

# Deep Generative Models

Philip Schulz and Wilker Aziz

# Generative Models

First Attempt: Log-linear Models

Second Attempt: Wake-Sleep

This is how we do: Variational Autoencoders

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# Recap: Generative Models

Joint distribution over observed data  $x$  and latent variables  $Z$ .

$$p(x, z|\alpha) = \overbrace{p(x|z, \alpha)}^{\text{likelihood}} \underbrace{p(z|\alpha)}_{\text{prior}}$$

The likelihood and prior are often standard distributions (Gaussian, Bernoulli) with simple dependence on conditioning information.

# Recap: Variational Inference

## Objective

$$\max_{q(z)} \mathbb{E} [\log p(x, z)] + \mathbb{H}(q(z))$$

- ▶ The ELBO is a lower bound on  $\log p(x)$
- ▶ Mean field assumption:  $q(z) = \prod_{i=1}^N q(z_i)$

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# Feature-rich Generative Models

Let us assume that  $z$  has internal structure (features). How can we exploit that?

## First Idea

Make  $p(x|z, \alpha)$  a log-linear model.

- ▶ Only discrete data
- ▶ Trainable with EM if we can efficiently enumerate  $\mathcal{X}$  and  $\mathcal{Z}$ .

# Log-linear Model

Let us treat  $z$  as observed.

$$p(x|z, \alpha = w) = \frac{\exp(w^\top f(x, z))}{\sum_{x \in \mathcal{X}} \exp(w^\top f(x, z))}$$



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## Weight Gradient

$$\frac{d}{dw} \log p(x|z, w) = f(x, z) - \mathbb{E}[f(X, z)|z, w]$$

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Updates need to be performed iteratively.

# Log-linear model with latent variables

Now let us treat  $z$  as latent.

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## Model

$$p(x, z|w) = \underbrace{\frac{\exp(w^\top f(x, z))}{\sum_{x \in \mathcal{X}} \exp(w^\top f(x, z))}}_{p(x|z, w)} \times \underbrace{p(z)}_{\text{arbitrary}}$$

# Log-linear model with latent variables

## Posterior

$$\begin{aligned} p(z|x, w) &= \frac{p(x, z|w)}{p(x|w)} = \frac{p(x, z|w)}{\sum_z p(x, z|w)} = \\ &= \frac{\frac{\exp(w^\top f(x, z))}{\sum_{x \in \mathcal{X}} \exp(w^\top f(x, z))} \times p(z)}{\sum_z \frac{\exp(w^\top f(x, z))}{\sum_{x \in \mathcal{X}} \exp(w^\top f(x, z))} \times p(z)} \end{aligned}$$

# Log-linear model with latent variables

## Weight Gradient

$$\begin{aligned}\frac{d}{dw} \mathbb{E}_{p(z|x, w)} [\log p(x, z|w)] &= \\ \frac{d}{dw} \sum_z p(z|x, w) \log p(x, z|w) &= \\ \sum_z p(z|x, w) \frac{d}{dw} \log p(x, z|w)\end{aligned}$$

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# Log-linear model with latent variables

## Weight Gradient

$$\begin{aligned} \frac{d}{dw} \mathbb{E}_{p(z|x,w)} [\log p(x, z|w)] = \\ \mathbb{E}_{p(z|x,w)} [f(x, Z)|x, w] - \mathbb{E}_{p(z|x,w)} [\mathbb{E} [(f(X, Z)|Z, w)] \end{aligned}$$



# Log-linear model with latent variables

## Weight Gradient

$$\frac{d}{dw} \mathbb{E}_{p(z|x,w)} [\log p(x, z|w)] =$$

$$\mathbb{E}_{p(z|x,w)} [f(x, Z)|x, w] - \mathbb{E}_{p(z|x,w)} [\mathbb{E} [(f(X, Z)|Z, w)]]$$

## Procedurally

$$E\_count(x, z) - E\_count(x, z) \times \mathbb{E} [X|z, w]$$

# EM

**E-step**  $p(z|x, w) = \frac{p(x, z|w)}{\sum_z p(x, z|w)}$  in  $\mathcal{O}(|\mathcal{X}| \times |\mathcal{Z}|)$

**M-step** Iteratively optimise  $w$  to match  $\text{E\_count}(x, z)$   
with  $\text{E\_count}(x, z) \times \mathbb{E}[X|z, w]$

