

School of Geography and Earth Sciences
McMaster University

Advanced Topics in Spatial Statistics

**Area Data
V & VI**

This session

- Modeling area data
 - Non-spatial regression models
- Assumptions
 - Non-constant variance
 - Data transformations
 - Error autocorrelation
 - Moran's I
 - Normality

Example

- Voter turnout

- What explains voter turnout in elections?

- What do we know about the data?

- Variables follow a spatial pattern (Spatial autocorrelation)
 - Variables are probably correlated

Example

- Voter turnout: Variables
 - VOTE
 - Voting age population (POP)
 - Population with grade 12 or higher education (EDU)
 - Number of owner occupied houses (HOUSE)
 - Aggregate income (INCOME)
- Unit of analysis: county

Example

- Do we have prior expectations about the direction of the relationships?

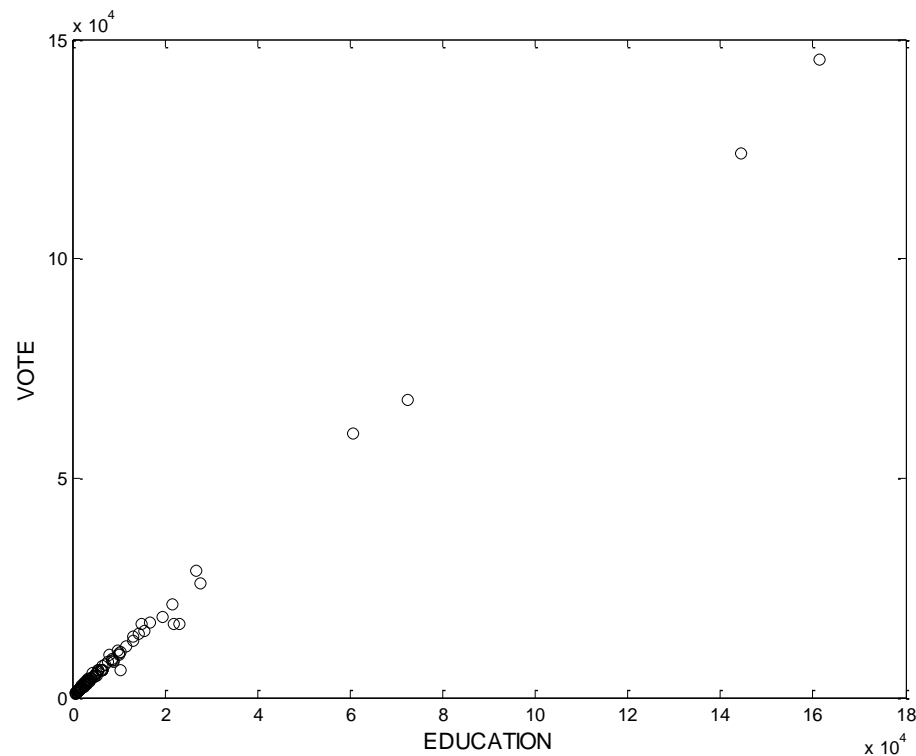
Example

- Bivariate analysis
 - Scatterplots
 - Correlation coefficients



Example

- Scatterplot (EDU vs. VOTE)



Example

- Bivariate analysis
 - Correlation coefficients

	VOTE	POP	EDU	HOUSE	INCOME
VOTE	1.00				
POP	0.993	1.00			
EDU	0.998	0.990	1.00		
HOUSE	0.997	0.994	0.994	1.00	
INCOME	0.994	0.983	0.998	0.989	1.00

Example

- Modeling area data
 - Non-spatial regression
 - Variables can be spatial
 - Variables may be autocorrelated
 - Assumes that there is no spatial autocorrelation
 - Multiple regression

$$\mathbf{Y} = \mathbf{X}\mathbf{b} + \mathbf{e}$$

Modeling Area Data

- Try different models
- Model evaluation guidelines

Modeling Area Data

○ Model 1

Model 1 (VOTE)

Variable	PARAMETER	t-value
CONST	695.21	5.23
EDU	0.89	163.61

$R^2 =$ 0.996

$R^2(\text{adj}) =$ 0.977

$\text{SIGMA}^2 =$ 1560013.858

$\text{SIGMA}^2 (\text{ML}) =$ 1530299.308

$\text{SIGMA} =$ 1249.005

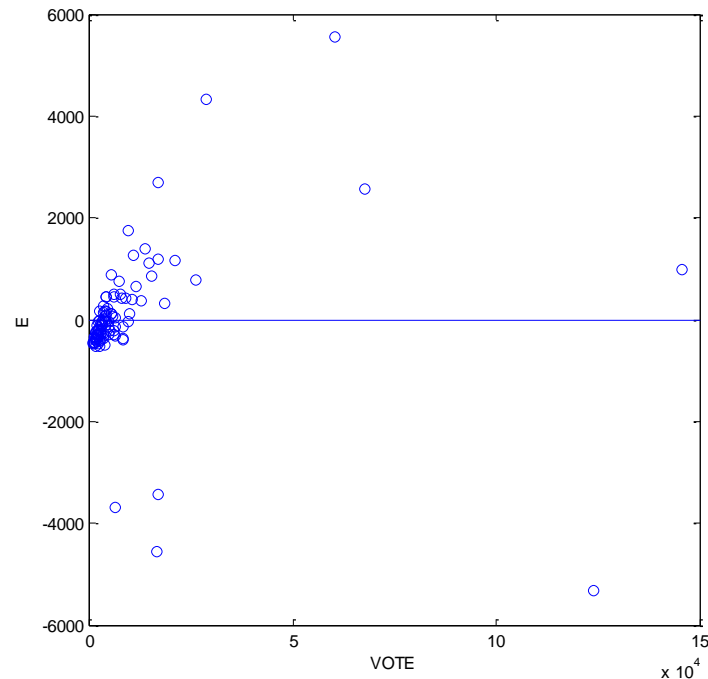
$n =$ 105

<< Normalized Moran's I >>

$Z(I) =$ -2.821

Analysis of Residuals

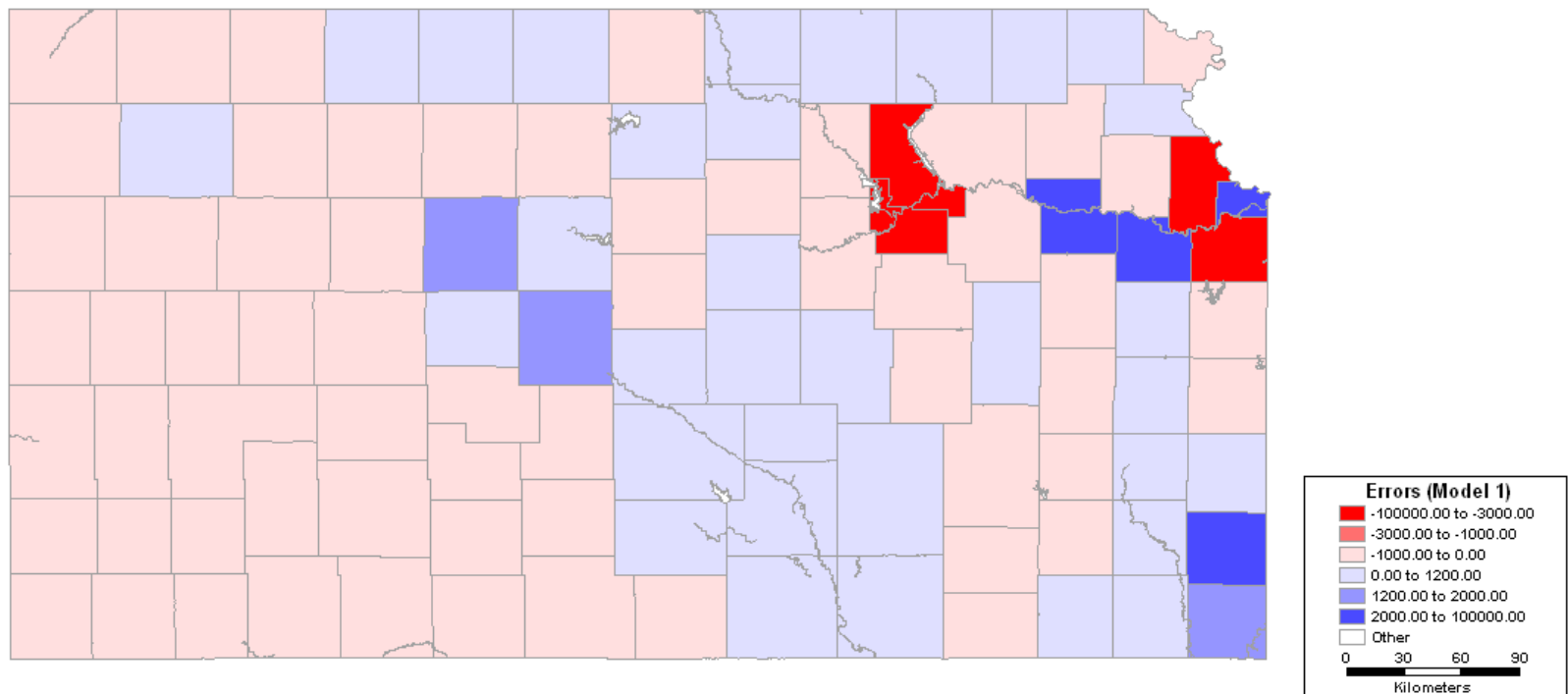
- Is variance constant?
 - Scatterplot of errors vs. variables



Analysis of Residuals

○ Are errors independent?

