NASA VCLS Demo 2 SDR Team 4: AstroChariot



Lead: Nicholas Turcios

Deputy Lead: Tyler Lyman

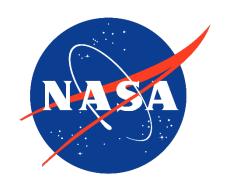
Sobhan Akhtar

Chase Edwards

Eliot Khachi

Dario Mejia-Solis

Virginia Sheinkman



Organizational Chart

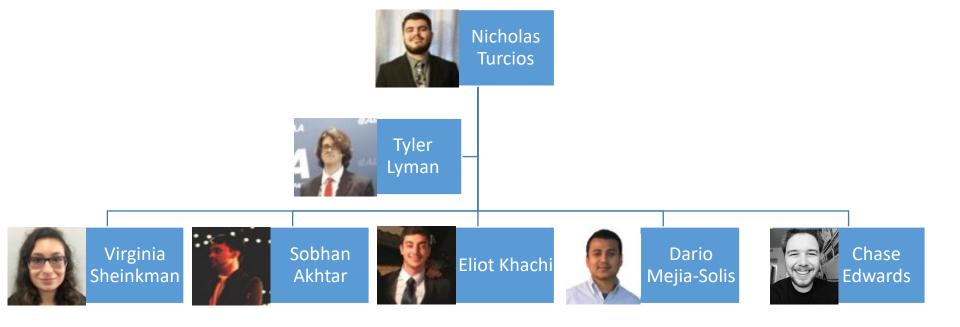






Table of Contents

Topic	Presenter	Slide No.
Team Organization	Nicholas Turcios	2
RFP	Nicholas Turcios	6
LV Design Methodology	Nicholas Turcios	7-8
Architecture 1 – Introduction	Sobhan Akhtar	9
Architecture 1 – Con-Ops and Design Specs	Virginia Sheinkman	10-12
Architecture 1 –LV Mass Methodology	Chase Edwards	13-14
Architecture 1 – Trajectory	Tyler Lyman	15-19
Architecture 1 – Sizing	Eliot Khachi	20-22
Architecture 1 – Ground and Wind Loads	Chase Edwards	23-26
Architecture 1 – Margin of Safety	Eliot Khachi	27-31
Architecture 1 – ACS, End of Mission, and Cost	Chase Edwards, Viginia Sheinkman	32-35
Architecture 1 – CAD models	Sobhan Aktar	36-39
Architecture 1 – Summary	Chase Edwards	40



Table of Contents

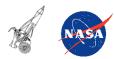
Торіс	Presenter	Slide No.
Architecture 2 – Introduction	Dario Mejia-Solis	41
Architecture 2 – Con-Ops and Design Specs	Virginia Sheinkman	42-44
Architecture 2 – LV Mass Methodology	Chase Edwards	45-46
Architecture 2 – Trajectory	Tyler Lyman	47-49
Architecture 2 – Sizing	Eliot Khachi	50-51
Architecture 2 – Ground and Wind Loads	Chase Edwards	52-55
Architecture 2 – Margin of Safety	Eliot Khachi	56-60
Architecture 2 – ACS, End of Mission, and Cost	Tyler Lyman, Virginia Sheinkman	61-64
Architecture 2 – CAD models	Dario Mejia-Solis	65-68
Architecture 2 – Summary	Tyler Lyman	69
Summary	Nicholas Turcios	70
Selection Criteria and LV Comparison	Nicholas Turcios	71-72
Next Steps	Nicholas Turcios	73
References	Nicholas Turcios	74
Backup		75-100





Acronyms

Acronym/Shorthand	Meaning
-X	Mission X
ACS	Attitude Control System
EOM	End of Mission
FS	Factor of Safety
MS	Margin of Safety
LV	Launch Vehicle
OEI	One Engine Inoperative
AP	Ammonium Perchlorate propellant
LCH ₄	Liquid Methane fuel
LOX	Liquid Oxygen



RFP-Specified Mission Requirements

Mission 1: A dedicated launch service for CubeSats that will include a single launch with a delivery of 30 kg payload mass to 500 km at inclination of TBP degrees between 40-60°.

Mission 2: A launch service with CubeSats as the primary payload. This includes a single launch for delivery of Constellation A and B. Constellation A is a 75 kg payload mass to a 550 km Sun-Synchronous Orbit (SSO). Constellation B is a second delivery of 20 kg to 550 km SSO with a minimum 10° plane change.



Mission Architecture Considerations

	Mission 1	Mission 2
Payload	30 kg	95 kg
Altitude	500 km	550 km
Inclination	60°	98°
Plane Change	None	10°
Orbit Shape	Circular	Circular
Launch Site	Kennedy Space Center	Vandenberg Air Force Base*
Launch Latitude	28.5°	34.74°
Azimuth Angle	34.48°	189.75°
Design Δv _{req}	9.54 km/s	10.99 km/s**

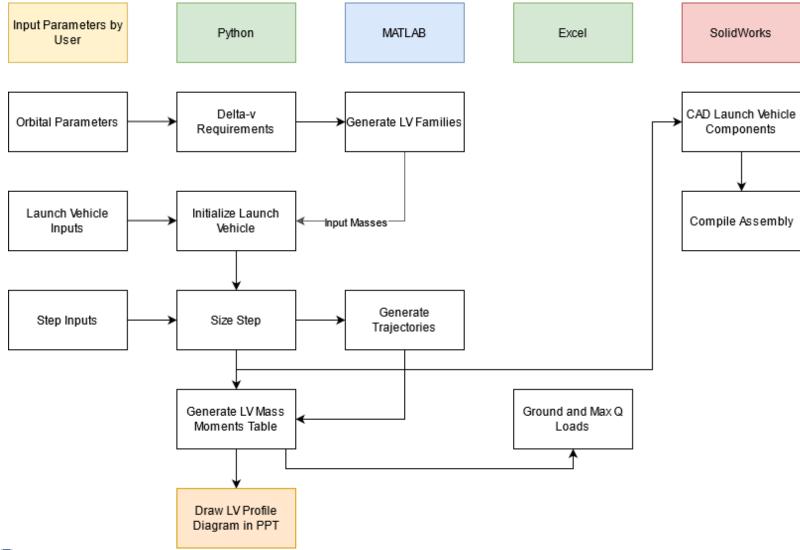
^{*}Refer to backup slide for Kodiak comparison

^{**} Δv_{req} includes the 10° inclination change.





Launch Vehicle Design Methodology







Architecture 1: Minerva

Staging Possibilities:

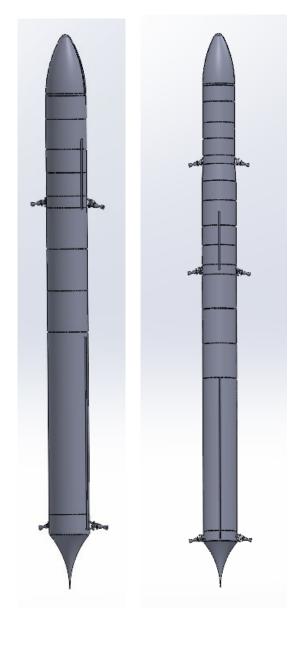
- Modular Launch Vehicle
 - Mission 1 utilizes 2 stages
 - Mission 2 utilizes 3 stages
- 1st stage is recovered and reused

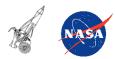
Propellant Choice:

- All stages are liquid propellant (RP-1/LO₂)
 - Adequate performance
 - Non-cryogenic nature makes it easy to handle

Nozzle Choice: aerospike for all stages

Compensates for altitude pressurization





Minerva Mission 1

v = 7.12 km/s, h = 233.8 km t @ SECO = 403 sec t @ end coast = 441 sec 5. SECO I & Coast

7. SECO II & Payload Delivery (30 kg Payload at 500 km)

4. Fairing Separation

6. Hohmann
Transfer
Maneuver
Δv = 0.152 km/s

 $\Delta t = 2752 \text{ s}$

8. 2^{nd} Stage Disposal $\Delta v = 0.145$ km/s

2. MECO & 1st Stage Separation

> v = 2.50 km/s h = 68.5 km t = 137 sec

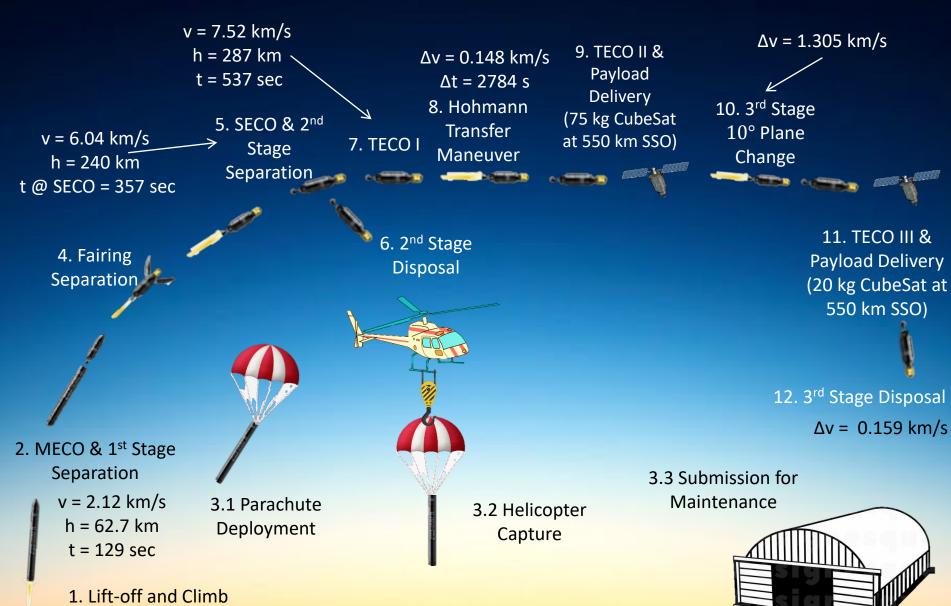
1. Lift-off and Climb

3.1 Parachute Deployment

3.2 Helicopter Capture



Minerva Mission 2





Minerva Design Specifications

	Mission 1 Thrust (kN)	Mission 2 Thrust (kN)	I _{sp} (sec)	Structural Mass Fraction σ
Minerva Stage 1 (SL)	77.9	83.3	296*	0.11
Minerva Stage 2 (Vacuum)	13.8	17.9	359*	0.11
Minerva Stage 3 (Vacuum)	N/A	3.8	359*	0.11

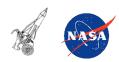
^{*} Minerva will have all aerospike nozzles (based on the J-2T-250K) attached to Merlin-type engines.







