Deep Generative Models: Continuous Latent Variables

Philip Schulz and Wilker Aziz

https:
//github.com/philschulz/VITutorial

Deep Generative Models

First Attempt: Wake-Sleep

This is how we do: Variational Autoencoders

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Generative Models

Joint distribution over observed data x and latent variables Z.

$$p(x, z|\theta) = \underbrace{p(z)}_{\text{prior}} \underbrace{p(x|z, \theta)}_{\text{likelihood}}$$

The likelihood and prior are often standard distributions (Gaussian, Bernoulli) with simple dependence on conditioning information.

Deep generative models

Joint distribution with deep observation model

$$p(x, z|\theta) = \underbrace{p(z)}_{\text{prior}} \underbrace{p(x|z, \theta)}_{\text{likelihood}}$$

mapping from z to $p(x|z,\theta)$ is a NN with parameters θ

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Marginal likelihood

$$p(x|\theta) = \int p(x, z|\theta) dz = \int p(z)p(x|z, \theta) dz$$

intractable in general

We want

richer probabilistic models

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- complex observation models parameterised by NNs

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We need approximate inference techniques!

Deep Generative Models

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Wake-sleep Algorithm

- Generalise latent variables to Neural Networks
- ► Train generative neural model
- Use variational inference! (kind of)

2 Neural Networks:

A generation network to model the data (the one we want to optimise) – parameters: θ

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- An inference (recognition) network (to model the latent variable) parameters: λ

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- A generation network to model the data (the one we want to optimise) parameters: θ
- An inference (recognition) network (to model the latent variable) parameters: λ
- Original setting: binary hidden units
- ▶ Training is performed in a "hard EM" fashion

Wake-sleep Training

Wake Phase

- Use inference network to sample hidden unit setting z from $q(z|x,\lambda)$
- ▶ Update generation parameters θ to maximize liklelihood of data given latent state $p(x|z,\theta)$

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Sleep Phase

- Produce dream sample \tilde{x} from random hidden unit z
- Update inference parameters λ to maximize probability of latent state $q(z|\tilde{x}, \lambda)$

Wake Phase Objective

Assumes latent state z to be fixed random draws from $q(z|x,\lambda)$.

$$\max_{\theta} \ \mathbb{E}_{q(z|x,\lambda)} \left[\log p(z,x|\theta) \right] + \mathbb{H}[q(z|x,\lambda)]$$

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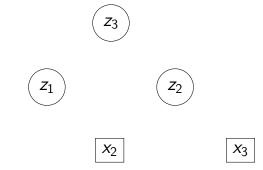
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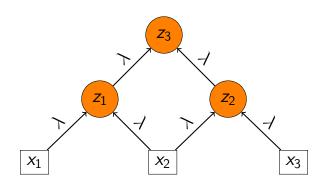
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This is simply supervised learning with imputed latent data!

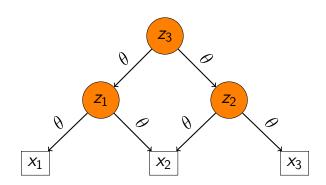
Wake Phase Sampling



Wake Phase Sampling



Wake Phase Update



Sleep Phase Objective

Assumes fake data \tilde{x} and latent variables z to be fixed random draw from $p(x, z|\theta)$.

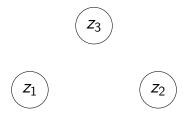
$$\max_{\lambda} \ \mathbb{E}_{p(\tilde{x},z|\theta)} \left[\log q(z|\tilde{x},\lambda) \right] + \mathbb{E}_{p(\tilde{x})} \left[\mathbb{H} \left(p(z|\tilde{x},\theta) \right) \right]$$

Sleep Phase Objective

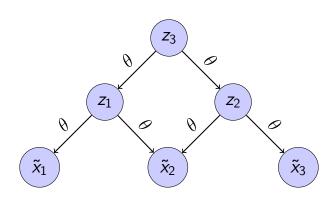
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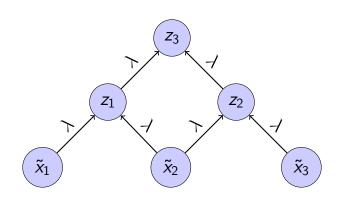
Sleep Phase Sampling



