HW_3

April 1, 2020

0.1 Task 1

```
[1]: #conda install -c conda-forge xgboost
[1]: import matplotlib.pyplot as plt
    import numpy as np
    import pandas as pd
    import sklearn
    import category_encoders
    from category_encoders.target_encoder import TargetEncoder
    from sklearn import datasets
    import os
    #%matplotlib widget
    from sklearn.model_selection import train_test_split, validation_curve, KFold,
    →cross_val_score, StratifiedKFold, GridSearchCV
    from sklearn.preprocessing import StandardScaler, OneHotEncoder, LabelEncoder,
    →PolynomialFeatures, scale
    from sklearn.linear_model import LogisticRegression, LinearRegression, Ridge, U
    →Lasso, ElasticNet
    from sklearn.neighbors import KNeighborsClassifier
    from sklearn.svm import LinearSVC,SVC,LinearSVR
    from sklearn import metrics
    from sklearn.ensemble import RandomForestRegressor, RandomForestClassifier
    import warnings
    warnings.simplefilter(action='ignore', category= FutureWarning)
    from sklearn.model_selection import GridSearchCV
    from sklearn.compose import make_column_transformer, ColumnTransformer, __
    →make_column_selector
    from sklearn.pipeline import make_pipeline,Pipeline
    from numpy.random import RandomState
    import random
    from numpy import cov
    from sklearn.experimental import
     →enable_iterative_imputer,enable_hist_gradient_boosting
    from sklearn.impute import SimpleImputer, KNNImputer, IterativeImputer
    from sklearn.ensemble import
     \hookrightarrow HistGradientBoostingClassifier,GradientBoostingRegressor
    from xgboost import XGBClassifier, XGBRegressor
```

```
from sklearn.inspection import permutation_importance
    from sklearn.feature_selection import SelectFromModel, SelectKBest, u
     →SelectPercentile, SelectFpr
    from sklearn.tree import DecisionTreeRegressor
    import seaborn as sns
    from sklearn.model selection import StratifiedKFold
    from sklearn.feature_selection import RFECV,RFE
[2]: vehicles = pd.read csv('/Users/racheltan/Desktop/QMSS/AML/vehicles.csv').

¬drop(['url', 'region_url', 'image_url', 'description'], axis = 1)
[7]: len(vehicles)
[7]: 509577
   vehicles.dtypes
[8]: id
                      int64
    region
                     object
    price
                      int64
                    float64
   year
   manufacturer
                     object
   model
                     object
    condition
                     object
    cylinders
                     object
   fuel
                     object
    odometer
                    float64
    title_status
                     object
    transmission
                     object
    vin
                     object
    drive
                     object
    size
                     object
    type
                     object
    paint_color
                     object
    county
                    float64
    state
                     object
    lat
                    float64
                    float64
    long
    dtype: object
[9]: vehicles.head()
[9]:
                           region price
                                             year manufacturer
                                                                       model \
               id
    0 7034441763
                                           2012.0
                   salt lake city
                                   17899
                                                    volkswagen
                                                                      golf r
    1 7034440610
                   salt lake city
                                        0
                                           2016.0
                                                          ford
                                                                       f-150
    2 7034440588
                   salt lake city
                                   46463
                                           2015.0
                                                                sierra 1500
                                                            gmc
    3 7034440546
                   salt lake city
                                        0
                                           2016.0
                                                           ford
                                                                       f-150
    4 7034406932
                                                                       f-450
                   salt lake city 49999
                                           2018.0
                                                           ford
                                 fuel odometer ... transmission \
       condition
                    cylinders
```

```
excellent
                    4 cylinders
                                            63500.0
                                                                 manual
                                      gas
     1 excellent
                             NaN
                                               10.0
                                                             automatic
                                      gas
     2
        excellent
                             NaN
                                      gas
                                             7554.0
                                                      . . .
                                                             automatic
     3
        excellent
                             NaN
                                               10.0
                                                             automatic
                                      gas
                                                      . . .
     4
               NaN
                             NaN
                                  diesel
                                            70150.0
                                                      . . .
                                                             automatic
                       vin drive
                                       size
                                                   type paint_color county
                                                                              state
                                             hatchback
                                                              black
     0
       WVWPF7AJ6CW316713
                              4wd
                                   compact
                                                                        NaN
                                                                                 ut
       1FTMF1EP3GKF13544
                              4wd
                                        NaN
                                                   NaN
                                                                 NaN
     1
                                                                        NaN
                                                                                 ut
     2 3GTU2WEC6FG228025
                              4wd
                                        NaN
                                                   NaN
                                                              white
                                                                        NaN
                                                                                 ut
     3 1FTEX1EF6GKD25447
                              4wd
                                                    NaN
                                                                 NaN
                                        NaN
                                                                        NaN
                                                                                 ut
     4 1FT8W4DT8GEA90427
                              4wd
                                        NaN
                                                pickup
                                                              white
                                                                        NaN
                                                                                 ut
            lat
                     long
     0 40.7372 -111.858
     1 40.5881 -111.884
     2 40.5881 -111.884
     3 40.5881 -111.884
     4 40.3744 -104.694
     [5 rows x 21 columns]
       What we noticed about the data - 43579 rows in the 'price' column are 0 - many missing values
    (NaN) in various columns
[10]: (vehicles['price'] == 0).sum()
[10]: 43579
[11]: vehicles.isnull().sum()
[11]: id
                            0
     region
                            0
     price
                            0
                        1527
     year
                       22764
     manufacturer
     model
                        7989
     condition
                      231934
     cylinders
                      199683
     fuel
                        3985
     odometer
                       92324
     title_status
                        3062
     transmission
                        3719
     vin
                      207425
     drive
                      144143
     size
                      342003
                      141531
     type
     paint_color
                      164706
```

