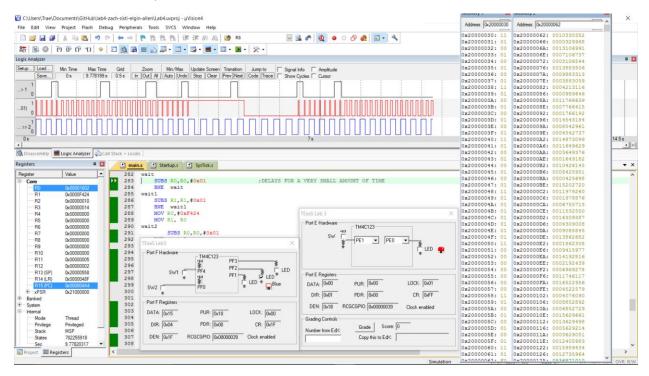
## Zach Sisti / Elgin Allen

## 1. Screenshot of system



## Assembly Code

```
GPIO_PORTE_DATA_R EQU 0x400243FC
GPIO_PORTE_DIR_R EQU 0x40024400
GPIO_PORTE_AFSEL_R EQU 0x40024420
GPIO_PORTE_DEN_R EQU 0x4002451C
GPIO_PORTF_DATA_R EQU 0x400253FC
GPIO_PORTF_DIR_R EQU 0x40025400
GPIO_PORTF_AFSEL_R EQU 0x40025420
GPIO_PORTF_PUR_R EQU 0x40025510
GPIO_PORTF_DEN_R EQU 0x4002551C
GPIO_PORTF_CR_R EQU 0x40025524
GPIO_PORTF_PCTL_R EQU 0x4002552C
GPIO_PORTF_LOCK_R EQU 0x40025520
SYSCTL_RCGCGPIO_R EQU 0x400FE608
                    EQU 0xE000E010
NVIC_ST_CTRL_R
NVIC_ST_RELOAD_R EQU 0xE000E014
NVIC_ST_CURRENT_R EQU 0xE000E018
; RAM Area
      AREA DATA, ALIGN=2
:-UUU-Declare and allocate space for your Buffers
; and any variables (like pointers and counters) here
DataBuffer SPACE 50
                                     ;each enty is 1 byte/8B
                           ; each entry is 4 bytes/32B
TimeBuffer SPACE 200
                                     ; Addresses are 32B
DataPt SPACE 4
TimePt SPACE 4
                                     ;Addresses are 32B
NEntries FILL 1,0,1
; ROM Area
   IMPORT TExaS_Init
           IMPORT SysTick_Init
;-UUU-Import routine(s) from other assembly files (like SysTick.s) here
   AREA |.text|, CODE, READONLY, ALIGN=2
   THUMB
   EXPORT Start
Start
; TExaS_Init sets bus clock at 80 MHz
   BL TExaS_Init; voltmeter, scope on PD3
   CPSIE I ; TExaS voltmeter, scope runs on interrupts
         LDR R1, =SYSCTL_RCGCGPIO_R;1) activate clock for Port F and E
         LDR R0, [R1]
         ORR R0, R0, #0x30 ;set bit 4,5 to turn on clock
         STR R0, [R1]
         NOP
         NOP ;allow time for clock to finish
         LDR R1, =GPIO_PORTF_LOCK_R
         LDR R0, =0x4C4F434B
         STR R0, [R1]
         LDR R1, =GPIO_PORTF_LOCK_R
         LDR R0, [R1]
         LDR R1, =GPIO_PORTF_PCTL_R
         STR R0, [R1]
         LDR R1, =GPIO_PORTF_CR_R
         MOV R0, #0x7FFF
         STR R0, [R1]
         LDR R1, =GPIO_PORTF_DIR_R;5) set direction register
         LDR R0, [R1]
         MOV R0, #0x04 ;set all pins as inputs
         STR R0, [R1]
         LDR R1, =GPIO_PORTF_DEN_R;7) enable Port F digital port
         LDR R0, [R1]
         MOV R0, #0x1F;1 means enable digital I/O
         STR R0, [R1]
         LDR R1, =GPIO_PORTF_AFSEL_R
         LDR R1, [R1]
```

```
STR R0, [R1]
         LDR R1, =GPIO_PORTF_PUR_R; pull-up resistors for PF4
         MOV R0, #0x10 ;enable weak pull-up on PF4
         STR R0, [R1]
         LDR R1, =GPIO_PORTE_DIR_R;5) set direction register
         LDR R0, [R1]
         MOV R0, #0x1 ;set pins 3-1 input, pin 0 as output
         STR R0, [R1]
         LDR R1, =GPIO_PORTE_DEN_R;7) enable Port E digital port
         LDR R0, [R1]
         MOV R0, #0x1B;1 means enable digital I/O
         STR R0, [R1]
         LDR R1, =GPIO_PORTE_AFSEL_R
         LDR R1, [R1]
         AND R0, R0, #0x00
         STR R0, [R1]
         MOV R10, #0
         MOV R11, #5
                           :PERIOD
         MOV R12, #1
                           ;DUTY CYCLE
         BL Debug_Init
loop
         LDR R1, =GPIO_PORTF_DATA_R
         LDR R2, [R1]
         AND R2, R2, #0x04
         EOR R2, R2, #0X04
         STR R2, [R1]
         LDR R1, =GPIO_PORTF_DATA_R
         LDR R2, [R1]
         AND R2, R2, #0x10
         AND R0, #0
                                              ;CLEAR R0
         CMP R2, R0
         BEQ breathe
         CMP R9, R0
         BGT noduty
         BL toggleLightOn
noduty
         ADD R0, R12, R0
                                    ;R0=DUTY
         BL delay
         BL delay
         SUB R0, R11, R12 ;R0=PERIOD-DUTY
         AND R1, R1, #0
         CMP R0, R1
         BEQ fullcycle
         BL toggleLightOff
fullcycle
         BL delay
         BL delay
         LDR R1, =GPIO_PORTE_DATA_R
                                              ;CHECKING SWITCH
         LDR R0, [R1]
         AND R2, R0, #0x02
         MOV R0, #0
                                                                CREATING CONSTANT FOR COMPARING
         CMP R2, R0
                                                                ;CHECKING SWITCH STATE
         BEQ notPressed
         AND R9, R9, #0
         AND R6, R6, #0
                                                       ;CLEAR R6
         ADD R6, R6, #1
                                              ;INDICATES SWITCH HAS BEEN PRESSED
         ADD R8, R8, #1
         ;CMP R8, #0
         ;BEQ DontCap
         ;BL Debug_Capture
         ;SUB R8, R8, #1
;DontCap
         B loop
notPressed
```

