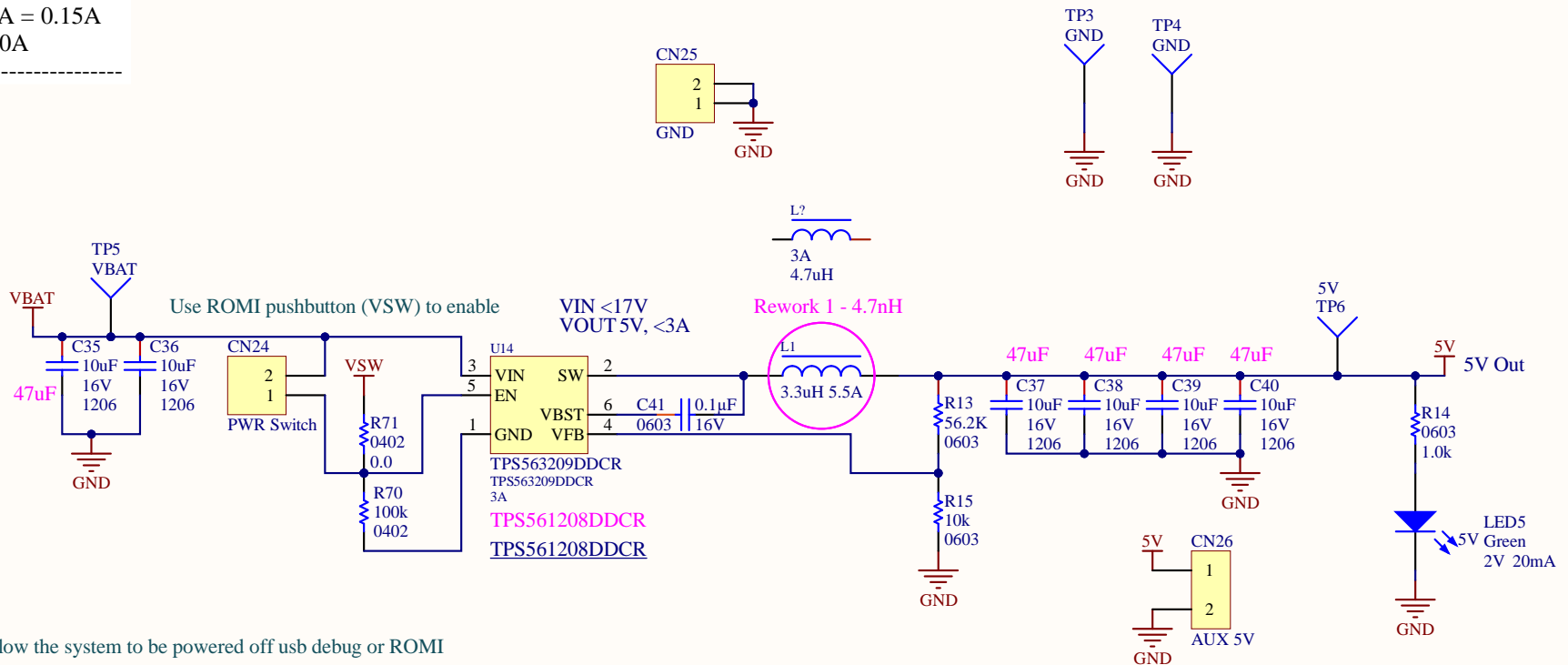


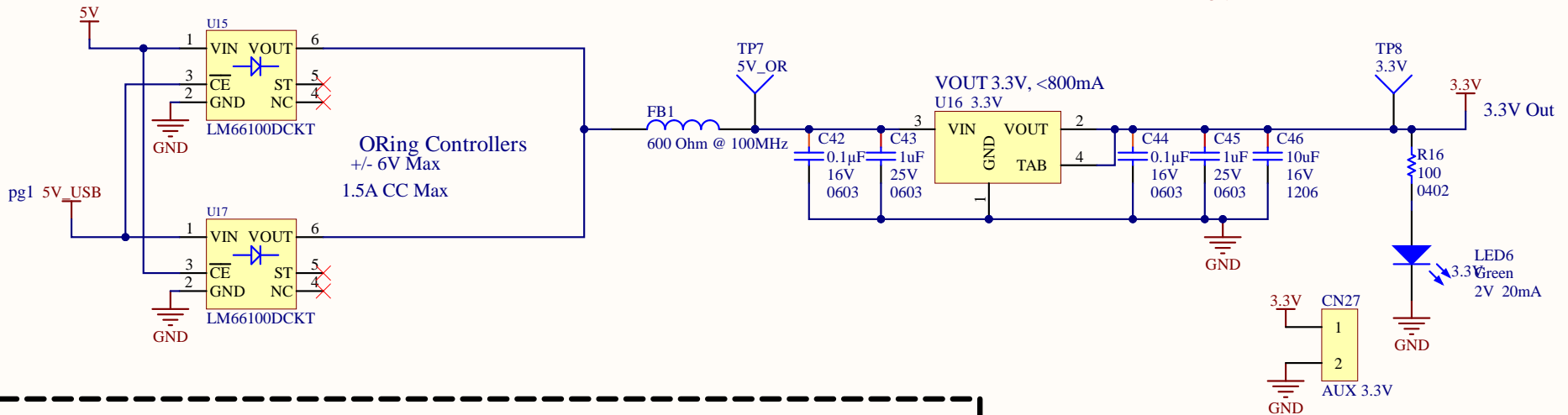
5V Power Usage:

$$10 \text{ RGB} * 0.015\text{A} = 0.15\text{A}$$

$$3.3\text{V LDO} = 0.80\text{A}$$

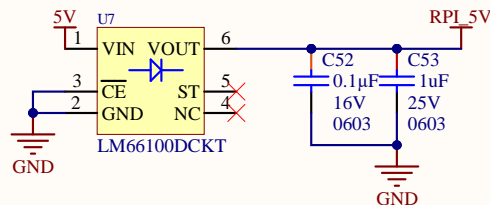


This will allow the system to be powered off usb debug or ROMI



Raspberry Pi Power

Ideal Diodes are used to power the pi off of the board voltages. This will prevent issues if the pi tries to backpower the board