county

state

509577

0

```
lat 10292
long 10292
dtype: int64
```

We drop the rows that do not have price, since we are focusing on cars that are not being given away for free.

```
[3]: vehicles = vehicles.loc[vehicles['price'] != 0]
 [4]: vehicles.isnull().sum()
 [4]: id
                            0
     region
                            0
                            0
     price
     year
                         1511
                        20985
     manufacturer
     model
                         7121
     condition
                       202939
     cylinders
                       180064
     fuel
                         3769
     odometer
                        82717
     title_status
                         2899
     transmission
                         3233
     vin
                       194565
     drive
                       131683
     size
                       310191
     type
                       130311
     paint_color
                       147461
                       465998
     county
     state
                            0
     lat
                         5424
                         5424
     long
     dtype: int64
 [5]: len(vehicles)
 [5]: 465998
[15]: len(vehicles.id.unique())
[15]: 465998
[16]: len(vehicles.vin.unique())
[16]: 162665
```

Leaking Information There are various features that we realise can leak information. 1) idsince the ID for each car is unique, the model could learn the information simply by matching the price of the car to its ID, without generalising, since there would be a strong association between the target column and the id column.

2) vin - vehicle identification numbers are also unique to the cars, and hence is another kind of identification number. There are repeated vins for when the car has been resold or relisted to reach a wider audience (still waiting on an answer as to how to deal with this.

Initial Preprocessing - attempted to convert 'cylinders' into numerical, however some have 'other' cylinders - decided to treat as a categorical variable instead - removed outliers for with very high prices or prices below 100 because they were unlikely, and was severely skewing and affecting the linear models - removed rows where odometer was 1 million miles and more, since even reaching 1 million miles is extremely rare!! (We googled how many miles a car usually drives and only 1 car has ever reached 3 million miles, and very few reach 1 million.) Although this decision removed quite a number of rows, it was necessary given that it was impossible for the car to drive so many miles.

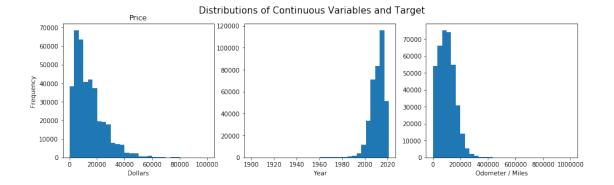
```
[7]: # Removing the outliers:
    print(vehicles.odometer.nlargest(5))
    print(vehicles.price.nlargest(5))
    print(vehicles.price.nsmallest(5))

    vehicles_skew = vehicles[vehicles.price < 100000]
    vehicles_skew = vehicles_skew[vehicles_skew.price > 100]
    vehicles_skew_1 = vehicles_skew[vehicles_skew.odometer <1000000]</pre>
```

```
89496
          10000000.0
89513
          10000000.0
          10000000.0
155140
170043
          10000000.0
81579
           9999999.0
Name: odometer, dtype: float64
345972
          3600028900
264595
          3567587328
473874
          2521176519
190773
          2490531375
353470
          1316134912
Name: price, dtype: int64
481
        1
1493
        1
1494
        1
2075
        1
2556
        1
Name: price, dtype: int64
```

```
[8]: #Length of vehicles
print("length of vehicles:",len(vehicles))
```

```
print("length of vehicles whose 100<price<100000:",len(vehicles_skew))</pre>
     print("length of vehicles ford whose 100<price <100000 and odometer<1000000:
      →",len(vehicles_skew_1))
     #removing outliers for odometer removes 15959 rows, however we have to assume,
      →that the car cannot drive millions of miles and this is probably a mistake of
      \rightarrow in the data.
    length of vehicles: 465998
    length of vehicles whose 100<price<100000: 461148
    length of vehicles_ford whose 100<price <100000 and odometer<1000000: 379641
 [9]: print(vehicles_skew_1.price.nlargest(5))
    125639
              99999
    244136
              99999
    461245
              99999
    128118
              99995
    198034
              99995
    Name: price, dtype: int64
[11]: fig, axes = plt.subplots(1, 3, figsize = (15, 4))
     price, year, odometer = axes.ravel()
     fig.suptitle('Distributions of Continuous Variables and Target', fontsize=15)
     axes[0].hist('price', data = vehicles_skew_1, bins = 30)
     axes[0].set_title('Price')
     axes[0].set_xlabel('Dollars')
     axes[0].set_ylabel('Frequency')
     axes[1].hist('year', data = vehicles_skew_1, bins = 30)
     #axes[1].set title('Year')
     axes[1].set_xlabel('Year')
     #axes[1].set_ylabel('Frequency')
     axes[2].hist('odometer', data = vehicles_skew_1, bins = 30)
     #axes[2].set title('Odometer')
     axes[2].set_xlabel('Odometer / Miles')
     #axes[2].set_ylabel('Frequency')
```



In removing the outliers we could see from our initial visualisations that the distributions were clustered for price below 100000 and for odometer below 1000000, hence we decided to remove outliers outside of this range.

[22]: print(vehicles_skew_1.isnull().sum())

id	0
region	0
price	0
year	1494
manufacturer	13713
model	3839
condition	154318
cylinders	128249
fuel	3717
odometer	0
title_status	2867
transmission	3083
vin	120685
drive	78779
size	244638
type	73732
paint_color	93406
county	379641
state	0
lat	5017
long	5017
dtype: int64	

We do a random subsample for the data to create a smaller dataset of n = 100000

```
[12]: vehicles_sample = vehicles_skew_1.sample(n = 100000, random_state = 123) len(vehicles_sample.manufacturer.unique())
```

[12]: 42

```
[13]: len(vehicles.manufacturer.unique()) #due to the subsample, 2 manufacturers are one of the manufacturers are whose model should be generalizable for the majority of the manufacturers
```

[13]: 44

The features we selected for analysis are - price (target) - condition - cylinders - fuel - odometer - title_status - transmission - drive - type - paint_color - state - manufacturer - model

The variables we dropped that were not useful - id (leaked data) - vin (leaked data) - region (not useful) - size (too many missing values, and similar information is present in 'type' column) - description (not useful) - lat (not useful) - long (not useful) - entry year (not useful)

0.2 Task 2

```
[14]: X = vehicles_sample[['condition',
                   'cylinders', 'fuel', 'odometer', 'title_status',
                    'transmission', 'drive', 'type', 'paint_color', 'state',
                           'model', 'manufacturer']]
     y = vehicles_sample['price']
[15]: X_train, X_test, y_train, y_test = train_test_split(X,y, test_size = 0.2)
[16]: X_train.dtypes
[16]: condition
                      object
     cylinders
                      object
     fuel
                      object
     odometer
                     float64
    title_status
                      object
     transmission
                      object
     drive
                      object
     type
                      object
    paint_color
                      object
                      object
     state
    model
                      object
                      object
     manufacturer
     dtype: object
[17]: categorical = X_train.dtypes == object
[18]: cat_preprocess = make_pipeline(SimpleImputer(strategy='constant',__
      →fill_value='NA'), #making a new category for NA values
                                     OneHotEncoder(handle unknown='ignore'))
     cont_preprocess_scale = make_pipeline(SimpleImputer(),
                                            StandardScaler())
     preprocess_scale = make_column_transformer(
         (cat_preprocess, categorical),
         (cont_preprocess_scale, ~categorical))
```

```
[19]: simple_model = make_pipeline(preprocess_scale, Ridge()) #we achieve our__

_baseline model

score_simple_model = cross_val_score(simple_model, X_train, y_train)

np.mean(score_simple_model)
```

