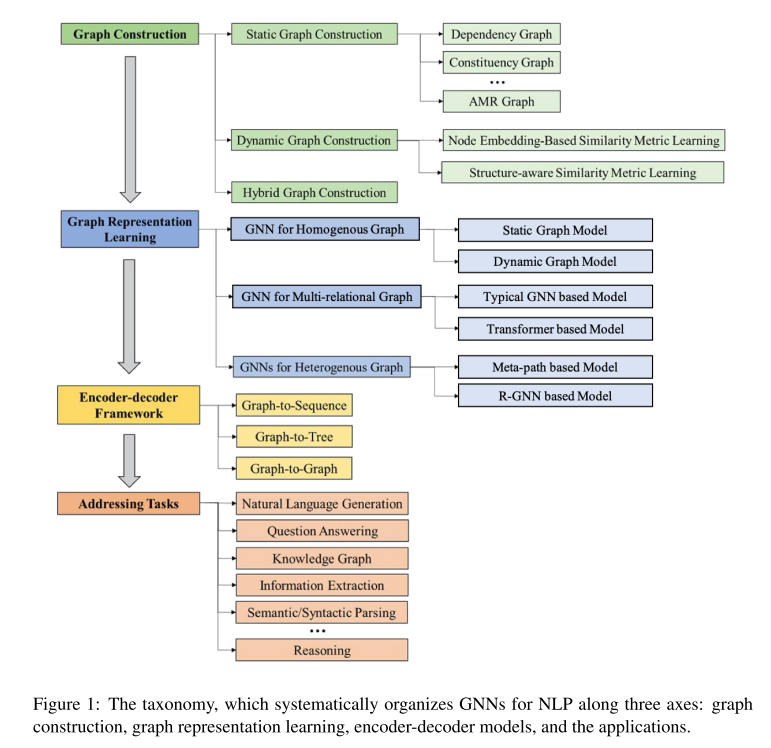
Graph Neural Networks (GNNs)

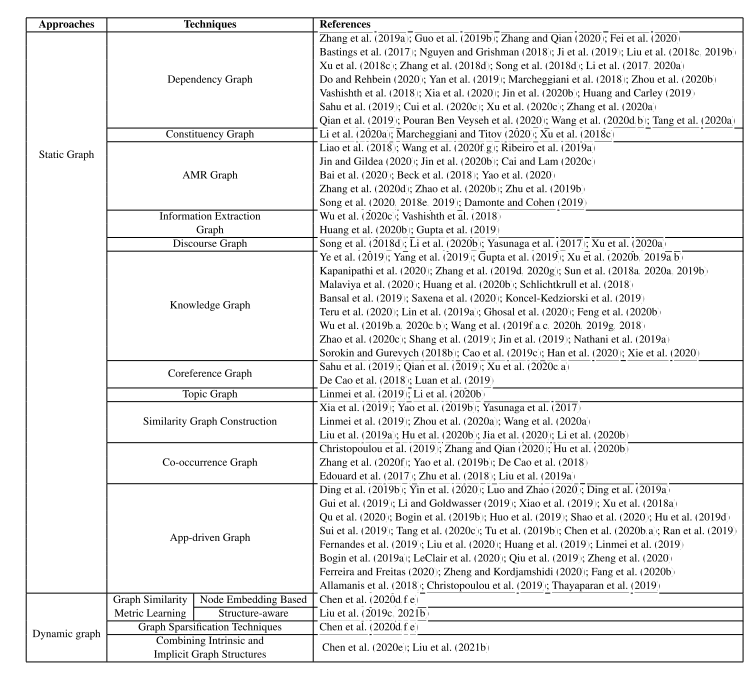
# Introduction

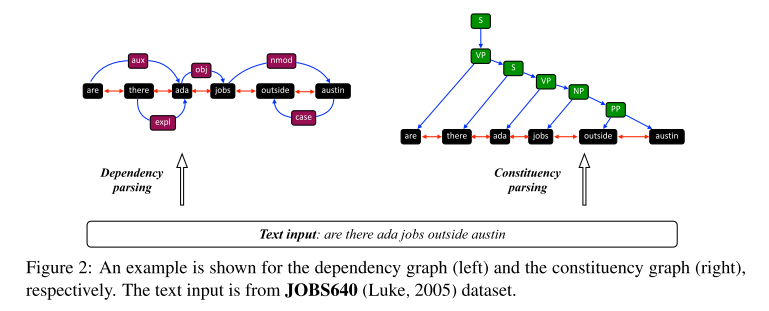
Current Machine Learning algorithms like Support Vector Classifier, Naïve Bayes, etc. expect independent features. That’s rarely the case, especially for Natural Language Processing (NLP) applications. Sparse or Dense embeddings used in ML of NLP, are related to each other contextually. Thus, traditional ML algorithms do not learn representation (underlying structure) well and warrant need to inter-dependent representation system such as Graph Neural Networks.

