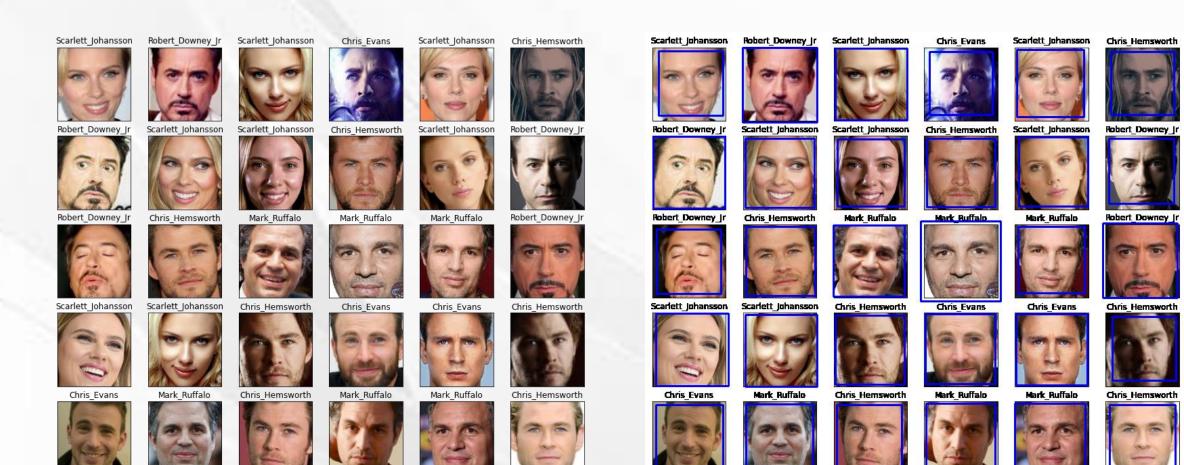


06

OBJECT DETECTION

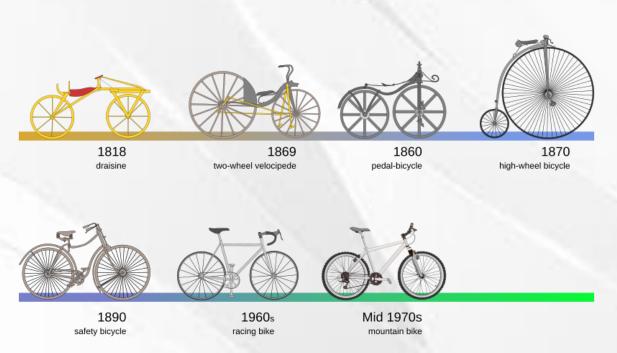
HAAR CASCADE CLASSIFIER

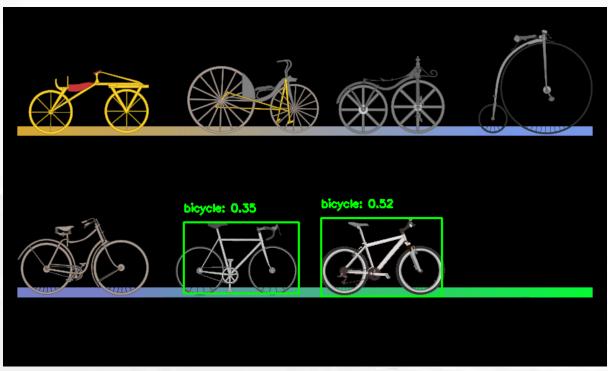
cv2.CascadeClassifier(cv2.data.haarcascades + 'haarcascade_frontalface_default.xml')



PRE-TRAINED DEEP LEARNING MODEL

cv2.dnn.readNetFromCaffe('path_to_deploy.prototxt', 'path_to_model.caffemodel')





07

IMAGE PROCESSING TECHNIQUES

THRESHOLDING

cv2.threshold(image, 127, 255, cv2.THRESH_BINARY)



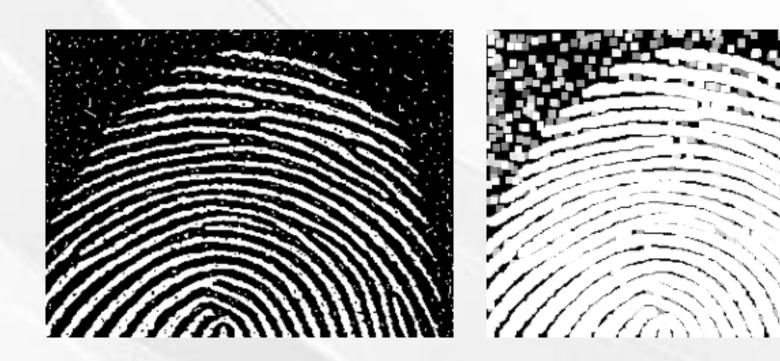


MORPHOLOGICAL OPERATIONS

DILATION
EROSION
OPENING AND CLOSING

DILATION

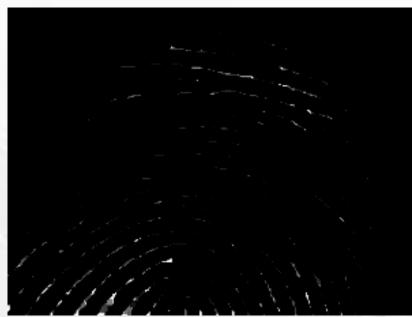
cv2.dilate(image, kernel, iterations=1)



EROSION

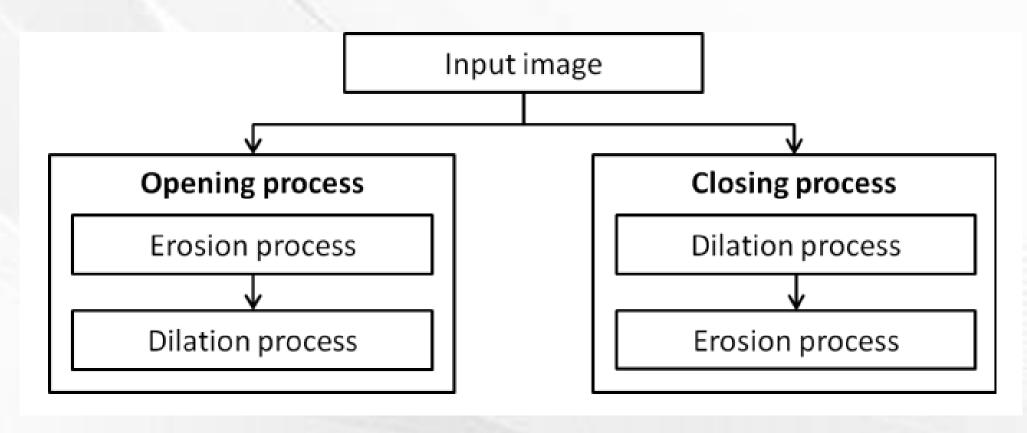
cv2.erode(image, kernel, iterations=1)





OPENING AND CLOSING

cv2.morphologyEx(image, cv2.MORPH_OPEN, kernel) cv2.morphologyEx(image, cv2.MORPH_CLOSE, kernel)



CONTOUR DETECTION

cv2.findContours(binary_image, cv2.RETR_TREE, cv2.CHAIN_APPROX_SIMPLE)





08

PRACTICAL EXAMPLES

How do you load an image in grayscale and display it using OpenCV?

How can you resize an image to 200x200 pixels?

How do you convert a colored image to a binary image using a threshold value of 127?

How can you detect edges in an image using the Canny edge detector?

How do you detect and draw contours on a binary image?



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THANK YOU!