- Numerically solved for Mission 2 masses
 - %Δv for stage 1 of values from 1% to 49%
 - %Δv for stage 3 of values from 1% to 49%
 - %Δv for stage 2 was the remaining percent
- Used propellant masses of Stage 1 and 2 to solve for capable Δv for Mission 1
- Used if-statements to determine the minimum mass that was still capable of Mission 1

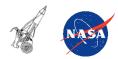




Minerva Lift-Off Mass Estimates

	Mission 1 (kg)	Mission 2 (kg)
Stage 3	N/A	426.8
Stage 2	1336.7	1306.7
Stage 1	4338.2	4338.2
Total	5704.9	6071.4

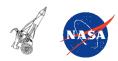
- Minerva has stage 3 for Mission 2
- Upper-most stage mass includes payload





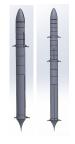


- Used MATLAB to simulate gravity turn and Hohmann transfer
- Program will simulate a large family of trajectories varying in:
 - Stage thrust
 - Initial pitch kick
 - Propellant mass left over per stage
- This method is preferred because it can down select trajectories without needing to 'trial & error' by hand
- Selection Criteria:
 - Powered ascent must leave enough mass to complete a Hohmann transfer to be valid
 - Of valid trajectories, which one requires the least Δv to circularize parking orbit
 - Included extra 'rule-of-thumb' criteria to rule out false positives

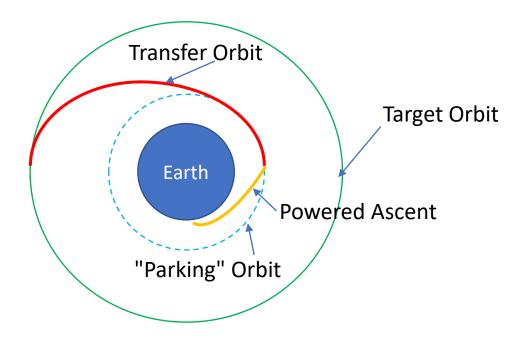


Trajectory Simulations

Hohmann Transfer



 The trajectory for both missions includes a Hohmann Transfer from a low altitude orbit to the target orbit to release the payload.











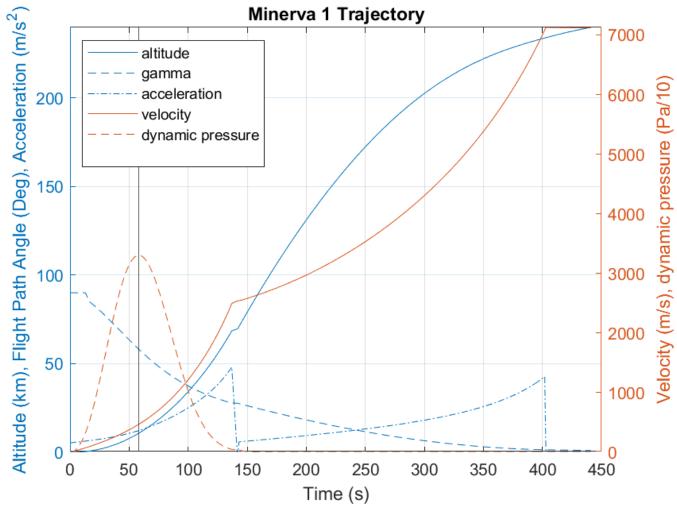
Below are the conditions at end of powered ascent phase:

	Mission 1	Mission 2
Altitude (km)	213.5	361.7
Velocity (km/s)	7.31	7.64

Following this, an appropriate kick burn is applied that effectively circularizes and enters the Hohmann Transfer.



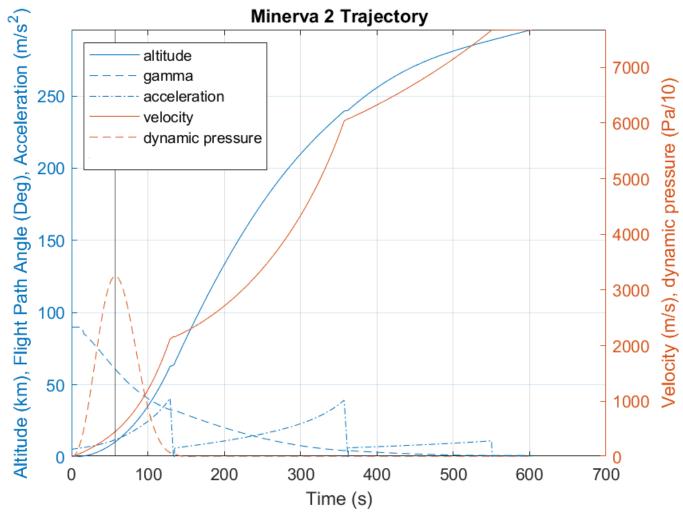
Minerva-1 Trajectory







Minerva-2 Trajectory





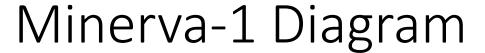
California State Polytechnic University Pomona Department of Aerospace Engineering



Launch Vehicle (LV) Sizing Methodology

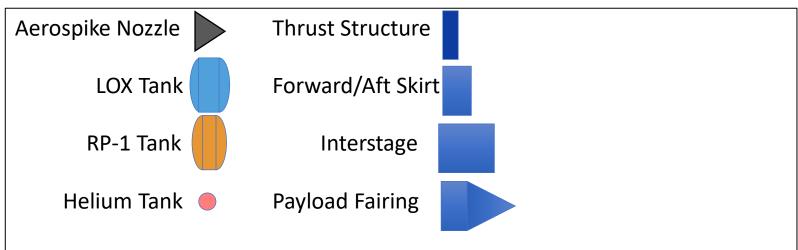
- Input Parameters Used:
 - MATLAB-Estimated Propellant Masses
 - Propellant Choice & Mixture Ratio
 - Engine Specific Impulse
 - Material of Components
 - Diameter of LV stages
- The diameter of the launch vehicle was selected to fulfill the following requirement
 - Minimize air resistance by being as slender as possible without exceeding an L/D of 17

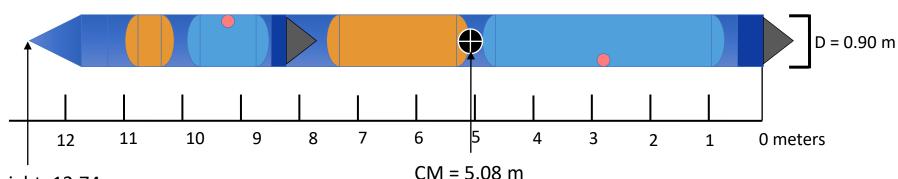


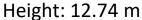


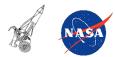


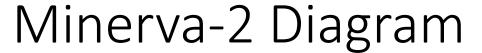






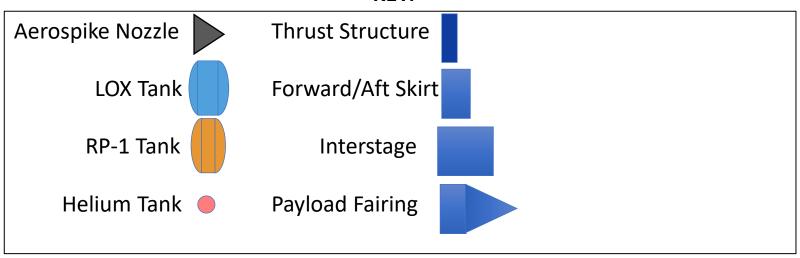


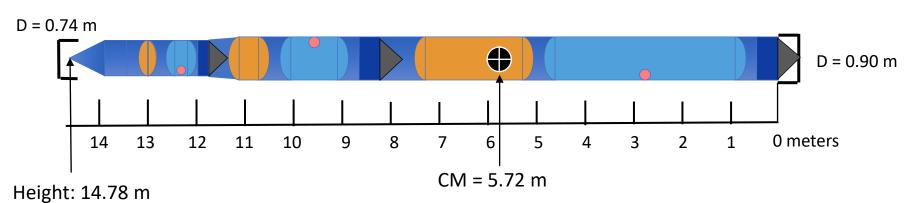






KEY:

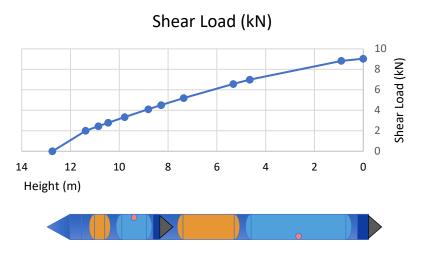


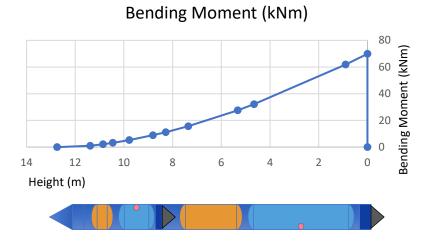


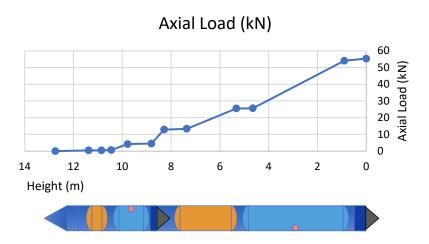




Minerva-1 Ground Loads Analysis







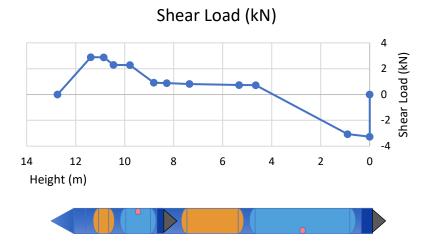
- Max shear is at the aft skirt
 - •9.0 kN
- Max bending moment is at the aft skirt
 - •69.8 kNm
- Max axial load is equal to the weight
 - •55.3 kN