[19]: 0.6367787297858178

0.3 Task 3. Feature Engineering and indepth preprocessing

We made some changes to preprocessing - Used KNNImputer instead of SimpleImputer: Did not help and not advisable for large datasets - Used Random Forest Iterative Imputer instead of Simple Imputer, only a slight improvement to the model - Used target encoding for the 'state' variable, and onehotencoder for the other categorical variables: actually caused the model to be less useful, so reverted back to onehotencoder

```
[20]: cat_preprocess = make_pipeline(SimpleImputer(strategy='constant',__
      →fill_value='NA'), #making a new category for NA values
                                    OneHotEncoder(handle unknown='ignore'))
     cont_preprocess_scale_rf =_
      →make_pipeline(IterativeImputer(estimator=RandomForestRegressor()),
                                            StandardScaler())
     preprocess_scale_target_rf = make_column_transformer(
         (cont_preprocess_scale_rf, ~categorical),
         (TargetEncoder(), ['state']),
         (cat_preprocess, ['condition', 'cylinders', 'fuel', 'title_status', _

→'transmission', 'drive',
                           'type', 'paint_color', 'model', 'manufacturer'])) #not_
      →sure why the accuracy actually decreases with target encoder..
     preprocess scale rf = make column transformer(
         (cont_preprocess_scale_rf, ~categorical),
         (cat preprocess, categorical))
[32]: #using random forest regressor as the imputer
     simple_model_2 = make_pipeline(preprocess_scale_rf, Ridge())
     score_simple_model_2 = cross_val_score(simple_model_2, X_train, y_train)
     np.mean(score_simple_model_2) #doesn't seem to contribute that much to the
      \rightarrowmodel
```

[32]: 0.642546407181241

```
[33]: simple_model_3 = make_pipeline(preprocess_scale_target_rf, Ridge())
score_simple_model_3 = cross_val_score(simple_model_3, X_train, y_train)
np.mean(score_simple_model_3) #target encoding in this case does not seem to_
help the model
```

[33]: 0.3999432220357084

Creating more features may help our model. We use PolynomialFeatures to add interactions between the continuous variables. We also looked at other linear models.

Ridge Model with Polynomial Features: 0.6768870464573238

```
[36]: polyLR_model = make_pipeline(preprocess_scale_poly, LinearRegression())
score_polyLR_model = cross_val_score(polyLR_model, X_train, y_train.values)
print("Linear Regression Model with Polynomial Features:", np.

-mean(score_polyLR_model))
```

Linear Regression Model with Polynomial Features: 0.6669703149854082

```
[37]: polyLs_model = make_pipeline(preprocess_scale_poly, Lasso())
score_polyLs_model = cross_val_score(polyLs_model, X_train, y_train.values)
print("Lasso Model with Polynomial Features:", np.mean(score_polyLs_model))
```

Lasso Model with Polynomial Features: 0.6321636636119524

Using Polynomial Features to create interactions for the continuous variables definitely helps our result! Ridge seems to be the best out of the linear models that we ran.

```
[23]: #gridsearch for Ridge Model which is the best linear model so far

param_grid_ridge = {'ridge__alpha': np.logspace(-3,3,9)}

grid_ridge = GridSearchCV(poly_model, param_grid_ridge, return_train_score = □

→True)

grid_ridge.fit(X_train, y_train.values)

print(grid_ridge.best_params_)

print(grid_ridge.best_score_)
```

```
{'ridge_alpha': 0.1778279410038923}
0.67701948350897
```

[24]: grid_ridge.score(X_test, y_test.values) #final validation on the test set for⊔

→best linear model

```
[24]: 0.6875409145005384
```

```
[25]: best_Ridge = grid_ridge.best_estimator_
```

0.4 Task 4 Any model

i. Adopt Regression Model -SVR and GBR

SVR

SVR Model with Polynomial Features: 0.47666439058087723

Gradient Boosting Regressor

GBR Model with Polynomial Features: 0.6364866973211745

Decision Tree Regressor

DT Model with Polynomial Features: 0.6033433349367916

GBR: best parameters: {'GBR_model__max_depth': 19}

```
DT: best mean cross-validation score: 0.641
DT: best parameters: {'DT_model__max_depth': 18}
```

Applying Gradient Boosting Regressor with gridsearch greatly improves the coefficient to 0.755 with max depth = 17.

```
[29]: gridGBR.score(X_test, y_test) #final validation on test set of best tree based_
→model
```