Title

Power

Size

Number

A

*

Revision

A

Date: 9/18/2020

Sheet 4 of 5

File: C:\github\STM32-ROMI_Rev_A_4_3V\DrSchBoc

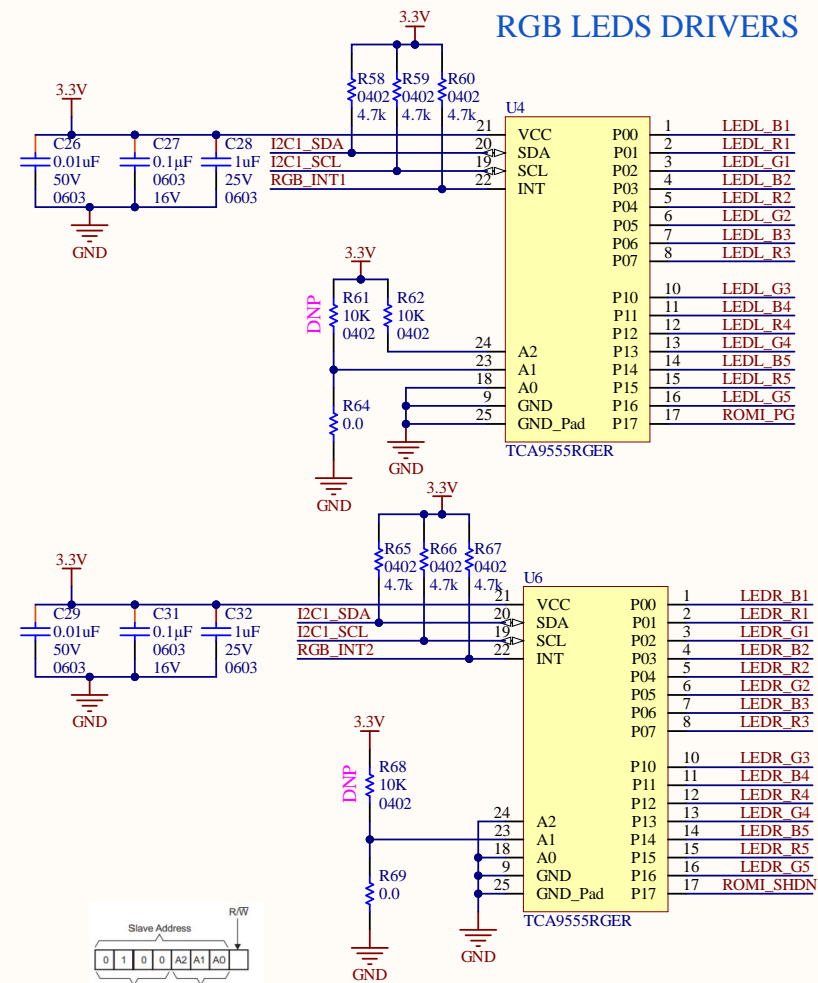
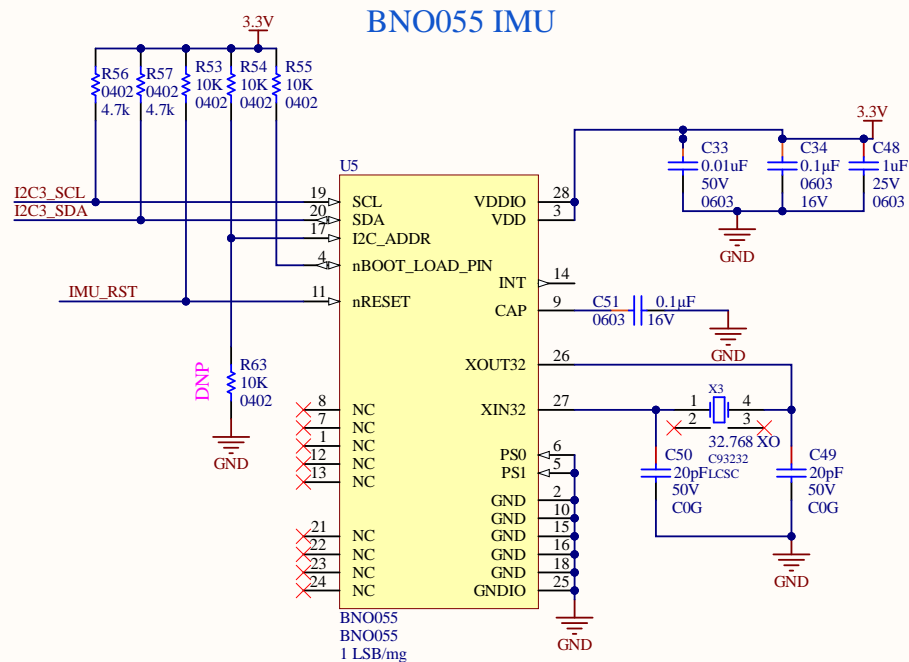
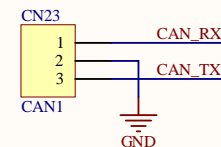


Table 2. Address Reference


INPUTS			I ² C BUS SLAVE ADDRESS
A2	A1	A0	
L	L	L	32 (decimal), 20 (hexadecimal)
L	L	H	33 (decimal), 21 (hexadecimal)
L	H	L	34 (decimal), 22 (hexadecimal)
L	H	H	35 (decimal), 23 (hexadecimal)
H	L	L	36 (decimal), 24 (hexadecimal)
H	L	H	37 (decimal), 25 (hexadecimal)
H	H	L	38 (decimal), 26 (hexadecimal)
H	H	H	39 (decimal), 27 (hexadecimal)

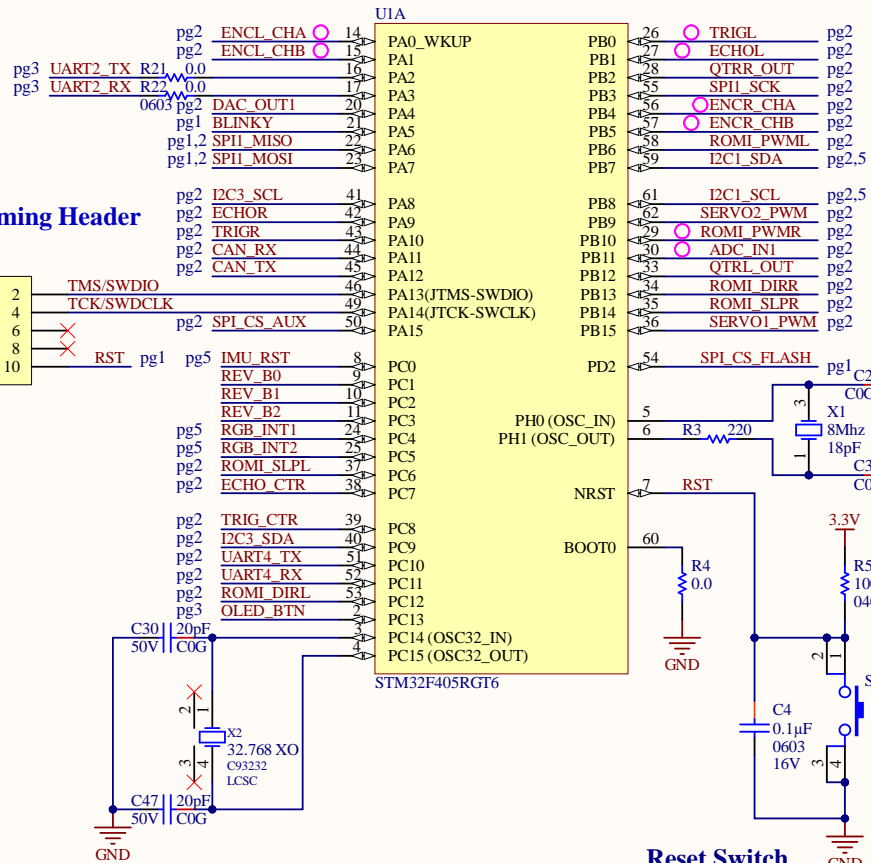


CAN BUS

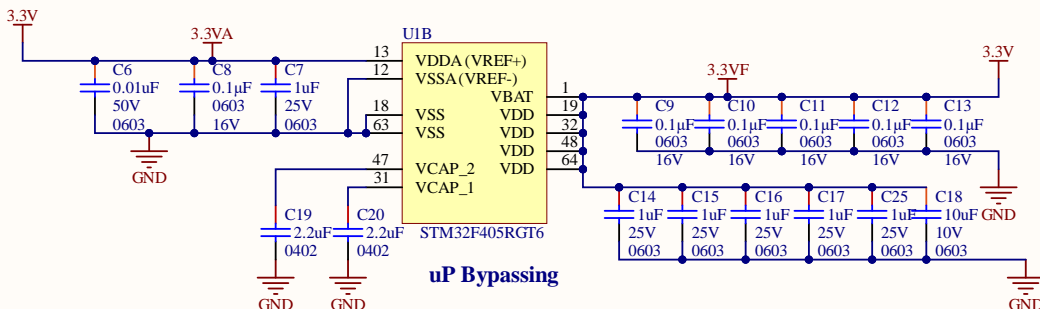
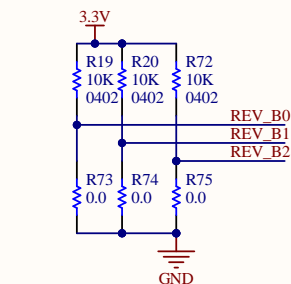



1	2	3	4
A			A
B			B
C			C
D			D
1	2	3	4

Title			Altium Limited L3, 12a Rodborough Rd Frenchs Forest NSW Australia 2086	
Size: A4	Number:	Revision:		
Date: 9/18/2020	Time: 3:17:33 PM	Sheet of		
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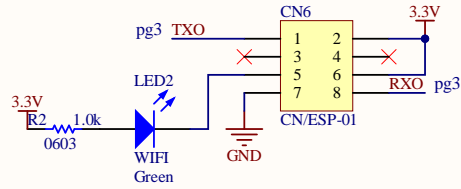


REVISION LEVEL Rev A = 0000

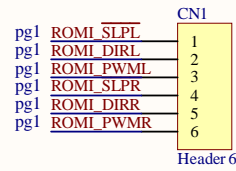


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Size: A4	Number:	Revision:			
Date: 9/18/2020	Time: 3:17:33 PM	Sheet of			
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ESP-01

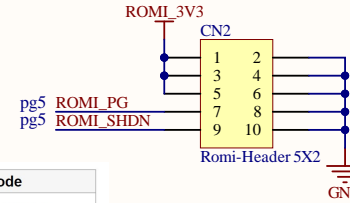


URXD: connect to TX of microcontroller
UTXD: connect to RX of microcontroller
GPIO0: connect to RESET of microcontroller
GPIO2: optionally connect green LED to 3.3V (indicates wifi status)

