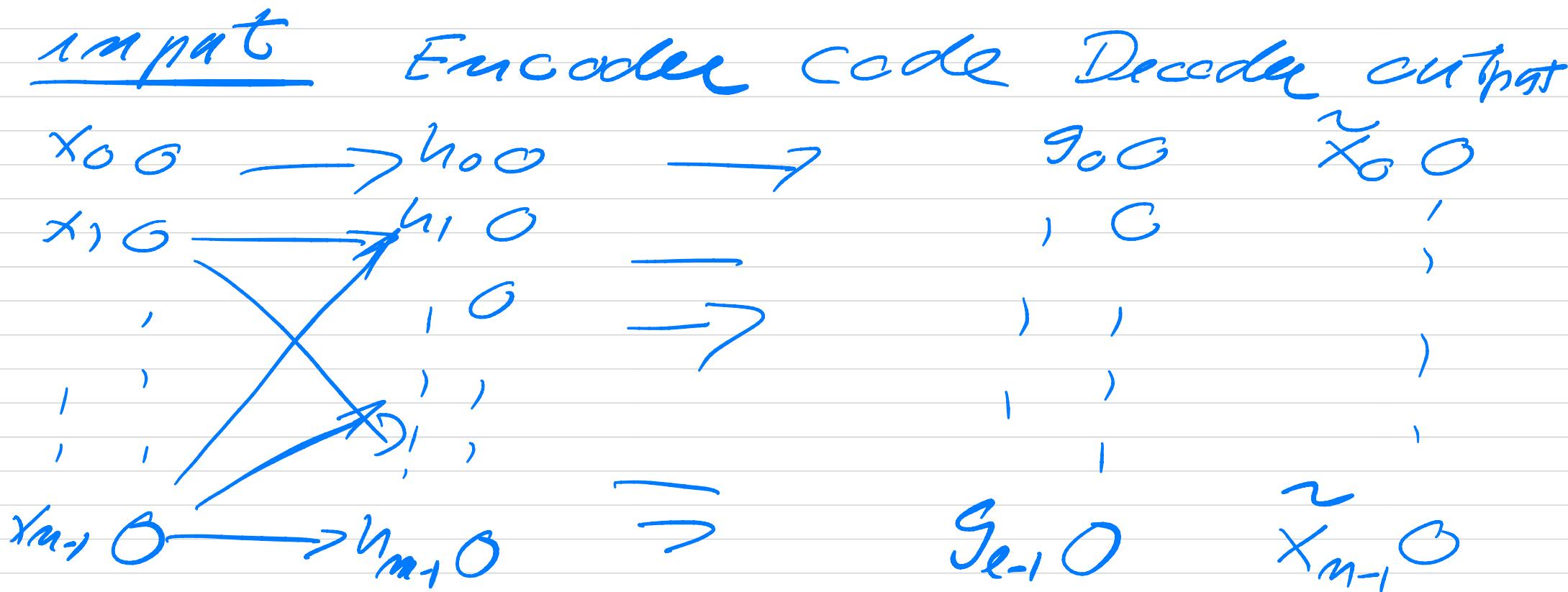


# Lecture FYS5429, March 12, 2024

FYS 5429/9429 MARCH 12, 2029



$$h = f(w, x)$$

$$g(v, h) = \tilde{x}$$

Define a metric

$$MSE = \frac{1}{n} \sum_{i=0}^{n-1} (x_i - \tilde{x}_i)^2$$

A simple linear dependence

$$\underset{W, V}{\arg \min} \frac{1}{n} \sum_{i=0}^{n-1} (x_i - \tilde{x}_i)^2$$

$$h = Wx$$

$$\tilde{x} = V \cdot W \cdot x$$

$$g = V \cdot h$$

$$\underset{W, V}{\arg \min} \frac{1}{n} \sum_{i=0}^{n-1} [(\tilde{y} - Vw) \tilde{x}_i]^2$$