[29]: 0.7666325899151005

ii. If we were to use a classifier, we could classify the price (y) into 5 categories according to the price hist graph above: 0-20000,40000,60000,80000,>80000 and further applied classification models SVM, Random Forest, Hist Gradient Boosting (question was later clarified to emphasize that we should use regressors - but this is for reference)

```
[39]: cat_y=[]
for i in y:
    if i <=20000:
```

```
cat_y.append(1)
         elif i <=40000:
             cat_y.append(2)
         elif i<=60000:
             cat_y.append(3)
         elif i<=80000:
             cat_y.append(4)
         else: cat_y.append(5)
     #print(cat y)
[40]: cX_train, cX_test, cy_train, cy_test = train_test_split(X,cat_y, test_size = 0.
       SVM
[42]: #given that this is just to demonstrate how we would use a classifier, we
      →reverted back to our simple preprocessing due to
     #considerations for computing times, and LinearSVC had trouble converging with ⊔
      → the polynomial features
     cat preprocess = make pipeline(SimpleImputer(strategy='constant', )
     →fill_value='NA'),
                                    OneHotEncoder(handle_unknown='ignore'))
     cont_preprocess_scale = make_pipeline(SimpleImputer(),
                                           StandardScaler())
     preprocess_scale_poly = make_column_transformer(
         (cat_preprocess, categorical),
         (cont_preprocess_scale, ~categorical))
[43]: LinearSVC_model = make_pipeline(preprocess_scale_poly,__
      →LinearSVC(max_iter=10000))
     score_Lsvm_model = cross_val_score(LinearSVC_model, cX_train, cy_train)
     np.mean(score_Lsvm_model) #doesnt converge with poly features..
[43]: 0.8752125
       Random Forest
[45]: cat_preprocess = make_pipeline(SimpleImputer(strategy='constant',__
      →fill_value='NA'), #making a new category for NA values
                                    OneHotEncoder(handle_unknown='ignore'))
     cont_preprocess = make_pipeline(SimpleImputer())
     preprocess_scale = make_column_transformer(
         (cat preprocess, categorical),
         (cont_preprocess, ~categorical))
     ## Trees are not sensitive to scaler
     RF_model = make_pipeline(preprocess_scale, RandomForestClassifier())
     score_RF_model = cross_val_score(RF_model, cX_train, cy_train)
     np.mean(score_RF_model)
```

[45]: 0.8970500000000001

Hist Gradient Boosting

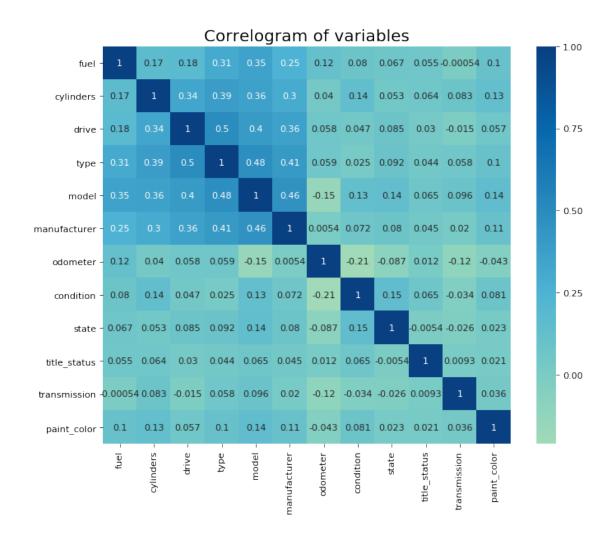
```
[46]: cat_preprocess = make_pipeline(SimpleImputer(strategy='constant',__
      →fill_value='NA'), #making a new category for NA values
                                    TargetEncoder()) # OneHotEncoder cannot be used;
      →here for HGB only adopts dense dataset
     cont_preprocess_scale = make_pipeline(SimpleImputer(),
                                            StandardScaler())
     preprocess_scale = make_column_transformer(
         (cat_preprocess, categorical),
         (cont_preprocess_scale, ~categorical))
[47]: | HGB_model = Pipeline([('preprocess', preprocess_scale),
      →('HGB', HistGradientBoostingClassifier())])
     score_HGB_model = cross_val_score(HGB_model, cX_train, cy_train)
     np.mean(score_HGB_model)
[47]: 0.881775
       XGBClassifier
[48]: XGB_model = Pipeline([('preprocess',preprocess scale), ('XGB',XGBClassifier())])
     score_XGB_model = cross_val_score(XGB_model, cX_train, cy_train)
     np.mean(score_XGB_model)
[48]: 0.8983625
       We choose HGB and XGBClassifier model to tune parameters
[49]: param_HGB = {'HGB_max_depth': np.arange(5,10,2),
                 'HGB_min_samples_leaf':np.arange(20,100,20)}
     gridHGB = GridSearchCV(HGB_model,__
      →param_grid=param_HGB,cv=10,return_train_score=True)
     gridHGB.fit(cX_train, cy_train)
     print("HistGB: best mean cross-validation score: {:.3f}".format(gridHGB.
      →best score ))
     print("HistGB: best parameters: {}".format(gridHGB.best_params_))
    HistGB: best mean cross-validation score: 0.894
    HistGB: best parameters: {'HGB_max_depth': 9, 'HGB_min_samples_leaf': 60}
[50]: param_XGB = {'XGB_max_depth': np.arange(5,10,2),
                 'XGB__subsample': [i / 10.0 for i in range(7, 10)]}
     gridXGB = GridSearchCV(XGB_model,__
      →param_grid=param_XGB,cv=10,return_train_score=True)
     gridXGB.fit(cX_train, cy_train)
```

```
print("XGB: best mean cross-validation score: {:.3f}".format(gridXGB.
       →best_score_))
      print("XGB: best parameters: {}".format(gridXGB.best_params_))
     XGB: best mean cross-validation score: 0.912
     XGB: best parameters: {'XGB__max_depth': 9, 'XGB__subsample': 0.9}
     0.5 Task 5 Feature Selection
     Correlation Here, we use TargetEncoder to encode the categorical data and Scale to standard-
     scale all the variables. And further have a look of the correlation
[329]: X_train, X_test, y_train, y_test = train_test_split(X,y, test_size = 0.2)
      X_train_target=X_train
      print(X_train.dtypes)
      Cat=['condition','cylinders','fuel','title_status','transmission','drive','type','paint_color
     condition
                       object
                       object
     cylinders
     fuel
                       object
     odometer
                      float64
     title_status
                       object
     transmission
                       object
     drive
                       object
                       object
     type
     paint_color
                       object
                       object
     state
     model
                       object
     manufacturer
                       object
     dtype: object
[330]: import warnings
      warnings.filterwarnings('ignore')
      te=TargetEncoder()
      X_train_target.loc[:,Cat]=te.fit_transform(X_train_target.loc[:,Cat],y_train)
      X_train_scaled = scale(X_train_target)
      X_train_scaled = pd.DataFrame(X_train_scaled,columns=X_train_target.columns)
      #X train scaled
[331]: order = np.array(hierarchy.dendrogram(hierarchy.ward(X_train_scaled.

→corr()),no_plot=True)['ivl'], dtype="int")
      X_train_scaled=X_train_scaled.iloc[:,order]
      fig = plt.figure() #figure
      # Plot
      plt.figure(figsize=(10,8), dpi= 80)
```

```
# Decorations
plt.title('Correlogram of variables', fontsize=18)
plt.xticks(fontsize=10)
plt.yticks(fontsize=10)
plt.show()
```

