## Example code for nonlinear case (problem 1 of HW2)

Find the solution of the following nonlinear equation,

$$\dot{x} = \begin{bmatrix} x_2 \\ (x_3 - \sin x_1 - x_2) / J \\ -x_3 - x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

where, 
$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$
;  $x(0) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ 

## % in main program ===========

 $options = odeset('RelTol', 1e-6, 'AbsTol', [1e-6\ 1e-6\ 1e-6]);$ 

U=[time, uff];

[t, state]=ode45('findx\_n',[0 8],[0 0 0],options,1,U);

% note: time and t are different

## % this function is saved as 'findx\_n'=========

function xdiff= fun(t, x\_n, flag, J, U)

time = U(:,1);

uff = U(:,2);

u = interp1(time, uff, t);

xdiff=zeros(3,1);

 $xdiff(1)=x_n(2);$ 

 $xdiff(2)=(x_n(3)-\sin(x_n(1))-x_n(2))/J;$ 

 $xdiff(3)=-x_n(3)-x_n(2)+u;$ 

return