# Dimensionality Reduction

1) Example: ordinary least square

$$\tilde{X} = X \Theta$$



~~X~~ feature matrix

$X \in \mathbb{R}^{n \times p}$

$\uparrow$        $\nwarrow$

# of features  
# of samples

$$X = \begin{bmatrix} | & | & & | \\ x_0 & x_1 & \cdots & x_{p-1} \\ | & | & & | \end{bmatrix}$$

$$\hat{e} = \frac{|}{\cancel{xx}} \times \cancel{x}$$

$$\tilde{x} = x \hat{e} = x \frac{|}{\cancel{xx}} x^T$$



$(R^{p \times p})$

$A \in R^{n \times n}$

$A^2 = A \in \mathbb{R}^{n \times n}$

$\tilde{x} = Ax$

NO-dimension  
reduction

$$\arg \min_{\tilde{x}} \frac{1}{n} \| (I - A^2) \tilde{x} \|_2^2$$

( $\ominus$ )

$$= \frac{1}{n} \| (I - A) \tilde{x} \|_2^2$$

autoencoder

$\xrightarrow{A}$

$$\arg \min_{w, v} \frac{1}{n} \| (I - vw) \tilde{x} \|_2^2$$

2) SVD

$$\hat{E} = \frac{1}{\sqrt{\pi}} \hat{X}^T \hat{X}$$

$$\hat{X}^T \hat{X} \in \mathbb{R}^{P \times P}$$

$$X \in \mathbb{R}^{n \times p}$$

$n \gg p$

$$\hat{X}^T \hat{X} = UDV^T$$

$$uu^T = u^Tu = \mathbf{1}_{n \times n}$$

$$vv^T = v^Tv = \mathbf{1}_{p \times p}$$

$$\bar{u}_i^T u_j = \delta_{ij}$$

$$v_i^T v_j = \delta_{ij}$$

$$U = \begin{bmatrix} 1 & & & 1 \\ u_0 & \dots & u_{n-1} \\ 1 & & & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} \tau_0 & & & 0 \\ 0 & \tau_1 & \dots & 0 \\ \vdots & \ddots & \ddots & \tau_{p-1} \\ 0 & \dots & 0 & \tau_{q-1} \end{bmatrix}$$

$\boxed{\tau_0 > \tau_1 > \dots > \tau_{p-1} > 0 > \dots}$

$$D = \begin{bmatrix} 2 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \quad D \in \mathbb{R}^{3 \times 2}$$

$$D^T D = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}$$

$$D D^T = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\cancel{X^T X} = U D V^T$$

$$\tilde{x} = \cancel{X} \frac{1}{\cancel{X^T X}} \overset{T}{X} =$$

$$= UDV^T \left[ \frac{1}{V D^T U^T U D V} \right] V D^T u^T x$$

~~$P \times P$~~

$$= UDV^T \frac{1}{V D^T D V} V D^T u^T x$$

linear algebra geom  
if  $A$  &  $B$  are square matrices and invertible

$$\frac{1}{AB} = B^{-1} A^{-1} \quad \left| \begin{array}{l} V^T V = \mathbb{1} \\ V = (V^T)^{-1} \end{array} \right.$$

$V$  is a square matrix  
and invertible

$$D^T D = \begin{bmatrix} \tau_0^2 & & \\ & \ddots & -\tau_{p-1}^2 \end{bmatrix}$$

$$\frac{1}{V D^T D V^T}$$

$$\tilde{x} = \underbrace{UDV^T}_{\mathbb{1}} \frac{1}{D^T D} \underbrace{V^T V D U^T}_{\mathbb{1}} x$$

$$= \left( \sum_{k=0}^{P-1} u_i \bar{u}_i^\top \right) \times$$

with SVD we have  
a projection with  $P$ -  
degrees of freedom.

We want an  $m \leq P$ .

Can we find such a  
value? Yes, PCA

# Dim-Reduction and PCA

$$\|x - Vw_x\|_2^2 \leq \epsilon$$

PCA tells us that we can define  $m \leq p$ . How do we define  $m$ ?

Basic elements of PCA analysis

input matrix  $X \in \mathbb{R}^{n \times p}$

$$X = \begin{bmatrix} & & \\ 1 & & \\ & \ddots & \\ x_0 & \cdots & x_{p-1} \\ & & \end{bmatrix}$$

$$\text{Cov}[x_i, x_j] = \frac{1}{n} \sum_k (x_{ki} - \bar{x}_i) \times (x_{kj} - \bar{x}_j)$$

$$\bar{x}_i = \frac{1}{n} \sum_k x_{ki}$$

$$x_i = \begin{bmatrix} x_{0i} \\ x_{1i} \\ \vdots \\ x_{n-1i} \end{bmatrix}$$

$$x_{ki} - \bar{x}_i = \tilde{x}_{ki} \Rightarrow$$

$\tilde{x}_{ki}$   
all data centered

Example

$$X = \begin{bmatrix} x_0 & x_1 \\ x_{00} & x_{01} \\ x_{0\emptyset} & x_{11} \\ x_{20} & x_{21} \end{bmatrix}$$