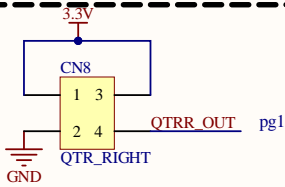
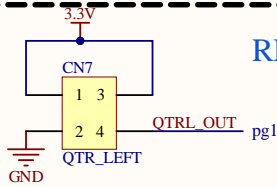


DIR	PWM	SLEEP	Motor +	Motor -	operating mode
0	PWM	1	PWM	L	forward/brake at speed <i>PWM</i> %
1	PWM	1	L	PWM	reverse/brake at speed <i>PWM</i> %
X	0	1	L	L	brake low (outputs shorted to ground)
X	X	0	Z	Z	coast (outputs floating/disconnected)

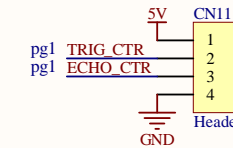
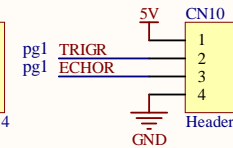
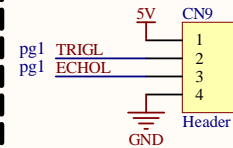
ROMI CONNECTOR



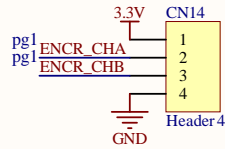
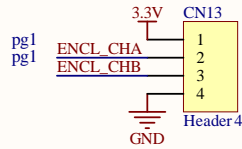
REFLECTOR



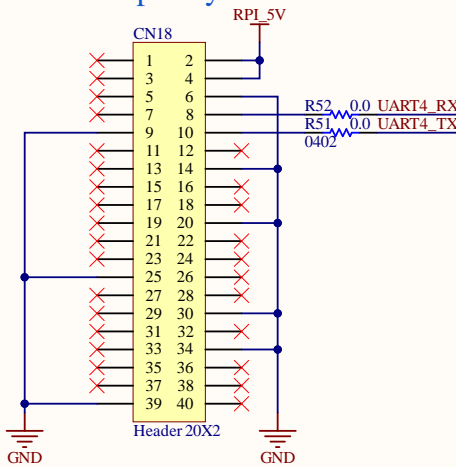
SONAR



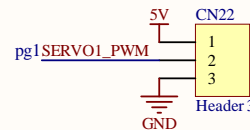
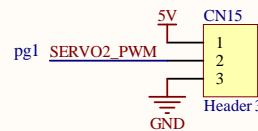
ENCODERS



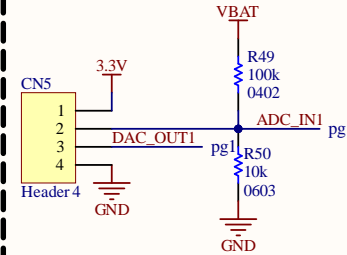
Raspberry Pi



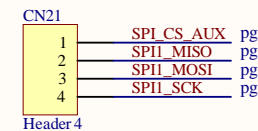
SERVOS



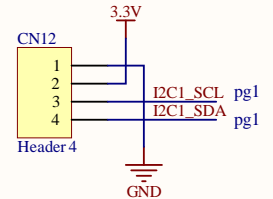
ADC/DAC



SPI1



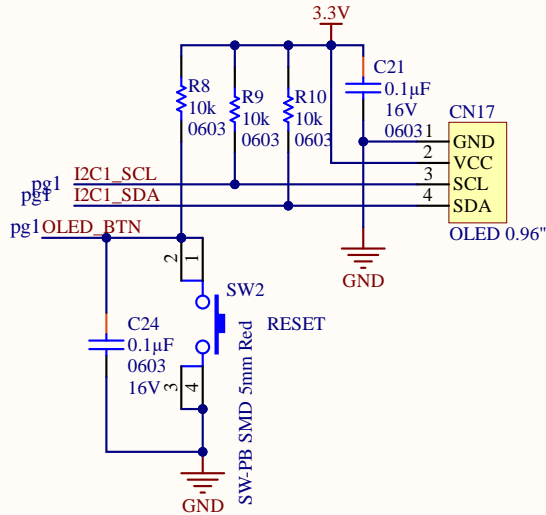
I2C1



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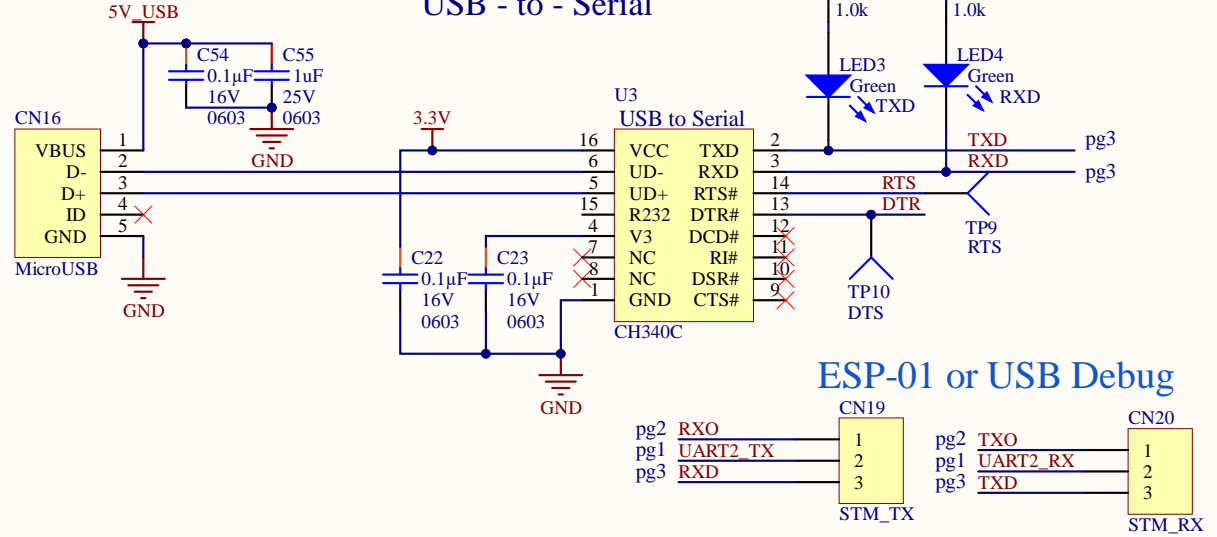


OLED Screen

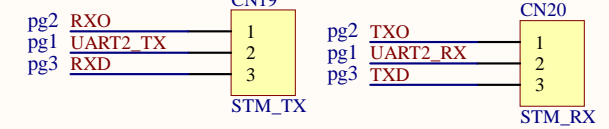


USB PCB Spec

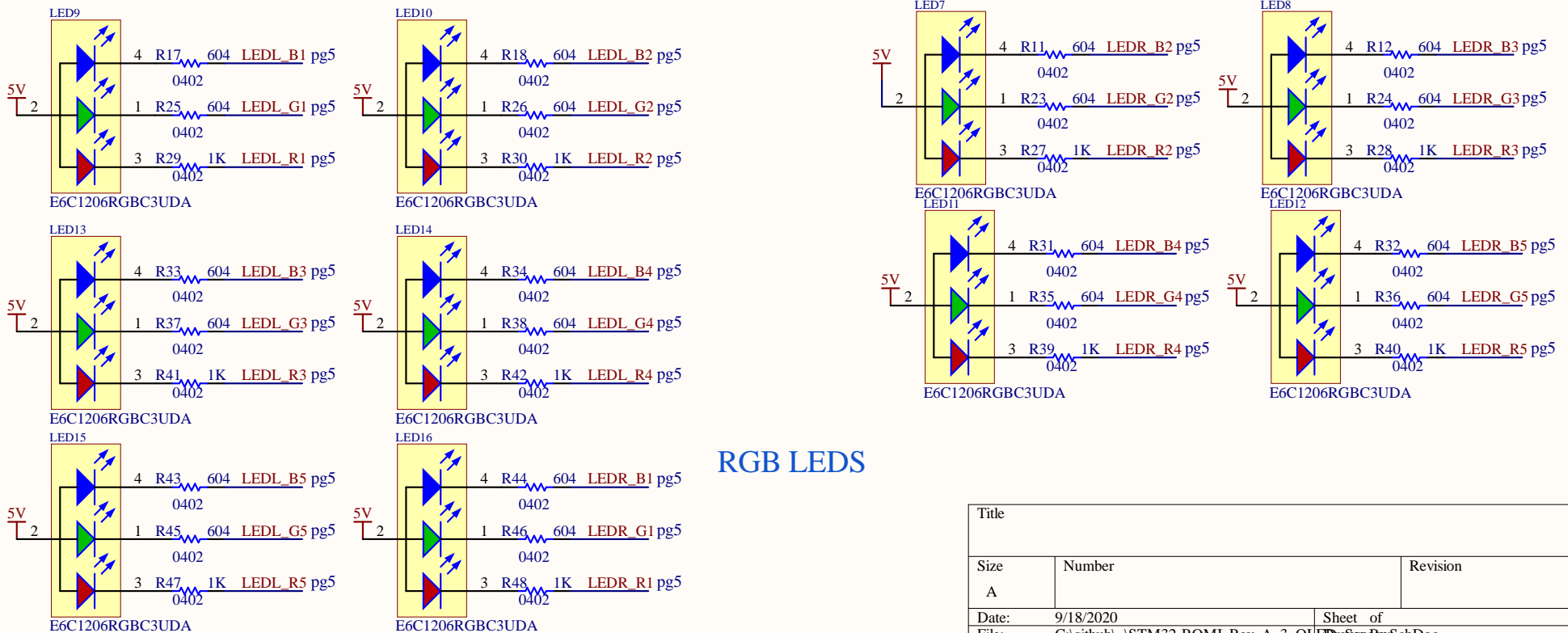
USB - to - Serial



ESP-01 or USB Debug




RGB LEDS



Title		
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