AND R0, R0, #0x00

```
AND R8, R8, #0
         AND R5, R5, #0
                                                        ;CLEAR R5
         CMP R6, R5
                                                                  ;CHECK IF SWITCH HAS BEEN PRESSED
         BEQ loop
         MOV R10, #7
         CMP R11, R12
                                                        ;CHECKS IF DUTY=PERIOD
         BEQ reset
         ADD R12, R12, #1
                                               ;IF NOT INCREASE DUTY (20%)
         AND R6, R6, #0
         B loop
reset
         AND R12, R12, #0
                                               ;RESETS DUTY TO 0%
         AND R6, R6, #0
         AND R9, R9, #0
         ADD R9, R9, #1
         B loop
breathe
         PUSH {R12, R7, R0, R11}
         MOV R11, #10
         MOV R7. #0
                                               :SET COUNTER TO 0
                                               ;UP/DOWN INDICATOR (0 UP, 1 DOWN)
         MOV R10, #0
         MOV R1, #0
                                               ;0 CONSTANT FOR COMPARING
breathe1
         BL toggleLightOn
ADD R0, R12, R0
                                     ;R0=DUTY
         BL delay
         BL toggleLightOff
         SUB R0, R11, R12
                           ;R0=PERIOD-DUTY
         BL delay
         CMP R10, R1
                                               ;increment or decrement (up/down indicator)
                                     ;if R10==0
         BEQ increment
         ADD R12, R12, #-1 ;decrement
         B skp
increment
         ADD R12, R12, #1
skp
         CMP R12, R11
                                     ; are we at top?
         BEQ top
         CMP R12, R1
                                               ; are we at bottom?
         BEQ bottom
         B fin
top
         MOV R10, #1
                                               ;set up/down indicator to down direction (1)
         B fin
bottom
         MOV R10, #0
                                               ;set up/down indicator to up direction (0)
         B fin
fin
         LDR R1, =GPIO_PORTF_DATA_R
                                                                  ;check if button is still pressed
         LDR R2, [R1]
         AND R2, R2, #0x10
         AND R0, #0
                                               ;CLEAR R0
         CMP R2, R0
         BEQ breathe1
         POP {R12, R7, R0, R11}
         B loop
toggleLightOn
         PUSH {R0, R1, R2, LR}
         LDR R1, =GPIO_PORTE_DATA_R
         LDR R0, [R1]
         ORR R0, R0, #0x01
                                                        ;SETTING PE0 TO 1
         STR R0, [R1]
                                                                  ;STORES NEW DATAREG
         CMP R8, #1
         BNE NoCNo
         BL Debug_Capture
         MOV R8, #-250
NoCNo
         CMP R10, #0
```

```
BEQ nocap
         BL Debug_Capture
         SUB R10, R10, #1
nocap
         POP {R0, R1, R2, LR}
        BX LR
toggleLightOff
         PUSH {R0, R1, R2, LR}
         LDR R1, =GPIO_PORTE_DATA_R
        LDR R0, [R1]
         AND R0, R0, #0xFE
                                                     ;SETTING PE0 TO 0
         STR R0, [R1]
                                                               STORES NEW DATAREG
         CMP R8, #0
         BNE nocap1
         CMP R10, #0
         BEQ nocap1
         BL Debug_Capture
        SUB R10, R10, #1
nocap1
         POP {R0, R1, R2, LR}
         BX LR
delay
         PUSH {LR, R1, R0, R2}
         ;MOV R2, #40
         ;MUL R0, R0, R2
while