Notes

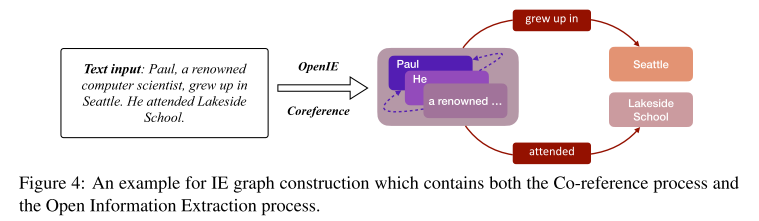
* Graph Neural Networks for Natural Language Processing: A Survey

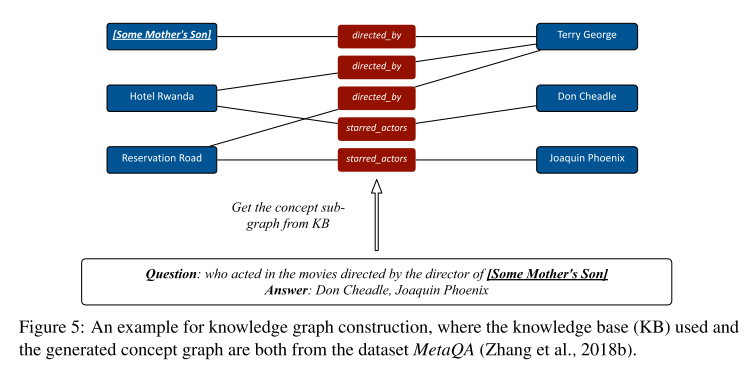




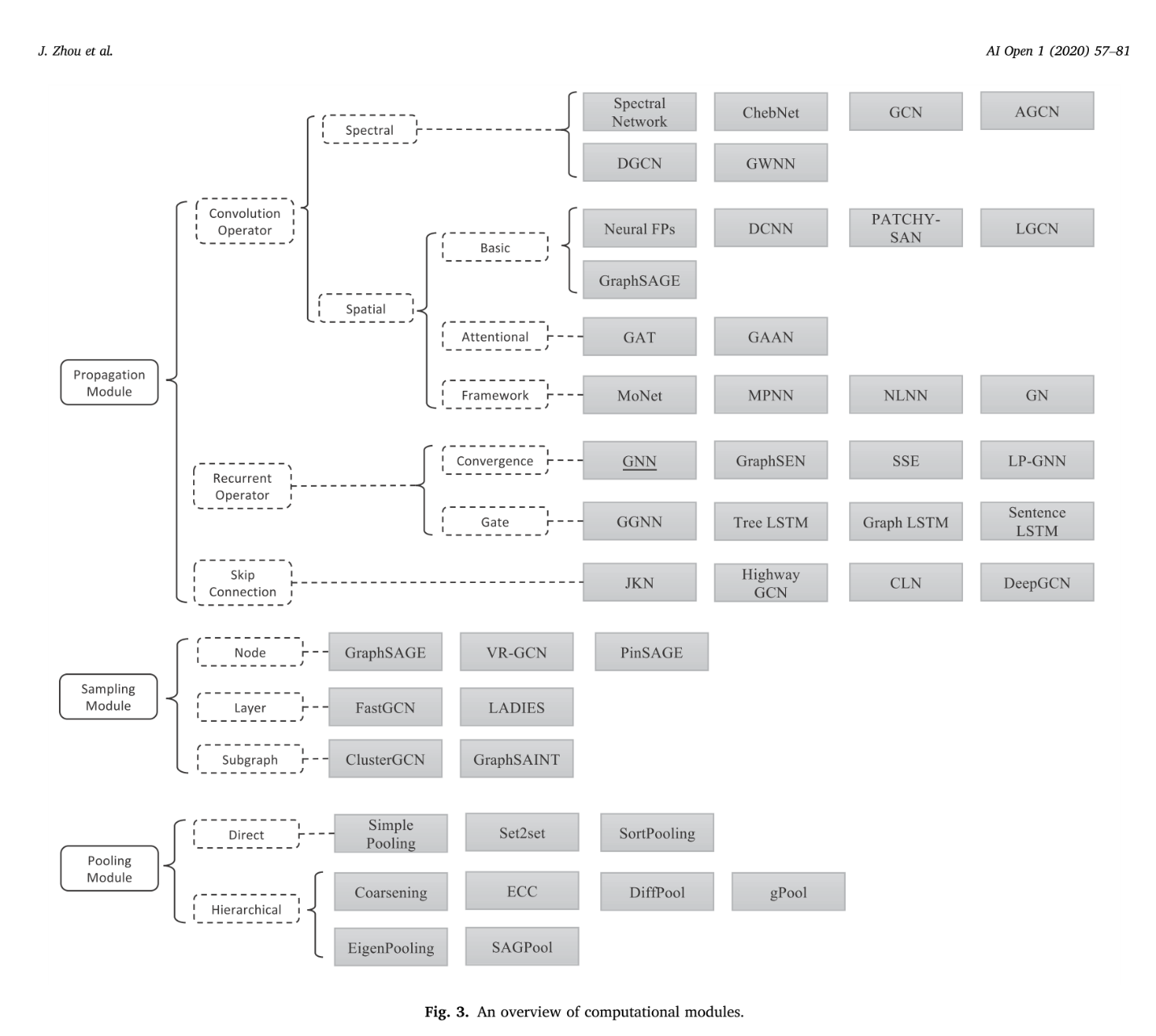


* + Constituency Graph Construction: constituency relation means the relation following the phrase structure grammars instead of the dependency relation and dependency grammars. Generally, the constituency relation derives from the subject (noun phrase NP)-predicate (verb phrase VP) relation. In this part, we only discuss the constituency relation deriving from the constituency parsing tree.
  + AMR Graph Construction: The AMR graphs are rooted, labeled, directed, acyclic graphs, which are widely used to represent the high-level semantic relations between abstract concepts of the unstructured and concrete natural text.