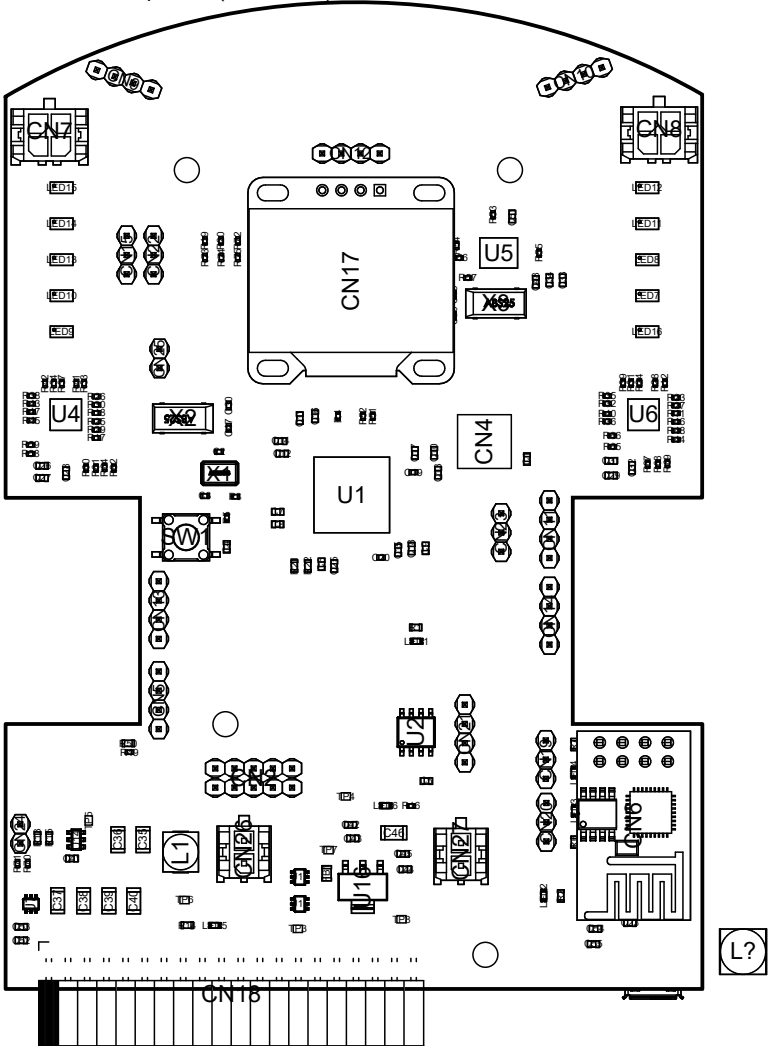
1	2	3	4
A	<div>STM32-ROMI</div> <div>Rework 1 - 3.3uH changed to 4.7uH Rework 2 - 5V buck is wrong version Rework 3 - CN20 silk flipped</div>		
B			
C			
D			
1	2	3	4