         MOV R1, #0
                                                                       ;CLEAR R1
        BL sub1
         ADD R0, #-1
                                                                       ;DECREMTENTS WHILE LOOP INDICATOR
         CMP R0, R1
         BGT while
                                                               ;REPEATS EACH 1/5 OF THE DUTY CYCLE
        POP~\{LR,\,R1,\,R0,\,R2\}
         BX LR
                                                                       ;DELAYS FOR 1/80th OF PERIOD
sub1
         PUSH {R0,R1}
                                                               ;SETS R0 TO ARBIRTRARY CONSTANT WHICH WE
        MOV R0,#0xF424
FOUND WITH TRIAL AND ERROR
        MOV R1, R0
                                                                       ;SETS R1 TO R0
wait
        SUBS R0,R0,#0x01
                                                     ;DELAYS FOR A VERY SMALL AMOUNT OF TIME
        BNE wait
wait1
         SUBS R1,R1,#0x01
        BNE wait1
        MOV R0,#0xF424
        MOV R1, R0
wait2
                 SUBS R0,R0,#0x01
         BNE wait2
wait3
         SUBS R1,R1,#0x01
         BNE wait3
         MOV R1, R0
         POP {R0, R1}
         BX LR
Debug_Init
         PUSH {R0, R1, R2, R3, R8, R9, LR, R10}
        LDR R0, =DataBuffer
        LDR R1, =TimeBuffer
         MOV R3, #50
                                                     ;Loop counter
ClearLoop
```

```
CMP R3, #0
                                                           ;Check if at end of array
          BEQ ExitClear
          MOV R8, #0xFF
                                        ;set current Data array value to FF
         STR R8, [R0]
          MOV R9, #0xFFFFFFF
                                        ;set current Time array value to 8 Fs
         STR R9, [R1]
          ADD R0, R0, #1
                                        ;Move to next value in Data array
          ADD R1, R1, #4
                                        ;Move to next value in TIme Array
          SUB R3, R3, #1
          BL ClearLoop
ExitClear
         LDR R0, =DataBuffer
          LDR R1, =DataPt
         STR R0, [R1]
                                        ;Set pointer at start of array
         LDR R0, =TimeBuffer
          LDR R1, =TimePt
         STR R0, [R1]
                                        ;Set pointer at start of array
          BL SysTick Init
          POP {R0, R1, R2, R3, R8, R9, LR, R10}
          BX LR
Debug_Capture
          PUSH {R0, R1, R2, R3, R4, R5}
          LDR R0, =NEntries
         LDR R1, [R0]
          CMP R1, #50
          BEQ FIN
         LDR\ R0, = GPIO\_PORTE\_DATA\_R
         LDR R1, [R0]
          AND R1, R1, #0x03
         LDR R0, =NVIC_ST_CURRENT_R
         LDR R4, [R0]
          LSL R2, R1, #3
          AND R2, R2, #0x10
          AND R1, R1, #0x01 ;prep data to be dumped
          ADD R1, R1, R2
          LDR R0, =DataPt
         LDR R3, [R0]
                                        ;store data
         STRB R1, [R3]
          ADD R3, R3, #1
                                        ;increment DataPt
         STR R3, [R0]
          LDR R0, =TimePt
         LDR R3, [R0]
                                        ;store Time
         STR R4, [R3]
          ADD R3, R3, #4
                                        ;increment TimePt
         STR R3, [R0]
         LDR R0, =NEntries
         LDR R1, [R0]
          ADD R1, R1, #1
         STR R1, [R0]
FIN
          POP {R0, R1, R2, R3, R4, R5}
          BX LR
   ALIGN
             ; make sure the end of this section is aligned
```

END

; end of file

## 3. Estimation of Execution time

Execution time: 975 ns

Average time between executions: 0.062503 seconds

Intrusiveness: .0015599251%

Death from the second File (50 outside)					F0		
Paste from the saved File (50 entries)			count:		50		
:020000042000DA							12.5 <- Time per tick
:0E006200F0A09D00F00805002FFFC700B17050	F0A09D00	F0080500	2FFFC700	Adjust-end		Differences	Time(ms)
:100070006C00F0662F0072D8D300B1CE96003340EA	B1706C00	F0662F00	72D8D300 B1CE9600				
:100080003B007C494000CE190F006F8BB3008F817D	33403B00	7C494000	CE190F00 6F8BB300		329968	10000384	·
:10009000760030F31A0050E9DD00F15A8200115168	8F817600	30F31A00	50E9DD00 F15A8200		13106991	4000193	
:1000A00045000BF2E2005DC2B10060AF37001E2ACE	11514500	0BF2E200	5DC2B100 60AF3700			6000254	
:1000B000190021179F00DF918000E27E0600A0F961	1E2A1900	21179F00	DF918000 E27E0600		3106544	4000193	
:1000C000E700FCC9B600FC311E008115670006F987	A0F9E700	FCC9B600	FC311E00 81156700	00D3D872	13883506	6000254	75.003175
:1000D000AF008BDCF80010C0410095A38A001A879E	06F9AF00	8BDCF800	10C04100 95A38A00	0096CEB1	9883313	4000193	50.0024125
:1000E000D300A46A1C0029AD8F00B090D8003774EB	1A87D300	A46A1C00	29AD8F00 B090D800	003B4033	3883059	6000254	75.003175
:1000F0002100BE576A00453BB300CC1EFC005302F2	37742100	BE576A00	453BB300 CC1EFC00	0040497C	4213116	16447159	
:1001000045003A323E009C158700799068005D7D7D	53024500	3A323E00	9C158700 79906800	000F19CE	989646	3223470	40.293375 <-time from press to release
:10011000EE003AF8CF001EE55500FB5F3700DF4CDC	5D7DEE00	3AF8CF00	1EE55500 FB5F3700	00B38B6F	11766639	6000223	75.0027875 <- next 6 time differences
:0A012000BD008A85F300DC55C20023	DF4CBD00	8A85F300	DC55C200	0076818F	7766415	4000224	50.0028
:0000001FF				001AF330	1766192	6000223	75.0027875
				00DDE950	14543184	4000224	50.0028
				00825AF1	8542961	6000223	75.0027875
				00455111	4542737	4000224	50.0028
				00E2F20B	14873099	6446854	
				00B1C25D	11649629	3223470	40.293375 <-time from press to release
				0037AF60	3649376	8000253	100.0031625 <- next 6 time differences
				00192A1E		2000194	25.002425
				009F1721	10426145	8000253	100.0031625
				008091DF		2000194	25.002425
				00067EE2	425698	8000253	
				00E7F9A0	15202720	2000194	25.002425
				00B6C9FC		3223460	
				001E31FC		10000384	
				00671581	6755713	12000379	·
				00071301 00AFF906	11532550	12000379	
				00F8DC8B		12000373	
				00/3DC3B		12000379	
				0041C010		12000379	
				000AA393		12000379	
							130.0047373
				001C6AA4		12000374	115 2042275 4 5 from 2000 to release
				008FAD29		9223547	·
				00D890B0		12000377	
				00217437			150.0047125
				006A57BE		12000377	
				00B33B45		12000377	
				00FC1ECC		12000377	
				00450253	4522579	12000377	150.0047125
				003E323A		446489	
				0087159C		12000414	·
				00689079		2000163	
				00EE7D5D		8000284	
				00CFF83A	13629498	2000163	
				0055E51E	5629214	8000284	
				00375FFB	3629051	2000163	25.0020375
				00BD4CDF	12405983	8000284	100.00355
				00530504	15050424	12222765	

00F3858A 15959434 00C255DC 12735964

13223765 3223470 40.293375