## Restrictions

- ▶ Only log-linear models
- ▶ Scales badly

# Generative Models

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Second Attempt: Wake-Sleep

This is how we do: Variational Autoencoders

# Wake-sleep Algorithm

- ▶ Generalise latent variables to Neural Networks
- ▶ Train generative neural model
- ▶ Use variational inference! (kind of)

# Wake-sleep Architecture

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- ▶ Original setting: binary hidden units



# Wake-sleep Architecture

## 2 Neural Networks:

- ▶ A generation network to model the data (the one we want to optimise) – parameters:  $\theta$
- ▶ An inference (recognition) network (to model the latent variable) – parameters:  $\lambda$
- ▶ Original setting: binary hidden units
- ▶ Training is performed in a “hard EM” fashion

# Wake-sleep Training

## Wake Phase

- ▶ Use inference network to sample hidden unit setting  $z$  from  $q(z|x, \lambda)$
- ▶ Update generation parameters  $\theta$  to maximize likelihood of data given latent state  $p(x|z, \theta)$

# Wake-sleep Training

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- ▶ Use inference network to sample hidden unit setting  $z$  from  $q(z|x, \lambda)$
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## Sleep Phase

- ▶ Produce dream sample  $\tilde{x}$  from random hidden unit  $z$
- ▶ Update inference parameters  $\lambda$  to maximize probability of latent state  $q(z|\tilde{x}, \lambda)$

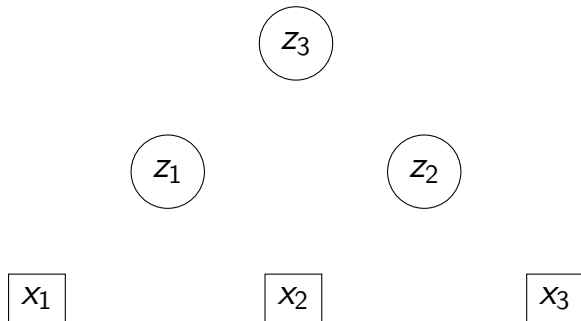
# Wake Phase Objective

Assumes latent state  $z$  to be fixed random draws from  $q(z|x, \lambda)$ .

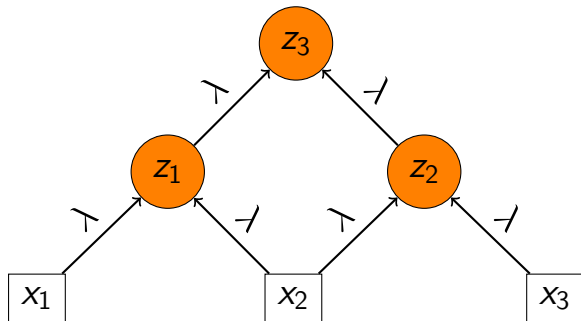
$$\max_{\theta} \log p(x|z, \theta)$$

This is simply supervised learning with imputed latent data!

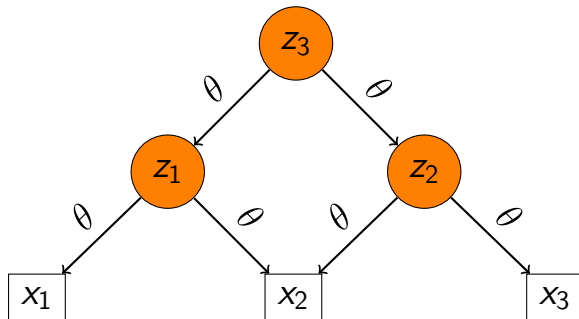
# Wake Phase Sampling



# Wake Phase Sampling



# Wake Phase Update



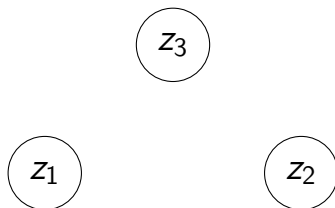
# Sleep Phase Objective

Assumes fake data  $\tilde{x}$  and latent variables  $z$  to be fixed random draw from  $p(x, z|\theta)$ .