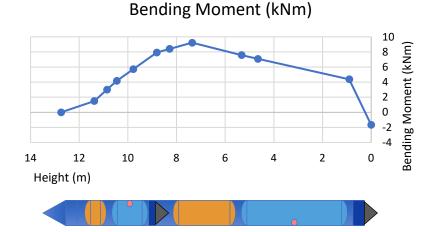


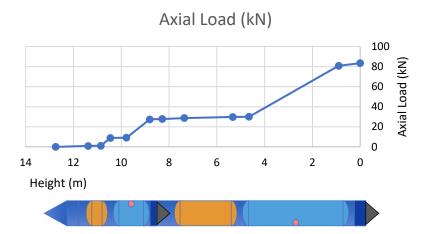




Minerva-1 Max-q Loads Analysis





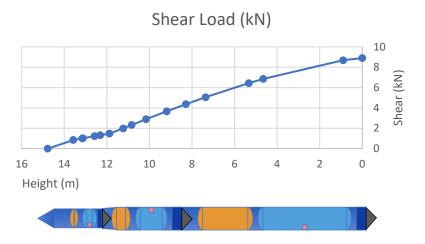


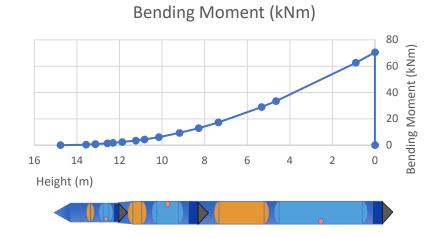
- Max shear ends close to 0
- Max bending moment ends close to 0
- Max axial load is equal to the thrust83.4 kN

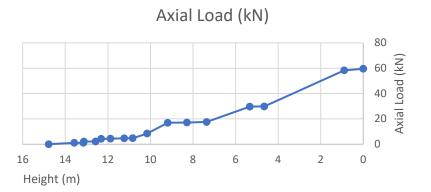




Minerva-2 Ground Loads Analysis







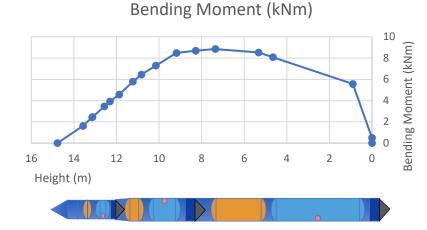
- Max shear is at the aft skirt
 - •8.9 kN
- Max bending moment is at the aft skirt
 - 70.5 kNm
- Max axial load is equal to the weight
 - •59.4 kN

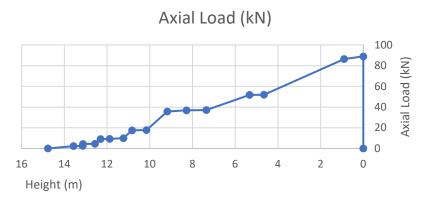




Minerva-2 Max-q Loads Analysis







- Shear load ends at 0
- Bending moment ends near 0
- Max axial load is equal to the thrust
 - •88.9 kN





Minerva Manufacturing: Material Selection

Launch Vehicle Component	Material	Coating
Cryogenic Propellant Tanks	Aluminum 2014-T6	Zinc Chromate
Non-Cryogenic Propellant Tanks	Aluminum 7075-T6	Zinc Chromate
Non-Pressurized Body Components	Aluminum 7075-T6	Zinc Chromate
Payload Fairing	Aluminum 2219- T852	Zinc Chromate

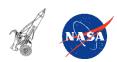






Minerva 1 – Margin of Safety on Ground

			MS Against \	Yielding	
Num	Component	Thickness (mm)	MS (%) Longitudinal	MS (%) Hoop	MS (%) Buckling
1	Forward Skirt	1	18,599	75,404	1,264
2	Stage 2 Fuel Tank	1	5,090	62,979	328
4	Stage 2 Ox Tank	1	2,170	2,479	72
5	Interstage	1	2,083	2,463	59
6	Stage 1 Fuel Tank	1.5	3,262	3,490	333
8	Stage 1 Ox Tank	1.5	1,975	1,189	397
9	Aft Skirt	1.9	2,876	1,523	624

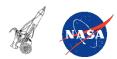




Minerva 1 – Margin of Safety at Max-q

MS	Against \	/ielding

			8		
Num	Component	Thickness (mm)	MS (%) Longitudinal	MS (%) Hoop	MS (%) Buckling
1	Forward Skirt	1	31,512	162,485	2,002
2	Stage 2 Fuel Tank	1	9,823	116,154	1,172
4	Stage 2 Ox Tank	1	3,494	15,671	310
5	Interstage 1	1	2,766	5,419	66
6	Stage 1 Fuel Tank	1.5	1,639	4,088	352
8	Stage 1 Ox Tank	1.5	657	1,827	124
9	Aft Skirt	1.9	770	2,348	50





Minerva 2 – Margin of Safety on Ground

			MS Against \	Yielding	
Num	Component	Thickness (mm)	MS (%) Longitudinal	MS (%) Hoop	MS (%) Buckling
1	Forward Skirt	1	14,780	24,612	1,113
2	Stage 3 Fuel Tank	1	9,166	13,217	6,633
4	Stage 3 Ox Tank	1	5,259	6,311	653
5	Interstage 2	1	4,705	6,204	275
6	Stage 2 Fuel Tank	1	2,974	3,946	139
8	Stage 2 Ox Tank	1	1,837	1,893	260
9	Interstage 1	1	1,783	1,831	43
10	Stage 1 Fuel Tank	1.5	2,691	1,964	251
11	Stage 1 Ox Tank	1.5	2,266	1,106	330
12	Aft Skirt	1.9	2,863	2,863	526







Minerva 2 – Margin of Safety at Max-Q

MS Against Yielding	
---------------------	--

Num	Component	Thickness (mm)	MS (%) Longitudinal	MS (%) Hoop	MS (%) Buckling
1	Forward Skirt	1	95,744	51.950	3,541
2	Stage 3 Fuel Tank	1	45,164	27,968	181,080
4	Stage 3 Ox Tank	1	20,401	13,590	1,121
5	Interstage 2	1	14,699	13,359	597
6	Stage 2 Fuel Tank	1	7,253	14,788	842
8	Stage 2 Ox Tank	1	3,339	4,106	415
9	Interstage 1	1	2,376	4,064	39
10	Stage 1 Fuel Tank	1.5	1,558	3,497	88
11	Stage 1 Ox Tank	1.5	648	1,688	112
12	Aft Skirt	1.9	762	2,176	48







Minerva Attitude Control System

- Minerva will use vernier engines for its ACS
- Minerva-1:
 - 2 Verniers at the bottom of all stages
 - Based on LR101-NA-7
 - Scaled down to produce 1.6 kN of thrust
 - Controllability ratio of 2.00
 - Time to double of 1.19s
- Minerva-2:
 - Will use same verniers as Minerva-1 for all stages
 - Controllability ratio of 2.05
 - Time to double of 1.48s





Minerva End of Mission



EOM disposal:

- Minerva's Stage 1 will be retrieved to be refurbished
- Subsequent stages will burn up on re-entry
- Recovery operations:
 - Minerva's 1st stage will be recovered by parachute deployment and helicopter capture
 - It will be sent off for cleaning, repair/replacement checks, and testing before being cleared for flight





Minerva Fault Analysis

- Minerva-1 and -2 all have one engine per stage, which means OEI will end mission
- To mitigate this risk, the likelihood of OEI shall be confirmed to be below 1/1000 (based on Merlin 1D reliability statistic)



Minerva Preliminary Cost Estimation

Source: Handbook of Cost Engineering for Space Transportation Systems including TRANSCOST 8.1 (2010)

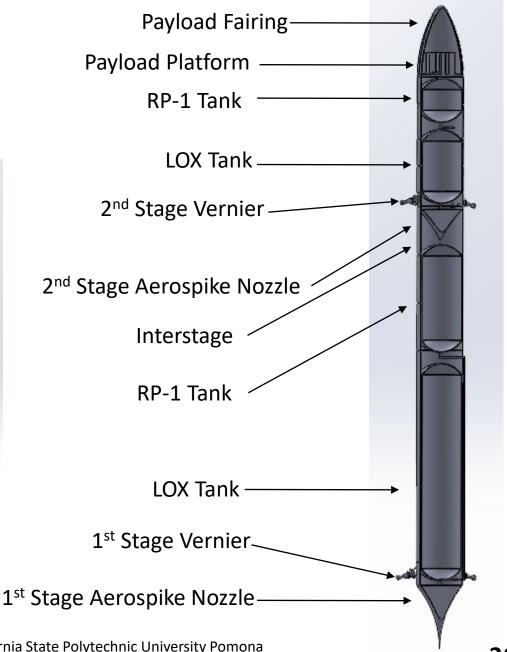
Methodology: Cost Estimating Relationships output Work-Years → convert to 2010 dollars → convert to 2021 dollars