$$\text{cov}[x_0, x_1] = \frac{1}{3} (x_{00}x_{01} + x_{10}x_{11} + \overbrace{\dots}^{n-1} x_{20}x_{21})$$

$$= x_0^T x_1 \cdot \frac{1}{n}$$

Covariance of  $\bar{X}$  ( $\bar{X}^T \bar{X}$ )

$$\text{Cov}[\bar{X}] = \frac{1}{n} \bar{X}^T \bar{X} \in \mathbb{R}^{P \times P}$$

$$P=2$$

$$\text{Cov}[\bar{x}] = \frac{1}{n} \begin{bmatrix} \bar{x}_0^T \bar{x}_0 & \bar{x}_0^T \bar{x}_1 \\ \bar{x}_1^T \bar{x}_0 & \bar{x}_1^T \bar{x}_1 \end{bmatrix}$$

$$\bar{x}_k^2 = \frac{1}{n} \sum_k x_{ki}^2$$

$$\text{Cov} [\bar{x}] = \begin{bmatrix} \frac{\sigma^2}{T_0} & \text{cov}[x_0, x_1] \\ \text{cov}[x_1, x_0] & \frac{\sigma^2}{T_1} \end{bmatrix}$$

$\text{Cov} [\bar{x}]$  which has elements

$$\frac{\text{cov}[x_i, x_j]}{\sqrt{\text{var}[x_i] \text{var}[x_j]}}$$

$$\text{Cov} [\bar{x}] = \begin{bmatrix} 1 & \text{cov}[x_0, x_1] \\ \text{cov}[x_1, x_0] & \ddots \end{bmatrix}$$

Link with SVD

$$\frac{1}{m} \bar{X}^T \bar{X} = \text{cov}[\bar{X}]$$

$$\bar{X}^T \bar{X} \text{ with SVD } X = UDV^T$$

$$\begin{aligned} \text{cov}[\bar{X}] &= \frac{1}{n} [V D^T \underbrace{\bar{u}^T \bar{u}}_{\frac{1}{n}} D V^T] \\ &= \frac{1}{n} V D^T \bar{D} V^T \end{aligned}$$

$$\frac{1}{n} (X^T X) V = \frac{1}{n} (V D^2 V^T) V$$

$$= \frac{1}{n} V D^2$$

$$V = \begin{bmatrix} & & \\ v_0 & v_1 & \cdots & v_{p-1} \\ & & \end{bmatrix}$$

$$\frac{1}{n} (X^T X) v_i = v_i \sigma_i^2$$

eigenvalues of  $\text{cov}[x]$

are the singular values  
 $\sigma_i^2$  with eigenvectors

$v_i$

Total variance is

$$\sum_{i=0}^{P-1} \sigma_i^2$$

The PCA constructs a set of orthogonal vectors

$$S = [s_0 \ s_1 \ \dots \ s_{P-1}]$$

$$S^T \text{cov}[x] S = \text{cov}[\bar{g}]$$

$$(S^T A S = I)$$

which is  
diagonal

so that

$$\sum_{i=0}^{m-1} \sigma_i^2$$

$\leq$

truncated  
total  
variance.

Define a reconstruction error

$$J(x) = \frac{1}{n} \| (x - S_0 S_0^T x) \|_2^2$$

$$\mathcal{L} = S_0^T \text{cov}[x] S_0 + \lambda_0 (I - S_0 S_0^T)$$

optimize w.r.t.  $S_0$  and  $x_0$

$$\text{cov}[x] S_0 = \lambda_0 S_0$$

multiply with  $S_0^T$

$$S_0^T \text{cov}[x] S_0 = \lambda_0 = \frac{\tau_0}{n}$$

next:  $S_1$

$$\mathcal{L} = S_1^T \text{cov}[x] S_1 + \lambda_1 (1 - S_1^T S_1) + \delta S_1^T S_0$$

Take derivatives wst  $\lambda_1, \gamma$

and  $S_1$

wst  $S_1$

$$\text{cov}[x] S_1 + \delta/2 S_0 = \lambda_1 S_1$$

$$S_1^T \text{cov}[x] S_1 + \delta/2 \underline{S_1^T S_0} = \lambda_1$$

$$S_1^T [ \cos \bar{t}x ] \underbrace{S_1}_{\mathcal{V}_1} = \lambda_1$$