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Analysis of Residuals

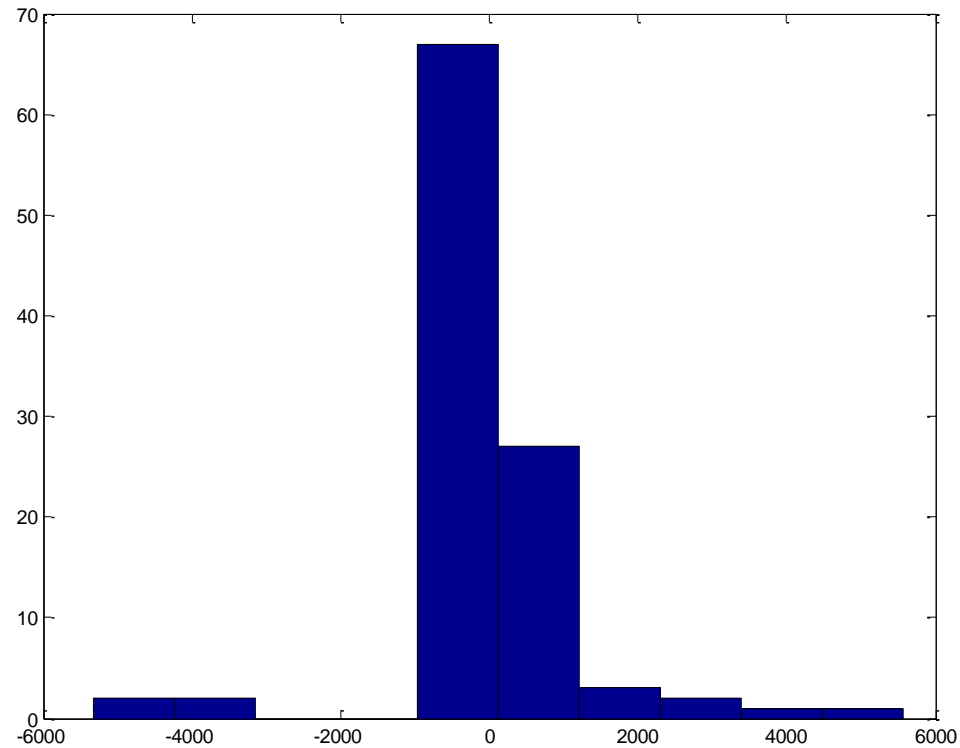
- Are errors independent?
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 - Expected (mean) value of e is zero

Analysis of Residuals

- Are errors normally distributed?
 - Histogram
 - Probability plot
 - Other tests (Jarque-Bera, Kolmogorov-Smirnov, Lilliefors)

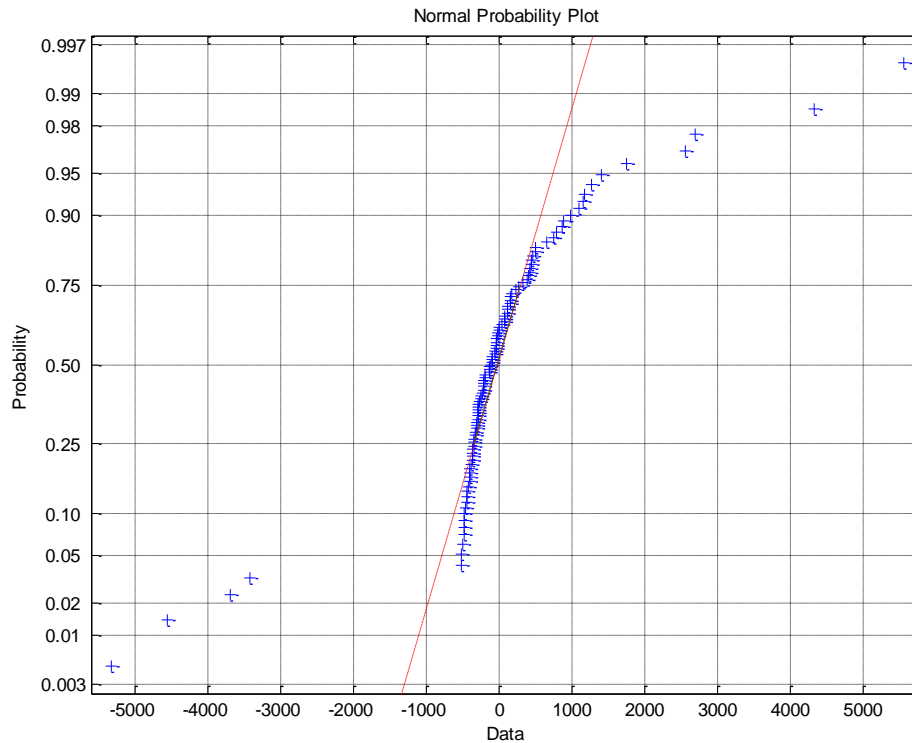
Analysis of Residuals

○ Histogram



Analysis of Residuals

- Probability plot



Modeling Area Data

- What is the conclusion regarding this model?

Modeling Area Data

- Data transformations
 - May help to reduce size effects
 - May increase the interpretability of the models

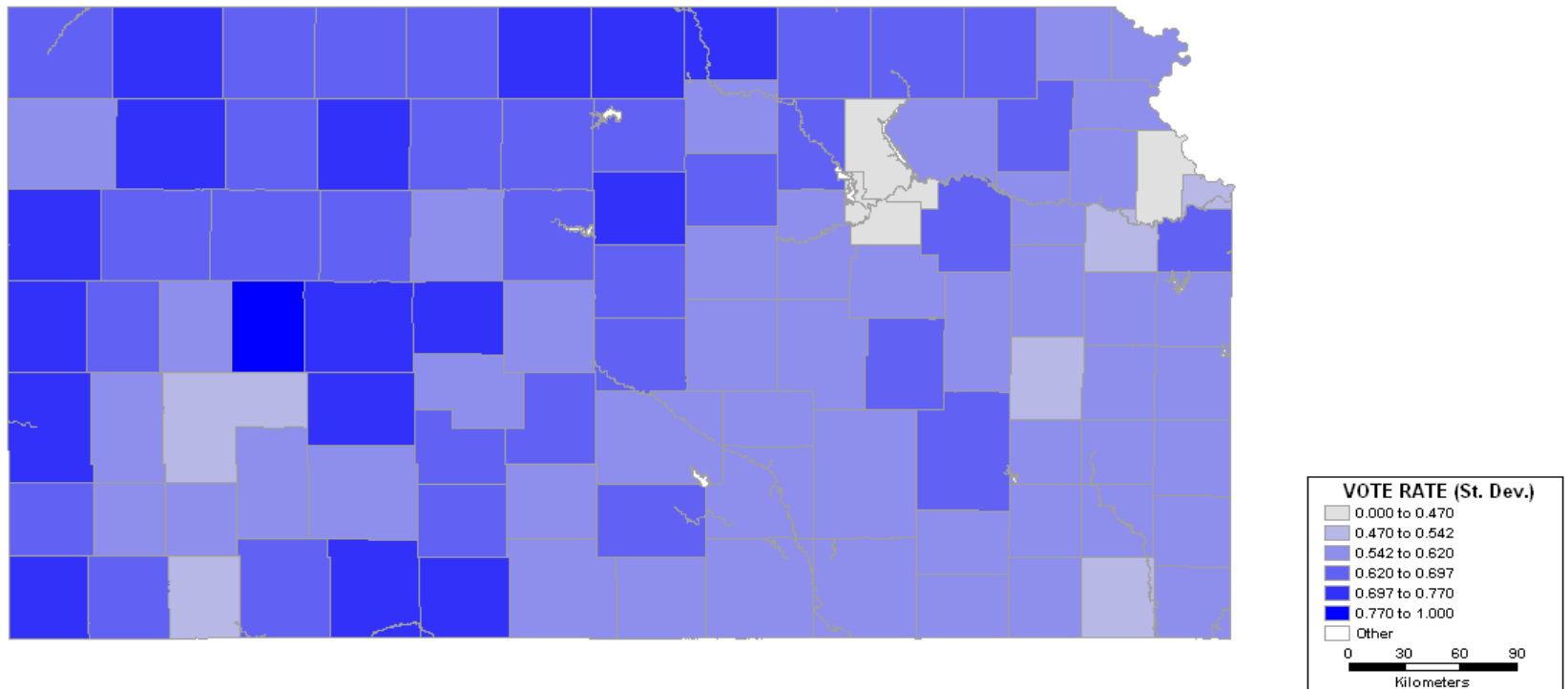
Modeling Area Data

- Data transformations
 - Instead of modeling totals, model the proportions
 - Proportional voter turnout: $VOTE/POP$

Exploring the Proportions

○ Choropleth map: PrVotes (Std. Dev.)

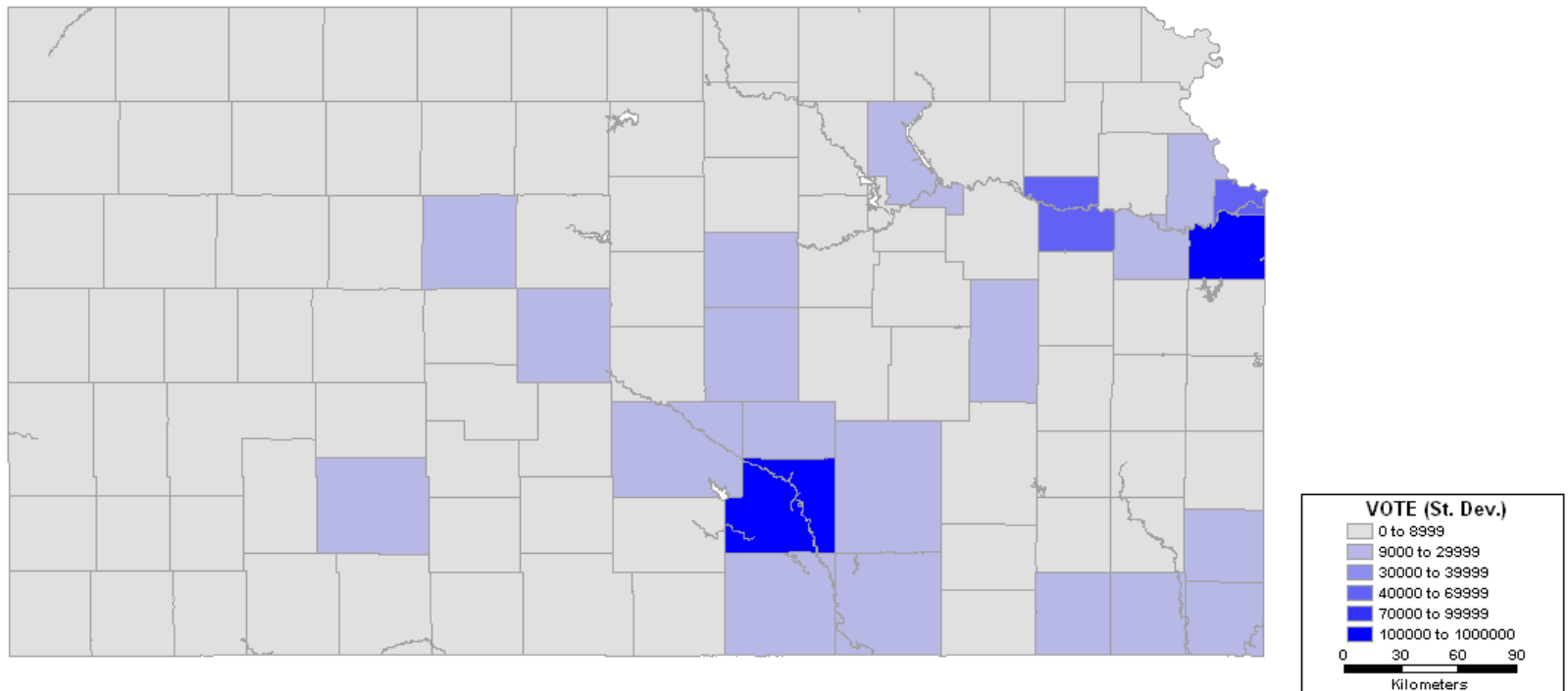
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Exploring the Proportions

○ Choropleth map: Votes (Std. Dev.)

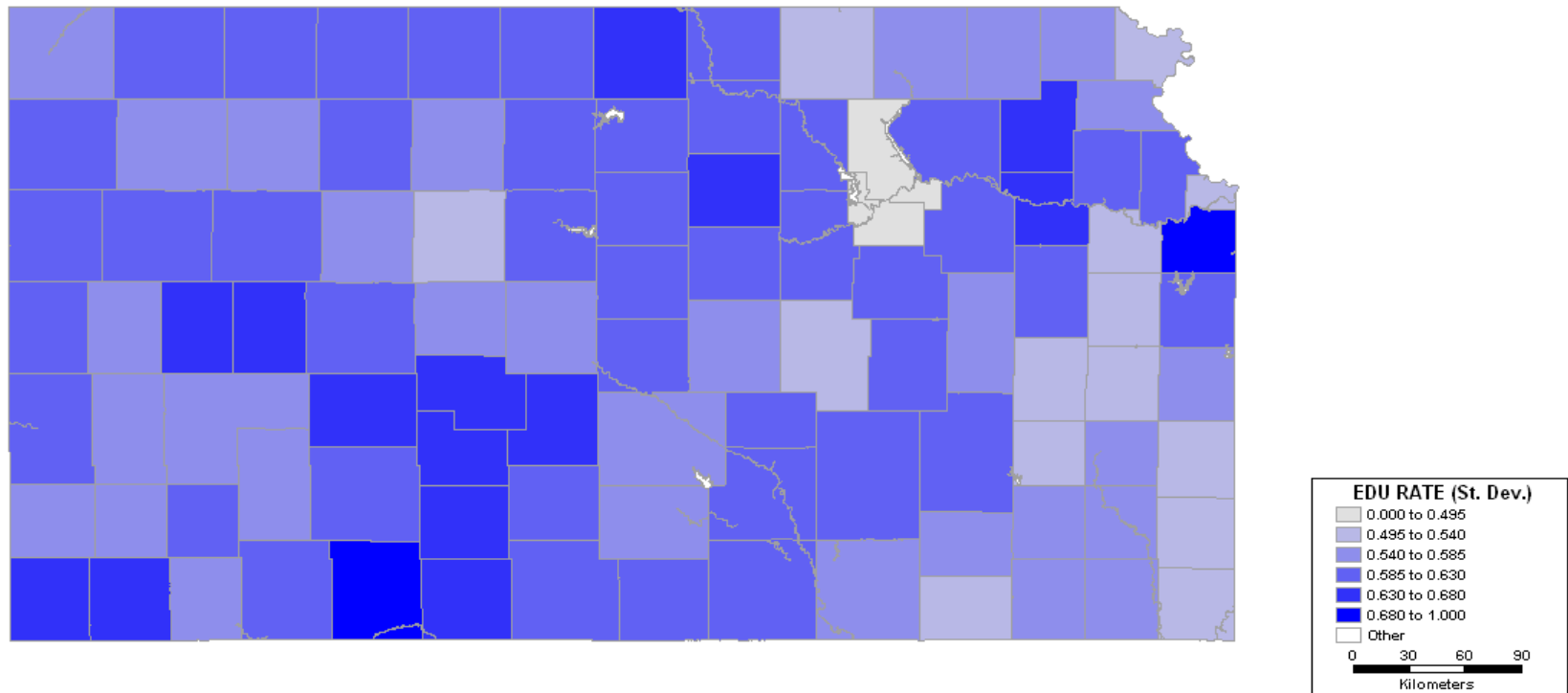
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Exploring the Proportions

○ PrEDU (Std. Dev.)