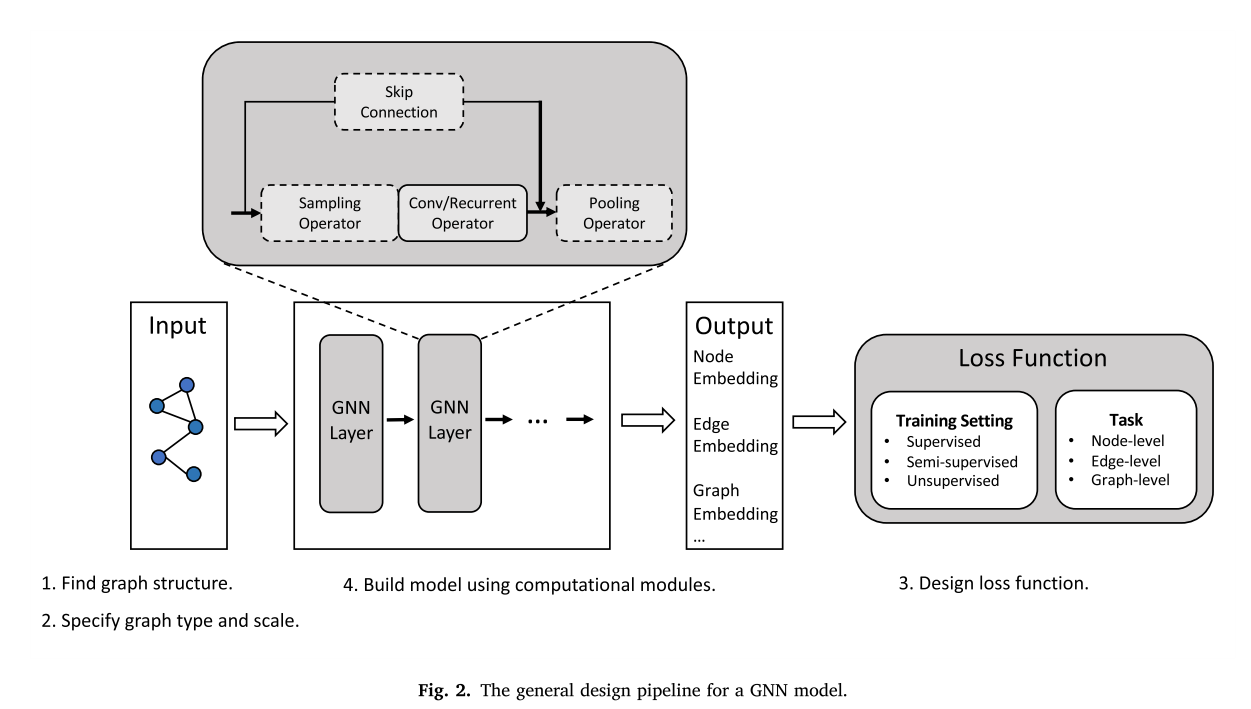




* Graph Neural Networks: A review of methods and applications – Jie Zhou



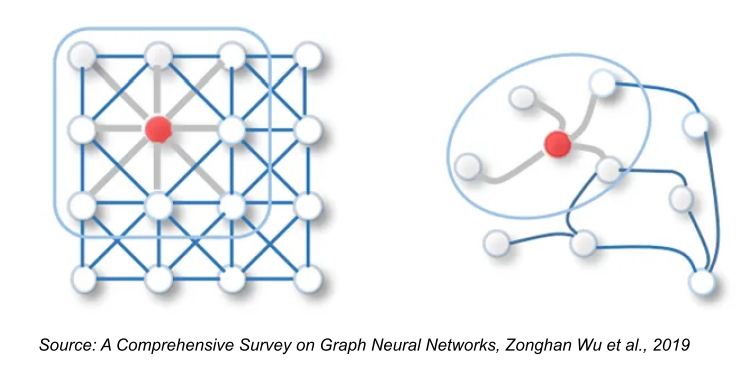
* + Propagation Module. The propagation module is used to propagate information between nodes so that the aggregated information could capture both feature and topological information. In propagation modules, the convolution operator and recurrent operator are usually used to aggregate information from neighbors while the skip connection operation is used to gather information from historical representations of nodes and mitigate the over-smoothing problem.
  + Sampling Module. When graphs are large, sampling modules are usually needed to conduct propagation on graphs. The sampling module is usually combined with the propagation module.
  + Pooling Module. When we need the representations of high-level subgraphs or graphs, pooling modules are needed to extract information from nodes.

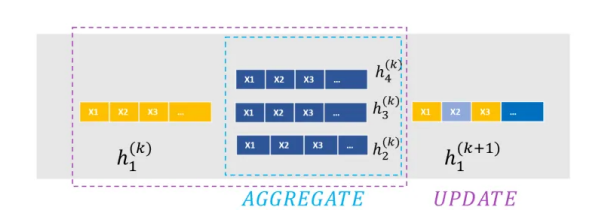


* Understanding Graph Neural Networks – DeepFindr
