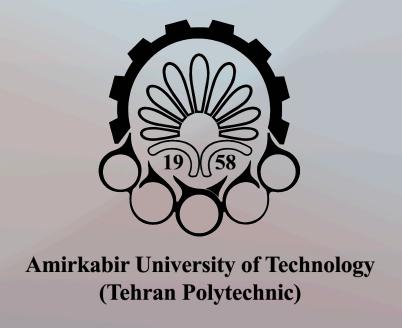
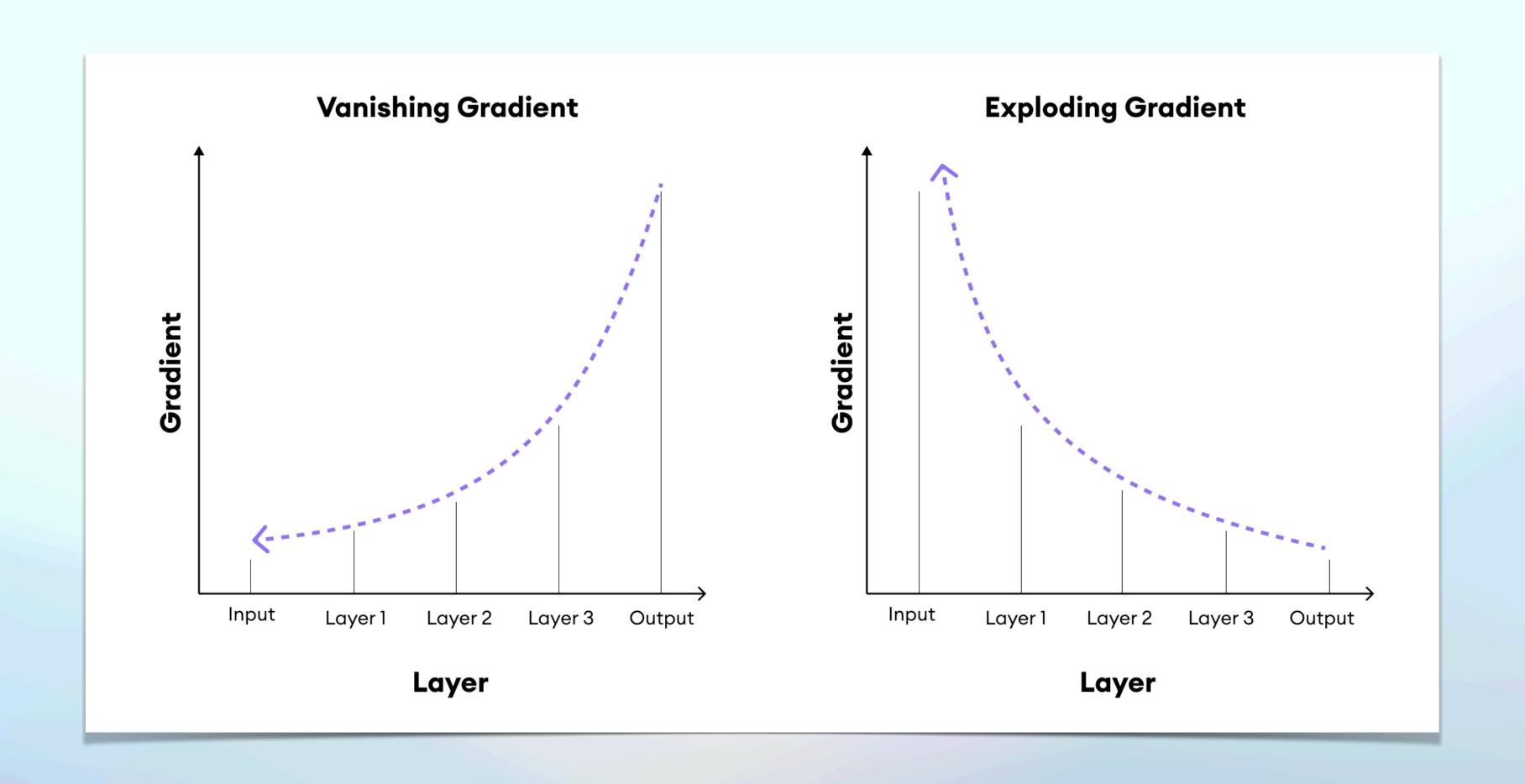
# Mastering MLP - Part 1

Computation Intelligence and its Application in Mechatronics



• **Issue:** As gradients backpropagate, they may shrink to near-zero (vanishing) or grow too large (exploding).

- Effect:
  - Vanishing gradients slow down learning or prevent deeper layers from learning.
  - Exploding gradients cause instability and divergence.



#### Solutions to Vanishing/Exploding Gradients

- 1. Better Weight Initialization (Glorot, He)
- 2. Nonsaturating Activation Functions (Leaky ReLU, etc.)
- 3. Batch Normalization
- 4. Gradient Clipping

#### Weight Initialization Techniques

#### **Glorot (Xavier) Initialization**

- Formula: Uniform Distribution  $w \sim U\left(-\frac{\sqrt{6}}{\sqrt{n_{\mathsf{in}} + n_{\mathsf{out}}}}, \frac{\sqrt{6}}{\sqrt{n_{\mathsf{in}} + n_{\mathsf{out}}}}\right)$ , Normal Distribution  $w \sim \mathcal{N}\left(0, \frac{2}{n_{\mathsf{in}} + n_{\mathsf{out}}}\right)$
- Suitable for sigmoid and tanh activations.

#### **He Initialization**

- Formula: Uniform Distribution  $w \sim U\left(-\frac{\sqrt{6}}{\sqrt{n_{\text{in}}}}, \frac{\sqrt{6}}{\sqrt{n_{\text{in}}}}\right)$ , Normal Distribution  $w \sim \mathcal{N}\left(0, \frac{2}{n_{\text{in}}}\right)$
- Best for ReLU and Leaky ReLU activations

#### Nonsaturating Activation Functions

Leaky ReLU (LReLU) = 
$$\begin{cases} x, & \text{if } x > 0 \\ \alpha x, & \text{if } x \le 0 \end{cases}$$

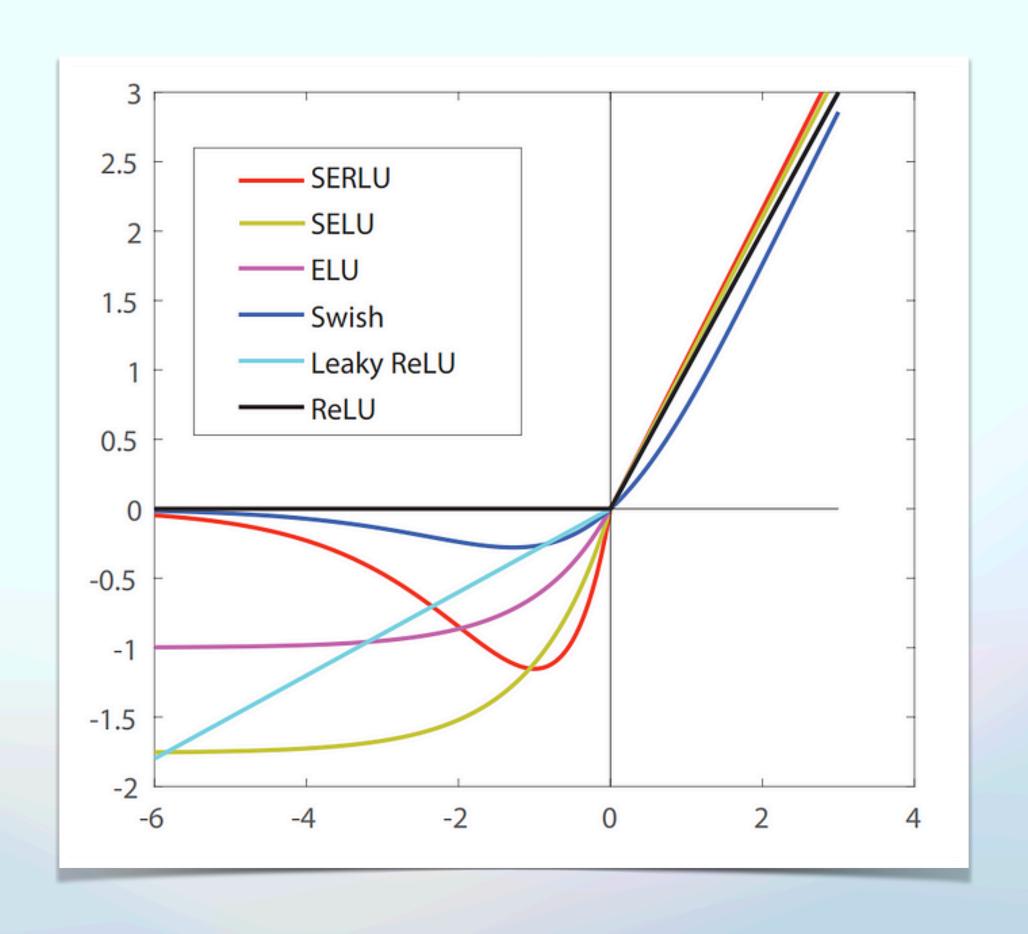
Randomized Leaky ReLU (RReLU) (randomizes  $\alpha$  during training)

