

Project proposal

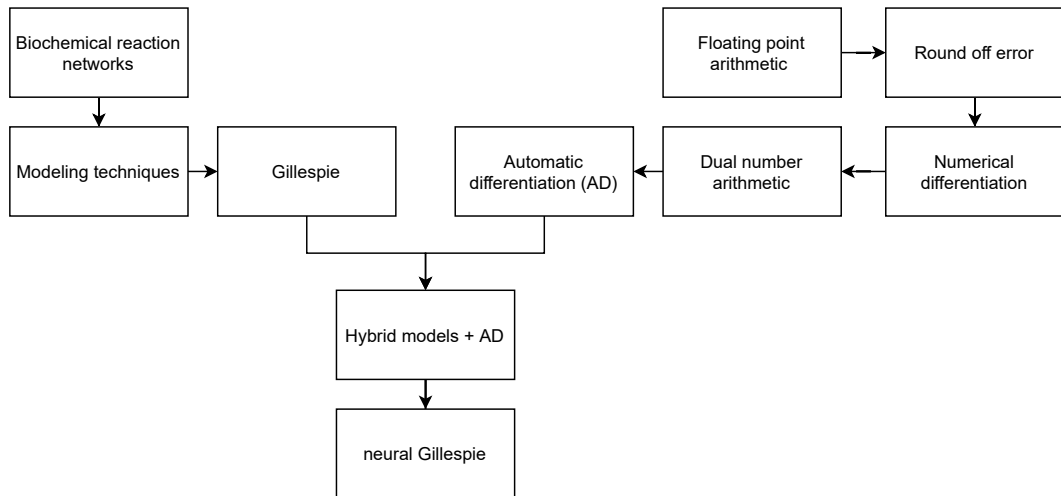
Accelerating Biochemical reaction models: A neural Gillespie Algorithm

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15th of August, 2021

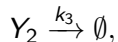
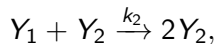
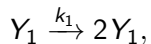


Talk overview

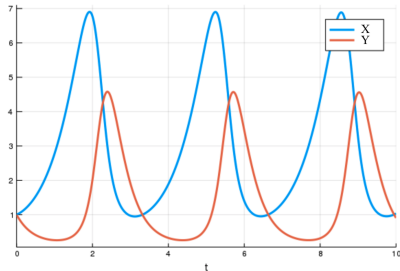


Modeling biochemical reaction networks

Example: Lotka -Volterra model



where Y_1, Y_2 are species and k_1, k_2, k_3 are rate constants.



Mass-action kinetics

- Use them to formulate **rates** based on the reactions and rate constants.
- These laws hold **only** under certain physical assumptions, such as "large molecule numbers for all species".¹

Example: Second reaction of LV model:

- ▶ Reaction: $Y_1 + Y_2 \xrightarrow{k_2} 2Y_2$
- ▶ Rate based on mass action kinetics: $k_2[Y_1][Y_2]$

Deterministic, continuous case:

- ▶ We are not counting molecules but species are measured as e.g. moles/liter.
- ▶ Using mass-action kinetics, we can get ODE models.
- ▶ This *can* be good starting point as approximation even if we know the true process is discrete and stochastic.

¹Details in e.g. D Schnoerr, G Sanguinetti, R Grima , "Approximation and inference methods for stochastic biochemical kinetics", Journal of Physics A: Mathematical and Theoretical, 2017.

