set5

October 26, 2017

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In [2]: import numpy as np
        import random as ran
In [3]: w = [1,1]
        r = 0.1
        E = lambda u,v: (u*np.e**v-2*v*np.e**(-u))**2
        dE_u = lambda u, v: 2*(np.e**v+2*v*np.e**(-u))*(u*np.e**v-2*v*np.e**(-u))
        dE_v = lambda u, v: 2*(u*np.e**v-2*v*np.e**(-u))*(u*np.e**v-2*np.e**(-u))
In [4]: iters = 0
        e = E(w[0], w[1])
        while e > 10 * * (-14):
            w0 = w[0] - r*dE_u(w[0], w[1])
            w1 = w[1] - r*dE_v(w[0], w[1])
            0w = [0]w
            w[1] = w1
            e = E(w[0], w[1])
            iters += 1
In [5]: print ('it took : ' + str(iters) + ' iterations')
it took: 10 iterations
In [6]: (w[0], w[1])
Out[6]: (0.04473629039778207, 0.023958714099141746)
In [7]: w = [1,1]
        e = E(w[0], w[1])
        for i in range (15):
            # move only in the u direction
            w0 = w[0] - r*dE_u(w[0], w[1])
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w[0] = w0
            # move only in the v direction
            w1 = w[1] - r \star dE \ v(w[0], w[1])
            w[1] = w1
            e = E(w[0], w[1])
In [8]: print ('error after 15 iterations is: ' + str(e))
error after 15 iterations is: 0.13981379199615324
In [9]: def getLine():
            (x1, y1) = (ran.uniform(-1,1), ran.uniform(-1,1))
            (x2, y2) = (ran.uniform(-1,1), ran.uniform(-1,1))
            line = lambda x: (y2-y1) / (x2-x1) * (x-x1)
            return line
In [10]: def labelPts(N, line):
             pts = []
             for i in range(N):
                  (x1,x2) = ran.uniform(-1,1), ran.uniform(-1,1)
                 pts.append([np.array([1,x1,x2,]),np.sign(x2-line(x1))])
             return pts
In [11]: def ptGradient(w, pt):
             exp = -pt[1] *w.dot(pt[0])
             return - (pt[1]*pt[0]/(1+np.e**(exp)))
         def ptCrossEntropyError(w, pt):
             exp = -pt[1] *w.dot(pt[0])
             return np.log(1+ np.e**(-exp))
In [12]: r = 0.01
         all\_epoc = []
         all_E_in = []
         all_E_out = []
         for i in range (100):
             line = getLine()
             pts = labelPts(100, line)
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epoc = 0
             w = np.array([0,0,0])
             while True:
                 options = list(range(len(pts)))
                 while len(options)>0:
                     choice = ran.choice(options)
                     options.remove(choice)
                     pt = pts[choice]
                     grad = ptGradient(w,pt)
                     w = w + r * qrad
                 diff = epoc\_end\_w - w
                 mag = np.sqrt(diff.dot(diff))
                 if mag < 0.01:
                     break
                 epoc\_end\_w = w
                 epoc += 1
             all_epoc.append(epoc)
             # get E_in
             E_in=0
             for pt in pts:
                 E_in += ptCrossEntropyError(w,pt)
             E_in /= float(len(pts))
             all_E_in.append(E_in)
             # approx E_out
             test_pts = labelPts(10000, line)
             E \text{ out } = 0.0
             for pt in test_pts:
                 E_out += ptCrossEntropyError(w,pt)
             E_out /= float(len(test_pts))
             all_E_out.append(E_out)
In [13]: print("average approx. E_out is: " + str(np.mean(all_E_out)))
average approx. E_out is: 0.10063694652
In [14]: print("average epocs: " + str(np.mean(all_epoc)))
                                    3
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 $epoc_end_w = np.array([0,0,0])$

average epocs: 333.21

In []: