

Queen's University
CISC/CMPE 457
Test 1

October 5, 2018
Duration: 50 minutes

Closed book

Initial of Family Name: ____

Student Number: SOLUTIONS
(Write this at the top of every page.)

There are 6 questions and 21 marks total.

Answer all questions.

This exam paper should have 8 pages,
including this cover page.

1 – Short Answers	/ 8
2 – Homogeneous Transformations	/ 3
3 – Histogram Equalization	/ 2
4 – Bilinear Interpolation	/ 3
5 – Convolution	/ 2
6 – Image Sharpening	/ 3
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Total	/ 21

The candidate is urged to submit with the answer paper a clear statement of any assumptions made if doubt exists as to the interpretations of any question that requires a written answer.

1 Short Answers — 8 points

Part A — 1 point What is the “quantum efficiency” of a photodiode?

THE PERCENTAGE OF ARRIVING PHOTONS
THAT ARE CAPTURED / DETECTED

Part B — 1 point What happens at the electronic level at a photodiode when “blooming” occurs?

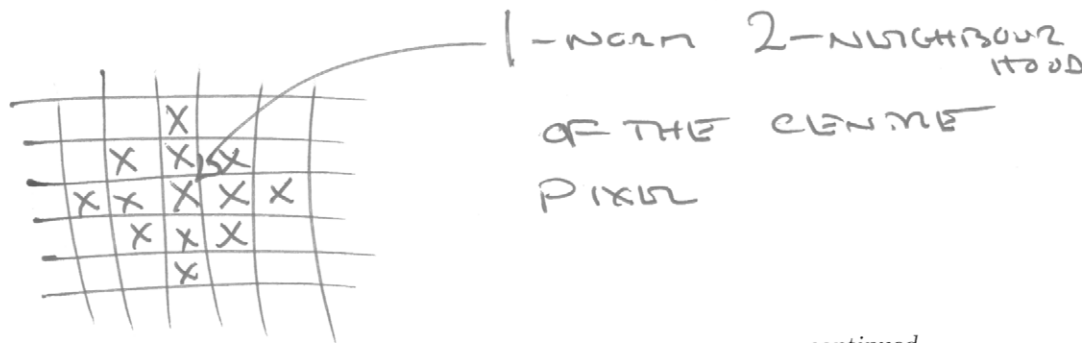
A PHOTODIODE'S ELECTRON WELL FILLS UP
AND ELECTRONS SPILL OVER INTO ADJACENT
WELLS, CAUSING THE CORRESPONDING PIXELS
TO BE BRIGHTER.

Part C — 1 point Why should the weights of a smoothing filter sum to 1?

TO KEEP THE SAME OVERALL
IMAGE BRIGHTNESS.

Part D — 1 point Write the equation of the distance, $d(a, b)$, between two pixels, $a = (a_x, a_y)$ and $b = (b_x, b_y)$, using the 1-norm. Draw the 2-neighbourhood of a pixel using the 1-norm.

