

Queen's University
CISC/CMPE 457
Test 1

October 5, 2018
Duration: 50 minutes

Closed book

Initial of Family Name: ____

Student Number: SOLUTIONS
(Write this at the top of every page.)

There are 6 questions and 21 marks total.

Answer all questions.

This exam paper should have 8 pages,
including this cover page.

1 – Short Answers	/ 8
2 – Homogeneous Transformations	/ 3
3 – Histogram Equalization	/ 2
4 – Bilinear Interpolation	/ 3
5 – Convolution	/ 2
6 – Image Sharpening	/ 3
Total	/ 21

The candidate is urged to submit with the answer paper a clear statement of any assumptions made if doubt exists as to the interpretations of any question that requires a written answer.

1 Short Answers — 8 points

Part A — 1 point What is the “quantum efficiency” of a photodiode?

THE PERCENTAGE OF ARRIVING PHOTONS
THAT ARE CAPTURED / DETECTED

Part B — 1 point What happens at the electronic level at a photodiode when “blooming” occurs?

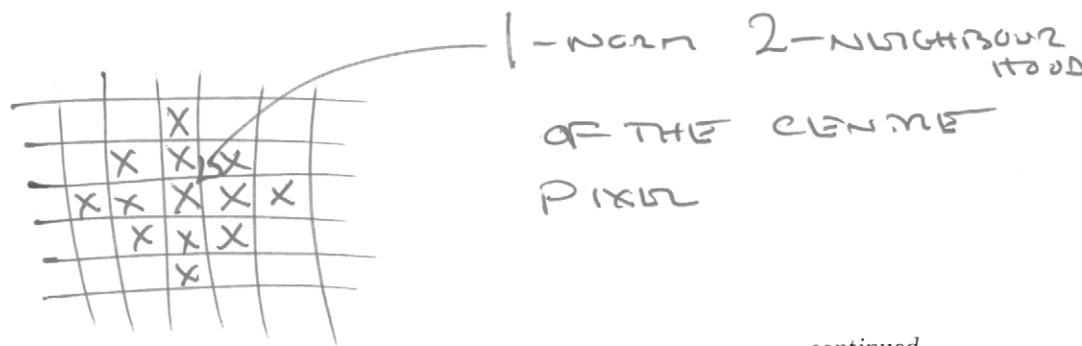
A PHOTODIODE'S ELECTRON WELL FILLS UP
AND ELECTRONS SPILL OVER INTO ADJACENT
WELLS, CAUSING THE CORRESPONDING PIXELS
TO BE BRIGHTER.

Part C — 1 point Why should the weights of a smoothing filter sum to 1?

TO KEEP THE SAME OVERALL
IMAGE BRIGHTNESS.

Part D — 1 point Write the equation of the distance, $d(a, b)$, between two pixels, $a = (a_x, a_y)$ and $b = (b_x, b_y)$, using the 1-norm. Draw the 2-neighbourhood of a pixel using the 1-norm.

