## Restricted Boltzmann Machines

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## Model Structure

### Model structure

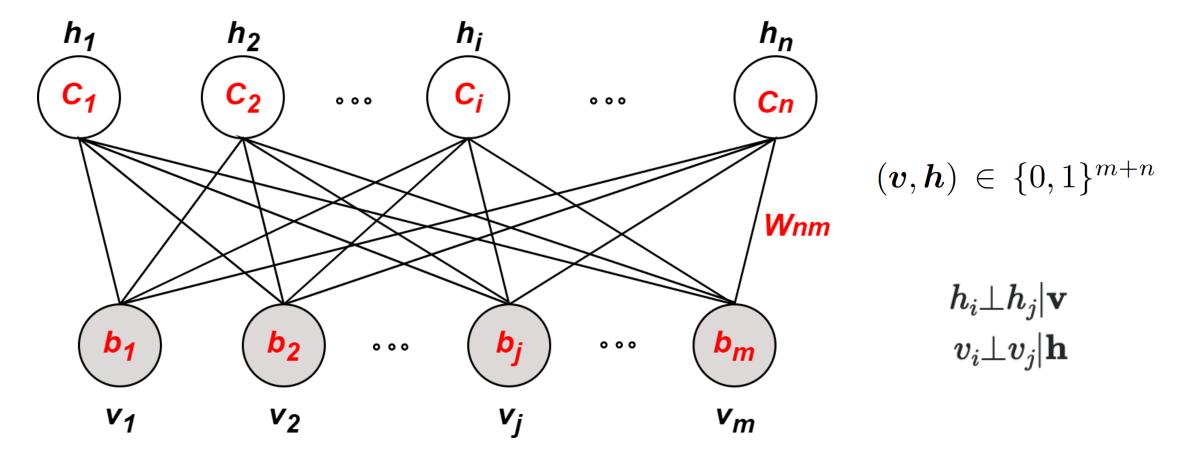
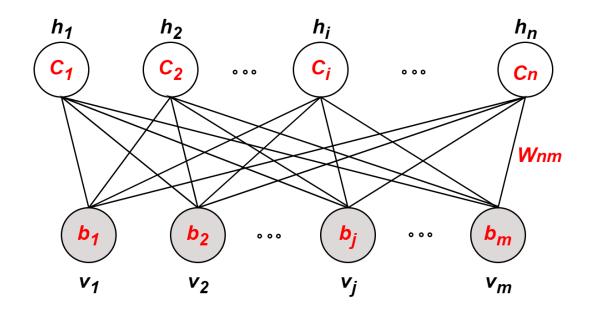


Fig. 1: The undirected graph of an RBM with n hidden and m visible variables

#### Gibbs distribution

$$p(\boldsymbol{v}, \boldsymbol{h}) = \frac{1}{Z} e^{-E(\boldsymbol{v}, \boldsymbol{h})}$$



### **Energy function**

$$E(\mathbf{v}, \mathbf{h}) = -\sum_{i=1}^{n} \sum_{j=1}^{m} w_{ij} h_i v_j - \sum_{j=1}^{m} b_j v_j - \sum_{i=1}^{n} c_i h_i$$

### **Factorization**

$$p(\boldsymbol{h} \mid \boldsymbol{v}) = \prod_{i=1}^{n} p(h_i \mid \boldsymbol{v}) \qquad p(H_i = 1 \mid \boldsymbol{v}) = \sigma \left( \sum_{j=1}^{m} w_{ij} v_j + c_i \right)$$

$$p(\boldsymbol{v} \mid \boldsymbol{h}) = \prod_{i=1}^{m} p(v_i \mid \boldsymbol{h}) \qquad p(V_j = 1 \mid \boldsymbol{h}) = \sigma \left( \sum_{i=1}^{n} w_{ij} h_i + b_j \right)$$

## Gibbs sampling

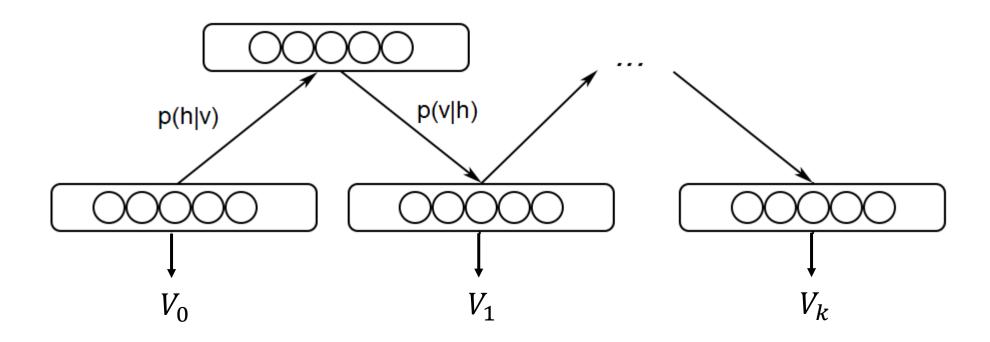


Fig. 2: Block Gibbs Sampling

# **RBM Training**

### Maximum Likelihood

The Log-Likelihood of a general MRF with latent variables is given by:

$$\ln \mathcal{L}(\boldsymbol{\theta} \mid \boldsymbol{v}) = \ln p(\boldsymbol{v} \mid \boldsymbol{\theta}) = \ln \frac{1}{Z} \sum_{\boldsymbol{h}} e^{-E(\boldsymbol{v}, \boldsymbol{h})} = \ln \sum_{\boldsymbol{h}} e^{-E(\boldsymbol{v}, \boldsymbol{h})} - \ln \sum_{\boldsymbol{v}, \boldsymbol{h}} e^{-E(\boldsymbol{v}, \boldsymbol{h})}$$

The gradient w.r.t. the parameters is:

$$\frac{\partial \ln \mathcal{L}(\boldsymbol{\theta} \mid \boldsymbol{v})}{\partial \boldsymbol{\theta}} = -\sum_{\boldsymbol{h}} p(\boldsymbol{h} \mid \boldsymbol{v}) \frac{\partial E(\boldsymbol{v}, \boldsymbol{h})}{\partial \boldsymbol{\theta}} + \sum_{\boldsymbol{v}, \boldsymbol{h}} p(\boldsymbol{v}, \boldsymbol{h}) \frac{\partial E(\boldsymbol{v}, \boldsymbol{h})}{\partial \boldsymbol{\theta}}$$

### Maximum Likelihood for RBM

The explicit derivative w.r.t the weights  $w_{ij}$  is:

$$\frac{\partial \ln \mathcal{L}(\boldsymbol{\theta} \mid \boldsymbol{v})}{\partial w_{ij}} = -\sum_{\boldsymbol{h}} p(\boldsymbol{h} \mid \boldsymbol{v}) \frac{\partial E(\boldsymbol{v}, \boldsymbol{h})}{\partial w_{ij}} + \sum_{\boldsymbol{v}, \boldsymbol{h}} p(\boldsymbol{v}, \boldsymbol{h}) \frac{\partial E(\boldsymbol{v}, \boldsymbol{h})}{\partial w_{ij}}$$

Computing the derivatives and using a factorization trick we obtain:

$$\frac{\partial \ln \mathcal{L}(\boldsymbol{\theta} \mid \boldsymbol{v})}{\partial w_{ij}} = p(H_i = 1 \mid \boldsymbol{v})v_j - \sum_{\boldsymbol{v}} p(\boldsymbol{v})p(H_i = 1 \mid \boldsymbol{v})v_j$$
OK

## **Contrastive Divergence**

To solve the problem we use the <u>contrastive divergence</u> technique:

$$CD_k(\boldsymbol{\theta}, \boldsymbol{v}^{(0)}) = -\sum_{\boldsymbol{h}} p(\boldsymbol{h}|\boldsymbol{v}^{(0)}) \frac{\partial E(\boldsymbol{v}^{(0)}, \boldsymbol{h})}{\partial \boldsymbol{\theta}} + \sum_{\boldsymbol{h}} p(\boldsymbol{h}|\boldsymbol{v}^{(k)}) \frac{\partial E(\boldsymbol{v}^{(k)}, \boldsymbol{h})}{\partial \boldsymbol{\theta}} \qquad \qquad k = 1$$

Maximum Likelihood:  $\longrightarrow$  Minimize  $\left[\mathrm{KL}(q|p)\right]$ 

Contrastive divergence:  $\longrightarrow$  Minimize  $ig[\mathrm{KL}(q|p) - \mathrm{KL}(p_k|p)ig]$ 

## Pseudocode of Contrastive Divergence

Input: RBM, training batch S

**Output:** gradient approximations

```
Init \Delta w = \Delta b = \Delta c = 0

forall v in a batch
\begin{array}{c} v^{(0)} \leftarrow v \\ \text{for t=0 step (k-1)} \\ v^{(k)} \leftarrow \text{ sample } h^{(t)} \text{ from p(h}|v^{(t)}) \text{ and subsequently } v^{(t+1)} \text{ from p(h}|v^{(t)}) \\ \text{update } \Delta w, \Delta b, \Delta c \text{ using CD rules} \end{array}
```

# Application

### Classification on MNIST dataset



- PREPROCESSING: scaling the pixel values in [0,1] with grayscale
- TRAINING: defining the RMB architecture by setting the number of hidden units and train on MNIST
- FEATURE EXTRACTION: transform the data with the features extracted by RBM
- **CLASSIFICATION**: training general classifiers with extracted features

Fig. 3: Sample from MNIST dataset 28x28 images

# Features extraction and classification

MODEL	ACCURACY RBM	ACCURACY RAW
Logistic	0.94	0.92
KNN	0.97	0.98
SVM	0.97	0.98

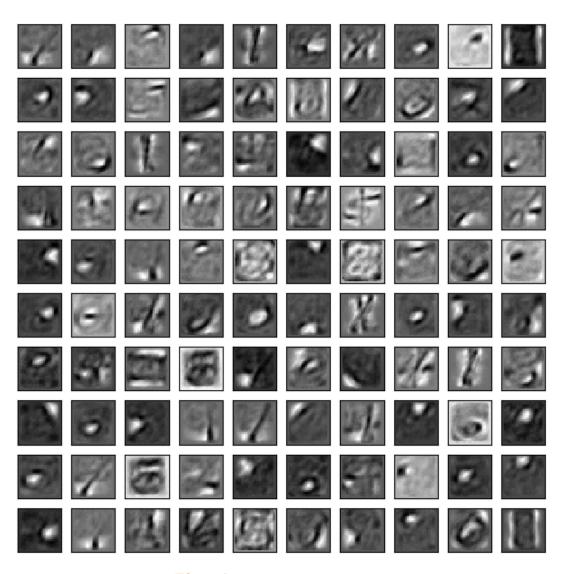


Fig. 4: 100 components

### Evaluation

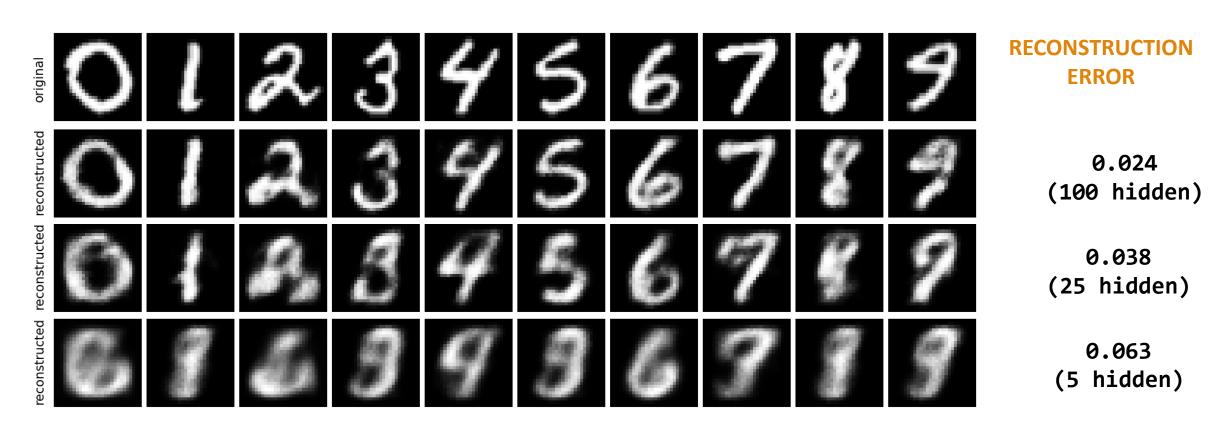


Fig. 5: Comparison of reconstruction with different numbers of hidden variables

## Conclusions

#### RBM vs raw pixels for classification

- Feature extraction
- Dimensionality reduction
- Unupervised learning

#### **Current application**

- Using RBM as building blocks of Deep neural networks

## References

- [1] A. Fischer and C. Igel, "An introduction to restricted Boltzmannmachines". In: Progress in Pattern Recognition, Image Analysis, Computer Vision, and Applications. Springer, Berlin Heidelberg, 2012.
- [2] Carreira-Perpiñán, M.A., Hinton, G.E.: On contrastive divergence learning. In: 10th International Workshop on Artificial Intelligence and Statistics (AISTATS 2005), pp. 59–66 (2005)
- [3] Hinton, G.E.: Training products of experts by minimizing contrastive divergence. Neural Computation 14, 1771–1800 (2002)

## Thank you for the attention!

## Factorization trick

$$\sum_{\mathbf{h}} p(\mathbf{h} \mid \mathbf{v}) \frac{\partial E(\mathbf{v}, \mathbf{h})}{\partial w_{ij}} = \sum_{\mathbf{h}} p(\mathbf{h} \mid \mathbf{v}) h_i v_j$$

$$= \sum_{\mathbf{h}} \prod_{k=1}^n p(h_k \mid \mathbf{v}) h_i v_j = \sum_{h_i} \sum_{\mathbf{h}_{-i}} p(h_i \mid \mathbf{v}) p(\mathbf{h}_{-i} \mid \mathbf{v}) h_i v_j$$

$$= \sum_{h_i} p(h_i \mid \mathbf{v}) h_i v_j \sum_{\mathbf{h}_{-i}} p(\mathbf{h}_{-i} \mid \mathbf{v}) = p(H_i = 1 \mid \mathbf{v}) v_j = \sigma \left( \sum_{j=1}^m w_{ij} v_j + c_i \right) v_j$$