  + Extends Convolutions to Graph Nodes through Message Passing. It is done simultaneously by all nodes in the graph – for each message passing layer.
  + This leads to an exchange of structural and feature information and after one iteration all

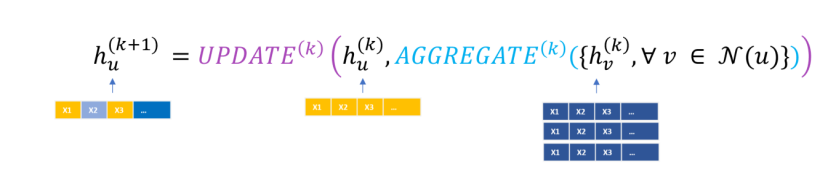
nodes are familiar with their neighbors + their neighbors feature information.

* + Number of layers in Message Passing network decides number if rings of neighbors.

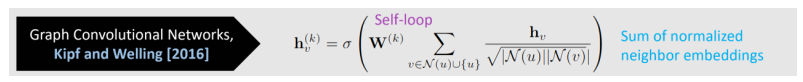




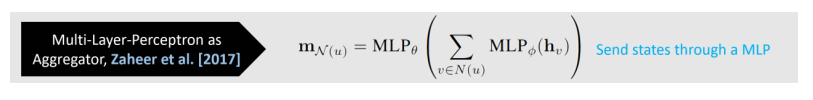
* + the new state h\_1^{k+1} are supposed to illustrate what is going on: neighbor information (blue) moves into the current state of node 1 (orange). This means, that node 1 knows something about its direct neighbors 2,3,4.
  + After many iterations, node 1 knows something about the green node (5) and its neighbors. This means our Graph Neural Network has compressed all the relevant information about the graph into one node embedding.
  + We can also combine the states of all nodes to obtain a representation of the whole graph.



