Cache Lab Implementation and Blocking

Marjorie Carlson Section A October 7th, 2013

Welcome to the World of Pointers!



Class Schedule

Cache Lab

- Due Thursday.
- Start now (if you haven't already).

■ The Midterm Starts in <10 Days!</p>

- Wed Oct 16th Sat Oct 19
- Start now (if you haven't already).
- No, really. Start now.

Outline

Memory organization

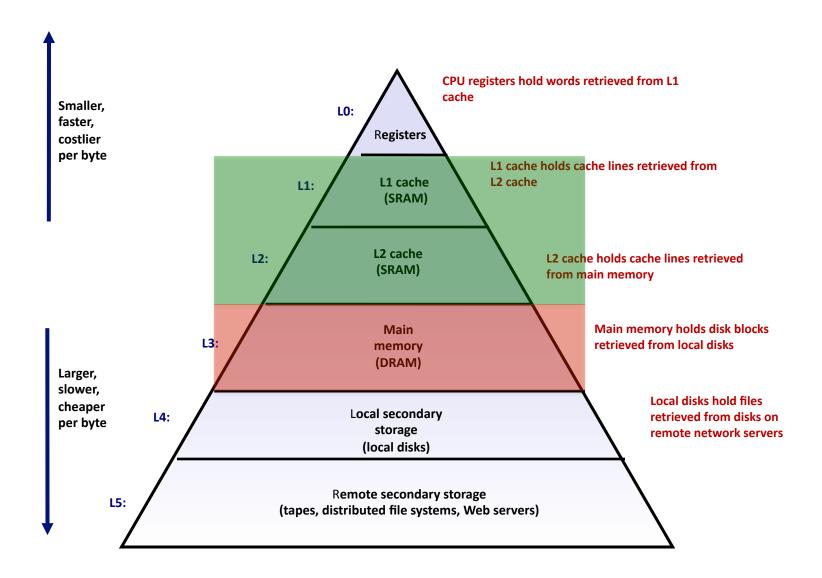
Caching

- Different types of locality
- Cache organization

Cachelab

- Part (a) Building Cache Simulator
- Part (b) Efficient Matrix Transpose

Memory Hierarchy



SRAM vs. DRAM tradeoff

SRAM (cache)

Faster:
L1 cache = 1 CPU cycle

Smaller: Kilobytes (L1) or Megabytes (L2)

More expensive and "energy-hungry"

DRAM (main memory)

Relatively slower: hundreds of CPU cycles

Larger: Gigabytes

Cheaper

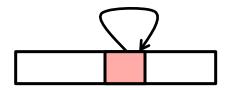
Locality

The key concept that makes caching work:

If you use a piece of data, you'll probably use it and/or nearby data again soon. So it's worth taking the time to move that whole chunk of data to SRAM, so subsequent access to that block will be fast.

Temporal locality

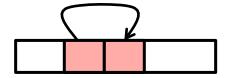
 Recently referenced items are likely to be referenced again in the near future



 After accessing address X in memory, save the bytes in cache for future access

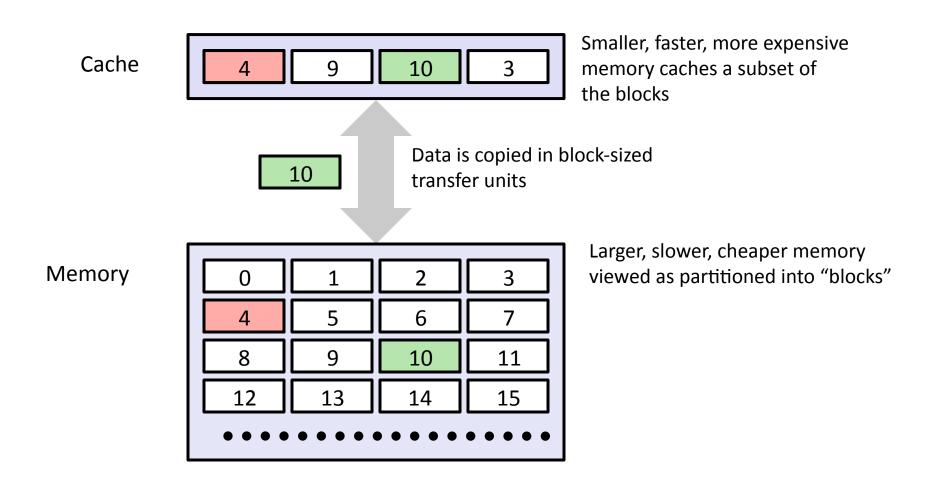
Spatial locality

 Items with nearby addresses tend to be referenced close together in time



 After accessing address X, save the block of memory around X in cache for future access

