

# 深度学习之 RNN

荣耀学院

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# 第一版序言

本书是《零基础自学神经网络 BP 算法》的续篇。熟悉后者可以根据本书快速掌握 RNN 神经网络的本质。考虑到熟悉后者，则具备一定的基础，因此本书只给出关键推导，次级细节不再详述。

本书最佳使用方式：拿出纸和笔，亲自推导所有公式。为了便于理解和学习，本书所有的推导给出了所有步骤，不做任何省略。



# 目 录

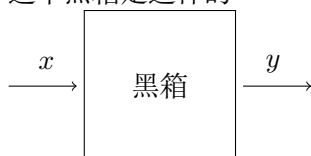
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# 第一章 最简 RNN

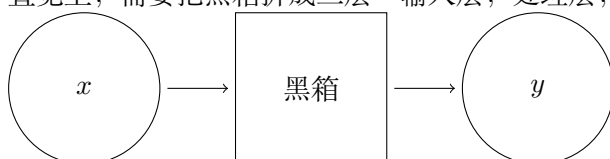
假如有一个分类器，这个分类器是黑箱：给黑箱输入  $x$ ，黑箱经过计算，输出  $y$ 。

这个黑箱是这样的：

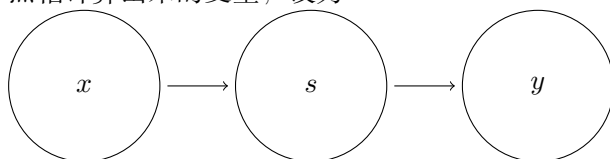


黑箱，原理不明，不知道它是咋个运行的，设计一个原理清晰的东西取代它。

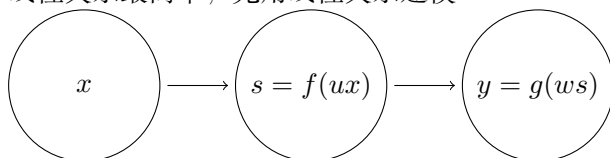
直觉上，需要把黑箱拆成三层：输入层，处理层，输出层：



黑箱计算出来的变量，设为  $s$ ：



线性关系最简单，先用线性关系建模：

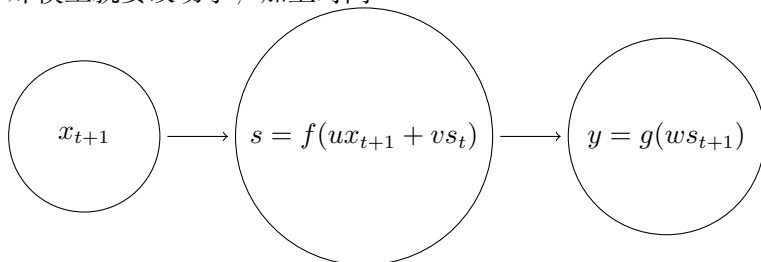


这里， $f(\cdot)$  和  $g(\cdot)$  是激活函数，比如 sigmoid 函数，其中  $u$  和  $w$  是常数，由黑箱决定的常数，不同的黑箱  $u$  和  $w$  是不同的，但对确定的黑箱来说， $u$  和  $w$  是固定的。

看起来好象差不多了，挺好的。

经过研究发现，有一个巨大的变动，这个黑箱计算输出值  $s$  的时候，会使用上一个时刻的  $s$ ，也就是说，如果  $t$  是时间点，计算  $s_{t+1}$  的时候，需要使用  $s_t$  的值，但不清楚具体系数。

那模型就要改动了，加上时间：



其中， $v$  也是黑箱决定的常数，跟  $u$  和  $w$  的性质是一样的。

这就是最简单的 RNN。



## 第二章 最简 RNN 的 BP 算法

最简 RNN 有三个参数： $u$ ， $v$ ， $w$ 。

用 BP 算法求解。

假设有一对  $t + 1$  时刻的训练样本， $[x_{t+1}, y_{t+1}]$ ， $x_{t+1}$  是输入， $y_{t+1}$  是目标值， $t$  时刻的  $s$  值  $s_t$  是已知的。设 RNN 的输出是  $o_{t+1}$ 。

定义目标函数：

$$Err = \frac{1}{2}(o_{t+1} - y_{t+1})^2$$

根据微分求极值，迭代计算  $u$ ， $v$ ， $w$ ，使得  $Err$  最小，迭代公式是：

$$u = u - \eta \frac{\partial Err}{\partial u}$$

$$v = v - \eta \frac{\partial Err}{\partial v}$$

$$w = w - \eta \frac{\partial Err}{\partial w}$$

其中， $\eta \in (0, 1)$ ，是学习速率。

推导  $Err$  对  $u$ ， $v$ ， $w$  的一阶偏导：

$$\begin{aligned}
\frac{\partial Err}{\partial w} &= \frac{\partial(\frac{1}{2}(o_{t+1} - y_{t+1})^2)}{\partial w} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial w} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial g(ws_{t+1})}{\partial w} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) \frac{\partial(ws_{t+1})}{\partial w} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) s_{t+1}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial v} &= \frac{\partial(\frac{1}{2}(o_{t+1} - y_{t+1})^2)}{\partial v} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial v} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial g(ws_{t+1})}{\partial v} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) \frac{\partial(ws_{t+1})}{\partial v} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w \frac{\partial s_{t+1}}{\partial v} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w \frac{\partial f(ux_{t+1} + vs_t)}{\partial v} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w f'(ux_{t+1} + vs_t) \frac{\partial(ux_{t+1} + vs_t)}{\partial v} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w f'(ux_{t+1} + vs_t) s_t
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial u} &= \frac{\partial(\frac{1}{2}(o_{t+1} - y_{t+1})^2)}{\partial u} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial u} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial g(ws_{t+1})}{\partial u} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) \frac{\partial(ws_{t+1})}{\partial u} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w \frac{\partial s_{t+1}}{\partial u} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w \frac{\partial f(ux_{t+1} + vs_t)}{\partial u} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w f'(ux_{t+1} + vs_t) \frac{\partial(ux_{t+1} + vs_t)}{\partial u} \\
&= (o_{t+1} - y_{t+1}) g'(ws_{t+1}) w f'(ux_{t+1} + vs_t) x_{t+1}
\end{aligned}$$

RNN 的核心部分就这些了，剩下的就是编程实现问题，可以参考《零基础自学神经网络 BP 算法》，不复杂。



## 第三章 LSTM 的 BP 算法

LSTM: long short term memory。

$x_t$  是  $t$  时刻的输入,  $x_{t+1}$  是  $t+1$  时刻的输入,  $o_{t+1}$  是  $t+1$  时刻的输出。  
 $y_{t+1}$  是  $t+1$  时刻的目标值。

$\sigma(\cdot)$  是 sigma 激活函数,  $\tanh(\cdot)$  是 tanh 函数。

假设  $t$  时刻的所有量都计算完成了, 所有量都是已知的。

LSTM 的输出, 即按照如下次序计算  $o_{t+1}$ :

遗忘门 (forget gate) 的输出:

$$f_{t+1} = \sigma(u^f o_t + v^f x_{t+1} + b^f)$$

输入门 (input gate) 的输出:

$$i_{t+1} = \sigma(u^i o_t + v^i x_{t+1} + b^i)$$

$$\tilde{C}_{t+1} = \tanh(u^C o_t + v^C x_{t+1} + b^C)$$

$$C_{t+1} = f_{t+1} C_t + i_{t+1} \tilde{C}_{t+1}$$

输出门 (output gate) 的输出

$$h_{t+1} = \sigma(u^o o_t + v^o x_{t+1} + b^o)$$

$$o_{t+1} = \tanh(C_{t+1}) h_{t+1}$$

其中,  $u^f, v^f, b^f, u^i, v^i, b^i, u^C, v^C, b^C, u^o, v^o, b^o$  是 LSTM 的参数。 $f_{t+1}$  是  $t+1$  时刻遗忘门的输出。 $i_{t+1}$  是  $t+1$  时刻输入门的输出。 $o_{t+1}$  是  $t+1$  时刻输出门的输出, 同时也是 LSTM 的输出。

尽管公式很多，实际上不复杂，推导只是个体力活。

目标函数：

$$Err = \frac{1}{2}(o_{t+1} - y_{t+1})^2$$

推导  $Err$  对  $u^f, v^f, b^f, u^i, v^i, b^i, u^C, v^C, b^C, u^o, v^o, b^o$  的一阶偏导。

$$\begin{aligned}
 \frac{\partial Err}{\partial u^o} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial u^o} \\
 &= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial u^o} \\
 &= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial u^o} \\
 &= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial u^o} \\
 &= (o_{t+1} - y_{t+1}) \tanh(C_{t+1}) \frac{\partial h_{t+1}}{\partial u^o} \\
 &= (o_{t+1} - y_{t+1}) \tanh(C_{t+1}) \sigma'(u^o o_t + v^o x_{t+1} + b^o) o_t
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial Err}{\partial v^o} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial v^o} \\
 &= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial v^o} \\
 &= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial v^o} \\
 &= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial v^o} \\
 &= (o_{t+1} - y_{t+1}) \tanh(C_{t+1}) \frac{\partial h_{t+1}}{\partial v^o} \\
 &= (o_{t+1} - y_{t+1}) \tanh(C_{t+1}) \sigma'(u^o o_t + v^o x_{t+1} + b^o) x_{t+1}
 \end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial b^o} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial b^o} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial b^o} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial b^o} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial b^o} \\
&= (o_{t+1} - y_{t+1}) \tanh(C_{t+1}) \frac{\partial h_{t+1}}{\partial b^o} \\
&= (o_{t+1} - y_{t+1}) \tanh(C_{t+1}) \sigma'(u^o o_t + v^o x_{t+1} + b^o)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial u^C} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1} C_t + i_{t+1} \tilde{C}_{t+1})}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) i_{t+1} \frac{\partial \tilde{C}_{t+1}}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) i_{t+1} \frac{\partial \tanh(u^C o_t + v^C x_{t+1} + b^C)}{\partial u^C} \\
&= \frac{(o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) i_{t+1} \tanh'(u^C o_t + v^C x_{t+1} + b^C) \cdot \partial(u^C o_t + v^C x_{t+1} + b^C)}{\partial u^C} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) i_{t+1} \tanh'(u^C o_t + v^C x_{t+1} + b^C) o_t
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial v^C} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial v^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial v^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial v^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \frac{\partial \tilde{C}_{t+1}}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \frac{\partial \tanh(u^C o_t + v^C x_{t+1} + b^C)}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \tanh'(u^C o_t + v^C x_{t+1} + b^C) \cdot \frac{\partial(u^C o_t + v^C x_{t+1} + b^C)}{\partial v^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \tanh'(u^C o_t + v^C x_{t+1} + b^C)x_{t+1}
\end{aligned}$$