Preliminary cost estimation for the Minerva Program: \$21.9 B



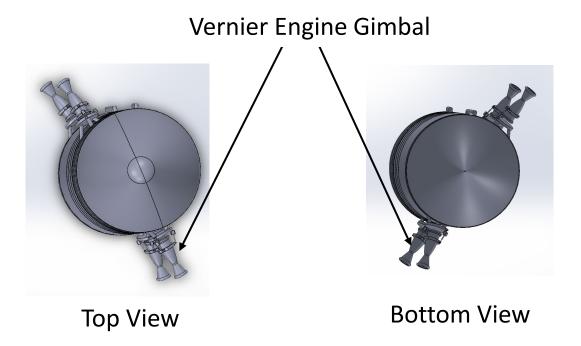
Minerva-1 3D Model







Minerva-1 3-View

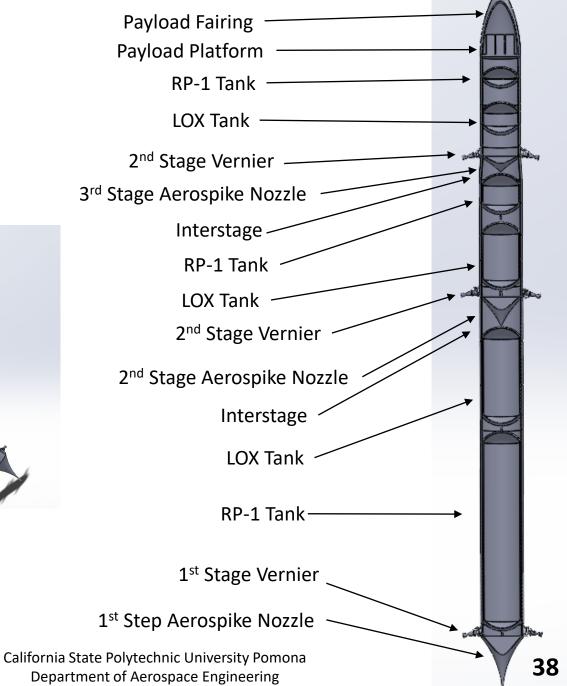






Minerva-2 3D Model

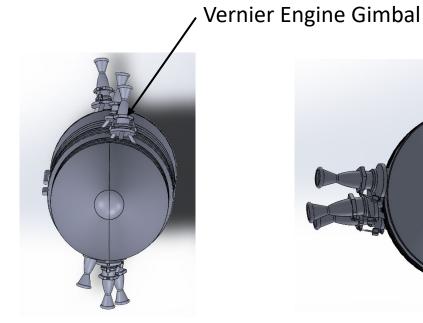




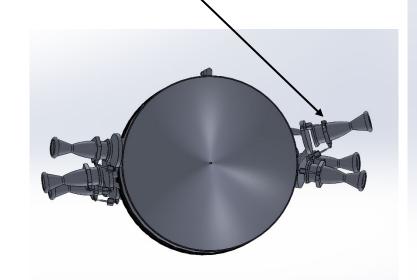




Minerva-2 3-View



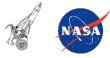




Bottom View



Front View



linerva Su	ımmary		
Stage 1	Stage 2	Stage 3	

	Stage 1	Stage 2	Stage 3
Diameter (m)	0.9	0.9	0.74
Length (m)	8.28	4.45	2.90
Engine Type	Liquid Propellant Aerospike	Liquid Propellant Aerospike	Liquid Propellant Aerospike
Propellant	RP-1/LOX	RP-1/LOX	RP-1/LOX
I _{sp} (s)	296	359	359
Propellant Mass (kg)	3980	1200	305
Dry Mass (kg)	310	115	60
Structural Ratio	0.11	0.11	0.11
T/W	1.4	1.05	0.9
GLOM (kg)	6075		





Architecture 2: Latona

Staging possibilities:

- TSTO to accommodate Mission 1
- 4 Parallel SRBs to accommodate the extra Δv for Mission 2

Propellant Choices:

- 1st stage (and SRBs) solid propellant: ammonium perchlorate composite (using AP for oxidizer, Al for fuel, and HTPB for binder)
 - Wide ambient temperature limits, good burnrate control, good storage stability
- 2nd Stage liquid propellants: LCH₄/LO₂
 - Higher performance/ $I_{sp} \rightarrow$ less quantity of methane required for lift off \rightarrow smaller tanks → mass savings

Nozzle Choice: bell nozzle for all stages





Latona Mission 1

v = 3.58 km/s h = 69.92 km t = 158 sec

2. Main Engine Burnout

& 1st Stage Separation

and Disposal

3. Fairing Separation

4. SECO I

v = 6.44 km/s h = 182 km, t = 346 sec

 $\Delta v = 0.183 \text{ km/s}$ $\Delta t = 2736 \text{ s}$

5. Hohmann Transfer Maneuver 6. SECO II &
Payload Delivery
(30 kg CubeSat at 500 km)

7. 2nd Stage Disposal

 $\Delta v = 0.145 \text{ km/s}$

1. Lift-off and Climb

Latona Mission 2

v = 5.8 km/s, h = 234 km, t = 400 sec

4. Main Engine Burnout
 & 1st Stage Separation
 and Disposal

 $\Delta v = 0.179 \text{ km/s}$ $\Delta t = 2768 \text{ s}$ 6. SECO I & Payload Delivery (75 kg CubeSat)

7. 2^{nd} Stage 10° Plane Change $\Delta v = 1.305$ km/s

3. Fairing Separation

6. Hohmann Transfer Maneuver

550 km SSO

8. SECO II & Payload Delivery
(20 kg CubeSat)

9. 2nd Stage Disposal

 $\Delta v = 0.159 \text{ km/s}$

2. Booster Separation and Disposal

v = 1.48 km/s, h = 45.33 km, t = 109 sec

1. Lift-off and Climb



Latona Design Specifications

Architecture	Mission 1 Thrust (kN)	Mission 2 Thrust (kN)	I _{sp} (sec)	Structural Mass Fraction σ
Latona Stage 0 (Sea Level)	N/A	81.8	265*	0.08
Latona Stage 1 (Sea Level)	21.1	21.1	265*	0.08
Latona Stage 2 (Vacuum)	2.8	3.0	380**	0.11

^{*} Solid propellant motors for its main engine and 4 strap-on boosters

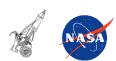
^{**}Latona will have a Raptor-type engine for its 2nd stage







- Solved for the minimum mass of Mission 1
- Used the mass of propellants for Mission 2
- Set up a system of equations based off $\%\Delta v$ for Stage 0 and $\%\Delta v$ for Stage 1 to solve numerically for the values

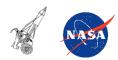




Latona Lift-Off Mass Estimates

	Mission 1 (kg)	Mission 2 (kg)
Stage 2	272.4	337.4
Stage 1	1269.6	1269.6
Stage 0	N/A	4319.6
Total	1542.0	5926.6

- Latona has SRBs for Mission 2
- Upper-most stage mass includes payload







Below are the conditions at end of powered ascent phase.

	Latona 1	Latona 2
Altitude (km)	196.5	293.2
Velocity (km/s)	6.93	7.47

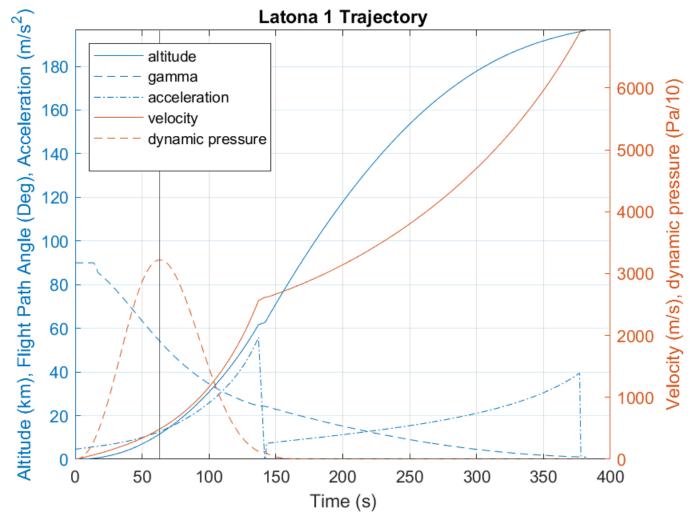
Following this, an appropriate kick burn is applied that effectively circularizes and enters the Hohmann Transfer.