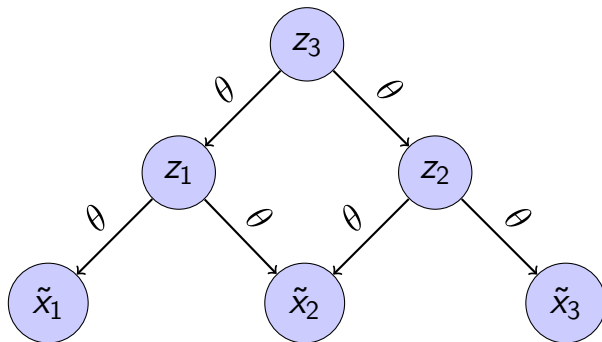
$$\min_{\lambda} \mathbb{E}_{q(z|\tilde{x}, \lambda)} [\log p(\tilde{x}, z|\theta)] + \mathbb{H}(q(z|\tilde{x}, \lambda))$$



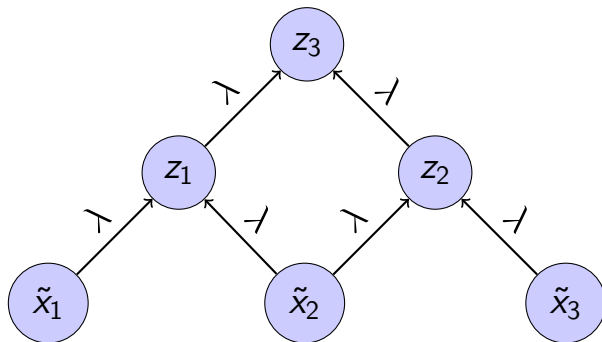
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# Sleep Phase Update



# Wake-sleep Algorithm

## Advantages

- ▶ Simple layer-wise updates
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## Drawbacks

- ▶ Inference and generative networks are trained on different objectives
- ▶ Inference weights  $\lambda$  are updated on fake data  $\tilde{x}$
- ▶ Generative weights are bad initially, giving wrong signal to the updates of  $\lambda$

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# Generative Model with NN Likelihood

## Goal

Define model  $p(x, z|\theta) = p(x|z, \theta)p(z)$  where the likelihood  $p(x|z, \theta)$  is given by a neural network.  
(We fix  $p(z)$  for simplicity.)

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$p(x) = \int p(x|z, \theta)p(z)dz$  is hard to compute.



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(We fix  $p(z)$  for simplicity.)

## Problem

$p(x) = \int \underbrace{p(x|z, \theta)}_{\substack{\text{highly} \\ \text{non-linear!}}} p(z) dz$  is hard to compute.

# Generative Model with NN Likelihood

Solution: VI

$$\log p(x) \geq \overbrace{\mathbb{E}_{q(z|x, \lambda)} [\log p(x, z|\theta)]}^{\text{ELBO}} + \mathbb{H}(q(z|x, \lambda))$$

# Generative Model with NN Likelihood

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 &= \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)p(z)] + \mathbb{H}(q(z|x, \lambda)) \\
 &= \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \underbrace{\text{KL}(p(z) \parallel q(z|x, \lambda))}_{\substack{\text{assume analytical} \\ \text{(true for exponential families)}}}
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 &= \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)p(z)] + \mathbb{H}(q(z|x, \lambda)) \\
 &= \underbrace{\mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)]}_{\text{approximate by sampling}} - \underbrace{\text{KL}(p(z) \parallel q(z|x, \lambda))}_{\substack{\text{assume analytical} \\ \text{(true for exponential families)}}}
 \end{aligned}$$

# Generation Network Gradient

$$\frac{d}{d\theta} \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \overbrace{\text{KL} (p(z) \parallel q(z|x, \lambda))}^{\text{constant}}$$

# Generation Network Gradient

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# Generation Network Gradient

$$\begin{aligned}
 & \frac{d}{d\theta} \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \overbrace{\text{KL}(p(z) \parallel q(z|x, \lambda))}^{\text{constant}} \\
 &= \mathbb{E}_{q(z|x, \lambda)} \left[ \frac{d}{d\theta} \log p(x|z, \theta) \right] \\
 &\approx_{\text{MC}} \frac{1}{S} \sum_{i=1}^S \frac{d}{d\theta} \log p(x|z_i, \theta)
 \end{aligned}$$

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 \end{aligned}$$

Note:  $q(z|x, \lambda)$  does not depend on  $\theta$ .

# Inference Network Gradient

$$\frac{d}{d\lambda} \left[ \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] - \text{KL} (p(z) \parallel q(z|x, \lambda)) \right]$$

# Inference Network Gradient

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 \end{aligned}$$

The first term again requires approximation by  
sampling

# Inference Network Gradient

$$\begin{aligned} & \frac{d}{d\lambda} \mathbb{E}_{q(z|x, \lambda)} [\log p(x|z, \theta)] \\ &= \frac{d}{d\lambda} \int q(z|x, \lambda) \log p(x|z, \theta) dz \end{aligned}$$

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MC estimator non-differentiable

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MC estimator non-differentiable