General Cache Concepts



Memory Address

memory address

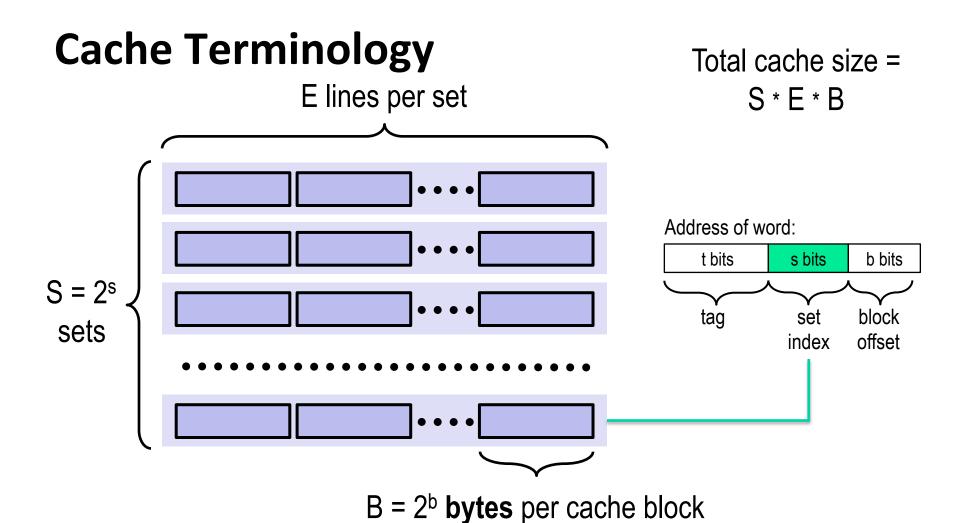
tag set index block offset

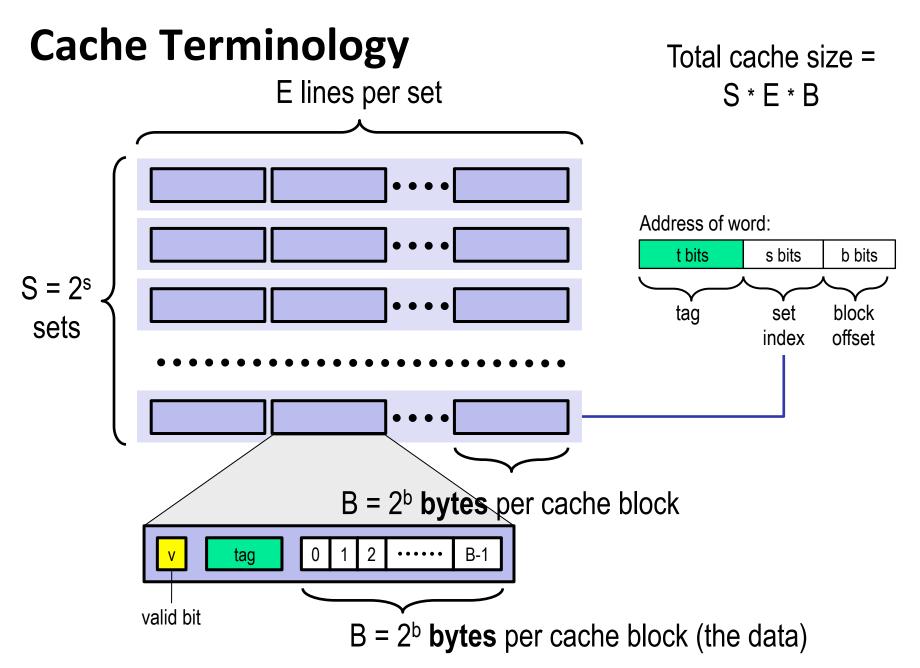
Block offset: b bits

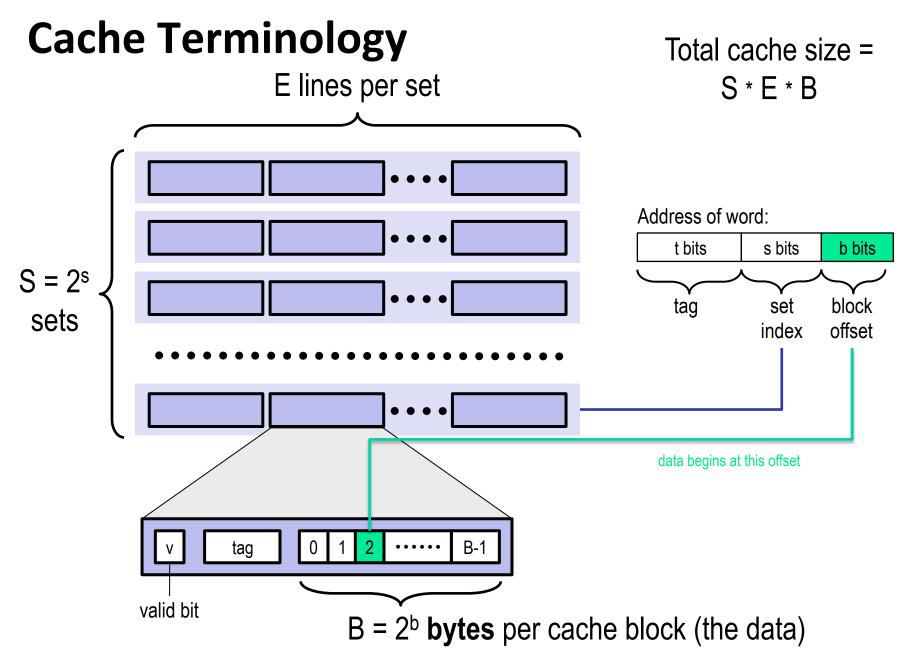
- \leftarrow
- Size of block $\mathbf{B} = 2^{b}$

■ Set index: **s** bits