<Figure size 432x288 with 0 Axes>

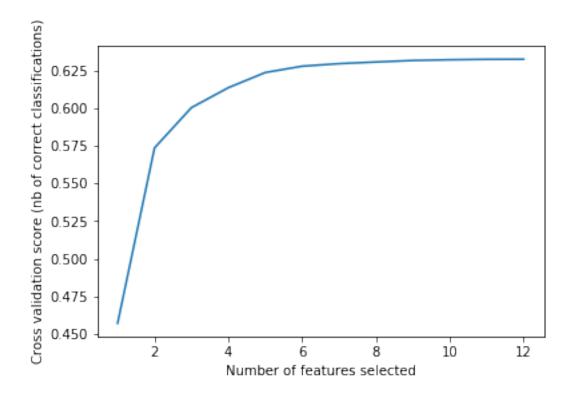


From the graph, we can see that the type, model, manufacturer are somehow correlated (nearly 0.5)

Select from model In this part we try RFECV and RFE to select the feature.

we firstly use RFECV and draw the graph which will help us know how the score goes as the number of features increases. In this part, we adopt Ridge model.

```
[332]: from sklearn.linear_model import Ridge
      Ridge1=Ridge().fit(X_train_scaled, y_train)
      print("Ridge coef (LabelEncoder & scaled):" , Ridge1.coef_)
     Ridge coef (LabelEncoder & scaled): [ 1737.86989427
                                                           259.4965026
     1003.42674329
                     284.39495463
                       233.01536172 -4072.50857233 1140.95240771
       5239.07726188
        747.52912518 445.82300471
                                       91.83825331
                                                     376.769848081
[336]: #from sklearn.model selection import StratifiedKFold
      from sklearn.feature_selection import RFECV,RFE
      #from sklearn.datasets import make_classification
      # Create the RFE object and compute a cross-validated score.
      Ridge1 = Ridge().fit(X_train_scaled, y_train)
      rfecv = RFECV(estimator=Ridge1, step=1)
      rfecv.fit(X_train_scaled, y_train)
      print("Optimal number of features : %d" % rfecv.n_features_)
      print("Ranking of features : %s" % rfecv.ranking_)
      print("Features Selected:" , X_train_scaled.columns[rfecv.support_])
      # Plot number of features VS. cross-validation scores
      plt.figure()
      plt.xlabel("Number of features selected")
      plt.ylabel("Cross validation score (nb of correct classifications)")
      plt.plot(range(1, len(rfecv.grid_scores_) + 1), rfecv.grid_scores_)
      plt.show()
     Optimal number of features : 12
     Ranking of features : [1 1 1 1 1 1 1 1 1 1 1]
     Features Selected: Index(['fuel', 'cylinders', 'drive', 'type', 'model',
     'manufacturer',
            'odometer', 'condition', 'state', 'title_status', 'transmission',
            'paint_color'],
           dtype='object')
```