- ▶ Sampling  $z$  neglects  $\frac{d}{d\lambda} q(z|x, \lambda)$



# Inference Network Gradient

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## MC estimator non-differentiable

- ▶ Sampling  $z$  neglects  $\frac{d}{d\lambda} q(z|x, \lambda)$
- ▶ Differentiating  $q(z|x, \lambda)$  breaks the expectation

# Inference Network Gradient

$$= \frac{d}{d\lambda} \int q(z|x, \lambda) \log p(x|z, \theta) dz$$

# Inference Network Gradient

$$\begin{aligned} &= \frac{d}{d\lambda} \int q(z|x, \lambda) \log p(x|z, \theta) dz \\ &= \frac{d}{d\lambda} \int q(\epsilon) \log p(x | \overbrace{h(\epsilon, \lambda)}^{=z}, \theta) d\epsilon \end{aligned}$$

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 &= \frac{d}{d\lambda} \int q(z|x, \lambda) \log p(x|z, \theta) dz \\
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 &= \int q(\epsilon) \frac{d}{d\lambda} \log p(x | h(\epsilon, \lambda), \theta) \times \frac{d}{d\lambda} h(\epsilon, \lambda) d\epsilon
 \end{aligned}$$

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 &= \mathbb{E}_{p(\epsilon)} \left[ \frac{d}{d\lambda} \log p(x|h(\epsilon, \lambda), \theta) \times \frac{d}{d\lambda} h(\epsilon, \lambda) \right]
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 &= \mathbb{E}_{p(\epsilon)} \left[ \frac{d}{d\lambda} \log p(x|h(\epsilon, \lambda), \theta) \times \frac{d}{d\lambda} h(\epsilon, \lambda) \right] \\
 &\stackrel{\text{MC}}{\approx} \frac{1}{S} \sum^S \frac{d}{d\lambda} \log p(x|h(\epsilon_i, \lambda), \theta) \times \frac{d}{d\lambda} h(\epsilon, \lambda)
 \end{aligned}$$

# Reparametrisation Trick

- ▶ Find transformation  $h(\epsilon, \lambda)$  of parameter-free variable  $\epsilon$
- ▶  $h(\epsilon, \lambda)$  needs to be invertible



# Gaussian Transformation

## Affine property

$$Ax + b \sim \mathcal{N}(\mu + b, A\Sigma A^T) \text{ for } x \sim \mathcal{N}(\mu, \Sigma)$$

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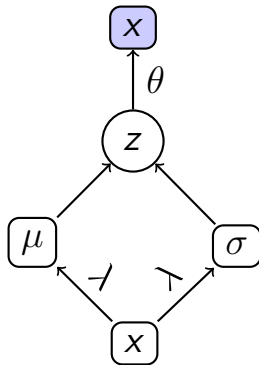
$$Ax + b \sim \mathcal{N}(b, AA^T) \text{ for } x \sim \mathcal{N}(0, I)$$

## Gaussian transformation

$$h(\epsilon, \lambda) = \mu(x, \lambda) + \sigma(x, \lambda) \odot \epsilon \quad \epsilon \sim \mathcal{N}(0, I)$$