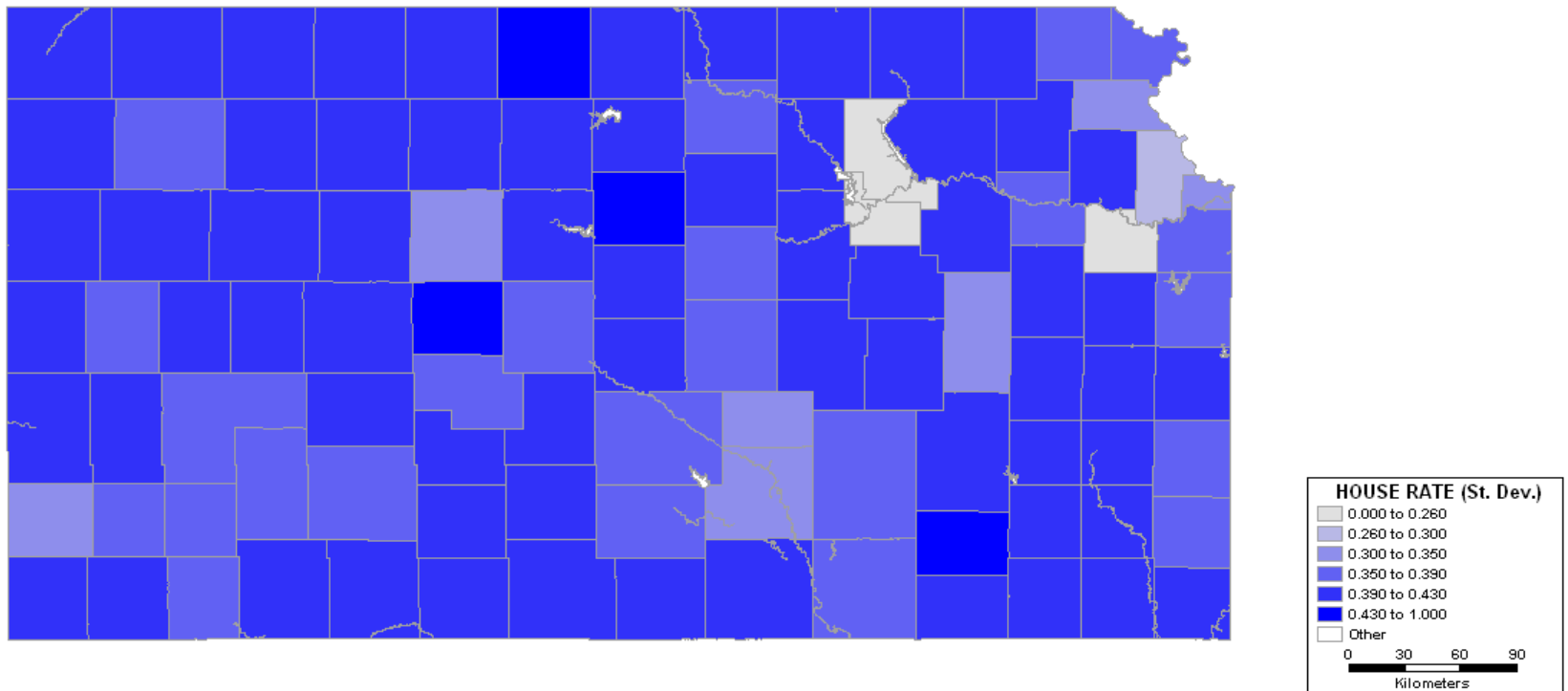
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Exploring the Proportions

○ PrHOUSE (Std. Dev.)

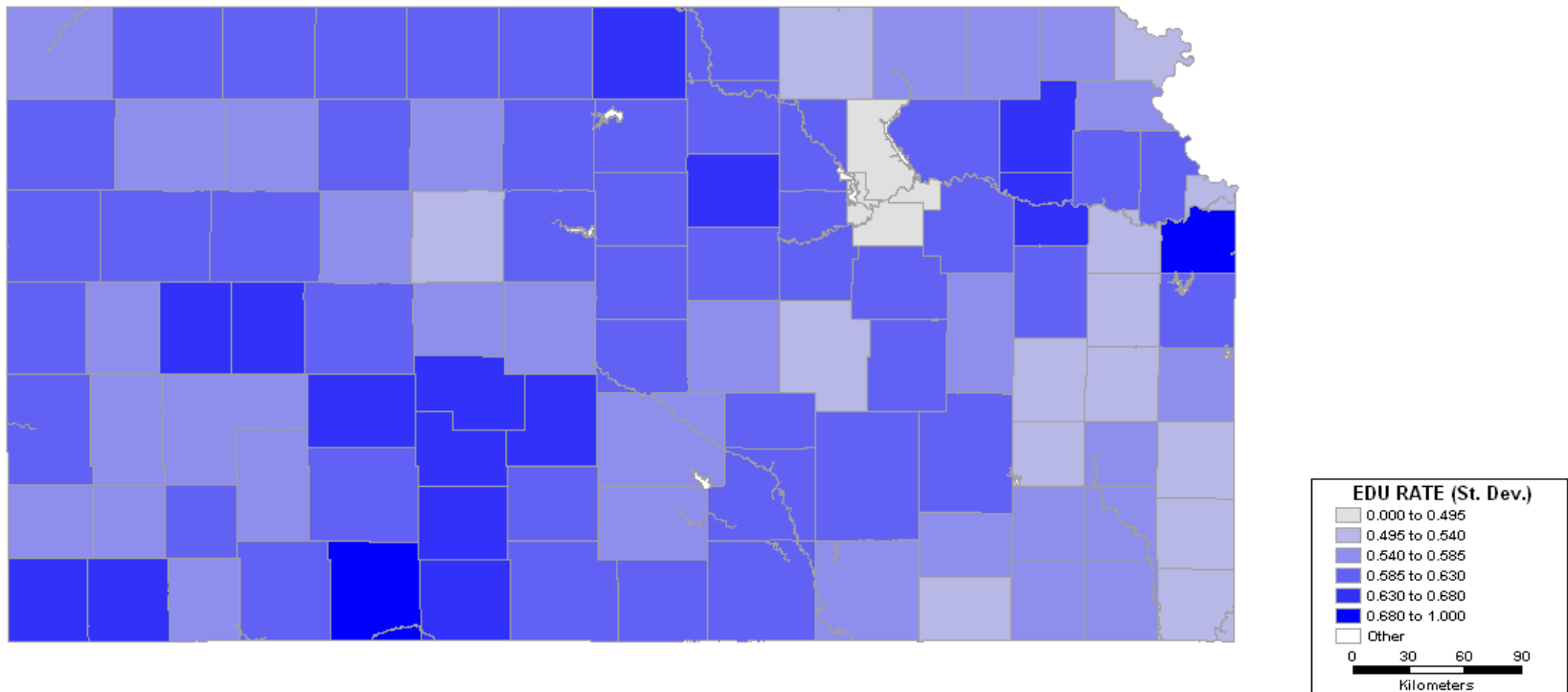
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Exploring the Proportions

○ PrINCOME (Std. Dev.)

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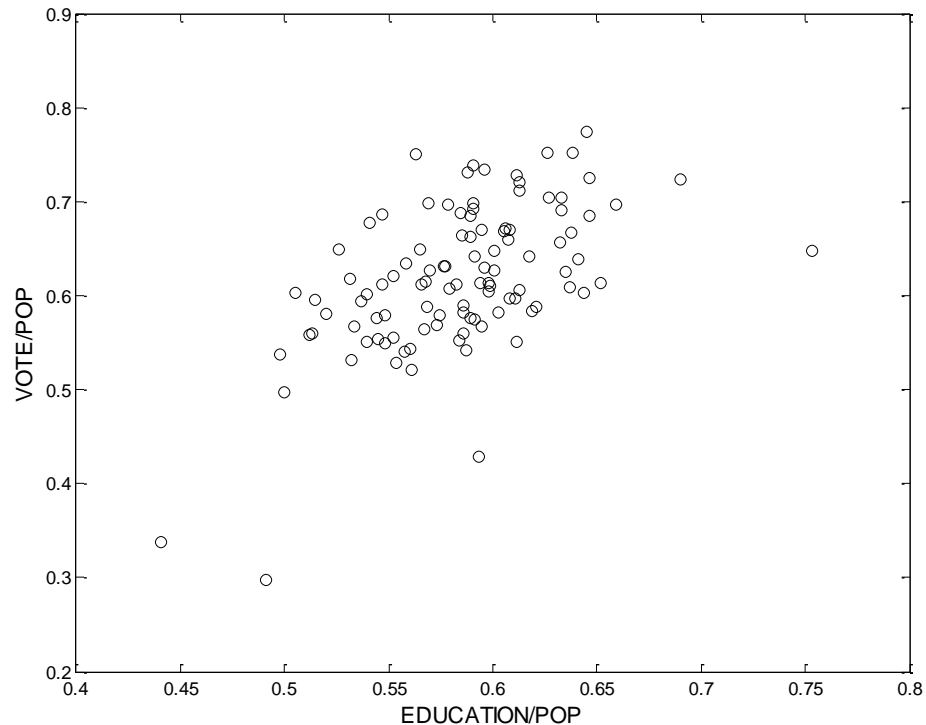
Example

- Bivariate analysis
 - Scatterplots
 - Correlation coefficients



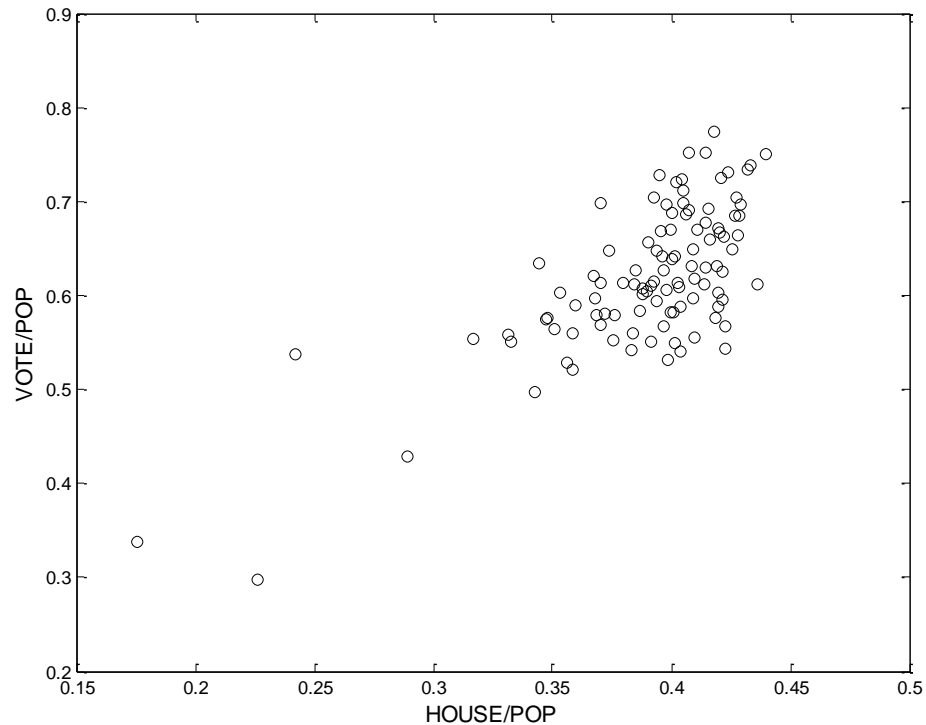
Example

- Scatterplot (EDU/POP vs. VOTE/POP)



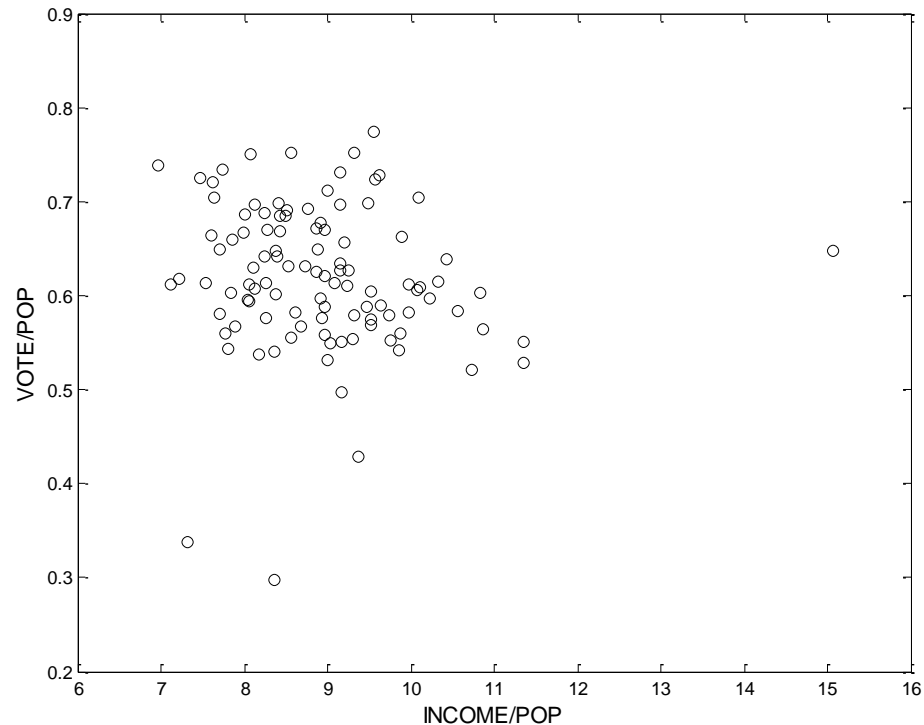
Example

- Scatterplot (HOUSE/POP vs. VOTE/POP)



Example

- Scatterplot (INCOME/POP vs. VOTE/POP)



Example

- Bivariate analysis
 - Correlation coefficients

	VOTE/POP	EDU/POP	HOUSE/POP	INCOME/POP
VOTE/POP	1.00			
EDU/ POP	0.563	1.00		
HOUSE/POP	0.718	0.392	1.00	
INCOME/POP	-0.111	0.426	-0.191	1.00

Example

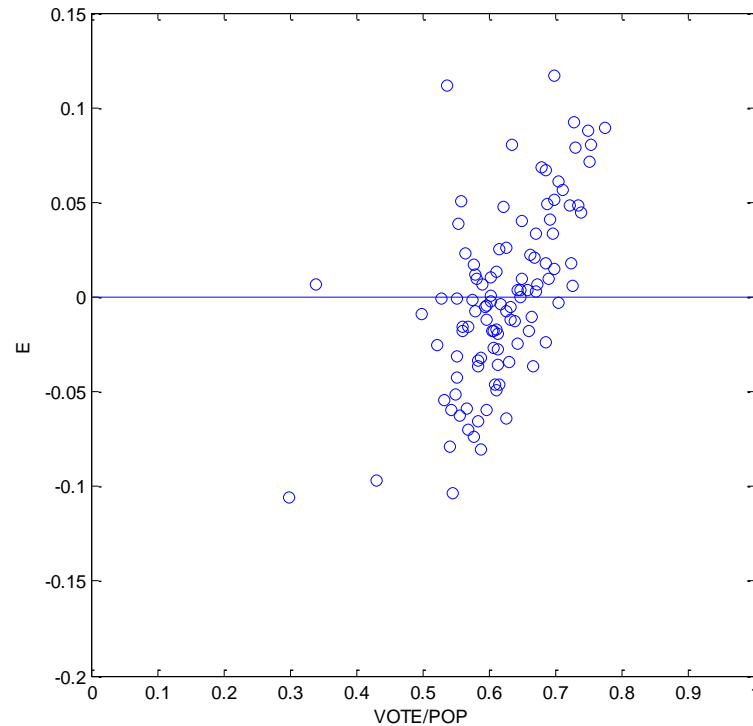
○ Model 2

Model 2 (VOTE/POP)

Variable	PARAMETER	t-value
CONST	-0.071	-1.04
EDU/POP	0.782	5.76
HOUSE/POP	0.934	6.83
INCOME/POP	-0.015	-2.85
<hr/>		
R ² =	0.636	
R ² (adj)=	0.611	
SIGMA =	0.047	
n=	105	
<< Normalized Moran's I >>		
Z (I) =	4.023	

Analysis of Residuals

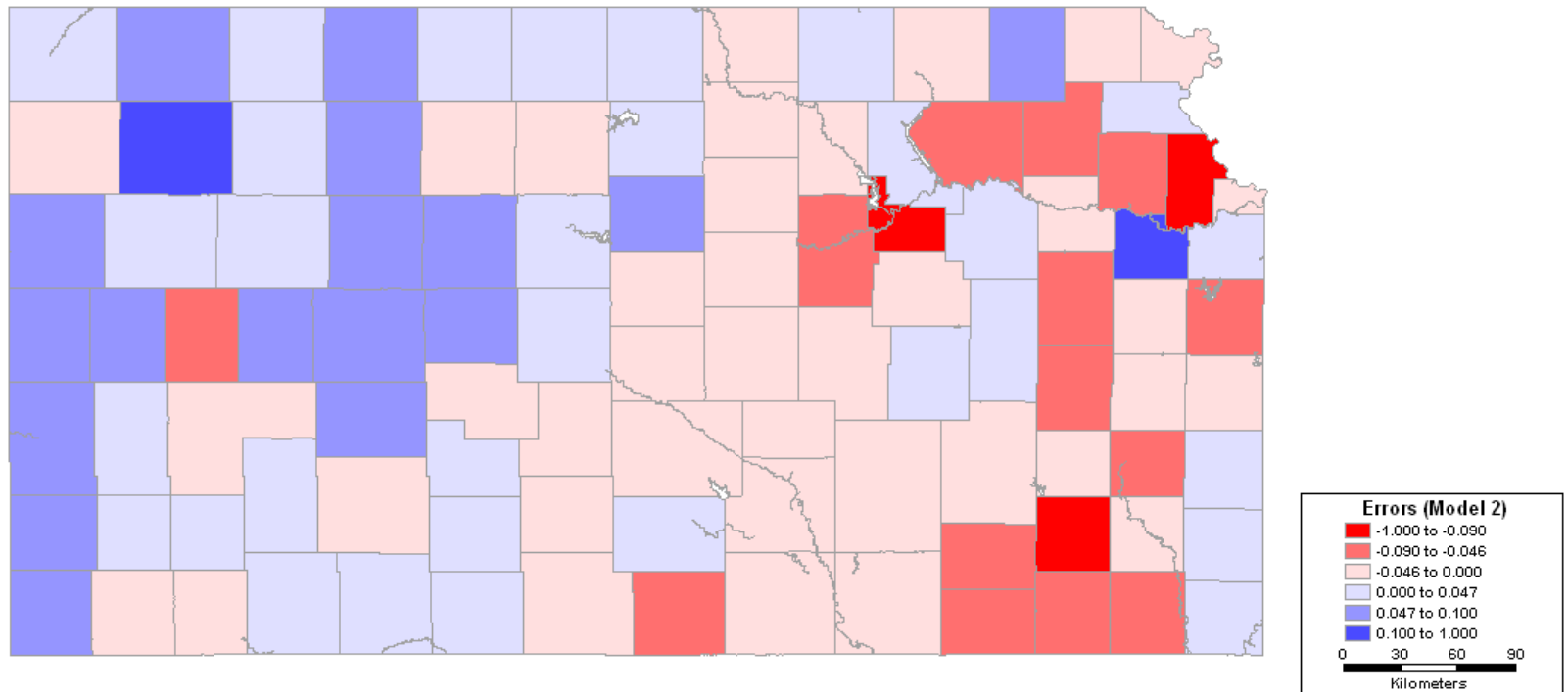
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Analysis of Residuals

○ Are errors independent?

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Analysis of Residuals

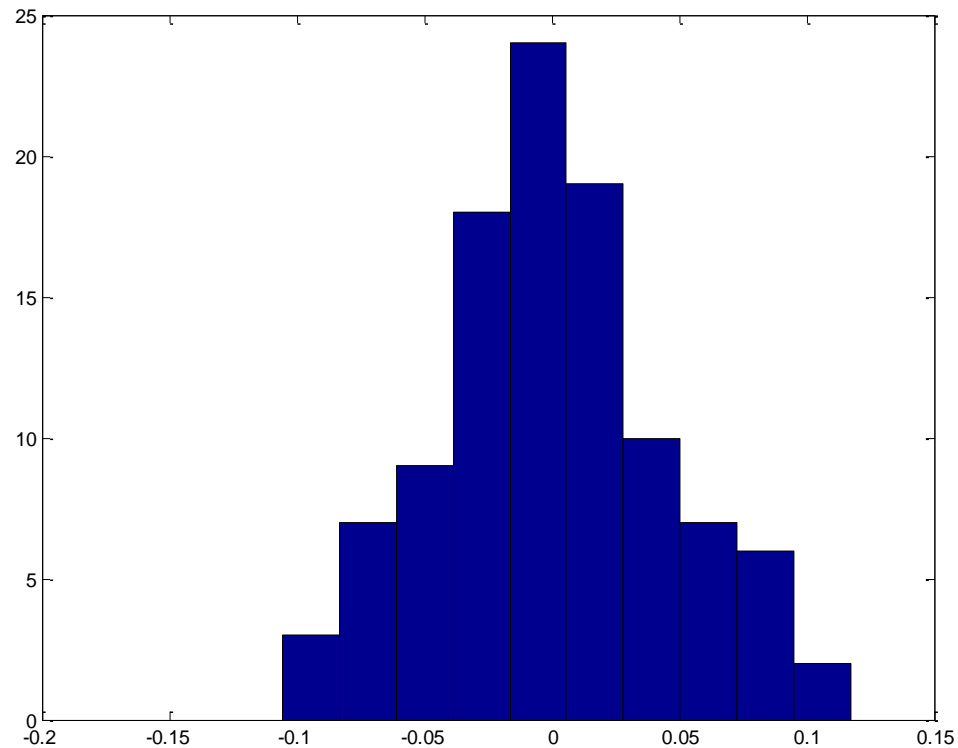
- Are errors independent?
 - Moran's I
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Analysis of Residuals

- Are errors normally distributed?
 - Histogram
 - Probability plot
 - Other tests (Jarque-Bera, Kolmogorov-Smirnov, Lilliefors)

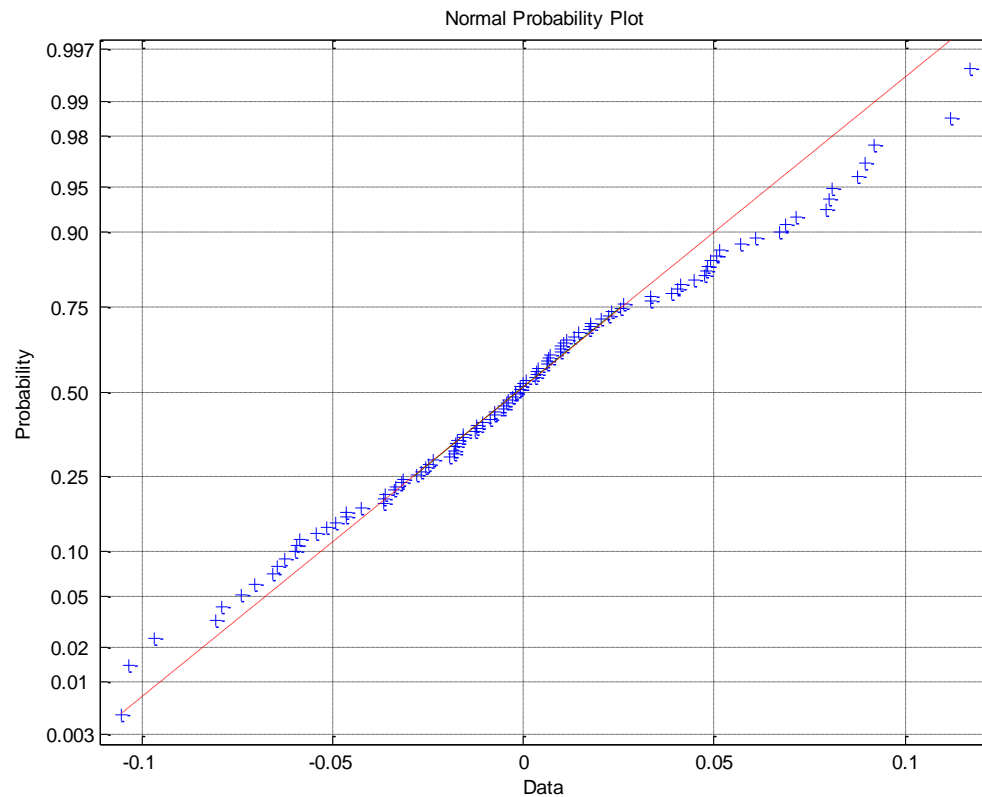
Analysis of Residuals

○ Histogram



Analysis of Residuals

- Probability plot



Modeling Area Data

- Data transformations

- Logarithm of proportional voter turnout:

$$\ln(\textit{PrVOTE})$$

- Correlation coefficients
- Model
- Analysis of residuals

Variable Transformations

- Taking logarithms: $\ln(PrVOTE)$

Model 3 $\ln(VOTE/POP)$

Variable	PARAMETER	t-value
CONST	0.926	4.70
$\ln(EDU/POP)$	0.710	5.28
$\ln(HOUSE/POP)$	0.614	8.21
$\ln(INCOME/POP)$	-0.205	-2.57
$R^2=$	0.674	
$R^2(adj)=$	0.649	
SIGMA =	0.081	
n=	105	
<< Normalized Moran's I >>'		
$Z(I) =$	3.138	

Normality? No

Constant variance? Yes

Conclusion

- Model selection
 - Totals
 - Proportions
 - Logarithm of Proportions

Conclusion

- All three models still show residual error pattern (error autocorrelation)

Non-spatial Regression

- Data transformations may help to reduce problems with the residuals + increase interpretability
- In the example: All three models show residual error pattern (error autocorrelation)
- Spatial regression models

Spatial Regression Modeling

- Objective:
 - Testing for and estimating regression models that incorporate spatial effects
- Recall GLS

$$Y = X\beta + U$$

$$E[U] = \mathbf{0}$$

$$E[UU'] = \mathbf{C}$$

Spatial Regression Modeling

- Generalized Least Squares

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{U}$$

- 2nd order effects?
- Questionable assumption of stationarity of 2nd order
- Distance measures?

Spatial Regression Modeling

- Autocorrelated errors model

$$Y = \underline{X\beta} + U$$

Non-spatial part

$$\underline{U} = \rho WU + \varepsilon$$

Spatial part (residual pattern)

Autocorrelated Errors Modeling

$$Y = X\beta + U$$

$$U = \rho WU + \varepsilon$$

$$E[\varepsilon] = 0$$

$$E[\varepsilon\varepsilon'] = \sigma^2 \mathbf{I}$$

- Rewriting:

$$Y = X\beta + \rho WY - \rho WX\beta + \varepsilon$$

$$C = \sigma^2 \left((\mathbf{I} - \rho W)^T (\mathbf{I} - \rho W) \right)^{-1}$$

Estimation of the Spatial Model

- OLS estimation not useful
- Maximum likelihood estimation of β and ρ

- Assumptions:

y_i are observations on n random variables Y , jointly normally distributed with Mean = $\mathbf{X}\beta$ and Covariance matrix \mathbf{C} , where

$$\mathbf{C} = \sigma^2 \left((\mathbf{I} - \rho \mathbf{W})^T (\mathbf{I} - \rho \mathbf{W}) \right)^{-1}$$

Estimation of a Spatial Model

- Maximum likelihood estimation of β and ρ
- What is the maximum likelihood function?

Alternative Spatial Models

- Lag models

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{U}$$

$$\mathbf{U} = \rho_1 \mathbf{W}^{(1)} \mathbf{U} + \rho_2 \mathbf{W}^{(2)} \mathbf{U} + \dots + \boldsymbol{\varepsilon}$$

Alternative Spatial Models

- Mixed regressive autoregressive

$$\mathbf{Y} = \underbrace{\rho \mathbf{W} \mathbf{Y}}_{\text{Spatial part}} + \underbrace{\mathbf{X} \boldsymbol{\beta}}_{\text{Non-spatial part}} + \boldsymbol{\varepsilon}$$

Spatial part

Non-spatial part

Alternative Spatial Models

- Pure autoregressive

$$\mathbf{Y} = \rho \mathbf{WY} + \varepsilon$$

Spatial part

Alternative Spatial Models

- Moving average model (map pattern)

$$\mathbf{Y} = (\mathbf{I} - \rho \mathbf{W}) \boldsymbol{\varepsilon}$$

Spatial part

Spatial Regression

- Fit autocorrelated errors model

Model 4 VOTE/POP

Variable	PARAMETER	t-value
CONST	0.032	0.52
EDU/POP	0.645	4.80
HOUSE/POP	0.898	6.92
INCOME/POP	-0.015	-3.09
RHO	0.468	4.14
SIGMA	= 0.002	
n=	105	
<< Lagrange Multiplier >>		
Omitted Sp. Lag=	1.038	--> Chi2 (1 DF)

Example

○ Model 2

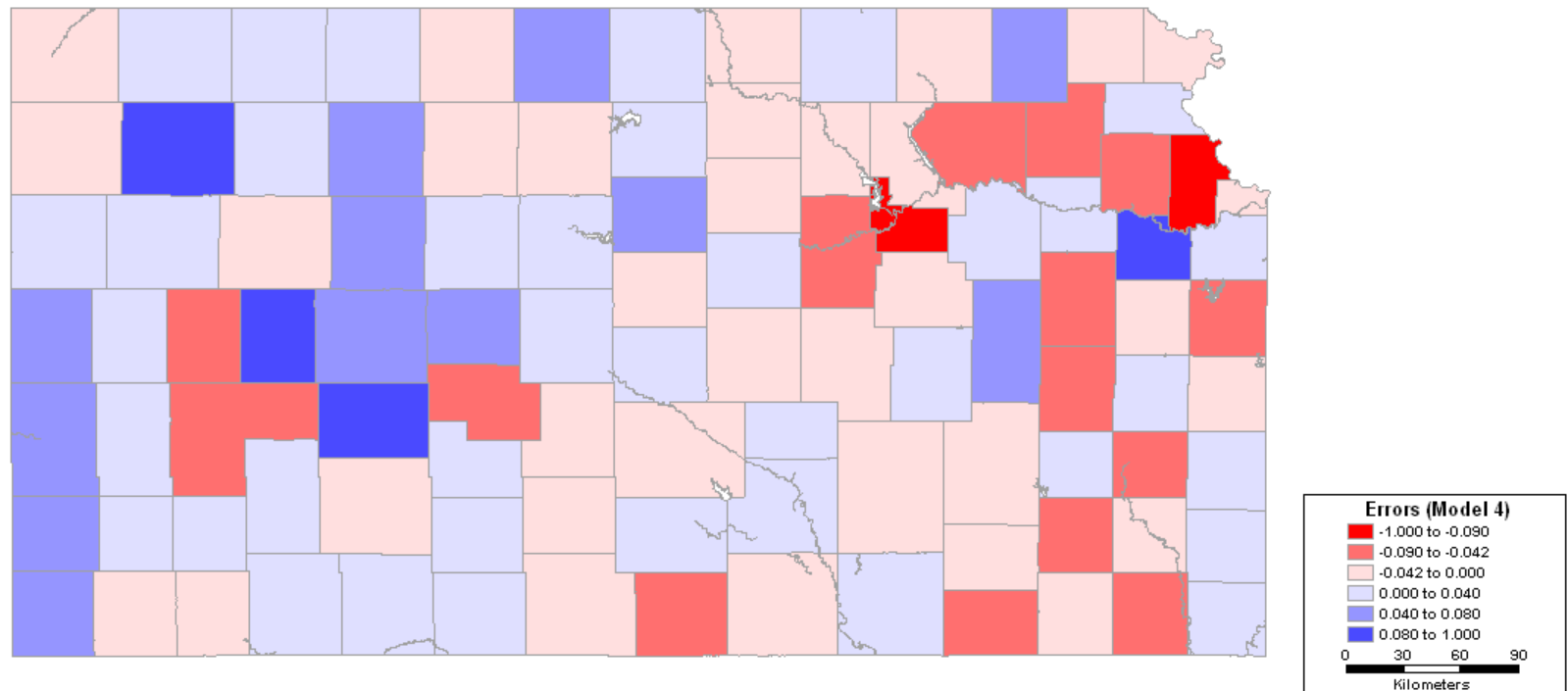
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R ² =	0.636	
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SIGMA =	0.047	
n=	105	
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Z (I) =	4.023	

Analysis of Residuals

○ Are errors independent? Model 4

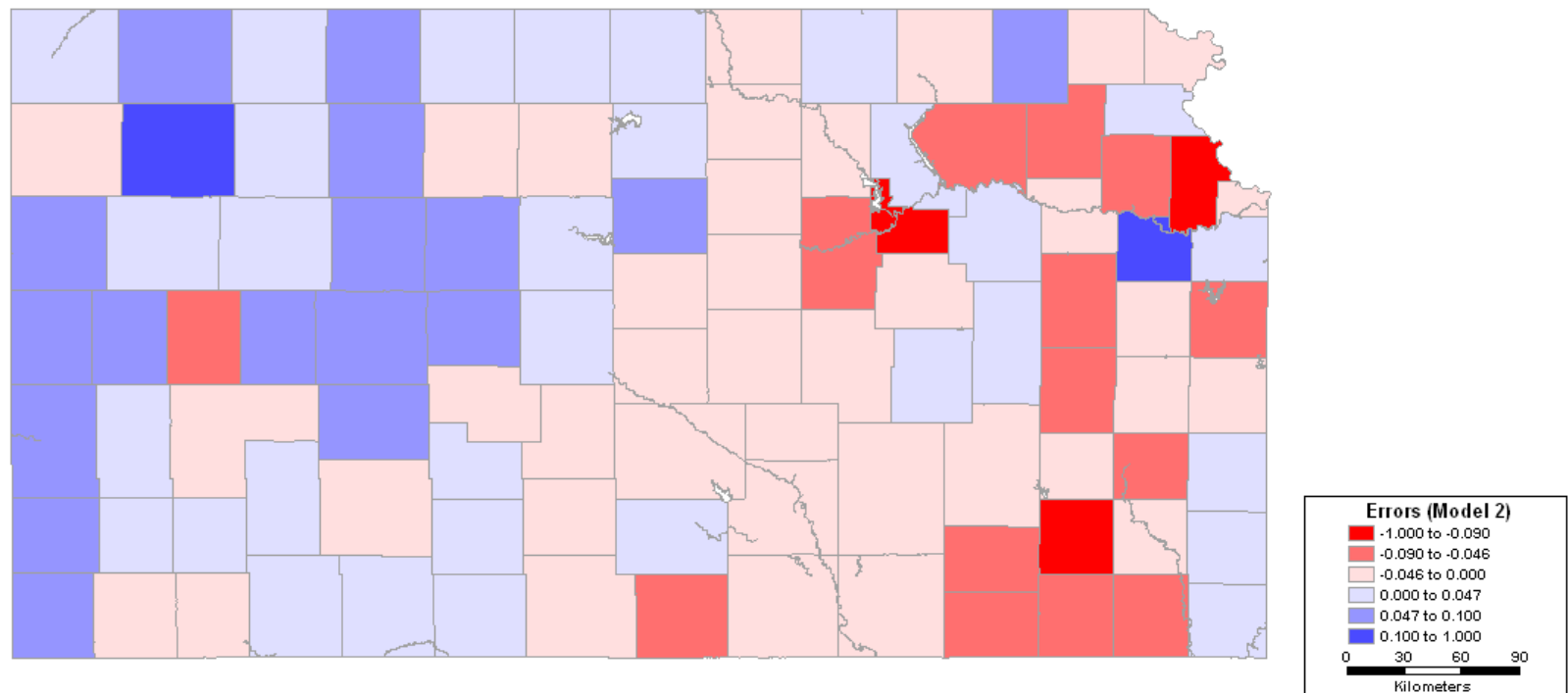
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Analysis of Residuals

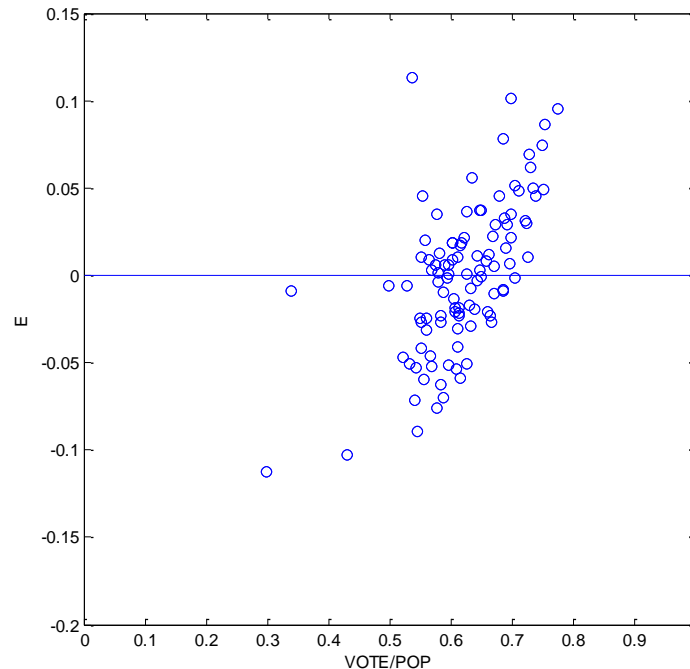
○ Are errors independent? Model 2

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Analysis of Residuals

- Is variance constant?
 - Scatterplot of errors vs. variables

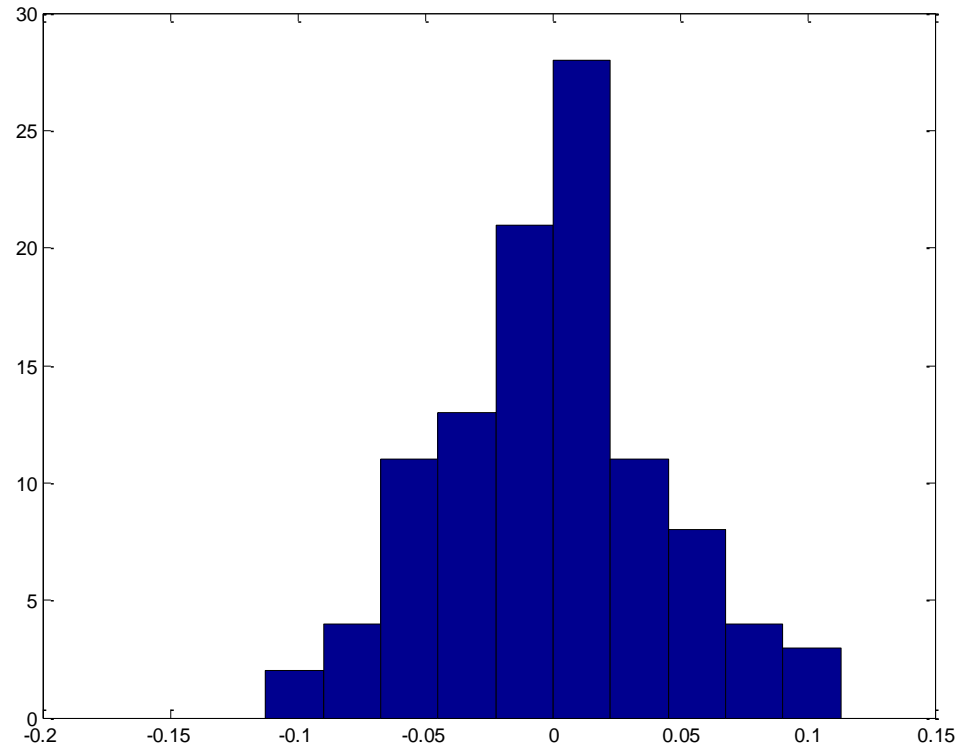


Analysis of Residuals

- Are errors normally distributed?
 - Histogram
 - Probability plot
 - Other tests (Jaques-Bera, Kolmogorov-Smirnov, Lilliefors)

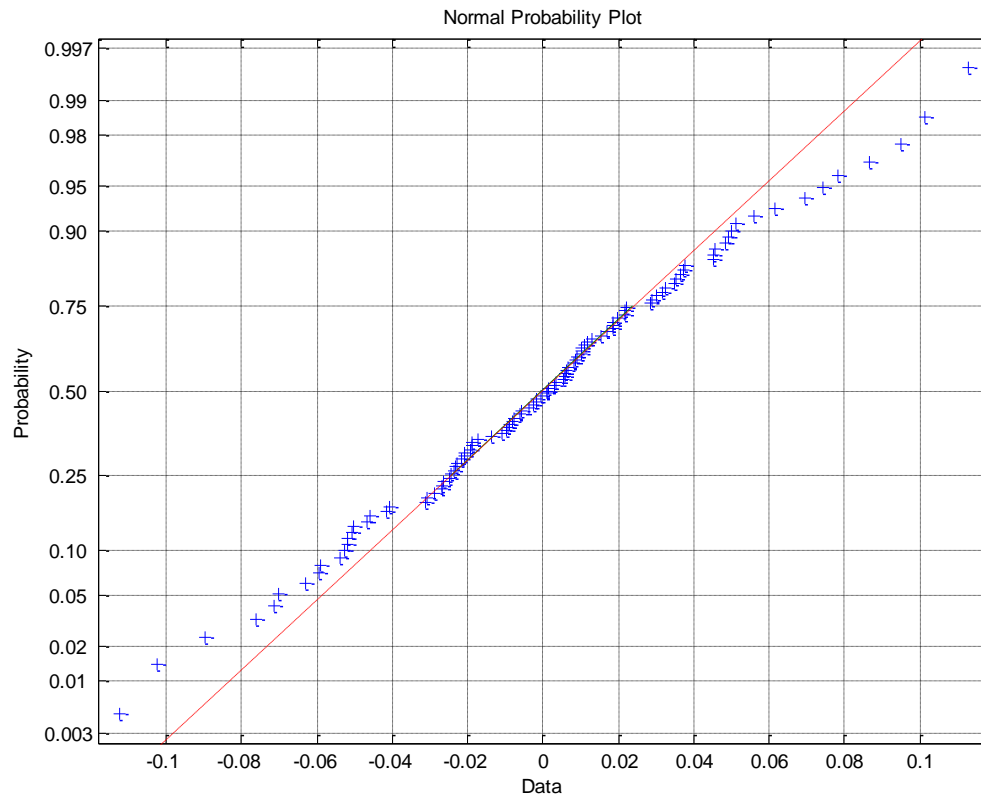
Analysis of Residuals

○ Histogram



Analysis of Residuals

- Probability plot



Analysis of Residuals

- Other tests

<u>Test</u>	<u>Normal?</u>
Jarque-Bera	YES
Kolmogorov-Smirnov	YES
<u>Lilliefors</u>	<u>YES</u>

Conclusion

- The autocorrelated errors model is the best alternative
 - Satisfies all major assumptions
 - Accounts for all systematic spatial variation

Summary of modeling approach

- Exploration
- Models – non-spatial models, check assumptions
- Models – spatial models, check assumptions and statistical fit
- Think Theory!