We find that RFECV chooses all 12 features. However, from the graph we can find that the score changes slowly when the number of features reaches 6. So we can further look into the top 6 features.

Now we choose the TOP 6 features, and have an initial check on the score changes before and after the Feature Selection. (Data preprocess with TargetEncoder and Scale)

```
[343]: np.mean(cross_val_score(Ridge(alpha=1.0), X_train_scaled, y_train, cv=10))
```

```
[343]: 0.6323069328550922
```

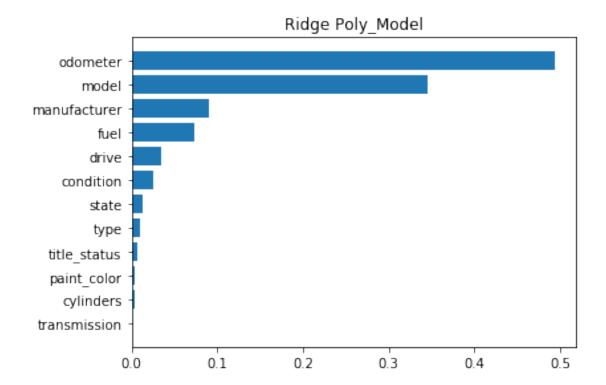
```
[344]: pipe_rfe_ridge = make_pipeline(rfe, Ridge(alpha=1.0))
np.mean(cross_val_score(pipe_rfe_ridge, X_train_scaled, y_train, cv=10))
```

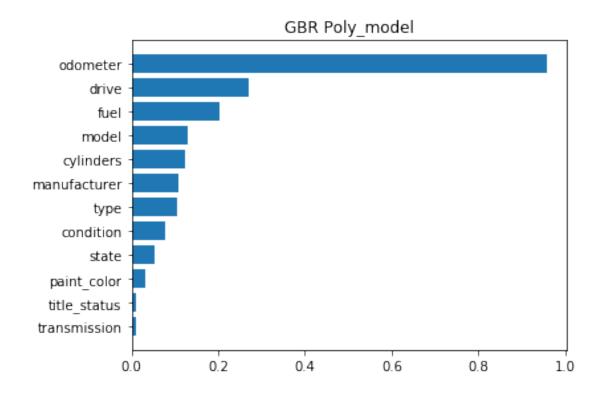
[344]: 0.6276737392442422

These 6 features can explain for the model

Permutation Importance For best regression model: Ridge model and GBR) Furthermore, we try permutation importance on our best models so far: Ridge and GBR, and see how features perform in these models.

Ridge





Feature Selection (Ridge Model/GBR) We apply this question only to our best models

The results of permutation importances is almost the same as the features we selected in the RFE part.

Thus, ['fuel', 'drive', 'model', 'odometer', 'condition', 'state'] are regarded as the most important parameters.

Thus, we select only these 6 parameters in the model and see the model performance for our two best models - Ridge and GBR.

```
preprocess_scale_poly2 = make_column_transformer(
         (cat_preprocess_poly, categorical2),
         (cont_preprocess_scale, ~categorical2))
     #using the same parameters as the best model, the only thing that is changed \Box
     → are the features
    feature_Ridge = Pipeline([('preprocess',preprocess_scale_poly2),_
     →('Ridge',Ridge(alpha = 0.1778279410038923))])
    feature_GBR = Pipeline([('preprocess',preprocess_scale_poly2),__
      [42]: print("original Best Ridge:", np.mean(cross_val_score(best_Ridge, X_train,_
     →y_train.values)))
    original Best Ridge: 0.6784036472138769
[43]: print("original Best Ridge (test):", best_Ridge.score(X_test,y_test))
    original Best Ridge (test): 0.7604959853708043
[44]: print("Feature-Selected Best Ridge:", np.mean(cross_val_score(feature_Ridge,__
      →X train2, y train.values)))
    Feature-Selected Best Ridge: 0.6643325689604389
[45]: feature_Ridge.fit(X_train2, y_train.values)
    print("Feature-Selected Best Ridge (test):", feature_Ridge.score(X_test2, □
      →y_test))
    Feature-Selected Best Ridge (test): 0.6690598468058899
[47]: best_GBR = gridGBR.best_estimator_
    print("original Best GBR:", np.mean(cross_val_score(best_GBR, X_train, y_train.
      →values)))
    original Best GBR: 0.75630409544584
[48]: print("original Best GBR (test):", best_GBR.score(X_test, y_test))
    original Best GBR (test): 0.7666325899151005
[49]: print("Feature-Selected Best GBR:", np.mean(cross_val_score(feature_GBR,__
      →X_train2, y_train.values)))
```