$$d(a, b) = |a_x - b_x| + |a_y - b_y|$$



... continued

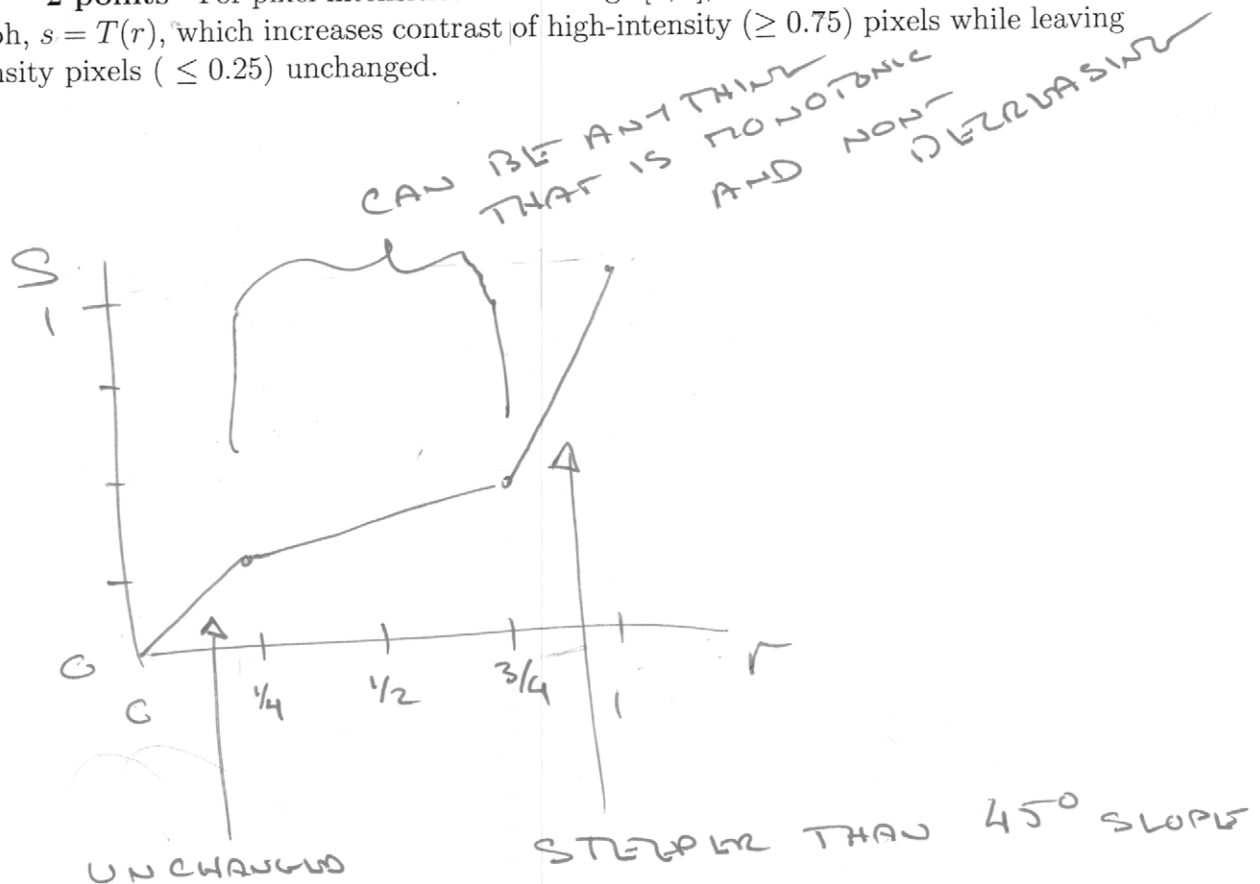
Part E — 1 point Briefly explain why averaging N images to reduce the noise is an inefficient process.

THE STANDARD DEVIATION OF THE NOISE IS REDUCED BY ONLY $\frac{1}{\sqrt{N}}$ FOR N SAMPLES, SO MANY IMAGES ARE REQUIRED TO REDUCE THE NOISE BY ONLY A SMALL AMOUNT.

Part F — 1 point A median filter is used to remove "salt and pepper" noise. Ignoring the processing time, is it better to have a 3×3 or 9×9 neighbourhood for a median filter? Explain.

3×3 . A SMALLER FILTER WILL REPLACE A PIXEL BY SOMETHING FROM ITS IMMEDIATE 1-NEIGHBOURHOOD, RESULTING IN LESS IMAGE DISTORTION

Part G — 2 points For pixel intensities in the range $[0, 1]$, draw an intensity transformation graph, $s = T(r)$, which increases contrast of high-intensity (≥ 0.75) pixels while leaving low-intensity pixels (≤ 0.25) unchanged.



2 Homogeneous Transformations — 3 points

Show a homogeneous (i.e. 3×3) transformation that scales 2D points around a centre position $(1, 2)$ by a factor of 5. Write only the product of transformation matrices; do not multiply them to get a single matrix.

SUBTRACT CENTRE, THEN SCALE, THEN ADD CENTRE!

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

3 Histogram Equalization — 2 points

Given this set of pixels 9 with values in the range $[0, 3]$

0	0	0
1	2	3
0	3	1

what is the value 2 mapped to by histogram equalization? Show your work. The value may be fractional.

HISTOGRAM

$$\begin{aligned} h(0) &= 4 \\ h(1) &= 2 \\ h(2) &= 1 \\ h(3) &= 2 \end{aligned}$$

$$T(r) = \frac{4}{9} \sum_{i=0}^r h(i) - 1$$

4 = NUMBER OF POSSIBLE INTENSITIES

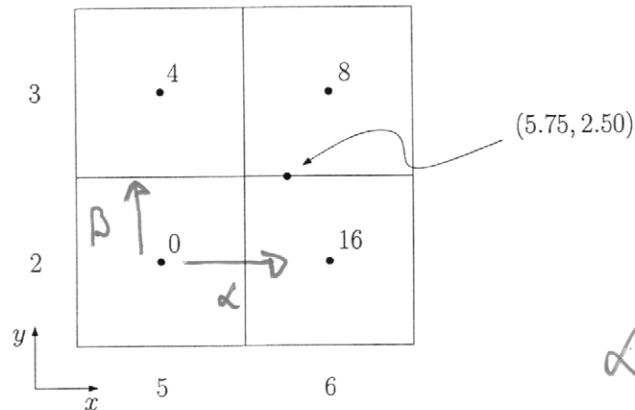
9 = NUMBER OF PIXELS IN HISTOGRAM

$$\begin{aligned} T(2) &= \frac{4}{9} (4+2+1) - 1 \\ &= \frac{28}{9} - 1 = \frac{19}{9} = 2\frac{1}{9} \end{aligned}$$