$$\begin{aligned}
\frac{\partial Err}{\partial b^C} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial b^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial b^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial b^C} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \frac{\partial \tilde{C}_{t+1}}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \frac{\partial \tanh(u^C o_t + v^C x_{t+1} + b^C)}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \tanh'(u^C o_t + v^C x_{t+1} + b^C) \cdot \frac{\partial(u^C o_t + v^C x_{t+1} + b^C)}{\partial b^C} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})i_{t+1} \tanh'(u^C o_t + v^C x_{t+1} + b^C)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial u^i} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \frac{\partial i_{t+1}}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \frac{\partial \sigma(u^i o_t + v^i x_{t+1} + b^i)}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \sigma'(u^i o_t + v^i x_{t+1} + b^i) \frac{\partial(u^i o_t + v^i x_{t+1} + b^i)}{\partial u^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \sigma'(u^i o_t + v^i x_{t+1} + b^i) o_t
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial v^i} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial v^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial v^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial v^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})\tilde{C}_{t+1} \frac{\partial i_{t+1}}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})\tilde{C}_{t+1} \frac{\partial \sigma(u^i o_t + v^i x_{t+1} + b^i)}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})\tilde{C}_{t+1} \sigma'(u^i o_t + v^i x_{t+1} + b^i) \frac{\partial(u^i o_t + v^i x_{t+1} + b^i)}{\partial v^i} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})\tilde{C}_{t+1} \sigma'(u^i o_t + v^i x_{t+1} + b^i)x_{t+1}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial b^i} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \frac{\partial i_{t+1}}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \frac{\partial \sigma(u^i o_t + v^i x_{t+1} + b^i)}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \sigma'(u^i o_t + v^i x_{t+1} + b^i) \frac{\partial(u^i o_t + v^i x_{t+1} + b^i)}{\partial b^i} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \tilde{C}_{t+1} \sigma'(u^i o_t + v^i x_{t+1} + b^i)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial u^f} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial u^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial u^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial u^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \frac{\partial f_{t+1}}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \frac{\partial \sigma(u^f o_t + v^f x_{t+1} + b^f)}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \sigma'(u^f o_t + v^f x_{t+1} + b^f) \frac{\partial(u^f o_t + v^f x_{t+1} + b^f)}{\partial u^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \sigma'(u^f o_t + v^f x_{t+1} + b^f) o_t
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial v^f} &= \frac{\partial \frac{1}{2}(o_{t+1} - y_{t+1})^2}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) C_t \frac{\partial f_{t+1}}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) C_t \frac{\partial \sigma(u^f o_t + v^f x_{t+1} + b^f)}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) C_t \sigma'(u^f o_t + v^f x_{t+1} + b^f) \frac{\partial(u^f o_t + v^f x_{t+1} + b^f)}{\partial v^f} \\
&= (o_{t+1} - y_{t+1}) h_{t+1} \tanh'(C_{t+1}) C_t \sigma'(u^f o_t + v^f x_{t+1} + b^f) x_{t+1}
\end{aligned}$$

$$\begin{aligned}
\frac{\partial Err}{\partial b^f} &= \frac{\partial_2^1(o_{t+1} - y_{t+1})^2}{\partial b^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(o_{t+1} - y_{t+1})}{\partial b^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial o_{t+1}}{\partial b^f} \\
&= (o_{t+1} - y_{t+1}) \frac{\partial(\tanh(C_{t+1})h_{t+1})}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \frac{\partial \tanh(C_{t+1})}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial C_{t+1}}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1}) \frac{\partial(f_{t+1}C_t + i_{t+1}\tilde{C}_{t+1})}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \frac{\partial f_{t+1}}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \frac{\partial \sigma(u^f o_t + v^f x_{t+1} + b^f)}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \sigma'(u^f o_t + v^f x_{t+1} + b^f) \frac{\partial(u^f o_t + v^f x_{t+1} + b^f)}{\partial b^f} \\
&= (o_{t+1} - y_{t+1})h_{t+1} \tanh'(C_{t+1})C_t \sigma'(u^f o_t + v^f x_{t+1} + b^f)
\end{aligned}$$