Deep Generative Models: Discrete Latent Variables

Philip Schulz and Wilker Aziz

https:
//github.com/philschulz/VITutorial

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- Main problem: the MC estimator is not differentiable
- Solution: reparametrisation gradient

Model Gradient

$$\frac{\partial}{\partial \theta} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z,\theta) \right] - \frac{\partial}{\partial \theta} \mathsf{KL} \left(q(z|\lambda) \mid\mid p(z|\theta) \right)$$

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Inference Network Gradient

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z,\theta) \right] - \frac{\partial}{\partial \lambda} \mathsf{KL} \left(q(z|\lambda) \mid\mid p(z|\theta) \right)$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z, \theta) \right]$$

$$\frac{\partial}{\partial \lambda} \mathbb{E}_{q(z|\lambda)} \left[\log p(x|z,\theta) \right] = \frac{\partial}{\partial \lambda} \mathbb{E}_{\phi(\epsilon)} \left[\log p(x|\widehat{h^{-1}(\epsilon,\lambda)},\theta) \right] = 0$$

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Reparametrisation for Discrete Variables?

Revisiting the Inference Gradient

Control Variates and Baselines

Semisupervised Learning

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Reparametrisation

In order to tranform variables, we need to compute the Jacobian (matrix of partial derivatives).

$$p(z) = \phi(h(z)) \left| \det J_{h(z)} \right|$$

The Jacobian

$$J_{ij} = \frac{\partial h_i(z)}{\partial z_j} \tag{1}$$

is generally not available for discrete variables.

Continuity

The outcome space of discrete variables is non-continuous. Thus, we cannot take derivatives with respect to real variables.

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Back to Basic Calculus

$$\frac{\mathrm{d}}{\mathrm{d}\lambda}\log f(\lambda)$$

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$$\frac{\mathrm{d}}{\mathrm{d}\lambda}\log f(\lambda) = \frac{\frac{\mathrm{d}}{\mathrm{d}\lambda}f(\lambda)}{f(\lambda)}$$

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Consequence

$$\frac{\mathrm{d}}{\mathrm{d}\lambda}f(\lambda) = \frac{\mathrm{d}}{\mathrm{d}\lambda}\log f(\lambda) \times f(\lambda)$$

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Apply this to the ELBO derivative.

$$\sum_{z} \frac{\partial}{\partial \lambda} q(z|\lambda) \times \log p(x|z,\theta) =$$

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$$\mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) \times \log p(x|z,\theta) \right]$$

Comparison Between Estimators

Score function gradient

$$\mathbb{E}_{q(z|\lambda)}\left[rac{\partial}{\partial \lambda}\log q(z|\lambda) imes\log p(x|z, heta)
ight]$$

Reparametrisation gradient

$$\mathbb{E}_{\phi(\epsilon)} \left[\frac{\partial}{\partial \lambda} \log p(x|h^{-1}(\epsilon,\lambda),\theta) \right]$$

Example Model

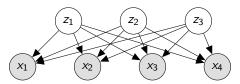
Let us consider a latent factor model for topic modelling. Each document x consists of n i.i.d. categorical draws from that model. The categorical distribution in turn depends on the binary latent factors $z = (z_1, \ldots, z_k)$ which are also i.i.d.

$$Z_j \sim \mathsf{Bernoulli}\left(\phi\right) \qquad (1 \leq j \leq k)$$

 $X_i | z \sim \mathsf{Categorical}\left(g(z)\right) \quad (1 \leq i \leq n)$

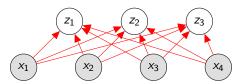
Here $g(\cdot)$ is a function computed by neural network with softmax output.

Example Model

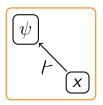


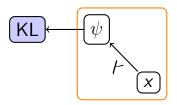
At inference time the latent variables are marginally dependent. For our variational distribution we are going to assume that they are not (recall: mean field assumption).

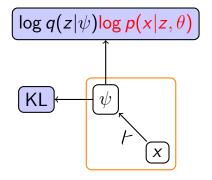
Inference Network

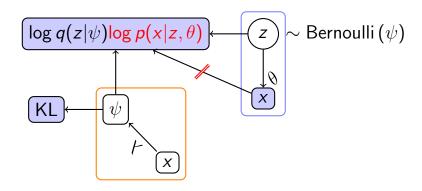


The inference network needs to predict k Bernoulli parameters ψ . Any neural network with sigmoid output will do that job.





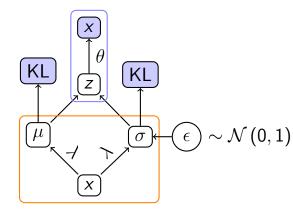




inference model

generation model





Pros and Cons

- Pros
 - Applicable to all distributions
 - Many libraries come with samplers for common distributions

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- Cons
 - High Variance!

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Fact

The Expectation of the score function is 0.

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$$\mathbb{E}_{q(z|x,\lambda)}\left[\frac{\partial}{\partial\lambda}\log q(z|x,\lambda)\right]=0$$

We attempt to centre the gradient estimate. To do this we learn a quantity C that we subtract from the reconstruction loss.

$$\mathbb{E}_{q(z|\lambda)}\left[\log q(z|\lambda)\left(\log p(x|z,\theta)-C\right)\right]$$

We call C a baseline. It does not change the expected gradient (Williams, 1992).

$$\mathbb{E}_{q(z|\lambda)}\left[\frac{\partial}{\partial \lambda}\log q(z|\lambda)\left(\log p(x|z,\theta)-C\right)\right]=$$

$$\mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) \left(\log p(x|z,\theta) - C \right) \right] =$$

$$\mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) \log p(x|z,\theta) \right] -$$
score function gradient

$$\mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) \left(\log p(x|z,\theta) - C \right) \right] = \\ \mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) \log p(x|z,\theta) \right] - \\ \mathbb{E}_{q(z|\lambda)} \left[\frac{\partial}{\partial \lambda} \log q(z|\lambda) \right] C$$

We can make baselines input-dependent to make them more flexible.

$$\log q(z|\lambda) \left(\log p(x|z,\theta) - C(x;\omega)\right)$$

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$$\log q(z|\lambda) \left(\log p(x|z,\theta) - C(x;\omega)\right)$$

However, baselines may not depend on the random value z! Quantities that may depend on the random value (C(z)) are called **control variates**.

See Blei et al. (2012); Ranganath et al. (2014); Gregor et al. (2014).

Baselines are predicted by a regression model (e.g. a neural net).

The model is trained using an L_2 -loss.

$$\min_{\omega} \left(C(x; \omega) - \log p(x|z, \theta) \right)^2$$

Control Variates and Baselines

 Reparametrisation not available for discrete variables.

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- Use score function estimator.
- ▶ High variance.
- Always use baselines for variance reduction!

We now know how to handle continuous and discrete latent variables. Let us combine these two treat partially observed data.

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Morphological Reinflection

Transform an inflected form of a verb into another.

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Morphological Reinflection

Transform an inflected form of a verb into another.

- ightharpoonup played
- ightharpoonup walks

What do we need to correctly inflect a word?

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▶ lemma

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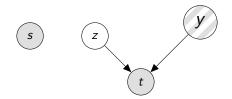
▶ lemma (real vector)

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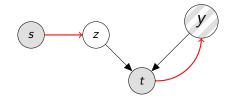
- ▶ lemma (real vector)
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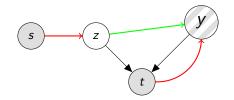
- ▶ lemma (real vector)
- morphological information (discrete vector)



- z = lemma (continuous)
- y = morphological features (discrete)
- ightharpoonup s = source form (inflected)
- ▶ t = target form (inflected)



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David M. Blei, Michael I. Jordan, and John W. Paisley. Variational bayesian inference with stochastic search. In *ICML*, 2012. URL http://icml.cc/2012/papers/687.pdf.

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What we covered today

- Derivation of VI
- Continuous VAE
- Discrete VAE
- Semisupervised Models

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► Do the coding tutorial (https:
//github.com/philschulz/VITutorial/
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- Stay in touch
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 - phschulz@amazon.com