```
Q2:

E + S \xrightarrow{k_1} ES \xrightarrow{k_2} E+P

[Ex]-[x] [s] \xrightarrow{k_1} ES \xrightarrow{k_2} E+P

8.1: Based on mass action, we can describe the rate of change of each following substance:

\frac{d[s]}{dt} = k_2 [ES] - k_1 [S] [E]
\frac{d[ES]}{dt} = (k_2 + k_2) [ES] - [LS] [E]
\frac{d[ES]}{dt} = k_1 [S] [E] - (k_2 + k_2) [ES]
\frac{d[P]}{ot} = k_2 [ES]
```

8.2:

Source code using MATLAB: It consists of two parts: the main function RK4 is used for iterative solving, and the subfunction f is used for storing differential equations.

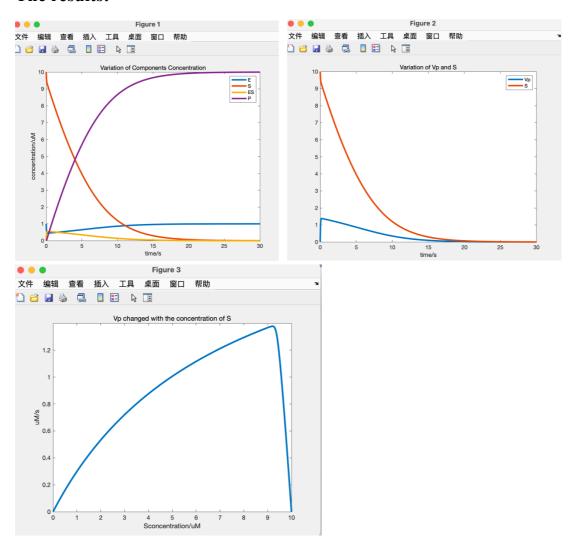
RK4.m:

```
function RK4
clear;clc;
% define initial values
E0=1;
k3=150/60;
% define step width and initial values of ES,S
h=0.001;
             % step width is 0.001s
t=0:h:30;
              % range is 0-30s
n=length(t); % quantity of t
Y(1,1)=0;
             % initial values of ES put in matrix Y
               % initial values of S put in matrix Y
Y(2,1)=10;
% define RK4 to find out the solution of S and ES
for k=1:n-1
   z1=f(t(k),Y(1:2,k)); % Y(1:2,k) means take the 1st and 2nd row of
kth line
   z2=f(t(k)+h/2,Y(1:2,k)+z1*h/2);
   z3=f(t(k)+h/2,Y(1:2,k)+z2*h/2);
   z4=f(t(k)+h,Y(1:2,k)+z3*h);
   Y(1:2,k+1)=Y(1:2,k)+h*(z1+2*z2+2*z3+z4)/6; % iteration of Y
                                        % new ES/S will be added into
matrix Y
                                       % ES to the 1st row, S to the
2nd row
end
```

```
ES=Y(1,:); % Y's 1st row
S=Y(2,:); % Y's 2nd row
%solution to E and P
E=E0-ES;
for i=1:1:n % initial value: step width: final value
   P(i)=k3*sum(ES(1:i))*h; % P is the integration of ES, ES is
discrete
                       P(0) = 0
                       % so Pi is the sumption of ES1-ESi * step wid
end
Vp=k3.*ES; % Vp is the change rate of P
        % n2.means conduct every element in matrix
% plot
figure(1); % 1st picture
plot(t,E,t,S,t,ES,t,P,'LineWidth',3); % x:t y:E,S,ES,P
legend('E','S','ES','P');
title('Variation of Components Concentration');
xlabel('time/s');
ylabel('concentration/uM');
figure(2); % 2nd picture
plot(t,Vp,t,S,'LineWidth',3); % x:t y:Vp,S
legend('Vp','S');
title('Variation of Vp and S');
xlabel('time/s');
figure(3); % 3rd picture
plot(S,Vp,'LineWidth',3); % x:s y:Vp
title('Vp changed with the concentration of S');
xlabel('Sconcentration/uM');
ylabel('uM/s');
end
f.m:
function F=f(t,Y)
% input t and matrix Y
% define variables
k1=100/60;
k2=600/60;
```

```
k3=150/60;
E0=1;
theta=k2+k3;
lamda=k1*E0;
% define the equation we want to solve
ES=Y(1,1); % Y is a 1*2 matrix
S=Y(2,1);
f1=lamda*S-(theta+k1*S)*ES; % equation of dES/dt
f2=-lamda*S+(k1*S+k2)*ES; % equation of dS/dt
F=[f1;f2]; % output of F is a matrix contain f1(ES) and f2(S) end
```

The results:



Notes: The above code borrows from:

https://blog.csdn.net/Tonyslp/article/details/122619031