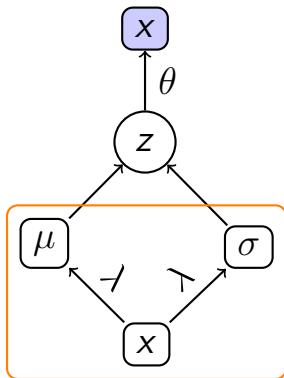
# Gaussian KL

# Computation Graph



# Computation Graph

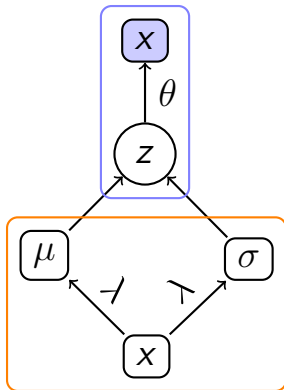
inference model



# Computation Graph

generation model

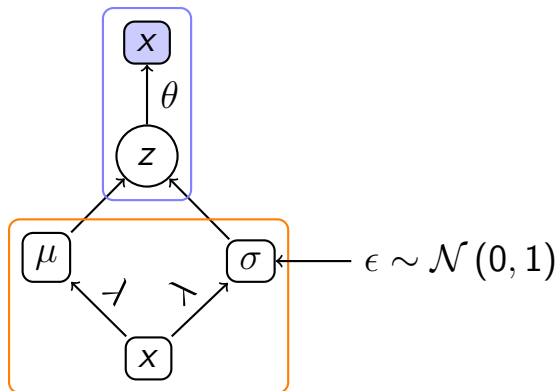
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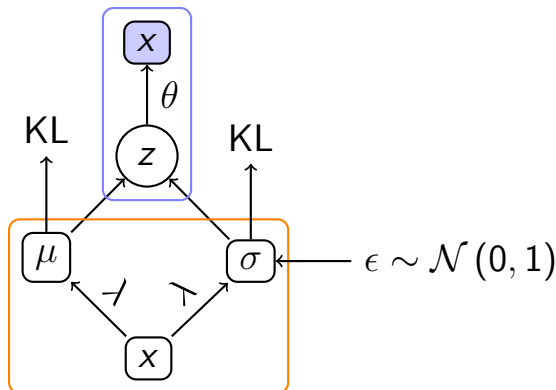




# Computation Graph

generation model

inference model



# Example

- ▶ Data: binary mnist
- ▶ Likelihood: product of Bernoullis
  - ▶ Let  $\phi = \sigma(\text{NN}(z))$
  - ▶  $\prod_{i=1}^N p(x_i|\phi) = \prod_{i=1}^N \phi^{x_i} \times (1 - \phi)^{1-x_i}$
- ▶ Prior over  $z$ :  $\mathcal{N}(0, 1)$
- ▶  $q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$
- ▶  $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$
- ▶  $\sigma(x, \lambda) = \text{NN}_{\sigma}(x; \lambda)$

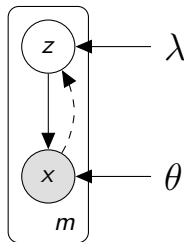
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- ▶  $\sigma(x, \lambda) = \text{NN}_{\sigma}(x; \lambda)$

## Mean Field assumption

Variational approximation factorises over latent dimensions.

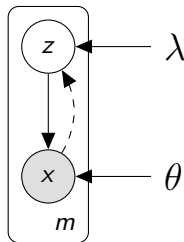
# Graphical Model



- approximate posterior

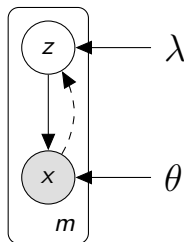
$$q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$$

# Graphical Model



- ▶ approximate posterior
$$q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$$
- ▶ where
  - ▶  $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$   
e.g.  $\mu(x, \lambda) = W^{(u)}x + b^{(u)}$

# Graphical Model



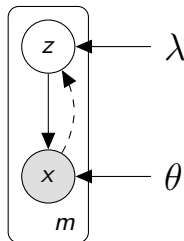
- ▶ approximate posterior

$$q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$$

- ▶ where

- ▶  $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$   
e.g.  $\mu(x, \lambda) = W^{(u)}x + b^{(u)}$
- ▶  $\sigma(x, \lambda) = \exp(\text{NN}_{\sigma}(x; \lambda))$   
e.g.  
 $\sigma(x, \lambda) = \exp(W^{(v)}x + b^{(v)})$

# Graphical Model



- ▶ approximate posterior
 
$$q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$$
- ▶ where
  - ▶  $\mu(x, \lambda) = \text{NN}_{\mu}(x; \lambda)$   
e.g.  $\mu(x, \lambda) = W^{(u)}x + b^{(u)}$
  - ▶  $\sigma(x, \lambda) = \exp(\text{NN}_{\sigma}(x; \lambda))$   
e.g.  
 $\sigma(x, \lambda) = \exp(W^{(v)}x + b^{(v)})$
  - ▶  $\lambda = (W^{(u)}, W^{(v)}, b^{(u)}, b^{(v)})$

# Variational Autoencoder

## Advantages

- ▶ Backprop training
- ▶ Easy to implement
- ▶ Posterior inference possible
- ▶ One objective for both NNs



# Variational Autoencoder

## Advantages

- ▶ Backprop training
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- ▶ One objective for both NNs

## Drawbacks

- ▶ Discrete latent variables are difficult
- ▶ Optimisation may be difficult with several latent variables

# Summary

- ▶ When  $|\mathcal{X}|$  and  $|\mathcal{Z}|$  are not too large, we can do EM with features
- ▶ Otherwise use VI with simple approximation
- ▶ Wake-Sleep: train inference and generation networks with separate objectives
- ▶ VAE: train both networks with same objective
- ▶ Reparametrisation
  - ▶ Transform parameter-free variable  $\epsilon$  into latent value  $z$
  - ▶ Update parameters with stochastic gradient estimates

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