Sleep Phase Sampling



Sleep Phase Update



Wake-sleep Algorithm

Advantages

- Simple layer-wise updates
- Amortised inference: all latent variables are inferred from the same weights λ

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Drawbacks

- Inference and generative networks are trained on different objectives
- Inference weights \(\lambda \) are updated on fake data \(\tilde{x} \)
- Generative weights are bad initially, giving wrong signal to the updates of λ

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Generative Model with NN Likelihood

Goal

Define model $p(x, z|\theta) = p(x|z, \theta)p(z)$ where the likelihood $p(x|z, \theta)$ is given by a neural network. (We fix p(z) for simplicity.)

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Define model $p(x, z|\theta) = p(x|z, \theta)p(z)$ where the likelihood $p(x|z, \theta)$ is given by a neural network. (We fix p(z) for simplicity.)

Problem

$$p(x) = \int \underbrace{p(x|z,\theta)}_{\substack{\text{highly} \\ \text{non-linear}}} p(z) dz \text{ is hard to compute.}$$

$$\log p(x|\theta) \geq \underbrace{\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x,Z|\theta)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}_{ ext{ELBO}}$$

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$$\begin{split} \log p(x|\theta) &\geq \underbrace{\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x,Z|\theta)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}_{\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|Z,\theta) + \log p(Z)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}_{=\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|Z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right) \\ \operatorname{arg\,max} \ \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|Z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right) \end{split}$$

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▶ assume KL $(q(z|x,\lambda) || p(z))$ analytical true for exponential families

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$$\operatorname{arg\,max}_{\theta,\lambda} \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|Z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

- ▶ assume KL $(q(z|x, \lambda) || p(z))$ analytical true for exponential families
- ▶ approximate $\mathbb{E}_{q(z|x,\lambda)}[\log p(x|z,\theta)]$ by sampling feasible because $q(z|x,\lambda)$ is simple

$$\frac{\mathrm{d}}{\mathrm{d}\theta} \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left(q(z|x,\lambda) \mid\mid p(z) \right)}^{constant}$$

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$$= \mathbb{E}_{q(z|x,\lambda)} \left[\frac{\mathrm{d}}{\mathrm{d}\theta} \log p(x|z,\theta) \right]$$

$$\overset{\mathsf{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{\mathrm{d}}{\mathrm{d}\theta} \log p(x|z_i,\theta)$$
where $z_i \sim q(z|x,\lambda)$

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Note: $q(z|x,\lambda)$ does not depend on θ .

$$rac{\mathrm{d}}{\mathrm{d}\lambda}\left[\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z, heta)
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The first term again requires approximation by sampling

$$\frac{\mathrm{d}}{\mathrm{d}\lambda}\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right]$$

$$\frac{\mathrm{d}}{\mathrm{d}\lambda} \mathbb{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) \right] \\ = \frac{\mathrm{d}}{\mathrm{d}\lambda} \int q(z|x,\lambda) \log p(x|z,\theta) \mathrm{d}z$$

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= \int \frac{\mathrm{d}}{\mathrm{d}\lambda} q(z|x,\lambda) \log p(x|z,\theta) \mathrm{d}z$$

Not an expected gradient!

Reparametrisation trick

Find a transformation $h: z \mapsto \epsilon$ such that ϵ does not depend on λ .

- $h(z, \lambda)$ needs to be invertible
- $h(z, \lambda)$ needs to be differentiable

Reparametrisation trick

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- $h(z, \lambda)$ needs to be invertible
- $h(z, \lambda)$ needs to be differentiable
- $h(z,\lambda) = \epsilon$
- $h^{-1}(\epsilon,\lambda)=z$

Affine property

$$Az + b \sim \mathcal{N}\left(\mu + b, A\Sigma A^{T}\right) ext{ for } z \sim \mathcal{N}\left(\mu, \Sigma\right)$$

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Gaussian transformation

$$h(z,\lambda) = \frac{z - \mu(\phi,\lambda)}{\sigma(\phi,\lambda)} = \epsilon \sim \mathcal{N}(0,I)$$

$$\underbrace{h^{-1}(\epsilon,\lambda)}_{-z} = \mu(\phi,\lambda) + \sigma(\phi,\lambda) \odot \epsilon \quad \epsilon \sim \mathcal{N}(0,I)$$

$$= \frac{\mathrm{d}}{\mathrm{d}\lambda} \int q(z|x,\lambda) \log p(x|z,\theta) \mathrm{d}z$$

$$= \frac{\mathrm{d}}{\mathrm{d}\lambda} \int q(z|x,\lambda) \log p(x|z,\theta) \mathrm{d}z$$

$$= \frac{\mathrm{d}}{\mathrm{d}\lambda} \int q(\epsilon) \log \left(p(x|h^{-1}(\epsilon,\lambda),\theta) \right) \mathrm{d}\epsilon$$

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$$= \int q(\epsilon) \frac{\mathrm{d}}{\mathrm{d}\lambda} \left[\log p(x|h^{-1}(\epsilon,\lambda),\theta) \right] \mathrm{d}\epsilon$$

$$\mathbb{E}_{q(\epsilon)}\left[\frac{\mathrm{d}}{\mathrm{d}\lambda}\log p(x|\widehat{h^{-1}(\epsilon,\lambda)},\theta)\right]$$

$$\mathbb{E}_{q(\epsilon)} \left[\frac{\mathrm{d}}{\mathrm{d}\lambda} \log p(x| \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}, \theta) \right]$$

$$\stackrel{\mathsf{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{\mathrm{d}}{\mathrm{d}\lambda} \log p(x| \overbrace{h^{-1}(\epsilon_i, \lambda)}^{=z}, \theta)$$
where $\epsilon_i \sim q(\epsilon)$

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$$\stackrel{\mathsf{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{\mathrm{d}}{\mathrm{d}z} \log p(x|\widehat{h^{-1}(\epsilon_{i},\lambda)}, \theta) \times \frac{\mathrm{d}}{\mathrm{d}\lambda} h^{-1}(\epsilon_{i},\lambda)$$
chain rule

Derivatives of Gaussian transformation

Recall:

$$h^{-1}(\epsilon,\lambda) = \mu(\phi,\lambda) + \sigma(\phi,\lambda) \odot \epsilon$$
.

We get two gradient paths!

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• one is deterministic $\frac{\partial h^{-1}(\epsilon,\lambda)}{\partial \mu(\phi,\lambda)} = \frac{\partial}{\partial \mu(\phi,\lambda)} [\mu(\phi,\lambda) + \sigma(\phi,\lambda) \odot \epsilon] = 1$

Derivatives of Gaussian transformation

Recall:

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We get two gradient paths!

- one is deterministic $\frac{\partial h^{-1}(\epsilon,\lambda)}{\partial \mu(\phi,\lambda)} = \frac{\partial}{\partial \mu(\phi,\lambda)} [\mu(\phi,\lambda) + \sigma(\phi,\lambda) \odot \epsilon] = 1$
- the other is stochastic $\frac{\partial h^{-1}(\epsilon,\lambda)}{\partial \sigma(\phi,\lambda)} = \frac{\partial}{\partial \sigma(\phi,\lambda)} [\mu(\phi,\lambda) + \sigma(\phi,\lambda) \odot \epsilon] = \epsilon$

Gaussian KL

ELBO

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

Gaussian KL

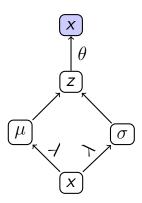
FI BO

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

Analytical computation of $- KL(q(z|x, \lambda) || p(z))$:

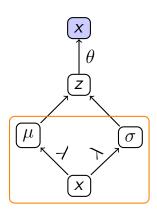
$$\frac{1}{2} \sum_{i=1}^{N} \left(1 + \log \left(\sigma_i^2 \right) - \mu_i^2 - \sigma_i^2 \right)$$

Computation Graph



Computation Graph

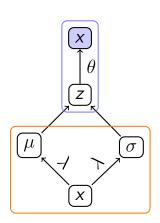
inference model



Computation Graph

generation model

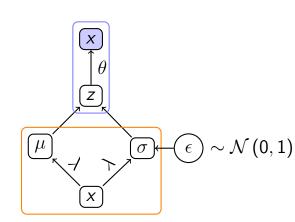
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Computation Graph

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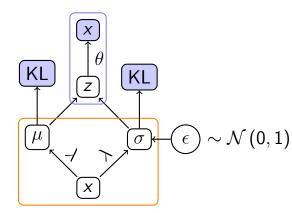
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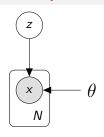


Computation Graph

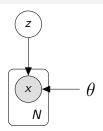


inference model



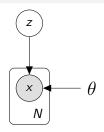


- ▶ Draw a document embedding $Z \sim \mathcal{N}(0, I)$
- ▶ Draw N words $X_i|z \sim \mathsf{Cat}(f(z,\theta))$



Generative story

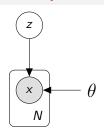
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Generative story

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$$h = \mathsf{relu}(W_1 z + b_1)$$

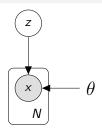


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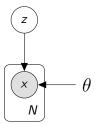
 $f(z, \theta) = \frac{\text{softmax}(W_2h + b_2)}{\text{softmax}(W_2h + b_2)}$



Generative story

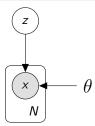
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$$h = \operatorname{\mathsf{relu}}(W_1z + b_1)$$
 $f(z, \theta) = \operatorname{\mathsf{softmax}}(W_2h + b_2)$
 $\theta = \{W_1, b_1, W_2, b_2\}$



Likelihood

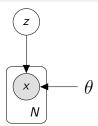
- ▶ Draw a document embedding $Z \sim \mathcal{N}(0, I)$
- ▶ Draw N words $X_i|z \sim \mathsf{Cat}(f(z,\theta))$



Likelihood

- ▶ Draw a document embedding $Z \sim \mathcal{N}(0, I)$
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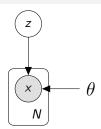
$$p(x_1^N|z,\theta) = \prod_{i=1}^N p(x_i|z,\theta)$$



Likelihood

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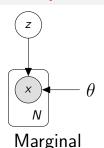
$$p(x_1^N|z,\theta) = \prod_{i=1}^N p(x_i|z,\theta) = \prod_{i=1}^N \mathsf{Cat}(x_i|\underbrace{f(z,\theta)}_{=\psi})$$



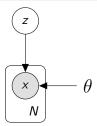
Likelihood

- ▶ Draw a document embedding $Z \sim \mathcal{N}(0, I)$
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$$egin{aligned}
ho(x_1^N|z, heta) &= \prod_{i=1}^N
ho(x_i|z, heta) = \prod_{i=1}^N \operatorname{Cat}(x_i|\underbrace{f(z, heta)}_{=\psi}) \ &= \prod_{i=1}^N \psi_{x_i} \end{aligned}$$



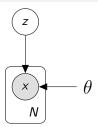
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Marginal

- ▶ Draw a document embedding $Z \sim \mathcal{N}(0, I)$
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$$p(x_1^N|\theta) = \int p(z) \prod_{i=1}^N p(x_i|z,\theta) dz$$



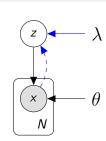
Marginal

- ▶ Draw a document embedding $Z \sim \mathcal{N}(0, I)$
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$$p(x_1^N|\theta) = \int p(z) \prod_{i=1}^N p(x_i|z,\theta) dz$$
$$= \int \mathcal{N}(z|0,I) \prod_{i=1}^N \text{Cat}(x_i|f(z,\theta)) dz$$

Inference model

 $ightharpoonup Z|x_1^N \sim \mathcal{N}(\mu(x_1^N,\lambda),\sigma(x_1^n,\lambda)^2)$



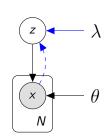
Inference model

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 $z \rightarrow \lambda$ $x \rightarrow \theta$

Inference model

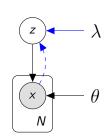
$$Z|x_1^N \sim \mathcal{N}(\mu(x_1^N, \lambda), \sigma(x_1^n, \lambda)^2)$$



$$s = \sum_{i=1}^{N} E_{x_i}$$

Inference model

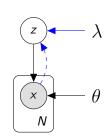
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$$s = \sum_{i=1}^{N} E_{x_i}$$
 $h = \text{relu}(M_1 s + c_1)$

Inference model

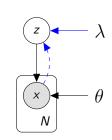
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$$s=\sum_{i=1}^N E_{x_i}$$
 $\mu(x_1^N,\lambda)=M_2h+c_2$ $h=\operatorname{relu}(M_1s+c_1)$

Inference model

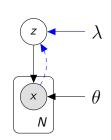
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$$s = \sum_{i=1}^{N} E_{x_i}$$
 $\mu(x_1^N, \lambda) = M_2 h + c_2$ $\sigma(x_1^N, \lambda) = \text{softplus}(M_3 h + c_3)$ $h = \text{relu}(M_1 s + c_1)$

Inference model

$$Z|x_1^N \sim \mathcal{N}(\mu(x_1^N, \lambda), \sigma(x_1^n, \lambda)^2)$$



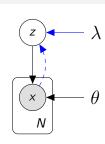
$$s = \sum_{i=1}^{N} E_{x_i}$$
 $\mu(x_1^N, \lambda) = M_2 h + c_2$ $\sigma(x_1^N, \lambda) = \text{softplus}(M_3 h + c_3)$ $h = \text{relu}(M_1 s + c_1)$ $\lambda = \{E, M_1^3, c_1^3\}$

Generative Model

- ▶ Prior: $Z \sim \mathcal{N}(0, I)$
- ▶ Likelihood: $X_i|z \sim \text{Cat}(f(z,\theta))$

Inference Model

 $ightharpoonup Z|x_1^N \sim \mathcal{N}(\mu(x_1^N,\lambda),\sigma(x_1^n,\lambda)^2)$

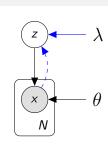


Generative Model

- ▶ Prior: $Z \sim \mathcal{N}(0, I)$
- ▶ Likelihood: $X_i|z \sim \text{Cat}(f(z,\theta))$

Inference Model

 $Z|x_1^N \sim \mathcal{N}(\mu(x_1^N, \lambda), \sigma(x_1^n, \lambda)^2)$



ELBO

$$\log p(x_1^N|\theta) \geq \mathbb{E}_{\frac{z-u}{s} \sim \mathcal{N}(0,I)} \left[\sum_{i=1}^N \log \psi_{x_i} \right] - \mathsf{KL} \left(\mathcal{N}(z|u,s^2) \mid\mid \mathcal{N}(z|0,I) \right)$$

where
$$u = \mu(x_1^N, \lambda)$$
, $s = \sigma(x_1^N, \lambda)$, and $\psi = f(z, \theta)$

Aside

If your likelihood model is able to express dependencies between the output variables (e.g. an RNN), the model may simply ignore the latent code. In that case one often scales the KL term. The scale factor is increased gradually.

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \beta \operatorname{\mathsf{KL}}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

where $\beta \rightarrow 1$.

Variational Autoencoder

Advantages

- Backprop training
- ► Easy to implement
- Posterior inference possible
- One objective for both NNs

Variational Autoencoder

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- Backprop training
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- Posterior inference possible
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Drawbacks

- Discrete latent variables are difficult
- Optimisation may be difficult with several latent variables

Summary

- Wake-Sleep: train inference and generation networks with separate objectives
- ▶ VAE: train both networks with same objective
- Reparametrisation
 - ightharpoonup Transform parameter-free variable ϵ into latent value z
 - Update parameters with stochastic gradient estimates

Literature I

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