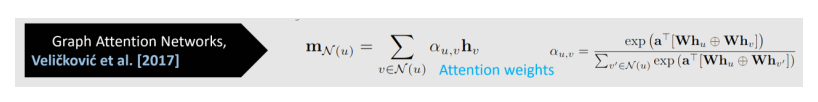
* + AGGREGATE: mean, sum or even Mult-Layer-Perceptron (MLP)
  + UPDATE: the mean, a MLP, or even a Gated Recurrent Unit (GRU)
  + Graph Convolutional Network (GCN):
    - No UPDATE
    - introduces self-loops – this means each node has a connection to itself
    - Normalization (Kipf-Normalization) of the node states to improve the aggregation.



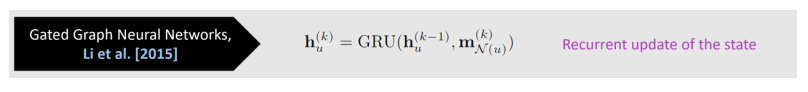
* + Multi-Layer-Perceptron as AGGREGATE



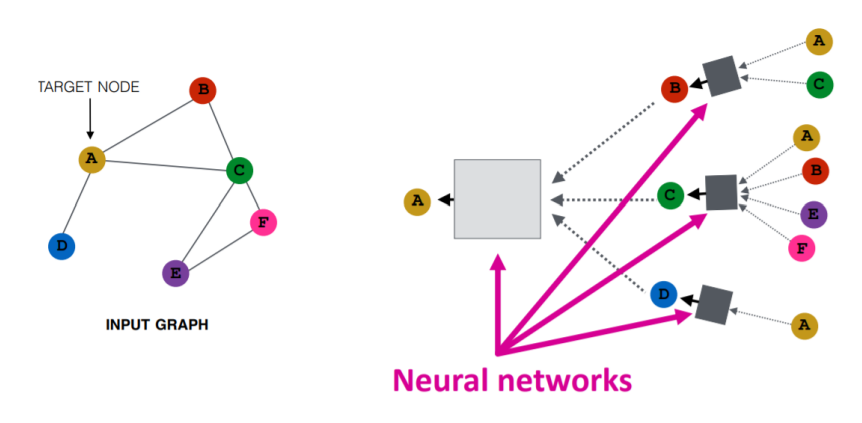
* + Graph Attention Networks (GAT): attention weights are used to aggregate neighbor states.



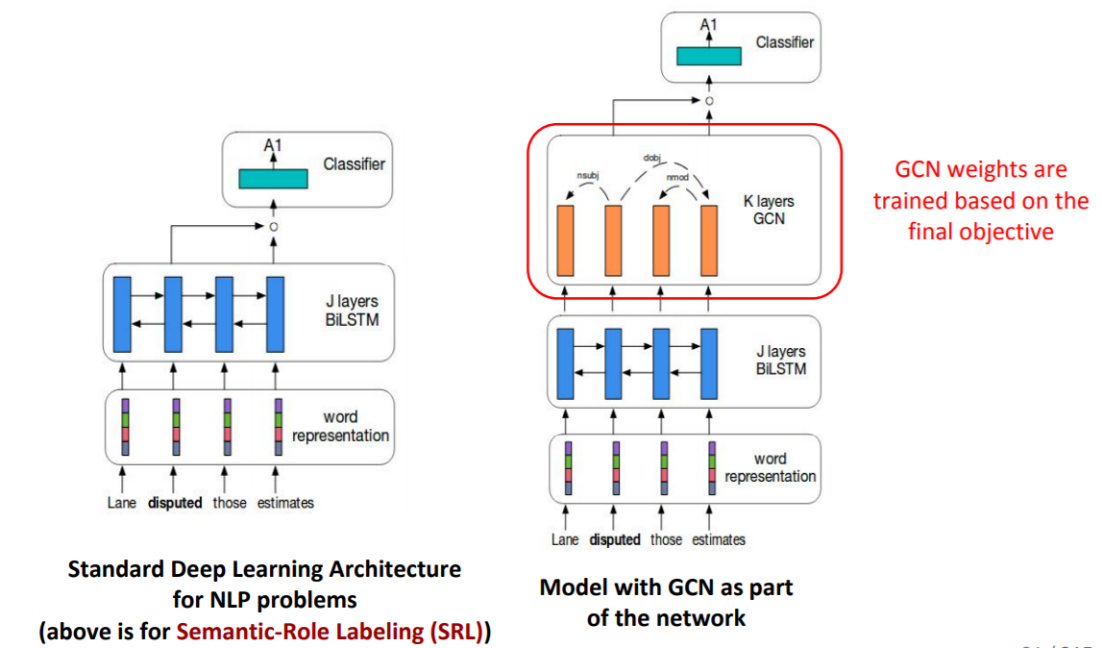
* + Gated Graph Neural Networks (GGNN): use a Gated Recurrent Unit to perform the UPDATE