Latona-1 Trajectory

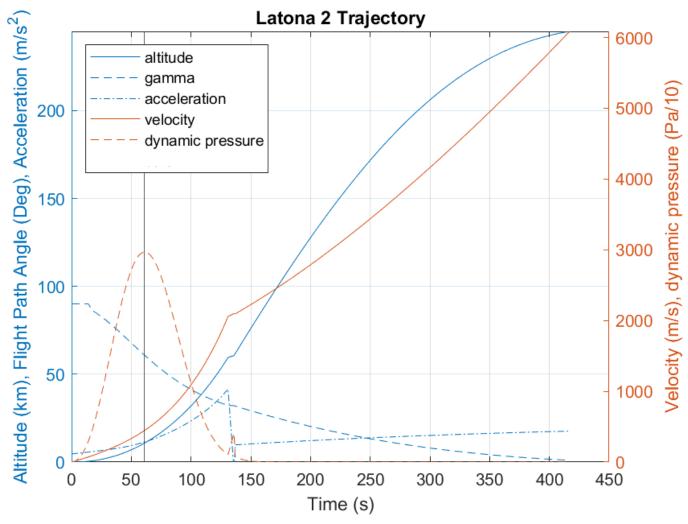






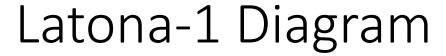


Latona-2 Trajectory



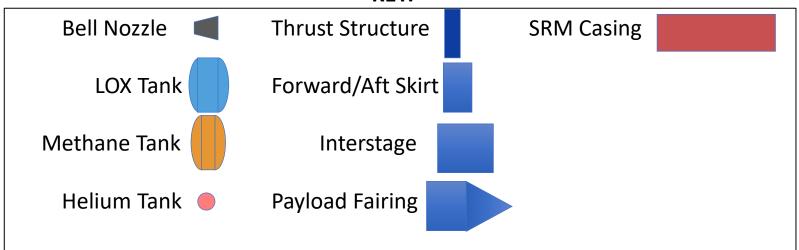


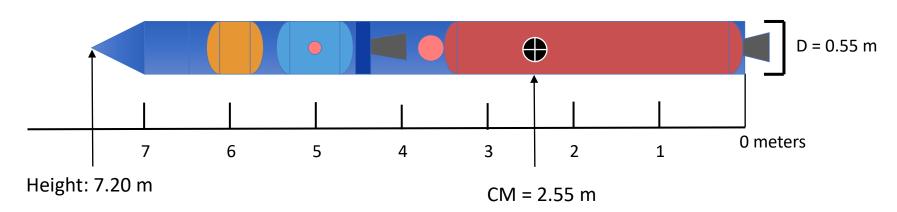


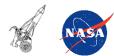






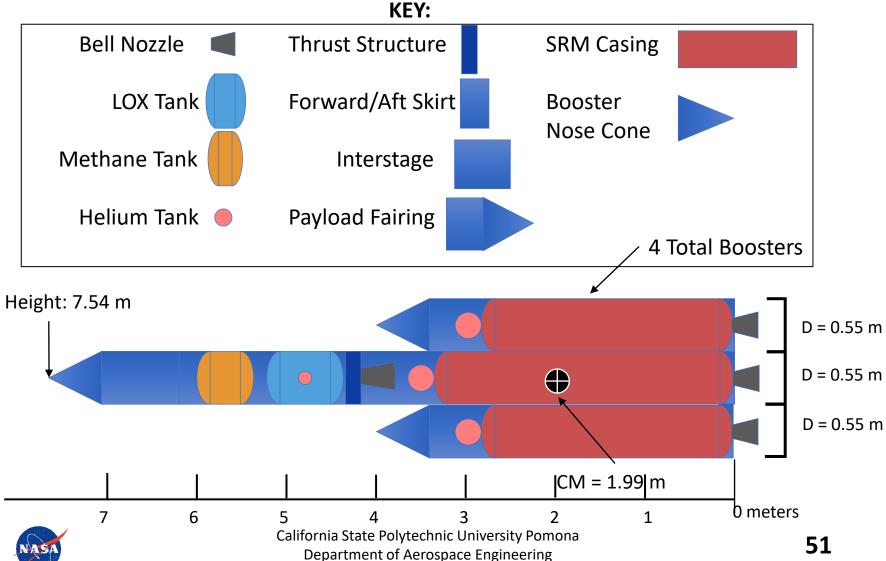






Latona-2 Diagram

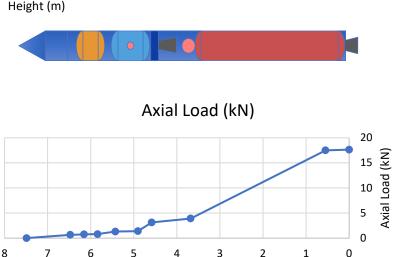


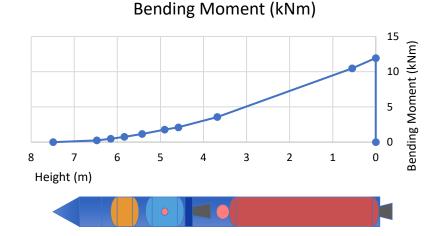




Latona-1 Ground Loads Analysis







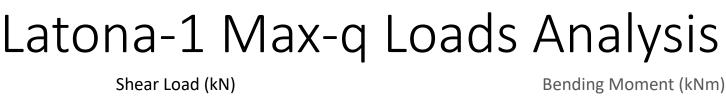
- Max shear is at the aft skirt
 - •2.7 kN
- Max bending moment is at the aft skirt
 - •11.9 kNm
- Max axial load is equal to the weight
 - 17.6 kN

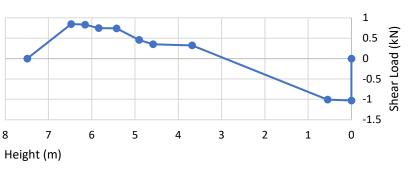


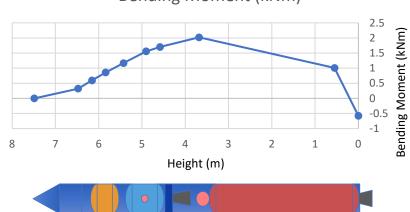


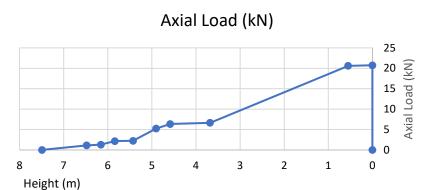
Height (m)











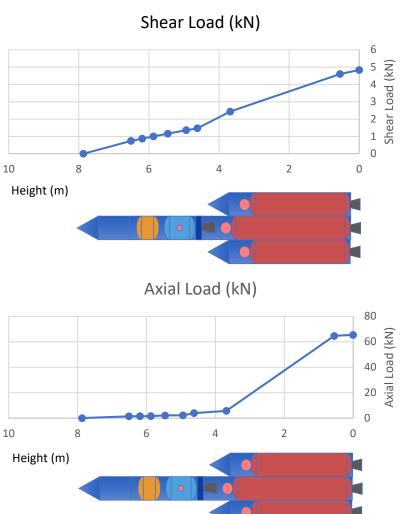
- Max shear ends at 0
- Max bending moment ends close to 0
- Max axial load is equal to the thrust
 - •20.7 kN

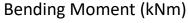


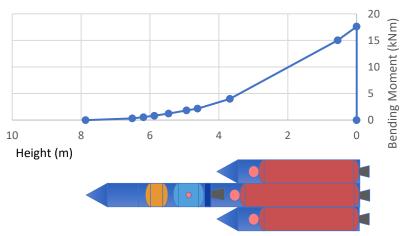




Latona-2 Ground Loads Analysis







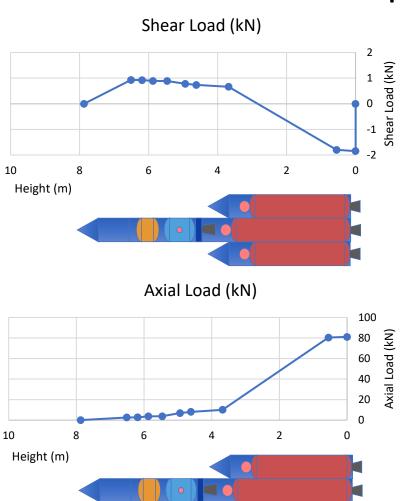
- Max shear is at the aft skirt
 - •4.8 kN
- Max bending moment is at the aft skirt
 - •17.6 kNm
- Max axial load is equal to the weight
 - •65.4 kN



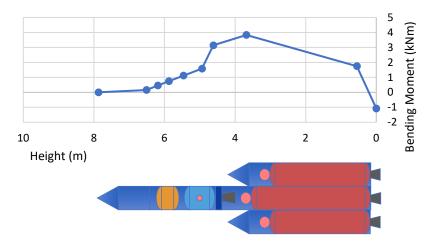




Latona-2 Max-q Loads Analysis



Bending Moment (kNm)



- Max shear ends at 0
- Max bending moment ends close to 0
- Max axial load is equal to the thrust
 - •81.0 kN







Latona Manufacturing: Material Selection

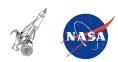
Launch Vehicle Component	Material	Coating
Cryogenic Propellant Tanks	Aluminum 2014-T6	Zinc Chromate
Non-Cryogenic Propellant Tanks	Aluminum 6061-T6	None
Non-Pressurized Body Components	Aluminum 6061-T6	None
Payload Fairing	Aluminum 2219- T852	Zinc Chromate





Latona 1 – Margin of Safety on Ground

			MS Against Yi	elding	
Num	Component	Thickness (mm)	MS (%) Longitudinal	MS (%) Hoop	MS (%) Buckling
1	Forward Skirt	1	13,659	21,254	3,962
2	Stage 2 Fuel Tank	1	9,906	19,402	1,710
3	Stage 2 Ox Tank	1	5,024	8,024	795
4	Interstage	1	2,446	3,665	652
5	Stage 1 SRM Casing	1	1,607	1,060	563
6	Aft Skirt	1.5	1,813	1,051	750





Latona-1 – Margin of Safety at Max-q

			MS Against	Yielding	
Num	Component	Thickness (mm)	MS (%) Longitudinal Stress	MS (%) Hoop Stress	MS (%) Buckling Stress
1	Forward Skirt	1	26,115	36,135	5,584
2	Stage 2 Fuel Tank	1	23,979	55,512	2,776
3	Stage 2 Ox Tank	1	6,475	30,557	1,128
4	Interstage	1	3,025	7,517	660
5	Stage 1 SRM Casing	1	526	1,266	465
6	Aft Skirt	1.5	724	1.934	287





Latona 2 – Margin of Safety on Ground

			MS Against Yielding		
Num	Component	Thickness (mm)	MS (%) Longitudinal Stress	MS (%) Hoop Stress	MS (%) Buckling Stress
1	Forward Skirt	1	12,636	9,131	3,660
2	Stage 2 Fuel Tank	1	9,106	11,346	1,863
3	Stage 2 Ox Tank	1	4,513	6,085	854
4	Interstage	1	1,443	2,871	356
5	Stage 1 SRM Casing	1	412	197	344
6	Aft Skirt	1.5	705	343	452





Latona-2 – Margin of Safety at Max-q

			MS Against \	Yielding	
Num	Component	Thickness (mm)	MS (%) Longitudinal Stress	MS (%) Hoop Stress	MS (%) Buckling Stress
1	Forward Skirt	1	19,391	16,148	3,497
2	Stage 2 Fuel Tank	1	13,869	26,023	2,250
3	Stage 2 Ox Tank	1	6,224	19,121	1,023
4	Interstage	1	2,919	5,932	613
5	Stage 1 SRM Casing	1	336	270	306
6	Aft Skirt	1.5	457	449	109





Latona Attitude Control System

- Latona will use Thrust Vectoring
- Latona 1:
 - Max Gimbal Angle approximately 5.57°
 - Time to Double approximately 0.71 seconds
- Latona 2:
 - Max Gimbal Angle approximately 2.60°
 - Time to Double approximately 0.86 seconds
- Latona is designed for a Controllability Ratio of 2





Latona End of Mission

- EoM disposal: Latona will be entirely disposable
 - Stage 0 and Stage 1 will be disposed in the ocean.
 - Stage 2 will be disposed by deorbiting and burn up upon reentry.





Latona Fault Analysis

- Latona-1 has one engine per stage, which means
 OEI will end mission
- Despite Latona-2 having 4 boosters on its 1st stage,
 OEI will also end mission because the engines are not redundant (stage 2 has 1 engine)
- To mitigate this risk, the likelihood of OEI shall be confirmed to be below 1/1000 (based on Merlin 1D reliability statistic)





Latona Preliminary Cost Estimation

Source: Handbook of Cost Engineering for Space Transportation Systems including TRANSCOST 8.1 (2010)

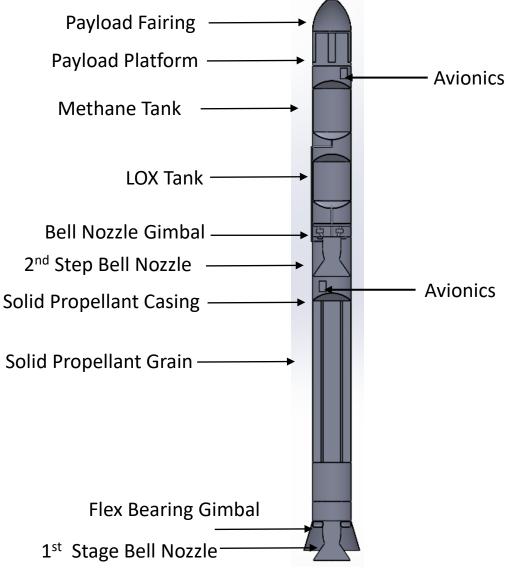
Methodology: Cost Estimating Relationships output Work-Years → convert to 2010 dollars → convert to 2021 dollars

Preliminary cost estimation for the Latona Program: \$4.94 B



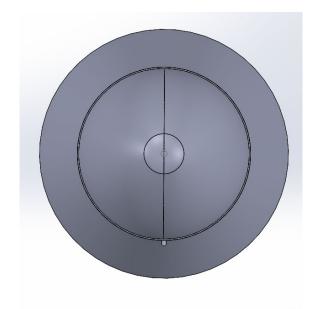
Latona-1 3D Model



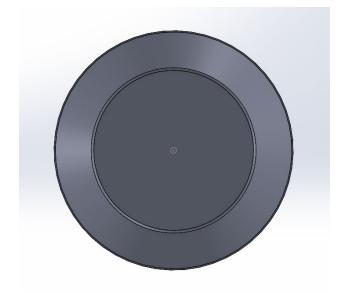




Latona-1 3-View



Top View



Bottom View

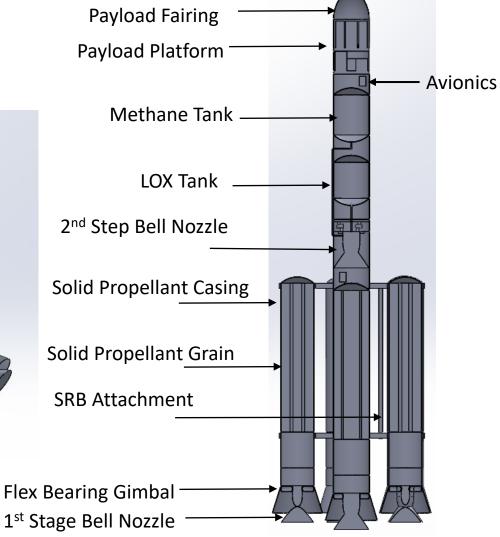






Latona-2 3D Model

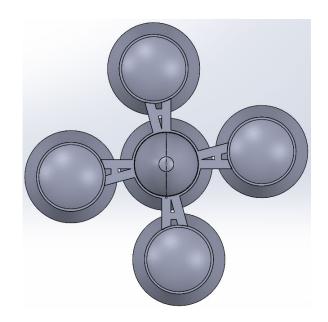




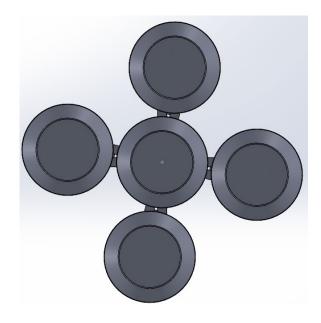




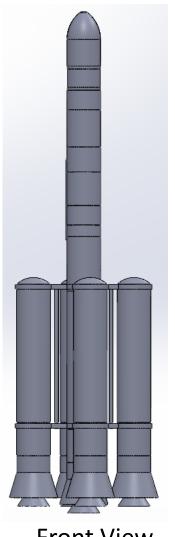
Latona-2 3-View



Top View



Bottom View



Front View





Latona Summary

	Stage 0	Stage 1	Stage 2	
Diameter (m)	0.55	0.55	0.55	
Length (m)	4.39	4.62	3.25	
Engine Type	Solid Propellant Bell Nozzle	Solid Propellant Bell Nozzle	Liquid Propellant Bell Nozzle	
Propellant	AP	AP	LCH₄/LOX	
I _{sp} (s)	265	265	380	
Propellant Mass (kg)	4000	1200	220	
Dry Mass (kg)	1900	190	50	
Structural Ratio	0.08	0.08	0.11	
T/W	1.4	1.4	1.05	
GLOM (kg)		7680	580	

Summary

- Goal: Create a launch vehicle system capable of taking 30 kg payload to 500 km orbit and of taking 95 kg payload to 550 km SSO
- Minerva is an innovative, partially-reusable design that features aerospike nozzles and a modular third stage
- Latona is a more traditional design featuring classic bell nozzles and modular SRBs



Selection Criteria

Affordability

- Low Lifetime Costs
- Competitive Price per Flight

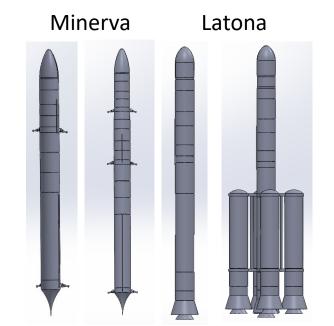
Reliability

- Low remanufacturing or refurbishing time to stay on schedule
- Low chance for mission failure

Feasibility

- Traditional manufacturing methods (tried-and-true)
- Research and development time





LV Comparison



Affordability

Latona has a lower program cost than Minerva ~(\$4.94 B vs. \$21.9 B)

Reliability

 Latona's parallel staging for Mission 2 has more failure modes compared to Minerva's series staging

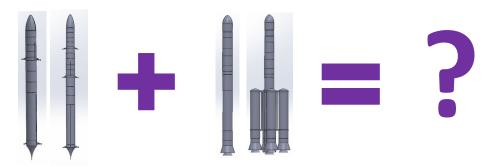
Feasibility

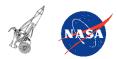
- Minerva's aerospikes are more difficult to manufacture compared to Latona's bell nozzles
- Minerva features a more experimental design compared to Latona (longer R&D time and cost)



New Architecture: Zephyr

- Will combine the best aspects of Minerva and Latona Architectures
 - Minerva series staging is preferable over Latona parallel staging
 - Latona bell nozzle engines are preferable over Minerva experimental aerospike engines
 - No first stage recovery





References

- [1] Design of Rockets and Space Launch Vehicles by Donald Edberg
- [2] Handbook of Cost Engineering for Space Transportation Systems (Revision 3a) including TRANSCOST 8.1
- [3] www.astronautix.com
- [4] *Rocket Propulsion Elements* (9th ed.) by Sutton and Biblarz
- [5] https://www.usinflationcalculator.com/



BACK-UP





Minerva-1 Mass, Inertia, Loaded and Dry

Case	Mass (kg)	CM (m)	J _{pitch/yaw} (kg m²)	J _{roll} (kg m²)
Empty Vehicle	602.8	5.6	13383	59
Fully Loaded Vehicle	4049.4	6.3	62128	59
Step 1 Dry, Step 2 Loaded	1798.8	8.9	42517	59
Step 2 Loaded Only	1441.5	10.6	35984	30
Step 2 Dry Only	245.3	10.5	6850	30
Step 1 Dry Only	357.3	3.9	6533	29



Minerva-2 Mass, Inertia, Loaded and Dry

Case	Mass (kg)	CM (m)	J _{pitch/yaw} (kg m ²)	J _{roll} (kg m²)
Empty Vehicle	786.0	7.7	27665	68
Fully Loaded Vehicle	4478.8	7.3	101551	68
Step 3 and 2 loaded, Step 1 dry	2288.8	10.28	70924	68
Step 3 and 2 Loaded	1924.0	11.8	62182	39
Step 3 Loaded, Step 2 dry	724.9	13.1	36300	39
Step 3 Loaded	557.0	14.1	33806	25
Step 3 Dry Only	253.3	14.3	16429	25
Step 1 Dry Only	364.7	3.9	39368	29



Latona-1 Mass, Inertia, Loaded and Dry

Case	Mass (kg)	CM (m)	J _{pitch/yaw} (kg m²)	J _{roll} (kg m²)
Empty Vehicle	377.1	3.4	1420	22
Fully Loaded Vehicle	1252.0	2.768	3169	22
Step 1 Dry, Step 2 Loaded	598.7	4.1	2659	22
Step 2 Loaded Only	381.3	5.1	2504	7
Step 2 Dry Only	159.7	5.3	1265	7
Step 1 Dry Only	217.4	2.1	153	15



Latona-2 Mass, Inertia, Loaded and Dry

Case	Mass (kg)	CM (m)	J _{pitch/yaw} (kg m²)	J _{roll} (kg m²)
Empty Vehicle	1246.8	2.7	3949	81
Fully Loaded Vehicle	6667.2	2.1	6293	81
Step 1 and 0 Dry, Step 2 Loaded	1468.7	3.0	5890	81
Step 2 Loaded Only	465.9	5.4	5442	13
Step 2 Dry Only	244.0	5.7	3500	13
Step 1 Dry Only	634.4	1.9	342	53



SLR Prioritization Methodology

Requirements are ranked based on Consequence Statements that state the consequence for having failed a requirement.

Ranking: 1 = Highest Priority 4 = Lowest Priority

Consequence Number	Consequence Statement		
1.0	Disqualified from winning the NASA Launch Services Program VCLS Demo 2 contract.	1	
2.0	Launch system fails to perform Mission 1 or 2 as outlined in the Statement of Work (SOW).	2	
3.0	The safety of involved personnel or the public is compromised.	3	
4.0	The schedule and/or cost-efficiency of the program management plan is compromised.	4	





REQ #	WBS #	FOM	FOM Requirement Statement	
T4.1	4.0	No	A single launch system must be able to complete both Mission 1 and Mission 2 in the VCLS RFP	2
T3.1	3.0	No The system must have the payload capacity for a 30 kg payload for Mission 1		2
T4.2	4.0	No	The system must reach a minimum orbit of 500 km and deliver the payload for Mission 1	2
T4.3	4.0	No	The system must achieve an inclination of 40-60 degrees for Mission 1	2
T3.2	3.0 Yes		The system must carry a 75 kg payload and a 20 kg payload for Mission 2	2
T4.4	The system must reach a minimum orbit of 550 km sunsynchronous orbit and deliver the 75 kg payload for Mission 2		2	
T4.5	4.0	Yes	The system must make a minimum 10-degree plane change with a 20 kg payload for Mission 2	2





REQ	WBS #	FOM	Requirement Statement	
P5.1	5.0	No	The team will ensure the safety of the public and personal property and equipment	
T6.1	6.0	No	The system must launch from Vandenberg and Kennedy Space Center	4
T3.3	3.0	No	The system must be able to deploy payload without causing the CubeSats damage that is detrimental to the completion of either mission	2
T5.2	5.0	Yes	The system must have a reliability of 1 in 1000 for the success of each mission	
C2.1	2.0	No	The system must abide by adequate price competition as prescribed under FAR15.403-1(C)	1
C2.2	2.0	Yes	The service must be more cost effective than existing launch vehicles that can perform Missions 1 & 2	4