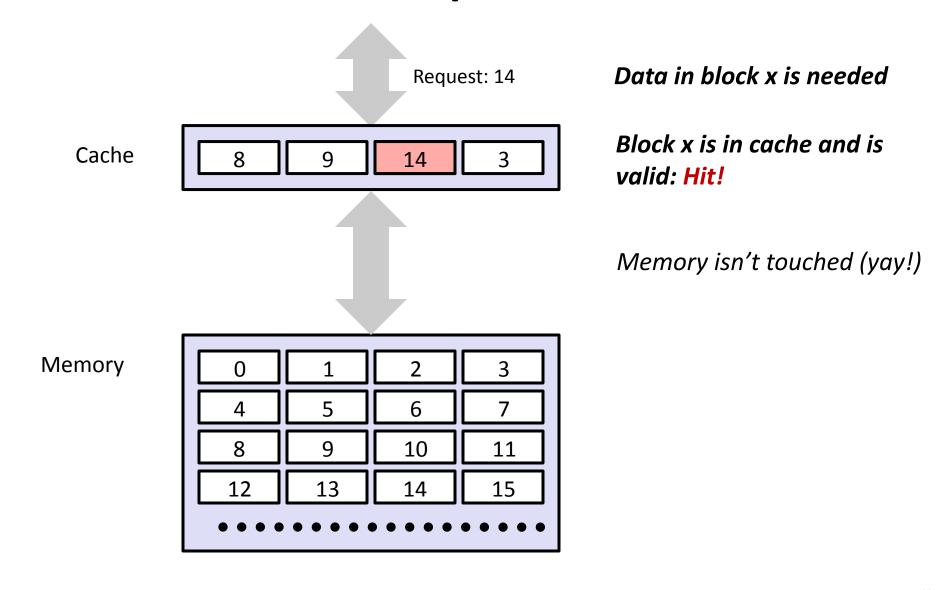
- Number of sets $S = 2^s$
- Tag Bits: t bits = {address size} b s
 (On shark machines, address size = 64 bits.)
- **Key point:** if the data at a given address is in the cache, it **has** to be in the *block offset*th byte of the *set index*th set but it can be in any line in that set.



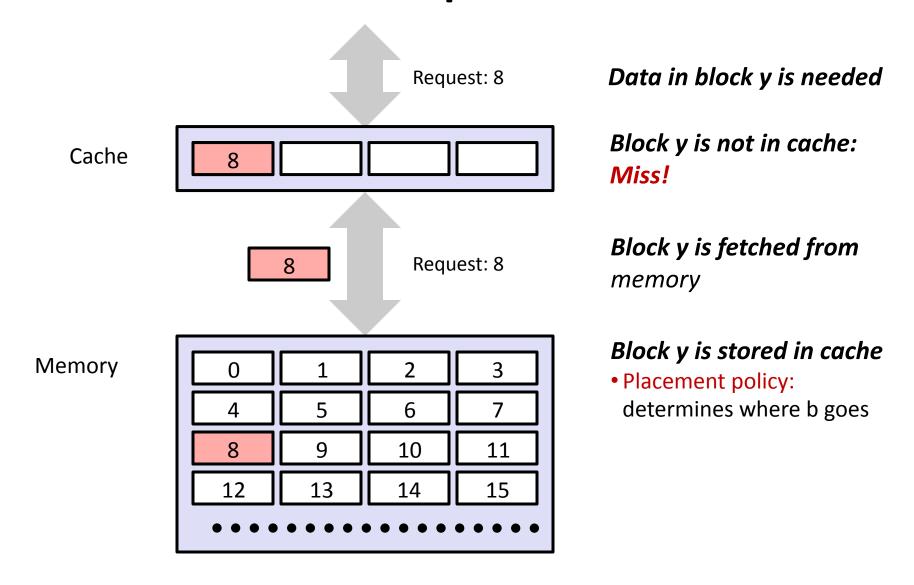




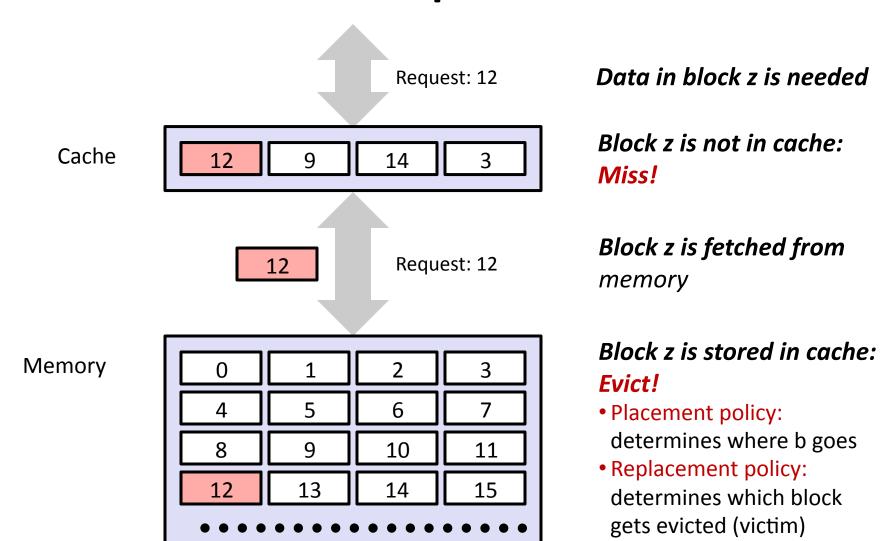
General Cache Concepts: Hit



General Cache Concepts: Miss



General Cache Concepts: Miss & Evict



General Caching Concepts: Types of Misses

Cold (compulsory) miss

The first access to a block has to be a miss.

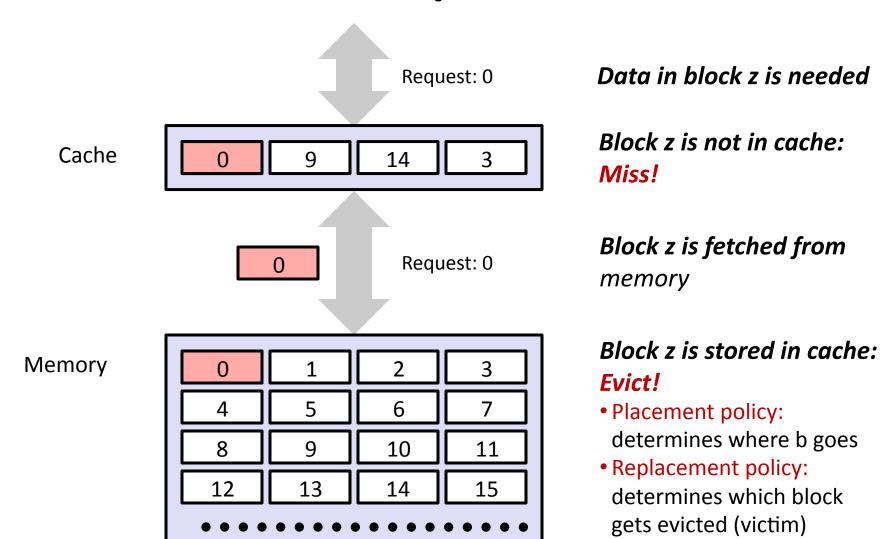
Conflict miss

- Conflict misses occur when the cache is large enough, but multiple data objects all map to the same block
 - e.g., referencing blocks 0, 8, 0, 8, 0, 8, ... would miss every time

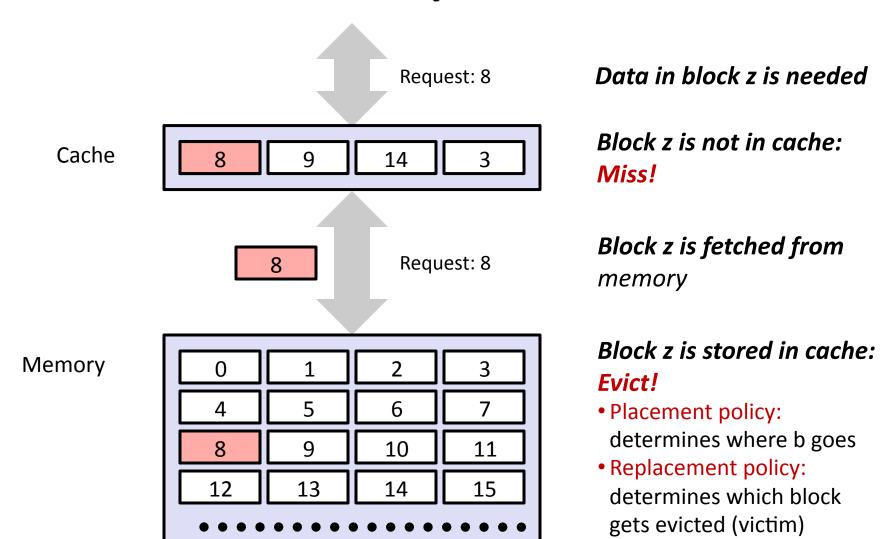
Capacity miss

 Occurs when the set of active cache blocks (working set) is larger than the cache

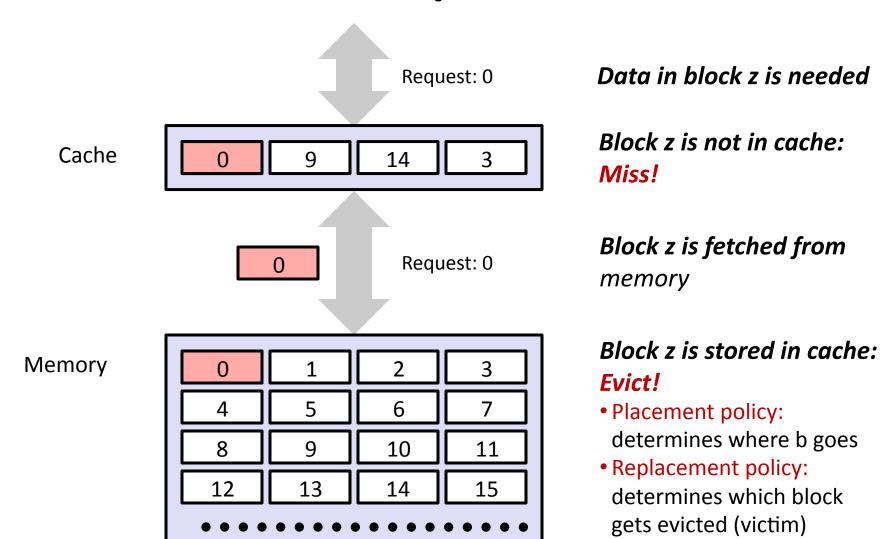
General Cache Concepts: Conflict Misses



General Cache Concepts: Conflict Misses



General Cache Concepts: Conflict Misses



Sets vs. Lines

Why arrange cache in sets?