* + Unlike Convolutional Neural Networks, stacking many layers might not make so much sense for Graph Neural Networks. The reason for this is, that the state-updates might oscillate, meaning that the node states already include all relevant information but still send and receive further messages. This leads to the fact that all states become increasingly similar, which makes them indistinguishable from another.
  + Therefore, with “standard” GNNs it is not recommended to go very deep, especially when working with small graphs
* Graphs Neural Networks in NLP. Capturing the beautiful semantic… | by Purvanshi Mehta | NeuralSpace | Medium

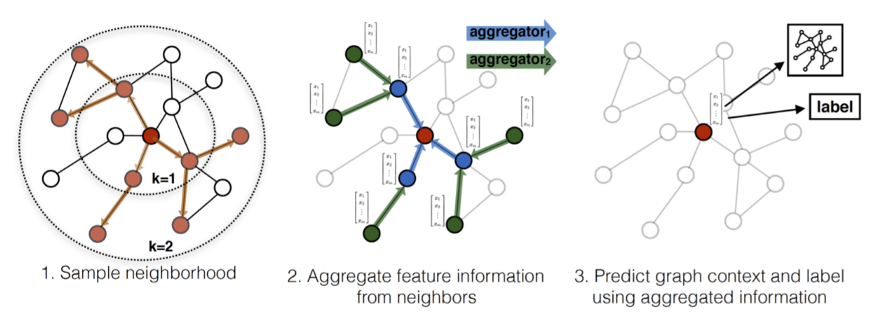


* + Although powerful attention mechanisms can automatically learn the syntactic and semantic relationships, it is linear and may have to be constrained to pick correct relationship.
  + Knowledge Graphs need to be input for NLP applications.
* Graph Node Embedding Algorithms (Stanford) <https://www.youtube.com/watch?v=7JELX6DiUxQ>
* CS224W: Machine Learning with Graphs <https://www.youtube.com/playlist?list=PLoROMvodv4rPLKxIpqhjhPgdQy7imNkDn>
* Spektral: graph deep learning, based on the Keras API and TensorFlow 2 <https://graphneural.network/> <https://arxiv.org/pdf/2006.12138.pdf>
* A Tutorial on Graph Neural Networks for Natural Language Processing <https://shikhar-vashishth.github.io/assets/pdf/emnlp19_tutorial.pdf> <https://arxiv.org/abs/1911.03042>



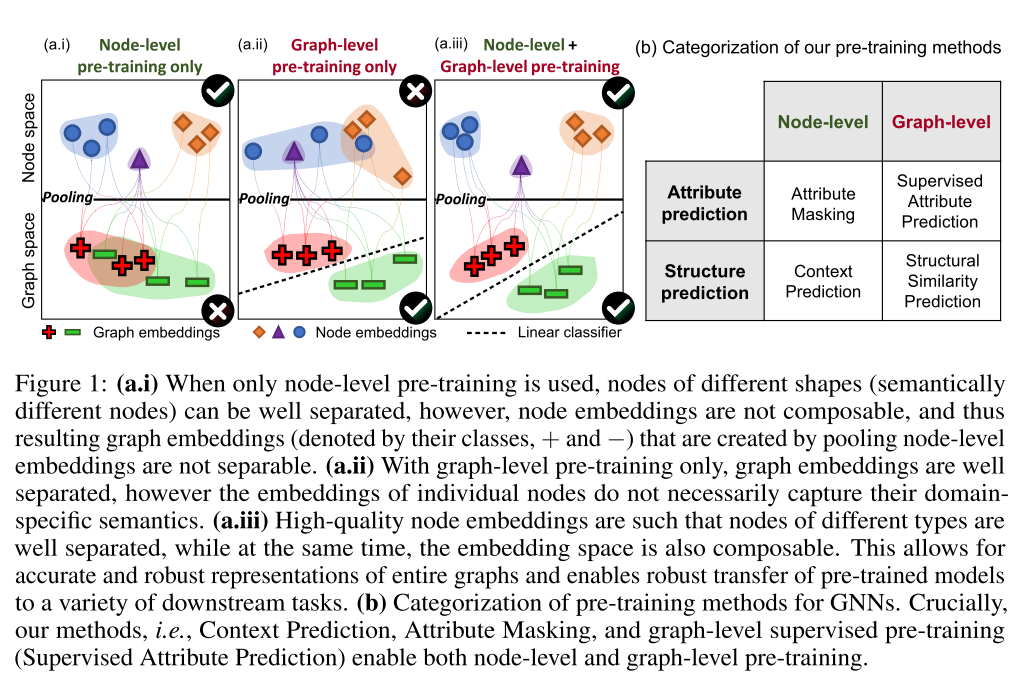
After standard LSTM, in sentiment classification algorithm, we can have Graph relations embedded in GCN and then do classification.