REQ #	WBS #	FOM	FOM Requirement Statement	
P2.3	2.0	Yes	The system must be ready for the launch date in the year 2027	
P1.1	1.0	No	The team will conduct periodic design reviews on dates that are TBP	
P2.4	2.0	No	The team will develop and maintain a master schedule and sub-tier schedules	
P2.5	2.0	No	The team will acquire all government permits, licenses, and approvals by the launch date	
P1.2	1.0	No The team will provide the recommended payload success criteria prior to the launch, the post-launch supporting data, and the Final Post Flight Report		4
C2.6	2.0	No	The team will acquire insurance to cover any damages to government property	1





REQ #	WBS #	FOM	Requirement Statement	P (1-4)
C2.7	2.0	No	The team will pay for all transportation cost and taxes	4
P6.2	6.0	No	The team will acquire a range safety document for Vandenberg and Kennedy Space Station	
P2.8	2.0	No	The team will obtain NPR 8621.1, NASA Procedural Requirements for Mishap and Close Call Reporting, Investigating, and Recordkeeping	1
P2.9	2.0	No	The team will obtain a Certification Regarding United States Commercial Provider of Space Transportation Services (Public Law 105-303, Title II, Section 201)	
T4.6	4.0	Yes	The system will utilize sufficient flight instrumentation to establish that the vehicle launch environments meet the requirements of the ICD	
P6.3	5.0, 6.0	No	The team will provide and make arrangements for all facilities, supplies, and services required for preparation and launch of the vehicle.	4





REQ #	WBS #	FOM	Requirement Statement	P (1-4)
P6.4	6.0	No	No The team will Identify launch vehicle ground and flight safety launch constraints	
P6.5	6.0	No	The team will provide and schedule the necessary support services at the launch range that are required for launch preparation of the launch vehicle, integrated testing with the payload, and launch.	1
P6.6	6.0	No	The team will provide access for up to three Government personnel at the launch site for familiarization and communication of launch status	1
P6.7	3.0	No	The team will provide a certified ISO 14644-1 Class 8 or better cleanroom for CubeSat integration	1
P6.8	3.0	No	The team will maintain the contamination environment within the payload fairing such that it meets ISO 14644-1 Class 8 or better	1





REQ #	WBS #	FOM	Requirement Statement	
P2.10	2.0	No	The team will establish, implement, and maintain risk management, safety, reliability, and quality assurance programs with AS9100, Aerospace Quality Management System	4

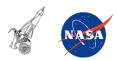


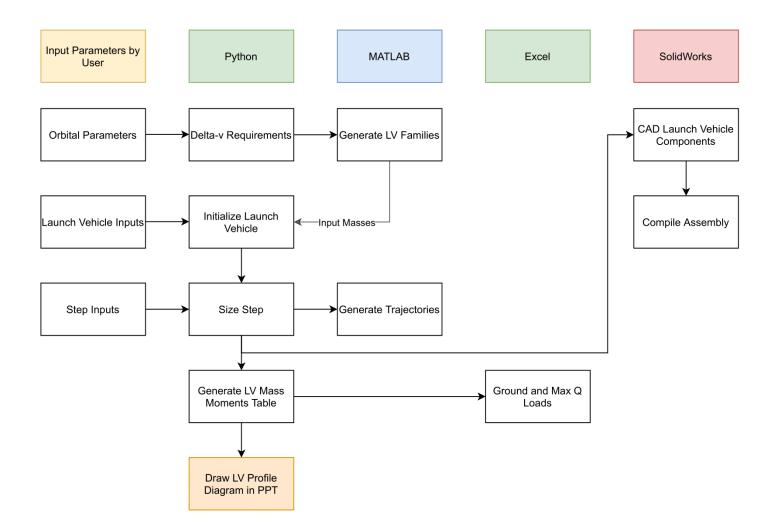


Kodiak vs Vandenberg

- Vandenberg has more launch windows due to daylight and weather conditions.
- Kodiak would save only approximately 100 m/s from the total mission Δv .
- To ship the Launch Vehicle to Kodiak would cost more than the savings from launching from Kodiak.

Vandenberg is thus more optimal



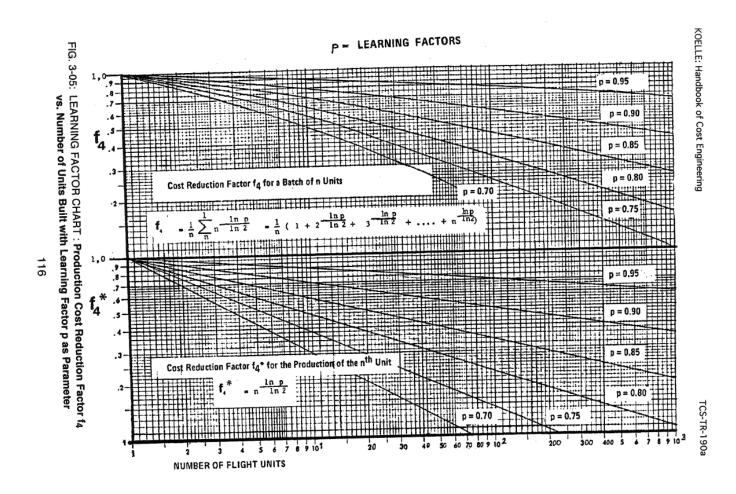


Minerva Engine Assumptions

- In order to estimate the performance of an aerospike nozzle attached to a Merlin-type engine, the following assumption was made:
- Merlin-1C (vac) $I_{sp} = 342 \text{ sec}$
- Merlin-1D (sea level) $I_{sp} = 282 \text{ sec}$
- Both Isp values are multiplied by 5% in order to simulate the improvement of an aerospike nozzle
- 342 sec x 0.05 = 17.1 + 342 = 359.1 sec $I_{sp \, vac}$
- 282 sec x 0.05 = 14.1 + 282 = 296.1 sec $I_{sp sea level}$



