

# Deep Generative Models: Continuous Latent Variables

Philip Schulz and Wilker Aziz

[https:  
//github.com/philschulz/VITutorial](https://github.com/philschulz/VITutorial)

## Deep Generative Models

First Attempt: Wake-Sleep

This is how we do: Variational Autoencoders

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# Generative Models

Joint distribution over observed data  $x$  and latent variables  $Z$ .

$$p(x, z|\theta) = \underbrace{p(z)}_{\text{prior}} \underbrace{p(x|z, \theta)}_{\text{likelihood}}$$

The likelihood and prior are often standard distributions (Gaussian, Bernoulli) with simple dependence on conditioning information.

# Deep generative models

Joint distribution with **deep observation model**

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Marginal likelihood

$$p(x|\theta) = \int p(x, z|\theta) \, dz = \int p(z)p(x|z, \theta) \, dz$$

**intractable** in general

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We need **approximate inference** techniques!

## Deep Generative Models

### First Attempt: Wake-Sleep

This is how we do: Variational Autoencoders

# Wake-sleep Algorithm

- ▶ Generalise latent variables to Neural Networks
- ▶ Train generative neural model
- ▶ Use variational inference! (kind of)

# Wake-sleep Architecture

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- ▶ An inference (recognition) network (to model the latent variable) – parameters:  $\lambda$
- ▶ Original setting: binary hidden units
- ▶ Training is performed in a “hard EM” fashion

# Wake-sleep Training

## Wake Phase

- ▶ Use inference network to sample hidden unit setting  $z$  from  $q(z|x, \lambda)$
- ▶ Update generation parameters  $\theta$  to maximize likelihood of data given latent state  $p(x|z, \theta)$

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## Sleep Phase

- ▶ Produce dream sample  $\tilde{x}$  from random hidden unit  $z$
- ▶ Update inference parameters  $\lambda$  to maximize probability of latent state  $q(z|\tilde{x}, \lambda)$

# Wake Phase Objective

Assumes latent state  $z$  to be fixed random draws from  $q(z|x, \lambda)$ .

$$\max_{\theta} \mathbb{E}_{q(z|x, \lambda)} [\log p(z, x|\theta)] + \mathbb{H}[q(z|x, \lambda)]$$

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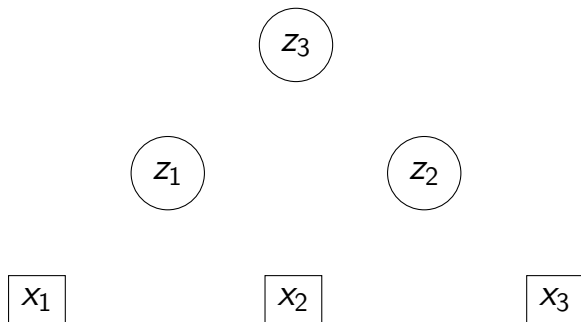
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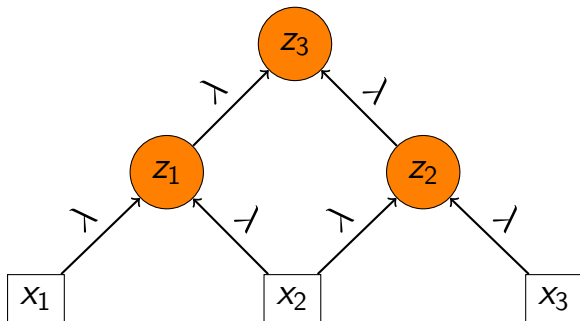
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This is simply supervised learning with imputed latent data!

# Wake Phase Sampling

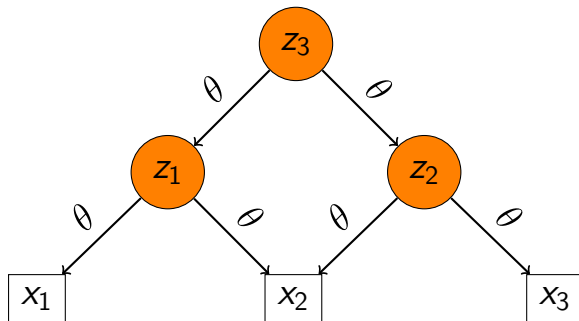


# Wake Phase Sampling





# Wake Phase Update



# Sleep Phase Objective

Assumes fake data  $\tilde{x}$  and latent variables  $z$  to be fixed random draw from  $p(x, z|\theta)$ .

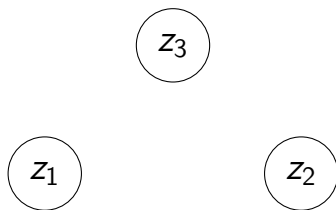
$$\max_{\lambda} \mathbb{E}_{p(\tilde{x}, z|\theta)} [\log q(z|\tilde{x}, \lambda)] + \mathbb{E}_{p(\tilde{x})} [\mathbb{H}(p(z|\tilde{x}, \theta))]$$

# Sleep Phase Objective

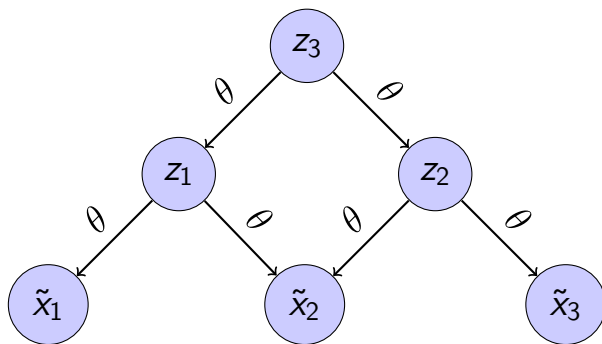
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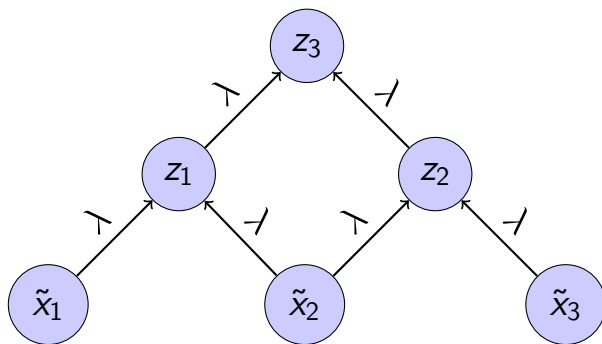
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# Wake-sleep Algorithm

## Advantages

- ▶ Simple layer-wise updates
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- ▶ Simple layer-wise updates
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## Drawbacks

- ▶ Inference and generative networks are trained on different objectives
- ▶ Inference weights  $\lambda$  are updated on fake data  $\tilde{x}$
- ▶ Generative weights are bad initially, giving wrong signal to the updates of  $\lambda$



## Deep Generative Models

First Attempt: Wake-Sleep

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# Generative Model with NN Likelihood

## Goal

Define model  $p(x, z|\theta) = p(x|z, \theta)p(z)$  where the likelihood  $p(x|z, \theta)$  is given by a neural network.  
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## Problem

$p(x) = \int \underbrace{p(x|z, \theta)}_{\substack{\text{highly} \\ \text{non-linear!}}} p(z) dz$  is hard to compute.

# Solution: Variational Inference

$$\log p(x|\theta) \geq \overbrace{\mathbb{E}_{q(z|x, \lambda)} [\log p(x, Z|\theta)] + \mathbb{H}(q(z|x, \lambda))}^{\text{ELBO}}$$

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- ▶ assume  $\text{KL}(q(z|x, \lambda) || p(z))$  analytical true for exponential families
- ▶ approximate  $\mathbb{E}_{q(z|x,\lambda)} [\log p(x|z, \theta)]$  by sampling feasible because  $q(z|x, \lambda)$  is simple

# Generator Network Gradient

$$\frac{d}{d\theta} \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \overbrace{\text{KL}(q(z|x, \lambda) || p(z))}^{\text{constant}}$$

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 &= \mathbb{E}_{q(z|x, \lambda)} \left[ \frac{d}{d\theta} \log p(x|z, \theta) \right] \\
 &\stackrel{\text{MC}}{\approx} \frac{1}{S} \sum_{i=1}^S \frac{d}{d\theta} \log p(x|z_i, \theta)
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 \end{aligned}$$

Note:  $q(z|x, \lambda)$  does not depend on  $\theta$ .

# Inference Network Gradient

$$\frac{d}{d\lambda} \left[ \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \text{KL} (q(z|x, \lambda) || p(z)) \right]$$

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The first term again requires approximation by  
sampling

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Not an expected gradient!

# Inference Network Gradient

## Reparametrisation trick

Find a transformation  $h : z \mapsto \epsilon$  such that  $\epsilon$  does not depend on  $\lambda$ .

- ▶  $h(z, \lambda)$  needs to be invertible
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- ▶  $h(z, \lambda) = \epsilon$
- ▶  $h^{-1}(\epsilon, \lambda) = z$

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## Gaussian transformation

$$h(z, \lambda) = \frac{z - \mu(\phi, \lambda)}{\sigma(\phi, \lambda)} = \epsilon \sim \mathcal{N}(0, I)$$

$$\underbrace{h^{-1}(\epsilon, \lambda)}_{=z} = \mu(\phi, \lambda) + \sigma(\phi, \lambda) \odot \epsilon \quad \epsilon \sim \mathcal{N}(0, I)$$

# Inference Network Gradient

$$= \frac{d}{d\lambda} \int q(z|x, \lambda) \log p(x|z, \theta) dz$$

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$$\begin{aligned} &= \frac{d}{d\lambda} \int q(z|x, \lambda) \log p(x|z, \theta) dz \\ &= \frac{d}{d\lambda} \int q(\epsilon) \log \left( p(x | \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}, \theta) \right) d\epsilon \end{aligned}$$

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 &= \int q(\epsilon) \frac{d}{d\lambda} \left[ \log p(x | \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}, \theta) \right] d\epsilon
 \end{aligned}$$

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# Derivatives of Gaussian transformation

Recall:

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$$\frac{dh^{-1}(\epsilon, \lambda)}{d\mu(\phi, \lambda)} = \frac{d}{d\mu(\phi, \lambda)} [\mu(\phi, \lambda) + \sigma(\phi, \lambda) \odot \epsilon] = 1$$

$$\frac{dh^{-1}(\epsilon, \lambda)}{d\sigma(\phi, \lambda)} = \frac{d}{d\sigma(\phi, \lambda)} [\mu(\phi, \lambda) + \sigma(\phi, \lambda) \odot \epsilon] = \epsilon$$

# Gaussian KL

## ELBO

$$\mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \text{KL} (q(z|x, \lambda) || p(z))$$

# Gaussian KL

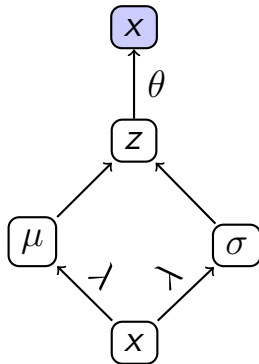
## ELBO

$$\mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \text{KL} (q(z|x, \lambda) \parallel p(z))$$

Analytical computation of  $-\text{KL} (q(z|x, \lambda) \parallel p(z))$ :

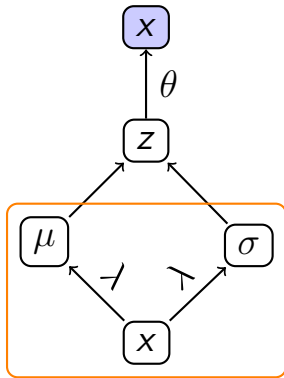
$$\frac{1}{2} \sum_{i=1}^N (1 + \log (\sigma_i^2) - \mu_i^2 - \sigma_i^2)$$

# Computation Graph



# Computation Graph

inference model

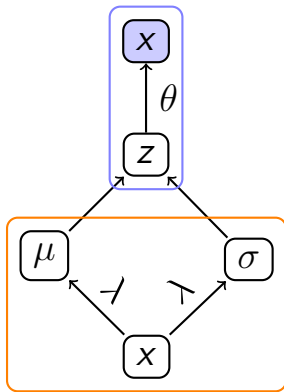




# Computation Graph

generation model

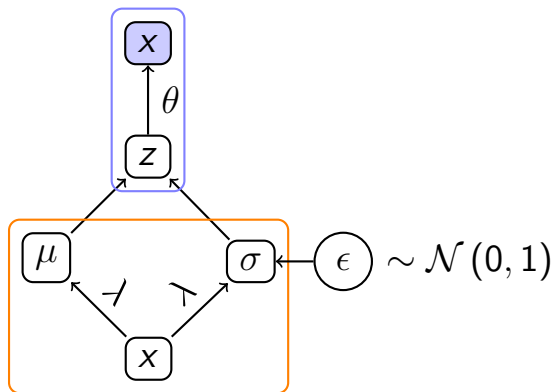
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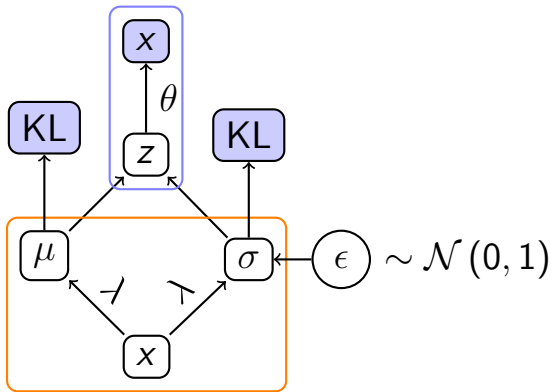
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# Computation Graph

generation model

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# Example

- ▶ Data: binary mnist
- ▶ Likelihood: product of Bernoullis
  - ▶ Let  $\phi = \sigma(\text{NN}(z))$
  - ▶  $\prod_{i=1}^N p(x_i|\phi) = \prod_{i=1}^N \phi^{x_i} \times (1 - \phi)^{1-x_i}$
- ▶ Prior over  $z$ :  $\mathcal{N}(0, 1)$
- ▶  $q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$
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- ▶  $\sigma(x, \lambda) = \text{NN}_{\sigma}(x; \lambda)$

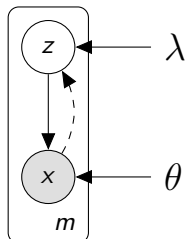
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- ▶  $\sigma(x, \lambda) = \text{NN}_\sigma(x; \lambda)$

## Mean Field assumption

Variational approximation factorises over latent dimensions.

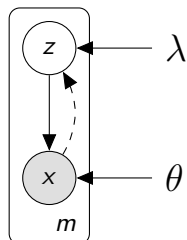
# Graphical Model



- approximate posterior

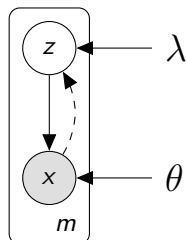
$$q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$$

# Graphical Model



- ▶ approximate posterior  
 $q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$
- ▶ where
  - ▶  $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$   
 e.g.  $\mu(x, \lambda) = W^{(u)}x + b^{(u)}$

# Graphical Model



- ▶ approximate posterior

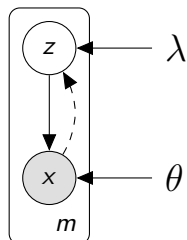
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- ▶ where

- ▶  $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$   
e.g.  $\mu(x, \lambda) = W^{(u)}x + b^{(u)}$
- ▶  $\sigma(x, \lambda) = \exp(\text{NN}_{\sigma}(x; \lambda))$   
e.g.  $\sigma(x, \lambda) = \log(1 + \exp(W^{(v)}x + b^{(v)}))$



# Graphical Model



- approximate posterior

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- $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$   
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- $\sigma(x, \lambda) = \exp(\text{NN}_{\sigma}(x; \lambda))$   
e.g.  $\sigma(x, \lambda) = \log(1 + \exp(W^{(v)}x + b^{(v)}))$
- $\lambda = (W^{(u)}, W^{(v)}, b^{(u)}, b^{(v)})$

# Aside

If your likelihood model is able to express dependencies between the output variables (e.g. an RNN), the model may simply ignore the latent code. In that case one often scales the KL term. The scale factor is increased gradually.

$$\mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \beta \text{KL} (q(z|x, \lambda) || p(z))$$

where  $\beta \rightarrow 1$ .

# Variational Autoencoder

## Advantages

- ▶ Backprop training
- ▶ Easy to implement
- ▶ Posterior inference possible
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# Variational Autoencoder

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- ▶ Backprop training
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## Drawbacks

- ▶ Discrete latent variables are difficult
- ▶ Optimisation may be difficult with several latent variables

# Summary

- ▶ Wake-Sleep: train inference and generation networks with separate objectives
- ▶ VAE: train both networks with same objective
- ▶ Reparametrisation
  - ▶ Transform parameter-free variable  $\epsilon$  into latent value  $z$
  - ▶ Update parameters with stochastic gradient estimates

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