$$d(a, b) = |a_x - b_x| + |a_y - b_y|$$



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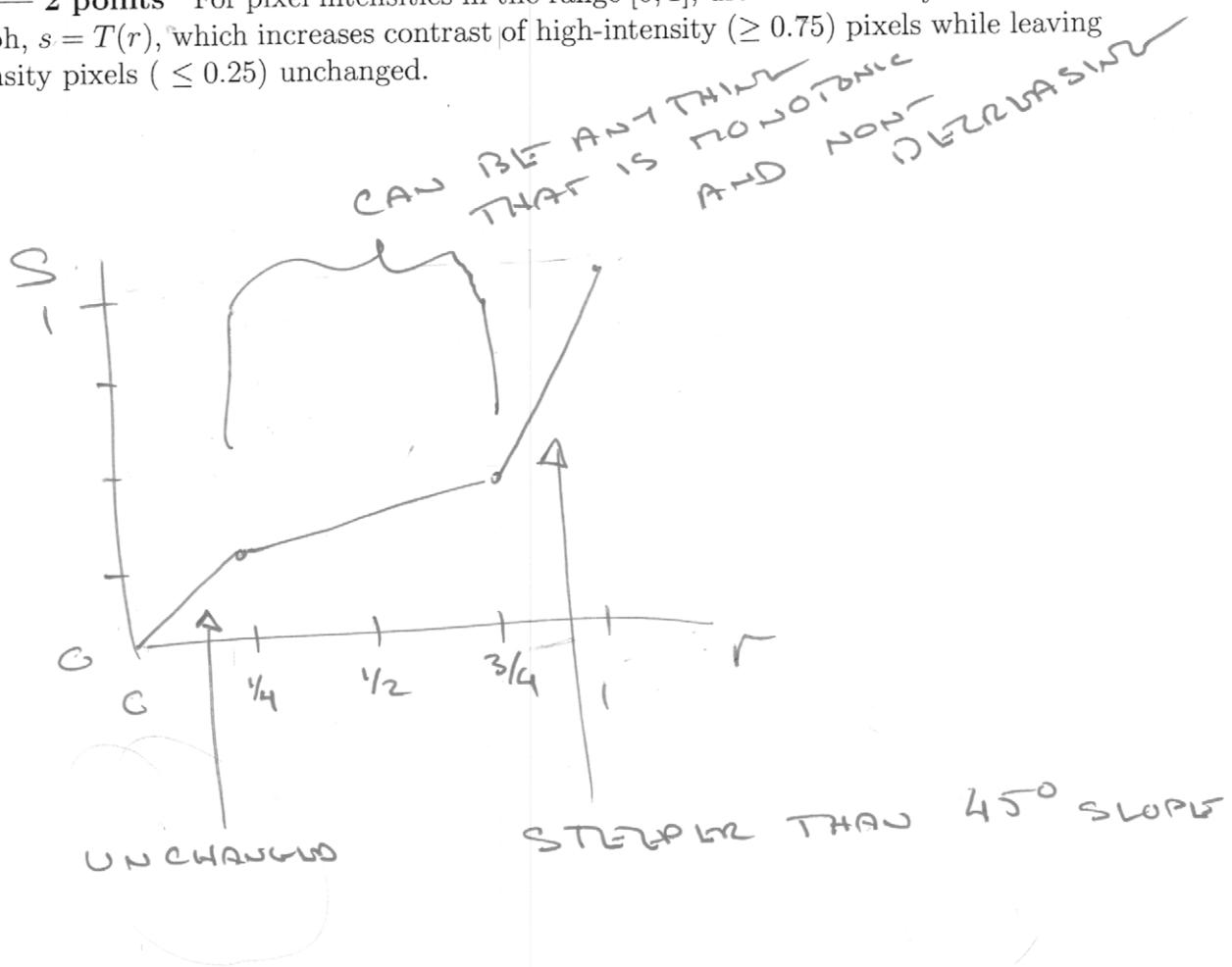
Part E — 1 point Briefly explain why averaging N images to reduce the noise is an inefficient process.

THE STANDARD DEVIATION OF THE NOISE IS REDUCED BY ONLY $\frac{1}{\sqrt{N}}$ FOR N SAMPLES, SO MANY IMAGES ARE REQUIRED TO REDUCE THE NOISE BY ONLY A SMALL AMOUNT.

Part F — 1 point A median filter is used to remove “salt and pepper” noise. Ignoring the processing time, is it better to have a 3×3 or 9×9 neighbourhood for a median filter? Explain.

3x3 . A smaller filter will replace a pixel by something from its immediate 1-neighbourhood, resulting in less image distortion

Part G — 2 points For pixel intensities in the range $[0, 1]$, draw an intensity transformation graph, $s = T(r)$, which increases contrast of high-intensity (≥ 0.75) pixels while leaving low-intensity pixels (≤ 0.25) unchanged.



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2 Homogeneous Transformations — 3 points

Show a homogeneous (i.e. 3×3) transformation that scales 2D points around a centre position $(1, 2)$ by a factor of 5. Write only the product of transformation matrices; do not multiply them to get a single matrix.

SUBTRACT CENTRE, THEN SCALE, THEN
ADD CENTRE

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

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3 Histogram Equalization — 2 points

Given this set of pixels 9 with values in the range [0, 3]

$$\begin{matrix} 0 & 0 & 0 \\ 1 & 2 & 3 \\ 0 & 3 & 1 \end{matrix}$$

what is the value 2 mapped to by histogram equalization? Show your work. The value may be fractional.

HISTOGRAM

$h(0)$	=	4
$h(1)$	=	2
$h(2)$	=	1
$h(3)$	=	2

$$T(r) = \frac{4}{9} \sum_{i=0}^r h(i) - 1$$

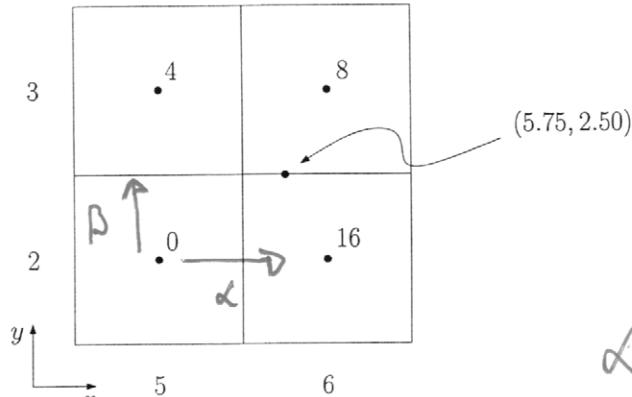
4 = number of possible intensities

9 = number of pixels in histogram

$$\begin{aligned} T(2) &= \frac{4}{9} (4+2+1) - 1 \\ &= \frac{28}{9} - 1 = \frac{19}{9} = 2\frac{1}{9} \end{aligned}$$