Parametric Leaky ReLU (PReLU) (learns the negative slope  $\alpha$  during training)

Exponential Linear Unit (ELU) = 
$$\begin{cases} x, & x > 0 \\ \alpha(\exp(x) - 1), & x \le 0 \end{cases}$$

Scaled Exponential Linear Unit (SELU)

#### Nonsaturating Activation Functions



#### Batch Normalization

Normalizes activations across the mini-batch:

$$\hat{x}_i = \frac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}}, \qquad z_i = \gamma \hat{x}_i + \beta$$

$$\mu_B = \frac{1}{m} \sum_{i=1}^m x_i$$
,  $\sigma_B^2 = \frac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2$ 

- $x_i$  is the input activation of the neuron.
- $\mu_B$  is the mean of the mini-batch.
- $\sigma_B^2$  is the variance of the mini-batch.
- $\hat{x}_i$  is the normalized activation.
- $oldsymbol{\epsilon}$  is a small constant to prevent division by zero.
- $\gamma$  (scale) and  $\beta$  (shift) are trainable parameters.

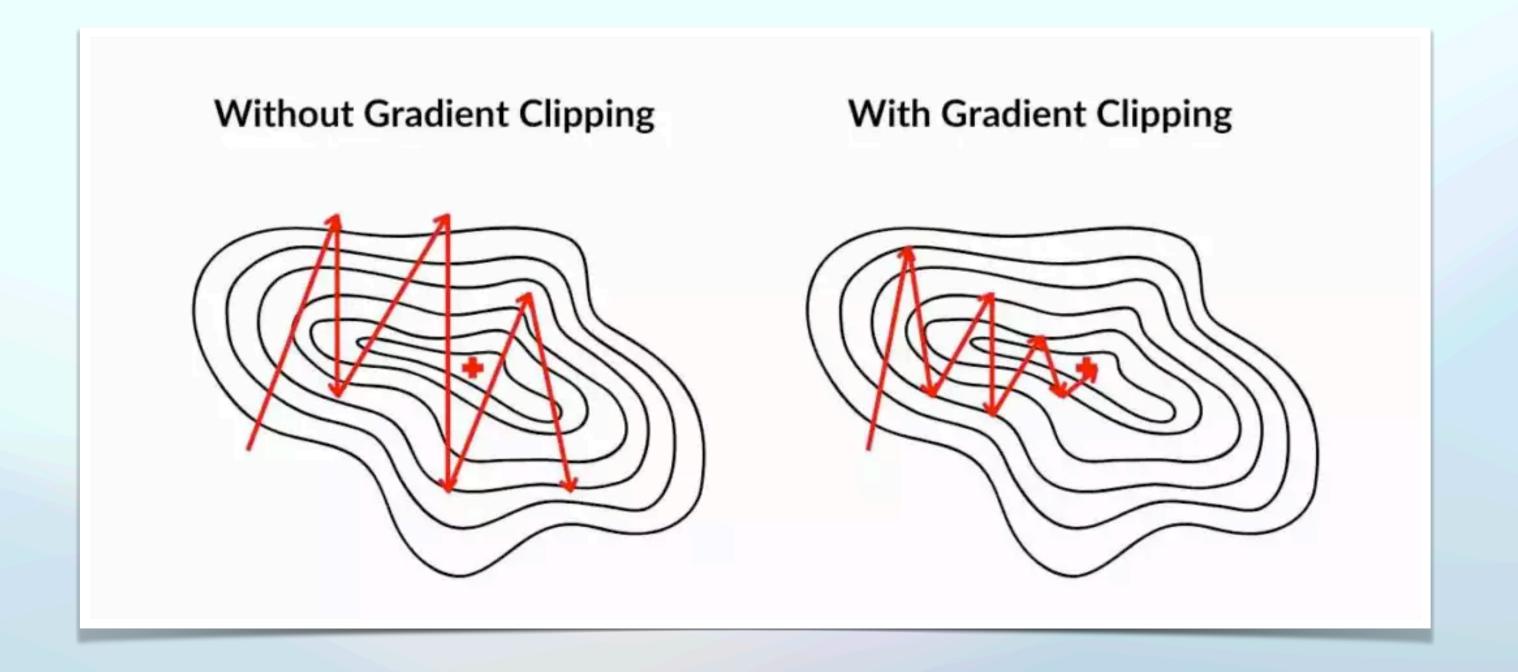
So during training, BN standardizes its inputs, then rescales and offsets them. Good!

