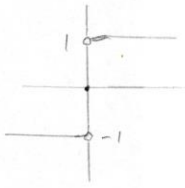


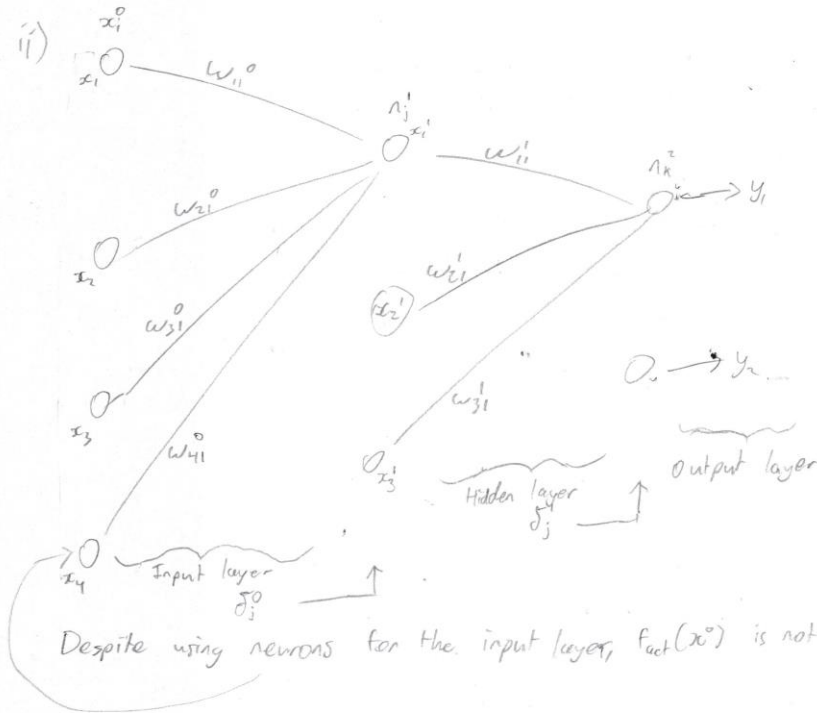
# Assignment 3

i)



$$\hat{y}_k = f_{SHL}(v_k + b_k) = \begin{cases} -1 & \text{if } v_k + b_k < 0 \\ 0 & \text{if } v_k + b_k = 0 \\ 1 & \text{if } v_k + b_k > 0 \end{cases}$$

ii)



• = dot multiply,  $X^T$  = transpose(X), \* = cross product/ matrix multiplication (\* in matlab)

$$\text{iii) } x_I^T \cdot w_{IJ} = z_J \\ = [-1 \ -1 \ 0 \ 0] * \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} = [-2 \ -1 \ -2] \quad f_{act}(z_J) = x_J^T = [-1 \ -1 \ 1]$$

$$x_J^T \cdot w_{JK} = z_K \\ = [-1 \ -1 \ 1] * \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix} = [-2 \ -3] \quad f_{act}(z_K) = y_L^T = [-1 \ -1]$$

$$\text{iv) } \delta_j^1 = y_L(1 - y_L)(d_L - y_L) \\ = [-1] \cdot [1 \ -1] \cdot [1 \ -1] = [-1] \cdot [2] \cdot [2] = [-4]$$

$$\text{v) } w_{JK}^{new} = w_{JK}^{old} + h \delta_j^1 x_j^1 \quad (\text{for matrix multiplication, use } x_j^1 * \delta_j^{1T}) \\ = \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix} + \begin{bmatrix} .5 & .25 \\ .5 & .25 \\ .5 & .25 \end{bmatrix} = \begin{bmatrix} 0.5 & 1.25 \\ 1.5 & 1.25 \\ 1.5 & 1.25 \end{bmatrix}$$

$$\text{vi) } \delta_i^0 = x_j^1 \cdot (1 - x_j^1) \cdot (w_{JK} * \delta_j^1) \\ = \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 0.5 & 1.25 \\ 1.5 & 1.25 \\ 1.5 & 1.25 \end{bmatrix} * \begin{bmatrix} -4 \\ -2 \end{bmatrix} = \begin{bmatrix} 9 \\ 17 \\ 17 \end{bmatrix}$$

$$\text{vii) } w_{IJ}^{new} = w_{IJ}^{old} + h \delta_i^0 x_i^0 \quad \text{Again, vectorise with } x_i^0 * \delta_i^{0T} \\ = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} + \begin{bmatrix} -1.125 & -2.125 & -2.125 \\ -1.125 & -2.125 & -2.125 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} -0.125 & -2.125 & -1.125 \\ -0.125 & -1.125 & -1.125 \\ 1 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$