Title			Altium Limited L3, 12a Rodborough Rd Frenchs Forest NSW Australia 2086	
Size: A4	Number:	Revision:		
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File: C:\github\STM32-ROMI\Altium\Reworks\STM32-ROMI_Rev_A-Reworks\STM32-ROMI_Rev_A_6_Reworks.SchDoc				

1

1

View from Top side (Scale 1:1)



2

2

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		FRACTIONAL±	ENG APPR.						
		ANGULAR: MACH± BEND ±	MFG APPR.						
		TWO PLACE DECIMAL ±							
		THREE PLACE DECIMAL ±							
		INTERPRET GEOMETRIC TOLERANCING PER:	Q.A.			COMMENTS:			
		MATERIAL							
		FINISH							
NEXT ASSY	USED ON	DO NOT SCALE DRAWING				SIZE	DWG. NO.		
APPLICATION						SCALE: 1:1	WEIGHT:	SHEET 1 OF 3	

A

B

C

D

Layer Stack Legend

	Material	Layer	Thickness	Dielectric Material	Type	Gerber
		Top Overlay			Legend	GTO
	Surface Material	Top Mask	0.02mm	Solder Resist	Solder Mask	GTS
	Copper	Top Copper	0.04mm		Signal	GTL
	Prepreg		0.10mm	2313	Dielectric	
	Copper	GND1	0.02mm		Signal	G1
	Core		1.26mm	FR-4	Dielectric	
	Copper	Power1	0.02mm		Signal	G2
	Prepreg		0.10mm	2313	Dielectric	
	Copper	Bottom Copper	0.04mm		Signal	GBL
	Surface Material	Bottom Mask	0.02mm	Solder Resist	Solder Mask	GBS
		Bottom Overlay			Legend	GBO
Total thickness: 1.60mm						

1

1

2

2

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		TWO PLACE DECIMAL ±										
		THREE PLACE DECIMAL ±										
		INTERPRET GEOMETRIC TOLERANCING PER:	Q.A.									
			COMMENTS:									
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APPLICATION		DO NOT SCALE DRAWING										

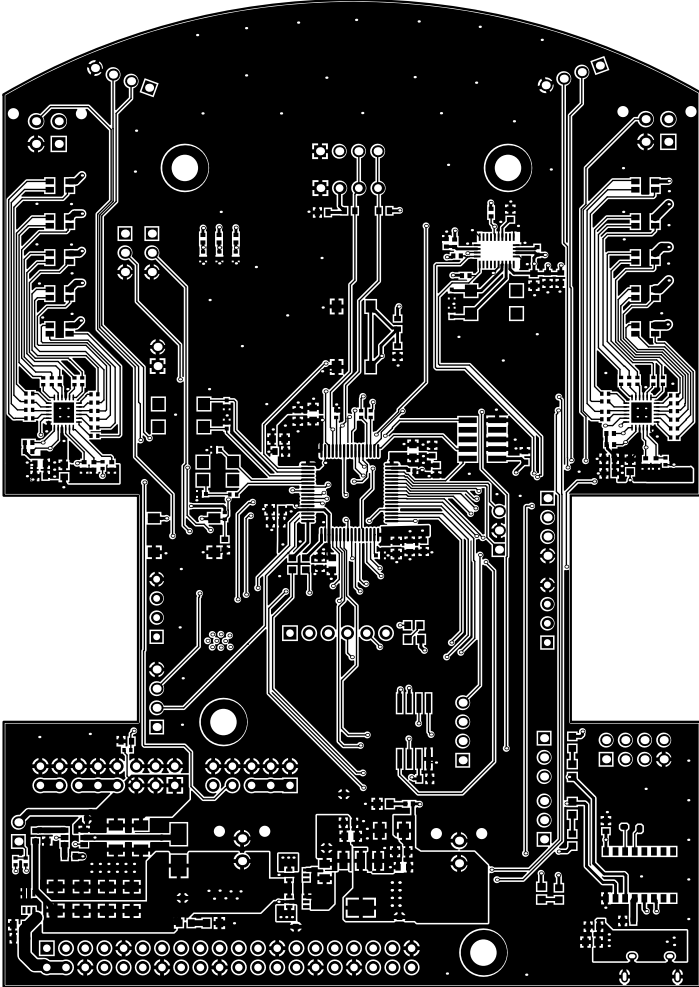
A

B

C

D

Top Copper (Scale: 1:1)



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		THREE PLACE DECIMAL ±				COMMENTS:			
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NEXT ASSY	USED ON	FINISH							
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