4 Bilinear Interpolation — 3 points

Calculate the intensity at position (5.75, 2.50) using bilinear interpolation of the intensities (= 0, 4, 8, and 16) below. Show your work.



$$\alpha = \frac{3}{4}$$

$$\beta = \frac{1}{2}$$

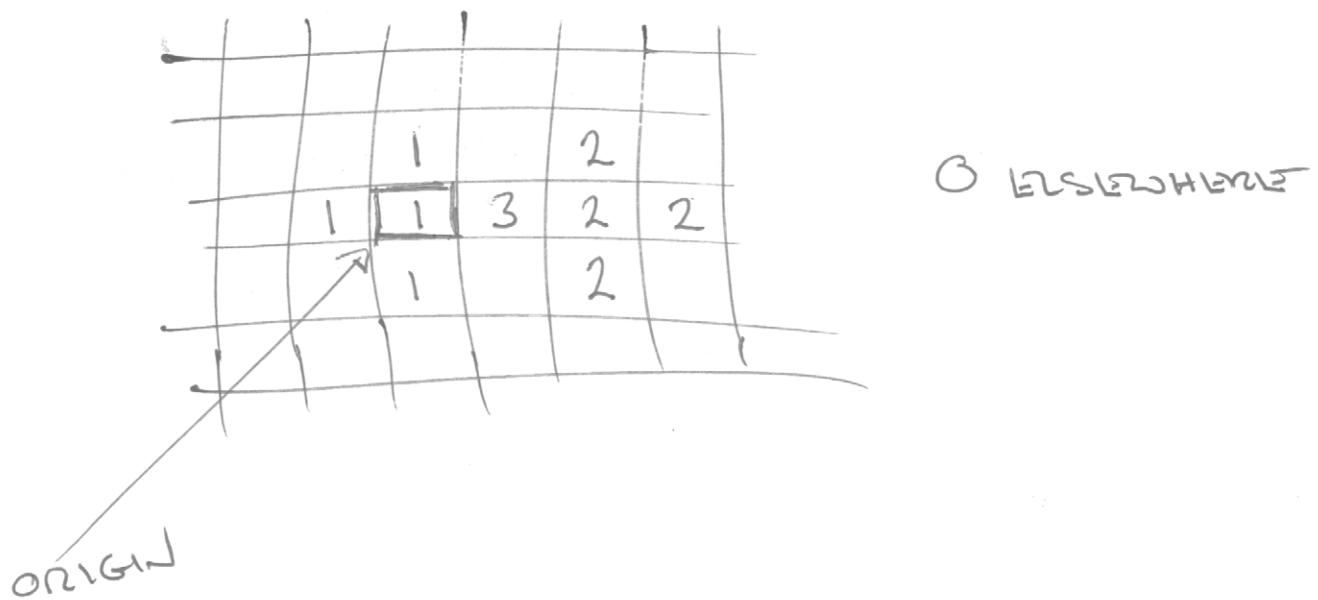
$$\begin{aligned}
 I(5\frac{3}{4}, 2\frac{1}{2}) &= (1-\alpha)(1-\beta) I(5,2) \\
 &\quad + (1-\alpha) \beta I(5,3) \\
 &\quad + \alpha (1-\beta) I(6,2) \\
 &\quad + \alpha \beta I(6,3)
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{4} \cdot \frac{1}{2} \cdot 0 + \frac{1}{4} \cdot \frac{1}{2} \cdot 4 \\
 &\quad + \frac{3}{4} \cdot \frac{1}{2} \cdot 16 + \frac{3}{4} \cdot \frac{1}{2} \cdot 8 \\
 &= \frac{1}{2} (0 + 1 + 12 + 6) \\
 &= 19 \frac{1}{2} = 28 \frac{1}{2}
 \end{aligned}$$

5 Convolution — 2 points

Convolve these two signals. The origin of each signal is in a box.

$$\begin{array}{ccccc} 0 & 0 & \boxed{1} & 0 & 2 \\ & & & & \\ 2 & 0 & \boxed{1} & & \end{array}$$



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6 Image Sharpening — 3 points

Part A — 2 points The Laplacian filter D is used to sharpen an image I . Write an equation for the sharpened image as a function of D and I and explain how the amount of sharpening is controlled.

$$I' = I + \kappa D * I$$

Increasing κ adds more sharpening

Part B — 1 point Explain why a “difference of Gaussians” filter can be more efficient than a “Laplacian of Gaussian” filter.

DoG can be separated into two 1D filters, making it more efficient

$$N \times N \text{ DoG becomes } (G_1 - G_2)$$

LoG is

$N \times N$

$\xrightarrow{\quad} N^2 \text{ operations}$

$$(G_1^H * G_1^V - G_2^H * G_2^V)$$

$\underbrace{\qquad\qquad}_{2N \text{ ops}} \quad \underbrace{\qquad\qquad}_{2N \text{ ops}}$

$4N$ operations