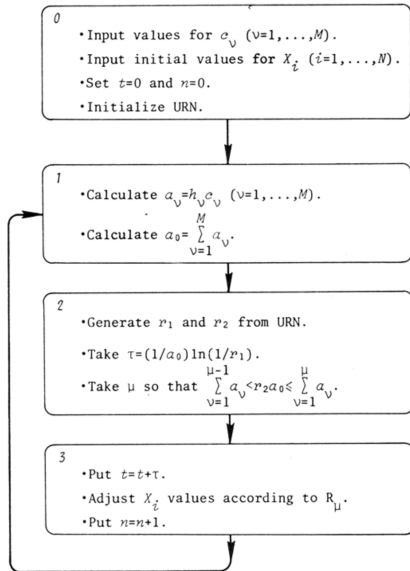
Stochasticity and discrete nature of true process

- ▶ Generally: Impact of stochasticity and discrete nature of the true process too significant to solely rely on "macroscopic" view via deterministic approximation.
- ▶ From molecular perspective: Time evolution of current state of the system is continuous time **Markov process with discrete state space**.
- ▶ Extension to stochastic mass-action kinetics:
→ Construct stochastic rates, based on reactions and rate constants.

Example: Second reaction of LV model:

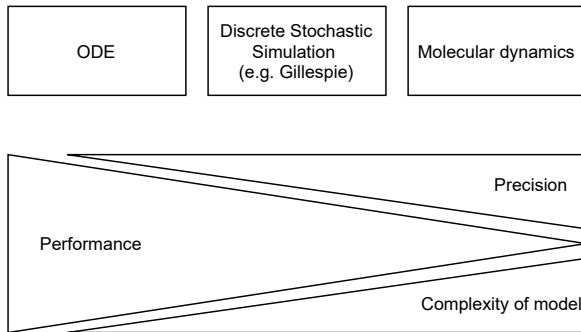
- ▶ Reaction: $Y_1 + Y_2 \xrightarrow{k_2} 2Y_2$
- ▶ Rate based on stochastic mass action kinetics: $k_2 y_1 y_2$

Gillespie algorithm (Gillespie, 1977)



- ▶ Based on reactions and rates
→ Make exact simulation of true process.
- ▶ Most famous way to do this:
→ Gillespie algorithm.
- ▶ A single Gillespie simulation:
→ An **exact** sample from the probability mass function that is the solution of the master equation.

Context and limitations of Gillespie algorithm



- ▶ Models every reaction event → Can be very slow.
- ▶ Biggest limitation: Speed.

Goal of project: Develop a new approach to make Gillespie faster.



How? Using a neural approach.

Differentiating the Gillespie algorithm

Question: What is the derivative with respect to p , where p is in the rate but not in the update function?

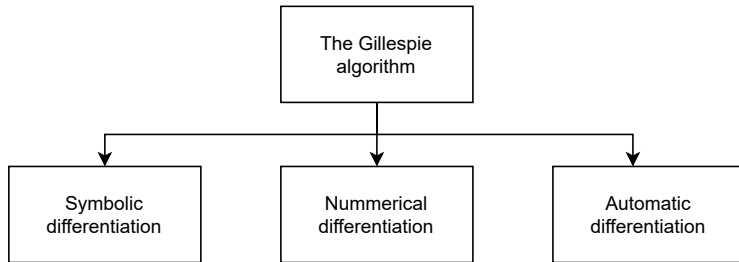
Example: Second reaction of LV model:

- ▶ Reaction: $Y_1 + Y_2 \xrightarrow{k_2} 2Y_2$
- ▶ Rate based on stochastic mass action kinetics: $k_2 y_1 y_2$
- ▶ p could be for example k_2 .

→ So p influences distribution of dt .

Reminder: $\Delta t = \text{rand}(\text{Exp}(\text{sum}(\mathbf{rates})))$

How do we differentiate something like this?



Numerical differentiation

Example:

- ▶ For function $f : \mathbb{R} \rightarrow \mathbb{R}$, the numerical differentiation via **finite differences** is given by,

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

where h represents a small change in x , $x \in \mathbb{R}$.

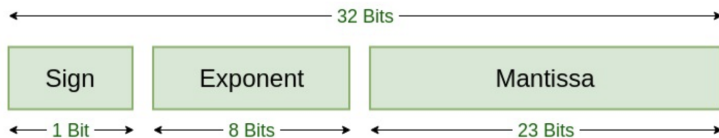
- ▶ Smaller step size $h \rightarrow$ better approximation.

The floating-point arithmetic

Floating-point arithmetic:

Representation of real numbers via floating-point arithmetic as an approximation (In Julia: e.g. Float32):

$$x = -32 * 10^{-5}$$



- Finite number of bits to save the real number x (trade off between range and precision).

Round off error

- ▶ One would assume: For $h \in \mathbb{R}$, it holds that $(1+h)-1=h$.
- ▶ Code example: Fix h and then do $h2 = (1+h)-1$. Question: Is $h==h2$?

```
julia> h = 1e-1rand()  
0.09399514921175445  
  
julia> h2 = (1+h)-1  
0.09399514921175456
```

Make h
smaller

```
julia> h = 1e-10rand()  
9.906183448919843e-11  
  
julia> h2 = (1+h)-1  
9.906186981822884e-11
```

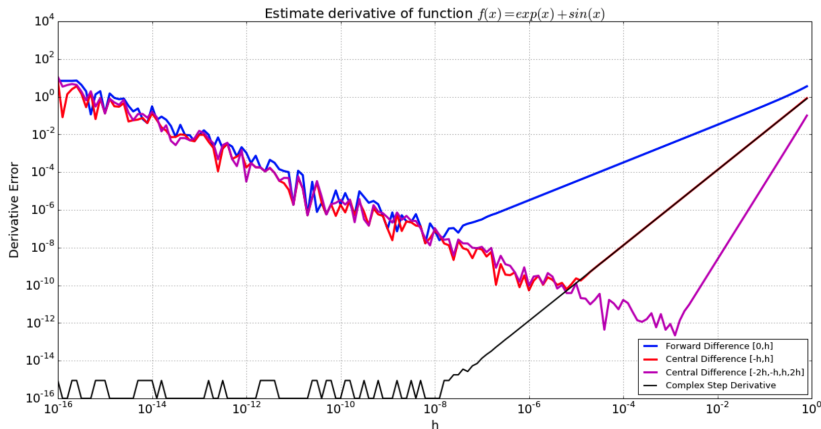


- ▶ Number of lost digits increases as the two numbers become more different.

$$\begin{array}{r} \boxed{5}\boxed{0}\boxed{0}\boxed{0} \\ + \quad \boxed{0}\boxed{0}\boxed{1}\boxed{1} \\ \hline \boxed{5}\boxed{0}\boxed{0}\boxed{1} \end{array} \quad \begin{array}{r} \boxed{5}\boxed{0}\boxed{0}\boxed{0} \\ + \quad \boxed{0}\boxed{0}\boxed{1}\boxed{1} \\ \hline \boxed{5}\boxed{0}\boxed{1}\boxed{1} \end{array}$$

- ▶ Large number + small number (such as a very small h) \rightarrow Large round off error.

Round off error in numerical differentiation



- ▶ Floating point representation + numerical differentiation can be very dangerous.
- ▶ Focus on black line! → Here round off error not there. Why?

Complex step differentiation: Differencing in a different dimension

- ▶ Idea: Let $x \in \mathbb{R}$ and $f : \mathbb{R} \rightarrow \mathbb{R}$ analytic.
→ We want to calculate the *real* derivative wrt x .
- ▶ Taylor series expansion (in complex direction): → Add perturbation h to x , but in complex direction.

$$f(x + ih) = f(x) + f'(x)ih + \mathcal{O}(h^2) \iff if'(x) = \frac{f(x + ih) - f(x)}{h} + \mathcal{O}(h)$$

$$\iff f'(x) = \frac{\text{Im}(f(x + ih))}{h} + \mathcal{O}(h).$$

- ▶ Note h never directly interacts with x as in the **two dimensions of the complex numbers**. → Keeping small perturbation separate from large ones.
- ▶ In code: h and x – as the real and imaginary part of a complex number – are stored in two different floating point representations (e.g. **two** Float64).
- ▶ This method brings us to automatic differentiation: AD extends the idea of complex step differentiation beyond complex analytic functions.

New arithmetic: Dual numbers

```
julia> struct Dual{T}
           val::T    # value
           der::T    # derivative
       end
```

Idea: Derivative measures **sensitivity** of function: How much changes the function output when input changes by small ϵ

$$f(a + \epsilon) = f(a) + \epsilon f'(a) + o(\epsilon).$$

Formally set: $\epsilon^2 = 0$ and function f be will represented by value $f(a)$ and the derivative $f'(a)$, encoded as the coefficients of a degree-1 Taylor polynomial in ϵ :

$$\rightsquigarrow f(a + \epsilon) = f(a) + \epsilon f'(a).$$

→ Set rules for functions on dual numbers².

²John L. Bell, "A Primer of Infinitesimal Analysis", Cambridge University Press, 2008.

Functions of dual objects

Given

$$f(a + \epsilon) = f(a) + \epsilon f'(a)$$

and

$$g(a + \epsilon) = g(a) + \epsilon g'(a)$$

we manipulate the Taylor expansions to combine the functions.

Sum rule:

$$(f + g) = [f(a) + g(a)] + \epsilon[f'(a) + g'(a)]$$

Product rule:

```
julia> # Product Rule
Base.*(f::Dual, g::Dual) = Dual(f.val*g.val, f.der*g.val + f.val*g.der)
```

→ Infer derivatives by taking the component of ϵ .

Example differentiation

- Based on arithmetic of dual numbers, we can differentiate an arbitrary function h .
- We present $a + \epsilon$ as `Dual(a,1)` which gives `Dual(h(a),h'(a))` when applying h to it.

```
julia> h(x) = x^2 + 2
h (generic function with 1 method)

julia> a = 3
3

julia> xx = Dual(a, 1)
Dual{Int64}(3, 1)

julia> h(xx)
Dual{Int64}(11, 6)
```

Test: $h(a) = 11$, $h'(a) = 2a = 6 \rightarrow$ Correct.

Extension: Higher dimensional functions

- ▶ Differentiating functions where $gg : \mathbb{R}^n \rightarrow \mathbb{R}$ such as $gg(x, y) = x^2 * y + x + y$
- ▶ In AD, we add n independent partial derivative components to dual numbers:

Multidimensional dual number in julia:

```
julia> struct MultiDual{N,T}
           val::T
           derivs::SVector{N,T}
       end
```

Defining primitive functions on them (via multiple dispatch):

```
julia> function +(f::MultiDual{N,T}, g::MultiDual{N,T}) where {N,T}
           return MultiDual{N,T}(f.val + g.val, f.derivs + g.derivs)
       end
+ (generic function with 203 methods)
```

AD on higher dimensional functions

$$gg(x, y) = x^2 * y + x + y.$$

Example: $(x, y) = (a, b)$ where $a = 1, b = 2$.

- ▶ $gg(x, 2) = x^2 * 2 + x + 2 \iff gg(x, 2) = 2x^2 + x \xrightarrow{\text{diff}_x} gg'(x) = 4x + 1$
- ▶ $gg(1, y) = 1^2 * y + 1 + y \iff gg(1, y) = 2y + 1 \xrightarrow{\text{diff}_y} gg'(x) = 2$

```
julia> gg(x, y) = x*x*y + x + y
gg (generic function with 1 method)

julia> (a, b) = (1.0, 2.0)
(1.0, 2.0)

julia> xx = MultiDual(a, SVector{1.0, 0.0})
MultiDual{2, Float64}(1.0, [1.0, 0.0])

julia> yy = MultiDual(b, SVector{0.0, 1.0})
MultiDual{2, Float64}(2.0, [0.0, 1.0])

julia> gg(xx, yy)
MultiDual{2, Float64}(5.0, [5.0, 2.0])
```

Test: $gg(1, 2) = 2 + 1 + 2 = 5$, $gg'(1, 2) = (4x + 1, 2) = (5, 2) \rightarrow$ Correct.

Differentiating functions with multiple outputs

- ▶ Differentiating functions where $ff : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such as $ff(x, y) = (x * x + y * y, x + y)$.
- ▶ In AD, we add calculate the $m \times n$ matrix of partial derivative components (e.i the Jacobian):

```
julia> ff(x, y) = SVector(x*x + y*y , x + y)
ff (generic function with 1 method)

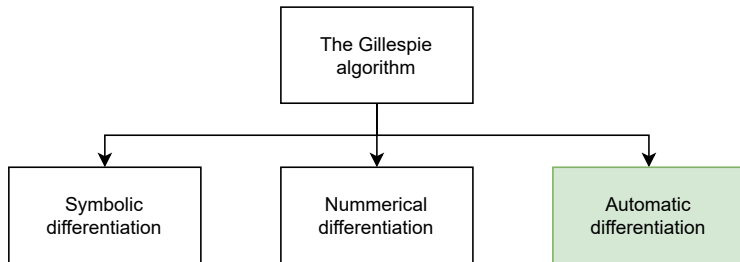
julia> ff(xx, yy)
2-element SVector{2, MultiDual{2, Float64}} with indices SOneTo(2):
MultiDual{2, Float64}(5.0, [2.0, 4.0])
MultiDual{2, Float64}(3.0, [1.0, 1.0])
```

In red: Value and partial derivatives.

Summary: Dual numbers and AD + Back to Gillespie

Question: What is the derivative of the Gillespie algorithm with respect to p , where p is in the rate but not in the update function?

Answer: AD takes a program \rightarrow recompiles it in this different arithmetic of dual number \rightarrow Accurate and fast calculation of directional derivatives.



Problematic with AD and Gillespie

- ▶ Δt is a constant.
- ▶ not dual \rightarrow derivative part of dual is zero.

\rightarrow this breaks the whole differentiation chain.

```
julia> h(x) = x^2 + 2
h (generic function with 1 method)

julia> h(3)
11

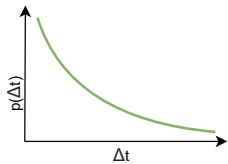
julia> xx=Dual(a,1)
Dual{Int64}(3, 1)

julia> h(xx)
Dual{Int64}(11, 6)

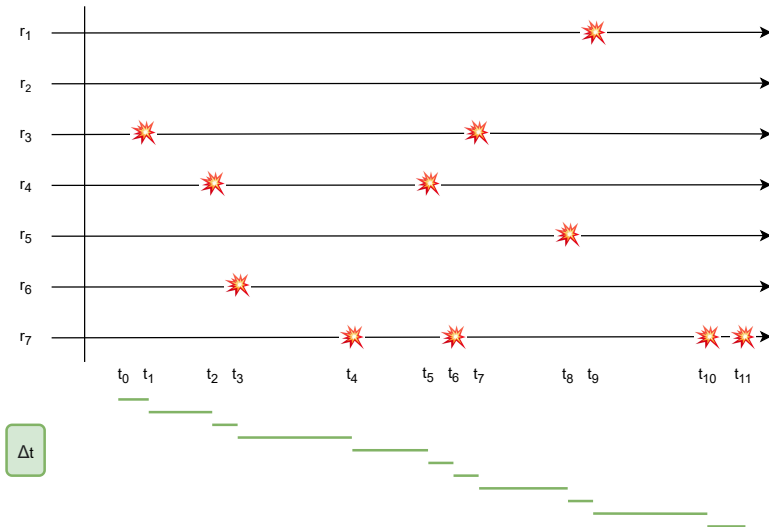
julia> xxx=Dual(a,0)
Dual{Int64}(3, 0)

julia> h(xxx)
Dual{Int64}(11, 0)
```

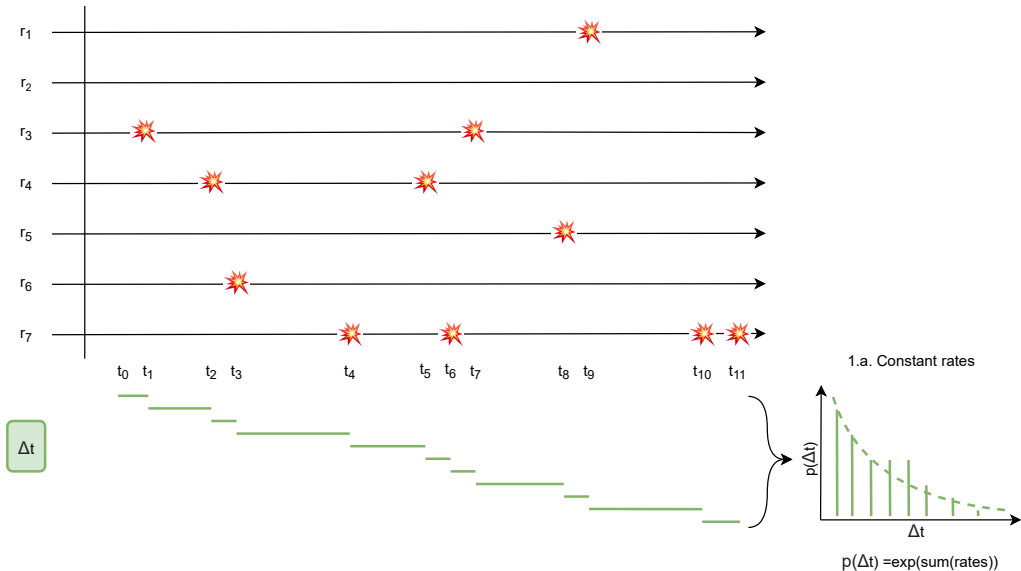
1. Gillespie: SSA



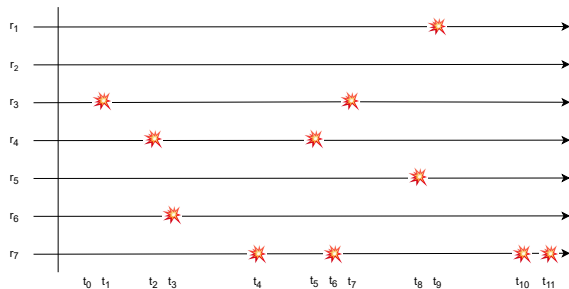
$$p(\Delta t) = \exp(-\sum(\text{rates}))$$



1. Gillespie: SSA

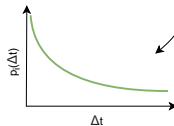


1. Gillespie: SSA

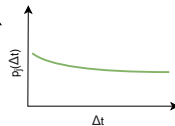


Δt

1.b. Non-constant rates

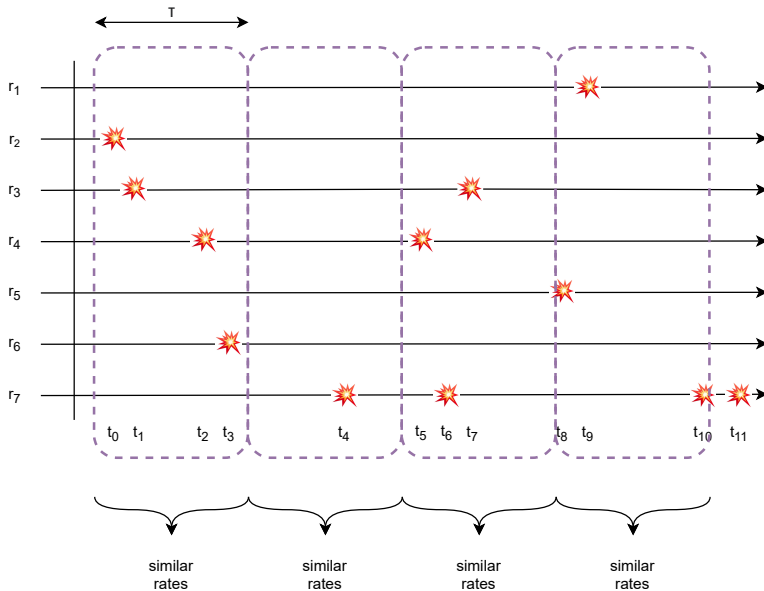


$$p_i(\Delta t) = \exp(\text{sum}(\text{rates}_i))$$



$$p_j(\Delta t) = \exp(\text{sum}(\text{rates}_j))$$

2. T- leaping



τ -leaping method: Approximating the SSA to be faster.

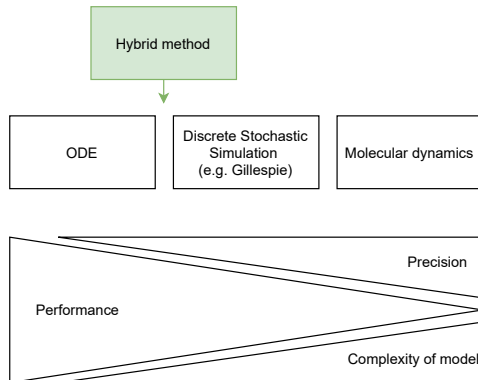
Leap Condition: Require τ to be small enough that the change in the state during $[t, t + \tau]$ will be so slight that no propensity function will suffer an appreciable (i.e., macroscopically noninfinitesimal) change in its value.

τ -leaping method: Select largest τ that fulfils the Leap Condition.

τ -leaping method

- ▶ Helpful for speeding up the SSA.
- ▶ Popular option for speeding up the SSA.
- ▶ But: I don't see how it is helpful for the differentiation problem we want to solve.
- ▶ We want to use a neural approach to speed up Gillespie, we are looking at other methods to find something that helps us with the differentiation problem, not speed up directly.

Hybrid methods



- ▶ Also method to speed up SSA.
- ▶ Slow reactions with species that occur in small numbers → SSA.
- ▶ Reactions where all species in large numbers → Reaction rate equations (ODEs).

Hybrid methods

- ▶ Linda Petzold: "We thought it's great, then we tried on our real problem and it failed." ³
- ▶ Postulated reason: Cannot efficiently handle fast reactions involving species present in small numbers.
- ▶ Their published solution: Slow scale SSA (ssSSA) ⁴
→ Stochastic partial equilibrium approximation for the not addressed ones.
- ▶ But: Hybrid models are differentiable!

³Talk by Petzold: "Discrete stochastic simulation of spatially inhomogeneous biochemical systems", published 10 Nov 2012:
https://www.youtube.com/watch?v=vvE4U7o51cU&ab_channel=MathsStatsUNSW

⁴Cao, Petzold, Gillespie, "The slow-scale stochastic simulation algorithm", THE JOURNAL OF CHEMICAL PHYSICS, 2004.

Hybrid models

- ▶ In Julia, implemented as `VariableRateJumps` combinable with normal ODEs and **differentiable**.
- ▶ Use ODE formulation to derive sensitivity for strong solution $u(t)$ wrt. p for set of random numbers.
- ▶ Sequential algorithm \rightarrow we propagate through the sequence of events \rightarrow we get sensitivity for each event \rightarrow brings us back to discrete space.
- ▶ Average sensitivities to get the gradient.
- ▶ TO DO: Show that exchange of derivatives i.e. expected value of derivative is equal to the derivative of the expected value.

Project overview and proposal