... continued

4 Bilinear Interpolation — 3 points

Calculate the intensity at position (5.75, 2.50) using bilinear interpolation of the intensities (= 0, 4, 8, and 16) below. Show your work.



$$\alpha = 3/4$$

$$\beta = 1/2$$

$$\begin{aligned} I(5.75, 2.50) &= (1-\alpha)(1-\beta) I(5, 2) \\ &+ (1-\alpha) \beta I(5, 3) \\ &+ \alpha (1-\beta) I(6, 2) \\ &+ \alpha \beta I(6, 3) \end{aligned}$$

$$\begin{aligned} &= \frac{1}{4} \cdot \frac{1}{2} \cdot 0 + \frac{1}{4} \cdot \frac{1}{2} \cdot 4 \\ &+ \frac{3}{4} \cdot \frac{1}{2} \cdot 16 + \frac{3}{4} \cdot \frac{1}{2} \cdot 8 \end{aligned}$$

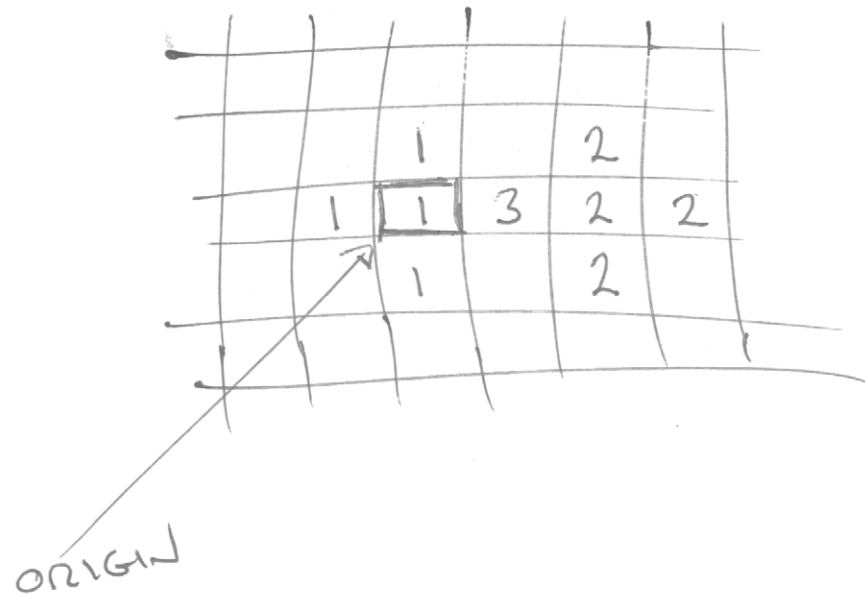
$$= \frac{1}{2} (0 + 1 + 12 + 6)$$

$$= \frac{19}{2} = 9.5$$

5 Convolution — 2 points

Convolve these two signals. The origin of each signal is in a box.

$$\begin{array}{ccccc}
 & & \boxed{1} & & \\
 0 & 0 & & 0 & 2 \\
 & & \boxed{1} & & \\
 2 & 0 & & &
 \end{array}
 \quad
 \begin{array}{ccc}
 0 & 1 & 0 \\
 1 & \boxed{1} & 1 \\
 0 & 1 & 0
 \end{array}$$



3 ELSEWHERE

6 Image Sharpening — 3 points

Part A — 2 points The Laplacian filter D is used to sharpen an image I . Write an equation for the sharpened image as a function of D and I and explain how the amount of sharpening is controlled.

$$I = I + k D * I$$

INCREASING k ADDS MORE SHARPENING

Part B — 1 point Explain why a “difference of Gaussians” filter can be more efficient than a “Laplacian of Gaussian” filter.

DOG CAN BE SEPARATED INTO TWO 1D FILTERS, MAKING IT MORE EFFICIENT

$N \times N$ DOG BECOMES

$$(G_1 - G_2)$$

LOG IS

$N \times N$

$\rightarrow N^2$ OPERATIONS

$N \times 1$ AND $1 \times N$

$$(G_1^H * G_1^V - G_2^H * G_2^V)$$

2N OPS

2N OPS

4N OPERATIONS