* Book: <https://www.manning.com/books/graph-powered-machine-learning>
* Using Graph Convolutional Neural Networks for NLP tasks <http://cs.virginia.edu/~ms5sw/GCN_for_NLP.pdf>
* Deep learning on graphs: successes, challenges, and next steps | Graph Neural Networks <https://www.youtube.com/watch?v=PLGcx65MhCc>
* Graph Convolutional Networks for Geometric Deep Learning <https://towardsdatascience.com/graph-convolutional-networks-for-geometric-deep-learning-1faf17dee008>
  + Graph Embedding: transforming a graph to a lower dimension.
  + Graph Convolution: convolutional methods are performed on the input graph itself, with structure and features left unchanged.
  + Images are represented on a 2-dimensional Euclidean grid, where a kernel can move left, right, etc. Graphs are non-Euclidean, and the notion of directions like up, down, etc. don’t have any meaning. Graphs are more abstract, and variables like node degree, proximity, and neighborhood structure provide for more information about the data. So, the ultimate question is: How do we generalize convolutions for graph data?
  + Types:
    - Spectral Graph Convolutional Networks: Graph Fourier transform. clustered graph would be sparse in the frequency domain allowing for a more efficient representation of the data.
    - Spatial Graph Convolutional Networks: Neighborhood sampling, Aggregation, Prediction



* An Introduction to Graph Neural Networks: Models and Applications <https://www.youtube.com/watch?v=zCEYiCxrL_0>
  + Input is nodes with own vector form. Output of GNNs is again nodes but with context information added to the node vector form. All incident edges info is in built now.
  + This update happens n all nodes, once at each time step, for n epochs.
* CS224W: Machine Learning with Graphs | 2021
  + Node Embedding: Have encoder network such that, cosine similarity of neighboring nodes is close.
  + GNNs (Graph Neural Networks) are Deep Graph Encoders. They are end-to-end learning machines.
  + Two steps: Decide node neighborhood, aggregate at a node using neighbors.
* KDD 2020: Hands-on Tutorials: Scalable Graph Neural Networks with Deep Graph Library <https://www.youtube.com/watch?v=Nd2BbbviOdk>
  + Tasks in Graph Learning
    - Node Classification:
      * Detect malicious accounts
      * Target right customers
    - Link Prediction
      * Recommendations
      * Predict missing relations in knowledge graph
    - Graph Classification
      * Predict property of entire graph like chemical compound
    - Embed nodes-edges- graph info in a vector and then use it for classifies.
      * Using manual feature engineering
      * Using unsupervised dimensionality reduction
      * Use Graph Neural Networks to learn embeddings, end-to-end fashion
  + GNNs are naturally inductive because they learn the same neural networks on all the nodes and edges. A new node in graph can be used for prediction, while it has been trained on the remaining sub-graph.
  + GNNs do not learn embedding as such but the function from input to output. But if you use one-hot embedding on nodes-edge, then inductive bias is lost and then becomes transaction-based.
  + GNNs take graph, update node embeddings, those then participate in node-wise prediction. Similarly, for edge-graph level embeddings.
  + For graph level embedding some aggregation (called 'readout' function) node-edge embeddings.
* A Comprehensive Survey on Geometric Deep Learning - Wenming Cao, IEEE
  + Euclidean domain == grid-like data. Full and fixed size.
  + Non-Euclidean domain == Graphs and manifolds. Not fully connected and variable size.
  + Deep Learning for non-Euclidean domain is called Geometric Deep Learning.
  + Graph is composed of nodes and edges of the network structure data.
  + Manifold data is geometric surface, modeled as point cloud. Irregularly arranged and randomly distributed, thus difficult to find neighbors.
  + Laplacian Matrix is difference of Degree Matrix (diagonal having node incidences) and the Adjacency Matrix
  + Spectral method is the eigen-decomposition of Laplacian matrix
  + A manifold is a topological space that locally resembles Euclidean space near each point ie Tangent plane is 2D for 3D surface at a neighborhood of a point.
  + GCN is spectral method
  + GNN is recursively updating the hidden representation of nodes until convergence, aka recurrent-based spatial GCN
  + Mixture Model Networks (MoNet) is a uniﬁed framework that can extend the CNN structure to non-Euclidean domains (graphs and manifolds), and can learn local, stationary and combinatorial specific task characteristics.
* A Friendly Introduction to Graph Neural Networks <https://www.kdnuggets.com/2020/11/friendly-introduction-graph-neural-networks.html>
  + RNNs are for sequences, which compute not only using inputs but also previous hidden state.
  + For GNN, there is no one input at a time, but whole graph input state. First, each node aggregates the states of its neighbors, called Message Passing.
  + We can simply matrix-multiply the array of node states by the adjacency matrix to sum the value of all neighbors and thus update the nodes states.

* Deep Learning on Graphs: Successes, Challenges, and Next Steps | Michael Bronstein <https://www.youtube.com/watch?v=qrV1KJREGuk>
  + Recipes for Graph Convolution
    - Weights are independent of features: Y = A(W)X , 'A' is non-linearity Activation. Ex. ChebNet, GCN, SGCN
    - Weights are dependent on features: Y = A(W,X)X Ex. MoNer, Graph Attention Networks
    - Activation is dependent on features X' = A\_X (W,X) Ex. Message Passing Neural Networks (MPNN), EdgeConv, Graph Networks
  + Latent Graph: Even though data does not have explicit graph structure, internally it has hidden (latent) graph structure. This is actually Manifold Learning. There, high dimensional data, can be reduced to core lower dimensional Manifold (3d surface has 2d planar manifold, ie in neighborhood).
* How to get started with Graph Machine Learning, Aleksa Gordic, <https://gordicaleksa.medium.com/how-to-get-started-with-graph-machine-learning-afa53f6f963a>
  + Example of Graph based regression: Maybe the nodes in your graphs are tweets and you want to regress the probability that a certain tweet is spreading fake news. Your model would associate a number between 0 and 1 to that node and that would be an example of a node regression task.
  + Graph embedding methods:
    - 'Deep Walk': sample “sentences” from the graph by doing random walks.
    - Once you have the sentence you can do the Word2Vec magic and learn your node embeddings such that those nodes that tend to be close in your sentences have similar embeddings.
  + Graph Neural Networks:
    - Spectral methods try to preserve the strict mathematical notion of convolution and had to resort to the frequency domain (Laplacian eigenbasis) for that. Main idea is to project the graph signal into that eigenbasis, filter the projected graph signal directly in the spectral domain by doing an element-wise multiplication with the filter, and reproject it back into the spatial domain. They are computationally expensive, so not used much.
    - Spatial (message passing) methods are not convolutions in the strict mathematical sense of the word, but we still informally call them convolutions, as they were very loosely inspired by the spectral methods. The goal is to update each and every node’s representation. You have the feature vectors from your node and from his neighbors at disposal. GCN uses constants instead of learnable weights as by GAT, while aggregating neighbors.
    - GraphSAGE — SAmple and aggreGatE, it introduced the concept of sampling your neighborhood and a couple of optimization tricks so as to constrain the compute/memory budget.
    - PinSage — One of the most famous real-world applications of GNNs — recommender system at Pinterest.
* Strategies for Pretraining Graph Neural Network
* Pretraining helps as
* task-speciﬁc labeled data can be extremely scarce
* test examples that are distributionally different from training ones
* Need both, Node and Graph level pre-training together. This ensures that node embeddings capture local neighborhood semantics that are pooled together to obtain meaningful graph-level representations, which, in turn, are used for downstream tasks.



* Attribute Masking pre-training works as:  Mask node/edge attributes and then we let GNNs predict those attributes based on neighboring structure
* Graph Embeddings are pretrained by composing meaningful node embeddings obtained earlier. Options are: making predictions about domain-speciﬁc attributes of entire graphs (e.g. , supervised labels), or making predictions about graph structure ie Similarity.