If a block can be stored anywhere, then you have to search for it everywhere.

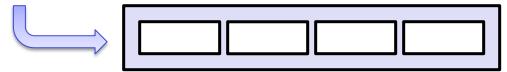
Why arrange cache in lines?

If a block can can only be stored in one place, it'll be evicted a lot.

"The rule of thumb is that doubling the associativity, from direct mapped to two-way, or from two-way to four-way, has about the same effect on hit rate as doubling the cache size." —Wikipedia, CPU Cache

Sets vs. Lines

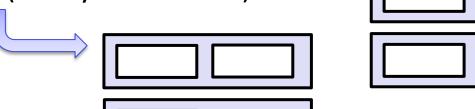
- An 8-byte cache with 2-byte blocks could be arranged as:
 - one set of four lines ("fully associative"):



four sets of one line ("direct-mapped"):



two sets of two lines (2-way associative):



Sets vs. Lines

	Data	ʻa'	ʻb'	ʻc'	ʻd'	'e'	"f"	ʻg'	ʻh'	T	ij'	'k'	T
P	Address	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011

- For each possible configuration of an 8-byte cache with 2bytes blocks:
 - How many how many hits/misses/evictions will there be for the following sequence of operations?
 - What will be in the cache at the end?
 - 1. L 0101
 - 2. L 0100
 - 3. L 0000
 - 4. L 0010

- 5. L 1000
- 6. L 0000
- 7. L 0101
- 8. L 1011

Outline

Memory organization

Caching

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- Cache organization

Cachelab

- Part (a) Building Cache Simulator
- Part (b) Efficient Matrix Transpose

Part (a) Cache simulator

- A cache simulator is NOT a cache!
 - Memory contents are not stored.
 - Block offsets are not used the b bits in your address don't matter.
 - Simply count hits, misses, and evictions.
- Your cache simulator needs to work for different values of s, b, and E — given at run time.
- Use LRU a Least Recently Used replacement policy
 - Evict the least recently used block from the cache to make room for the next block.
 - Queues? Time stamps? Counter?

Part (a) Hints

- Structs are a great way to represent your cache line. Each cache line has:
 - A valid bit.
 - A tag.
 - Some sort of LRU counter (if you are not using a queue).
- A cache is just 2D array of cache lines:
 - struct cache_line cache[S][E];
 - Number of sets: S = 2s
 - Number of lines per set: E
 - You know S and E at run time, but not at compile time. What does that mean you'll have to do when you declare your cache?

Part (a) malloc/free

- Use malloc to allocate memory on the heap.
- Always free what you malloc, otherwise you will leak memory!

```
my_pointer = malloc(sizeof(int));
... use that pointer for a while ...
free(my_pointer);
```

- Common mistake: freeing your array of pointers, but forgetting to free the objects those pointers point to.
- Valgrind is your friend!

Part (a) getopt

- getopt() automates parsing elements on the Unix command line.
 - It's typically called in a loop to deal with each flag in turn. (It returns -1 when it's out of inputs.)
 - Its return value is the flag it's currently parsing ("x", "y", "r"). You can then use a switch statement on the local variable you stored that value to.
 - If a flag has an associated argument, getopt also gives you optarg, a pointer to that argument ("1", "3"). Remember this argument is a string, not an integer.
 - Think about how to handle invalid inputs.

Part (a) getopt Example

```
./point -x 1 -y 3 -r
```

```
int main(int argc, char** argv){
 int opt, x, y;
 int r = 0;
 while(-1 != (opt = getopt(argc, argv, "x:y:r"))){
    switch(opt) {
      case 'x':
        x = atoi(optarg);
        break;
      case 'y':
        y = atoi(optarg);
        break;
      case 'r':
        r = 1;
        break;
      default:
        printf("Invalid argument.\n");
        break;
```

Part (a) fscanf

- fscanf will be useful in reading lines from the trace files.
 - L10,4
 - M 20,8
- fscanf() is just like scanf() except it can specify a stream to read from (i.e., the file you just opened).
- Its parameters are:
 - 1. a stream pointer (e.g. your file descriptor).
 - 2. a format string with information on how to parse the file
 - 3-n. the appropriate number of **pointers** to the variables in which you want to store the data from your file.
- You typically want to use it in a loop; it returns -1 if it hits EOF (or if the data doesn't match the format string).

Part (a) fscanf Example

Part (a) Header files!

- If you use a library function, always remember to #include the relevant library!
- Use man <function-name> to figure out what header you need.
 - man 3 getopt
 - If you're not using a shark machine, you'll need <getopt.h> as well as <unistd.h>. (So why not use a shark machine?)
- If you get a warning about a missing or implicit function declaration, you probably forgot to include a header file.

Part (a) Relevant tutorials

- getopt:
 - http://www.gnu.org/software/libc/manual/html_node/ Getopt.html
- fscanf:
 - http://crasseux.com/books/ctutorial/fscanf.html
- Google is your friend!

Part (b) Efficient Matrix Transpose

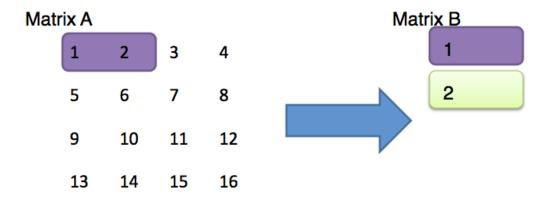
Matrix Transpose (A -> B)

Matrix A Matrix B

How do we optimize this operation using the cache?

Part (b) Efficient Matrix Transpose

Suppose block size is 8 bytes. Each int is 4 bytes.



- Access A[0][0]: cache miss
- Access B[0][0]: cache miss
- Access A[0][1]: cache hit
- Access B[1][0]: cache miss

Should we handle 3 & 4 next or 5 & 6?

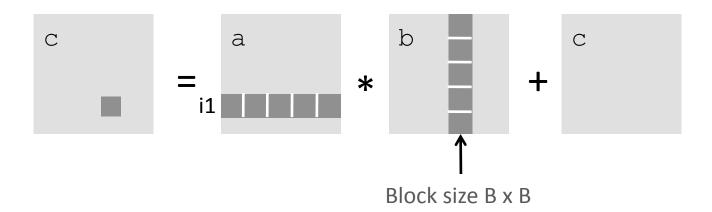
Part (b) Blocked Matrix Multiplication

```
c = (double *) calloc(sizeof(double), n*n);

/* Multiply n x n matrices a and b */
void mmm(double *a, double *b, double *c, int n) {
```

"Sometimes it is faster to do more faster work than less slower work."
-Greg Kesden

```
/* B x B mini matrix multiplications */
for (i1 = i; i1 < i+B; i++)
   for (j1 = j; j1 < j+B; j++)
      for (k1 = k; k1 < k+B; k++)
        c[i1*n+j1] += a[i1*n + k1]*b[k1*n + j1];
}</pre>
```



Part (b) Blocking

- Blocking: dividing your matrix into sub-matrices.
- The ideal size of each sub-matrix depends on your cache block size, cache size, and input matrix size.
- Try different sub-matrix sizes and see what happens!
- http://csapp.cs.cmu.edu/public/waside/wasideblocking.pdf

Part (b) Specs

Cache:

- You get 1 KB of cache
- It's directly mapped (E=1)
- Block size is 32 Bytes (b=5)
- There are 32 sets (s=5)

Test Matrices:

- **32** by 32
- 64 by 64
- 61 by 67
- Your solution need not work on other size matrices.

General Advice: Warnings are Errors!

Strict compilation flags:

- -Wall "enables all the warnings about constructions that some users consider questionable, and that are easy to avoid."
- -Werror treats warnings as errors.

■ Why?

- Avoid potential errors that are hard to debug.
- Learn good habits from the beginning.

```
#
# Student makefile for Cache Lab
#
CC = gcc
CFLAGS = -g -Wall -Werror -std=c99
...
```

General Advice: Style!!!

- The rest of the labs in this course will be hand-graded for style as well as auto-graded for correctness.
- Read the <u>style guideline</u>.
 - "But I already read it!"
 - Good, read it again.
- Pay special attention to failure and error checking.
 - Functions don't always work
 - What happens when a system call fails?
- Start forming good habits now!