What about at test time?



#### Gradient Clipping

Prevents exploding gradients by limiting their magnitude.



#### Avoiding Overfitting - Regularization Techniques

#### L1 and L2 regularization

L1 regularization: lasso regression

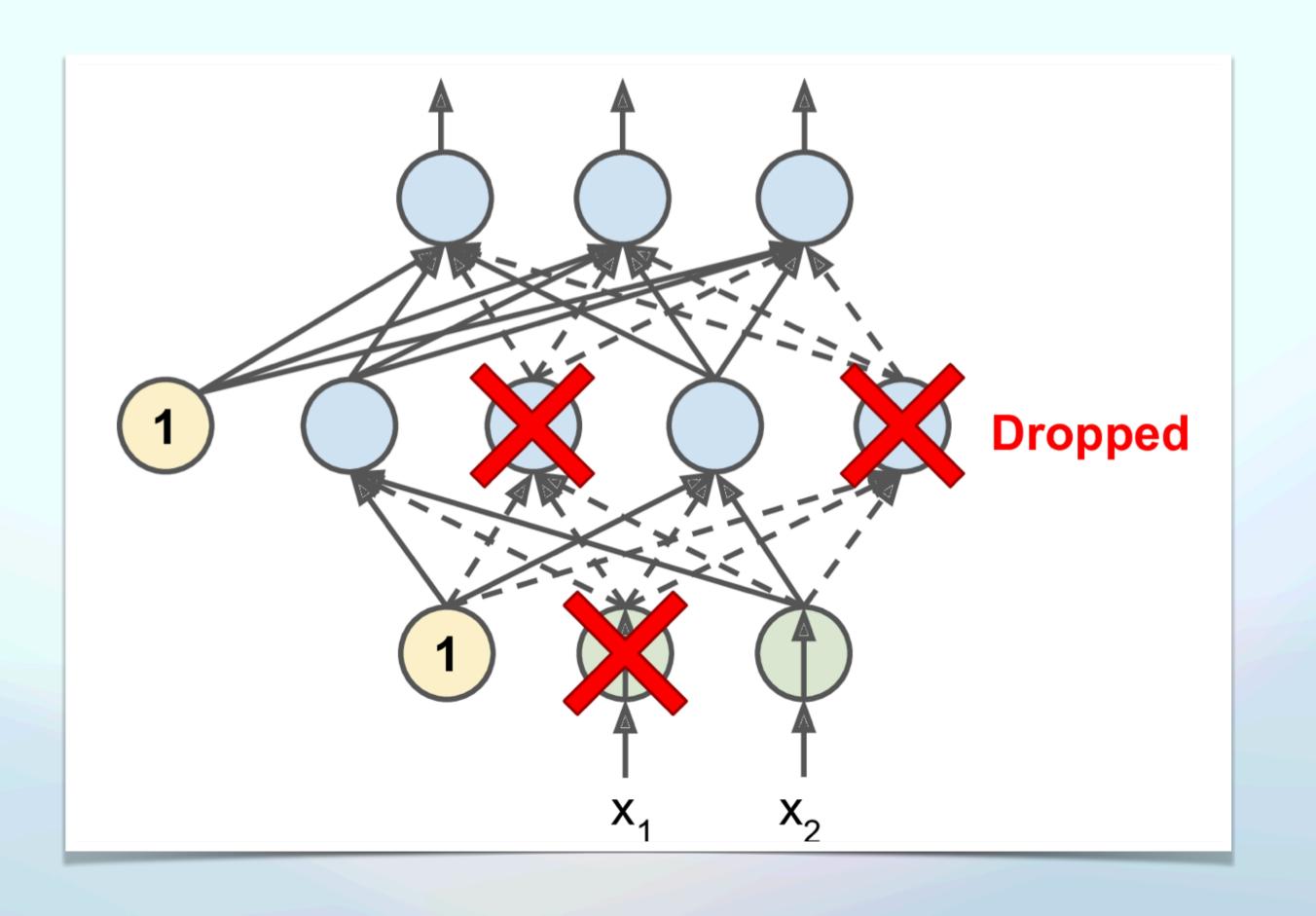
New Cost = 
$$\frac{1}{n} \sum_{i=1}^{i} y_i - \hat{y}_i + \lambda \sum_{i=1}^{i} |w_i|$$

L2 regularization: ridge regression

New Cost = 
$$\frac{1}{n} \sum_{i=1}^{i} y_i - \hat{y}_i + \lambda \sum_{i=1}^{i} w_i^2$$

#### Avoiding Overfitting - Regularization Techniques

Dropout



# What's Coming Next

Training your model with faster optimizers