

Recitation 10, November 2018 Graph Algorithms

Objectives

- 1. What is a Graph?
- 2. Depth First Search
- 3. Breadth First Search
- 4. Exercise
 - a. Challenge 1 (Silver Badge)
 - b. Challenge 2 (Gold Badge)

In real world, many problems are represented in terms of objects and connections between them. For example, in an airline route map, we might be interested in questions like: "What's the fastest way to go from Denver to San Francisco" or "What is the cheapest way to go from Denver to San Francisco" To answer these questions we need information about connections between objects. Graphs are data structures used for solving these kinds of problems.

Graph: A graph is a pair (V, E), where V is a set of nodes, called vertices and E is a collection of pairs of vertices, called edges.

Directed Edge

- Ordered pair of vertices (u, v)
- First vertex u is the origin
- Second vertex v is the destination
- Example: one way road traffic





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Undirected Edge:

- Unordered pair of vertices (u, v)
- Example: Railway lines



Applications of Graphs

- Representing relationships between components in electronic circuits.
- Transportation networks: Highway network, Flight network
- Computer networks: Local area network, Internet web

Graph Representation

As in other Abstract Data types, to manipulate graphs we need to represent them in some useful form. Basically, there are two ways of doing this:

- Adjacency Matrix
- Adjacency Lists

Graph Traversals

To solve problems on graphs, we need a mechanism for traversing the graphs. Graph traversal algorithms are also called a graph search algorithms. Like tree traversal algorithms (Inorder, Preorder, Postorder traversals), graph search algorithms can be thought of as starting at some source vertex in a graph, and 'search' the graph by going through the edges and making the vertices. Now, we will discuss two such algorithms for traversing the graphs.

- Depth First Search (DFS)
- Breadth First Search (BFS)

Depth First Search (DFS)

The strategy followed by depth-first search is, as its name implies, to search "deeper" in the graph whenever possible.



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The DFS algorithm is a recursive algorithm that uses the idea of backtracking. The idea is to travel as deep as possible from neighbour to neighbour before backtracking. What determines how deep is possible is that you must follow edges, and you don't visit any vertex twice. To do this properly we need to keep track of which vertices have already been visited, plus how we got to where we currently are, so that we can backtrack.

Here, the word backtrack means that when you are moving forward and there are no more nodes along the current path, you move backwards on the same path to find nodes to traverse.

All the nodes on the current path are visited, after which the next path will be selected. We would be using the Adjacency lists to get the neighbours of any vertex.

Here's a pseudocode of this recursive approach:

```
DFS(G, u)
    u.visited = true
    for each v ∈ G.Adj[u]
        if v.visited == false
            DFS(G,v)

init() {
    for each u ∈ G
        u.visited = false
        for each u ∈ G
            If u.visited==false
            DFS(G, u)
}
```

Make sure that the nodes that are visited are marked. This will prevent you from visiting the same node more than once. If you do not mark the nodes that are visited and you visit the same node more than once, you may end up in an infinite loop.

This recursive behaviour can be simulated by an iterative algorithm using a stack. So, DFS uses a stack to push nodes we mean to visit onto that.

We gave a pseudocode for DFS traversal using recursion and we will be giving a visualization of DFS traversal using stacks to help you understand better. The following will give you the basic idea of Stack implementation.



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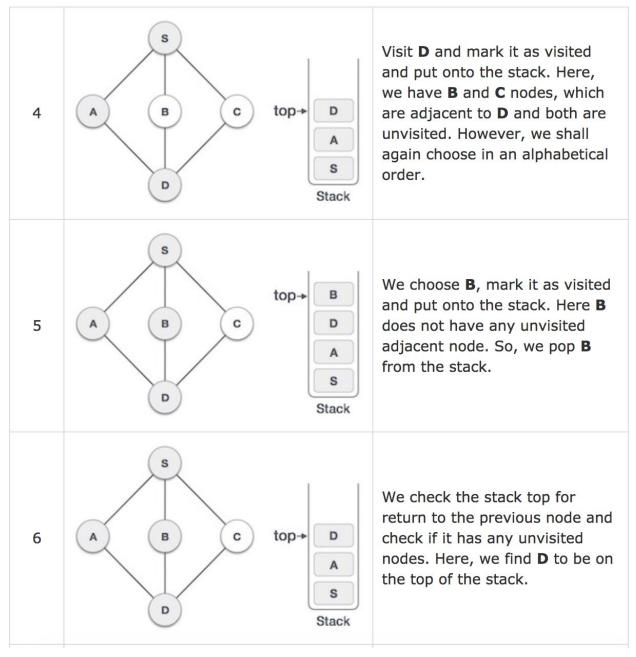
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Step	Traversal		Description
1	A B C	Stack	Initialize the stack.
2	A B C	top→ S Stack	Mark S as visited and put it onto the stack. Explore any unvisited adjacent node from S . We have three nodes and we can pick any of them. For this example, we shall take the node in an alphabetical order.
3	A B C	top→ A s Stack	Mark A as visited and put it onto the stack. Explore any unvisited adjacent node from A. Both S and D are adjacent to A but we are concerned for unvisited nodes only.



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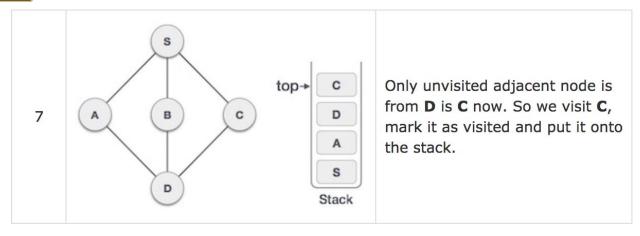
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As C does not have any unvisited adjacent node so we keep popping the stack until we find a node that has an unvisited adjacent node. In this case, there's none and we keep popping until the stack is empty.

Applications of DFS

- Finding connected components (Number of islands in a network)
- Solving puzzles, such as mazes (DFS helps to reach the goal faster)

Breadth First Search (BFS)

Breadth-first search is one of the simplest algorithms for searching a graph and the archetype for many important graph algorithms.

BFS works level by level. Initially, BFS starts at a given vertex, which is at level 0. In the first stage it visits all vertices at level 1. In the second stage, it visits all vertices at second level. These new vertices are the one which are adjacent to level 1 vertices.

BFS continues this process until all the levels of the graph are completed. Generally queue data structure is used for storing the vertices of a level. As similar to DFS, assume that initially all vertices are marked as unvisited. Vertices that have been processed and removed from the queue are marked visited. We use a queue to represent the visited set as it will keep the vertices in order of when they were first visited.

Breadth-first search is so named because it expands the frontier between discovered and undiscovered vertices uniformly across the breadth of the frontier. That is, the algorithm discovers all vertices at distance k from s before discovering any vertices at distance k + 1.

Similarly we have an example for BFS as well using queues.



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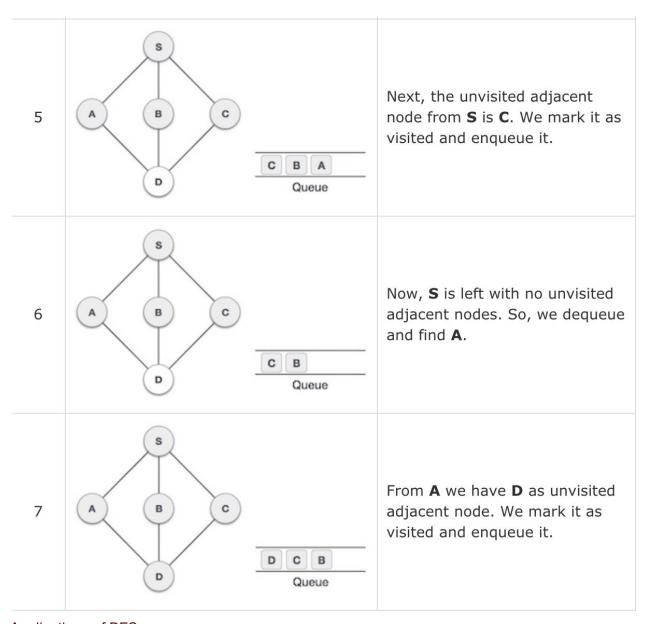
Graph Algorithms

Step	Traversal	Description
1	A B C Queue	Initialize the queue.
2	A B C Queue	We start from visiting S (starting node), and mark it as visited.
3	A B C A Queue	We then see an unvisited adjacent node from S . In this example, we have three nodes but alphabetically we choose A , mark it as visited and enqueue it.
4	A B C B A Queue	Next, the unvisited adjacent node from S is B . We mark it as visited and enqueue it.



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Applications of BFS

- Finding all connected components in a graph.
- Finding all nodes within one connected component.
- Finding the shortest path between two nodes.

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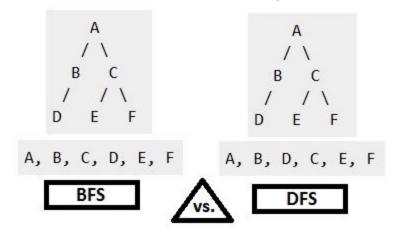
Comparison between DFS and BFS

The biggest advantage of DFS is that it has much lower memory requirements than BFS, because it's not required to store all the child pointers at each level.

DFS is related to preorder traversal of a tree. Like preorder traversal simply DFS visits each node before its children.

Metric	BFS	DFS
Optimality	Good for finding shortest distance between 2 vertices	Not optimal to find shortest path.
Data Structure used	Queue	Stack (May be system stack if the stack is not initialised explicitly in the code)
Memory	Slow and requires more memory	Fast and requires less memory

Comparison of BFS vs DFS on a simple graph:



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Exercise

- A. Silver Badge Problem
- 1. Download the **Level_Order.cpp** file from moodle.
- 2. Given a binary tree, use the BFS logic to print the elements of the tree, level by level.
- B. Gold Badge Problem
 - 1. Download the **GoldMain.cpp** file from moodle and complete the DFS functionality.
 - 2. Given an adjacency matrix of edges and nodes, find the total **number of connected components** or number of islands in the graph using DFS.