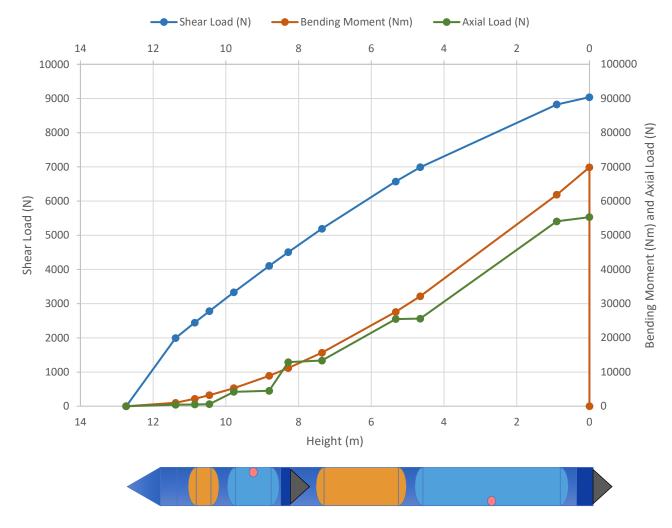
Graph from Transcost







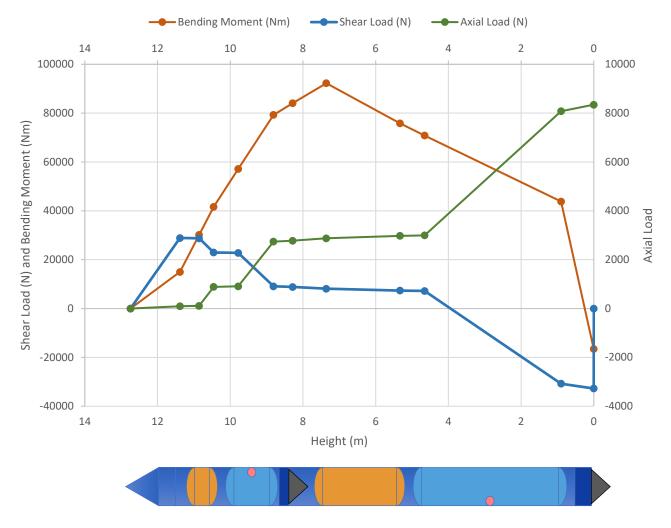
Minerva-1 Ground Loads







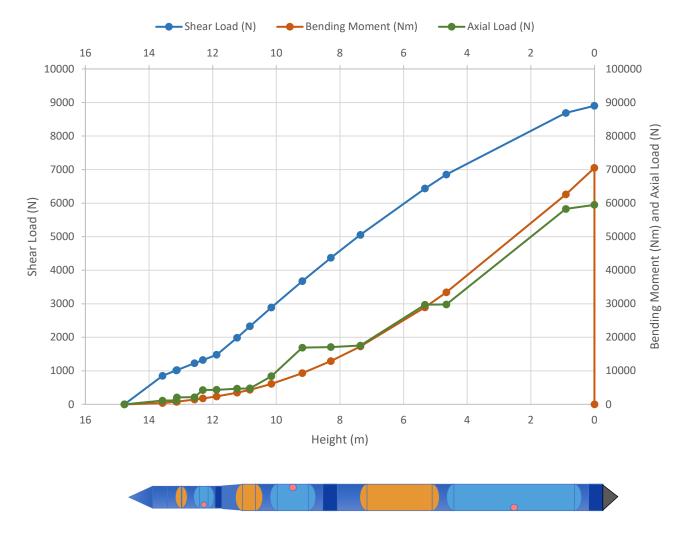
Minerva-1 Wind Loads







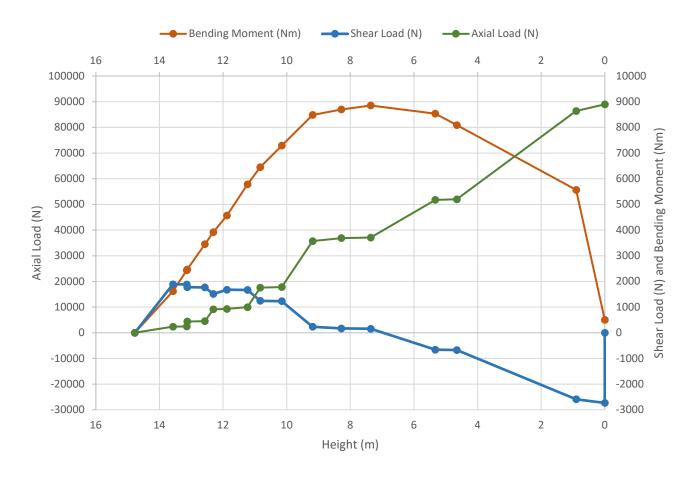
Minerva-2 Ground Loads







Minerva-2 Wind Loads





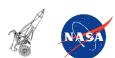


Fault Analysis Reference

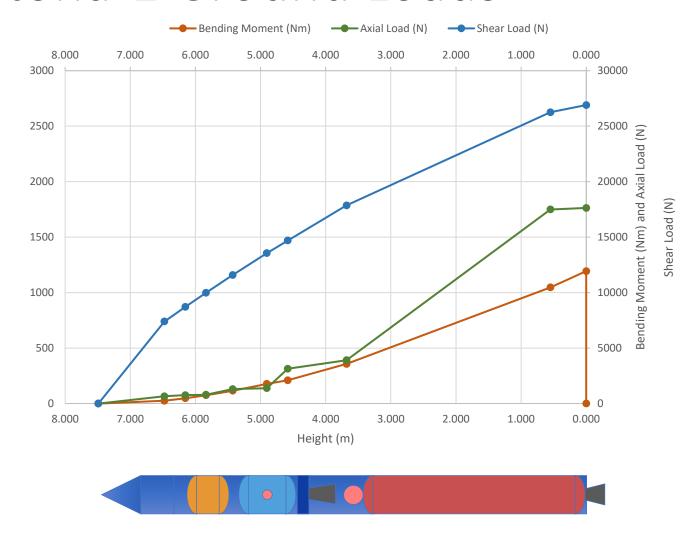


Actual Engine Reliability = PDH ("Pretty Darn High")

Engine	Qty	Fails/ Uses	Reliability	Vehicle
Merlin 1D	9	1/990*	0.99899 = 99.90%	Falcon 9
Rutherford	9	0/162*	1.000 = 100%	Electron
RS-25	3	1/405	0.9975 = 99.75%	Shuttle
RD-180	1	1/86	0.9883 = 98.83%	Atlas V
RD-107/108	5	1/1335	0.9992 = 99.92%	Soyuz, post-2000
F-1	5	0/65	1.000 = 100%	Saturn V



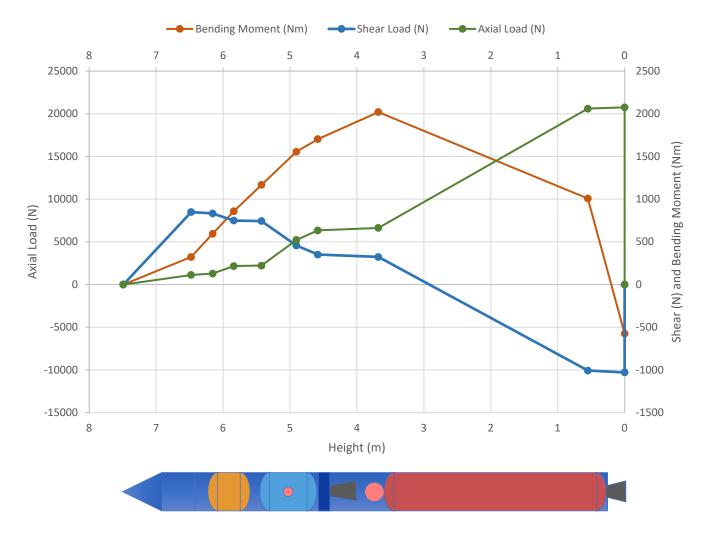
Latona-1 Ground Loads







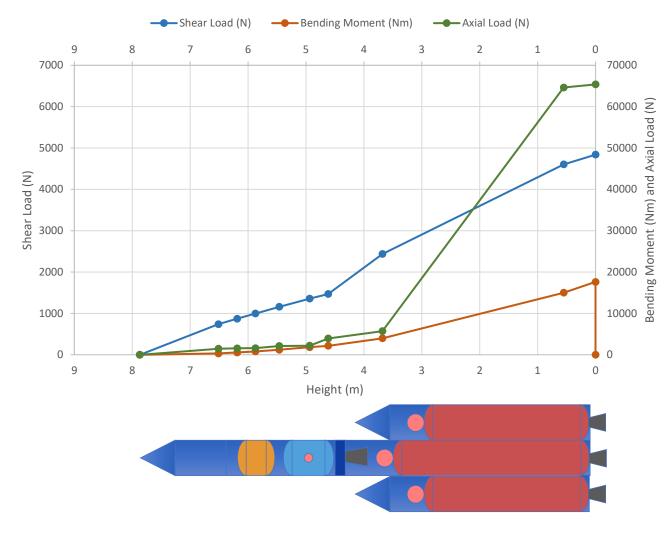
Latona-1 Wind Loads







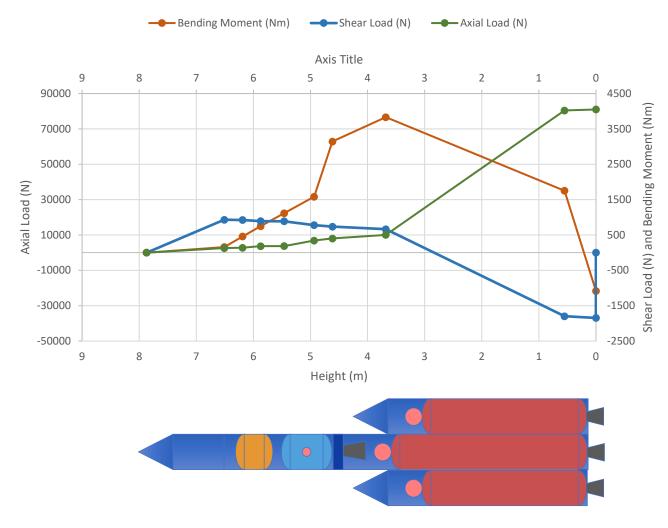
Latona-2 Ground Loads







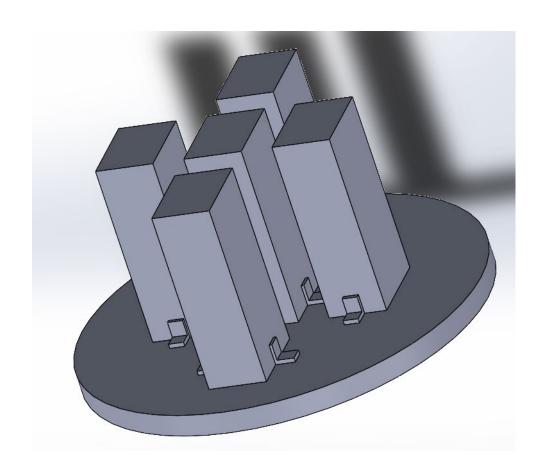
Latona-2 Wind Loads



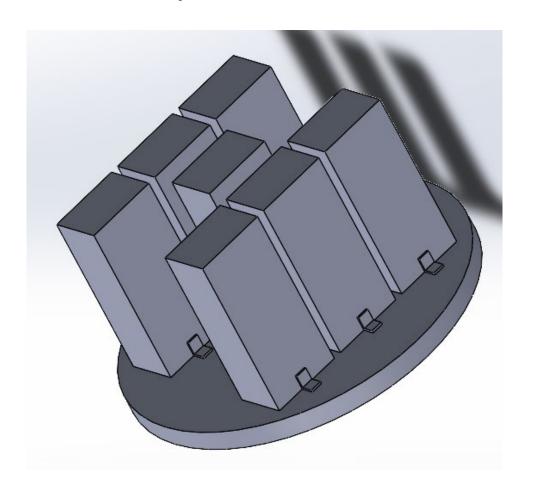




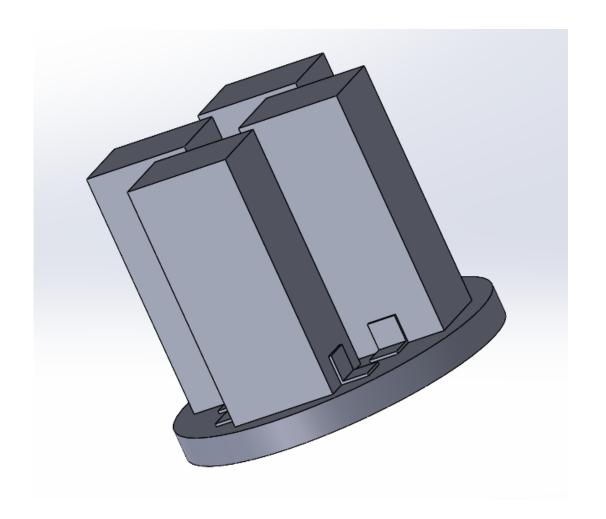
Minerva-1 Payload Accomodation



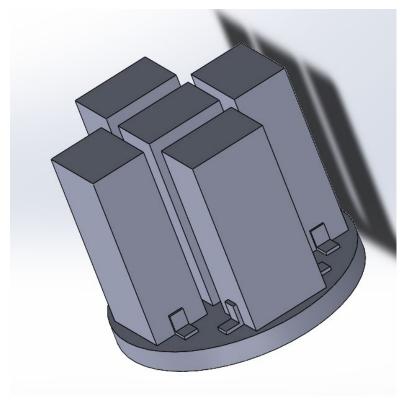
Minerva-2 Payload Accomodation

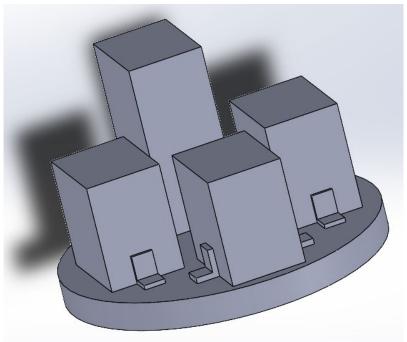


Latona-1 Payload Accomodation



Latona-2 Payload Payload Accomodation





Latona Preliminary Cost Assumptions

- Mission 1 vehicles will be manufactured at a rate of 12/year
- Minerva engines will have 6 qualification firings per turbo-pump engine
- Latona engines will have 4 qualification firings per turbopump engine
- All vehicles will be assembled horizontally
- https://www.usinflationcalculator.com/