Feature-Selected Best GBR: 0.6954427333458565

```
[50]: feature_GBR.fit(X_train2, y_train.values)
     print("Feature-Selected Best GBR (test):", feature_GBR.score(X_test2, y_test))
```

```
Feature-Selected Best GBR (test): 0.6986352176903936
```

As the comparison of two models showed above, there is a slight drop in performance after the feature selection, and the difference is larger for the Ridge model than the GBR. The drop in performance is to be expected because removing the less important features still means that there is less information for the model to learn. However given that the performance did not drop very drastically, it shows that "fuel", "odometer", "drive", "model", "condition", "state" are the primary parameters.

0.5.1 Task 6 An explainable model

We attempt an explainable tree model

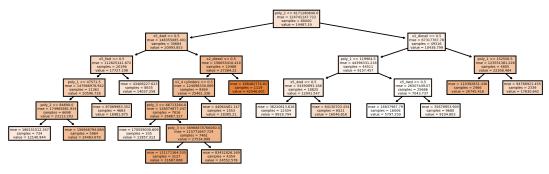
A decision tree regressor with a small max depth will act as an explainable model because it is easy to plot. We could run the regressor with feature selection or without to compare.

```
[36]: categorical = X_train.dtypes == object
     cat_preprocess_poly = make_pipeline(SimpleImputer(strategy='constant',__

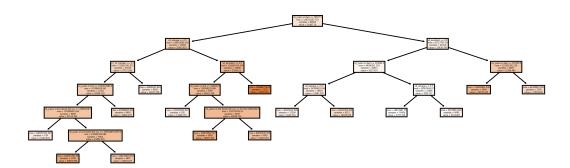
→fill_value='NA'),
                                    OneHotEncoder(handle_unknown='ignore'))
     cont_preprocess =_
      →make_pipeline(IterativeImputer(estimator=RandomForestRegressor()),
                                           poly) #trees not sensitive to scale
     preprocess_scale = make_column_transformer(
         (cat_preprocess_poly, categorical),
         (cont_preprocess, ~categorical))
     categorical2 = X_train2.dtypes == object
     preprocess_scale2 = make_column_transformer(
         (cat_preprocess_poly, categorical2),
         (cont_preprocess, ~categorical2))
[37]: | ## DT_model with limited leaf nodes, but all the features
     DT_model2 = make_pipeline(preprocess_scale,_
      →DecisionTreeRegressor(max_leaf_nodes = 15))
     score_DT_model2 = cross_val_score(DT_model2, X_train, y_train)
     np.mean(score_DT_model2)
[37]: 0.5033505009778759
```

```
[38]: ## DT model with limited leaf nodes and feature selection
     DT_model3 = make_pipeline(preprocess_scale2,_
     →DecisionTreeRegressor(max_leaf_nodes = 15))
     score_DT_model3= cross_val_score(DT_model3, X_train2, y_train)
     np.mean(score_DT_model3)
```

[38]: 0.49864061713912095



```
[54]: ## plot of DTmodel with feature selection
from sklearn.tree import plot_tree
plt.figure(figsize=(10, 3), dpi=300)
tree_dot = plot_tree(plot_model3[1], feature_names = featurenames, filled=True)
```



From out previous exploration, we already know that a DecisionTreeRegressor of max_depth = 18 is the best performing decision tree, with a score of 0.641. We also know that our best GBR

model reached a score of 0.755 with max_depth = 17, although this is not easily explainable given that GBR builds an additive model.

Although we tried different parameters, in order to create an explainable model, max_depth should be around 3 or max_leaf_nodes around 10-20. This however caused a drop in the performance of the model to 0.50 and as such the model was not nearly as good as our best model. It is possible that explainability comes at the cost of model performance.

For a decision tree model, reducing the number of features does not really help with explainability since the explainability depends on having a smaller number of leaves, hence it seems best to use the decision tree with the full features to achieve the best performance with limited leaves.

[]: