## Deep Generative Models

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Philip Schulz and Wilker Aziz

https:
//github.com/philschulz/VITutorial
```

#### Deep Generative Models

Generative Models

## Recap: Generative Models

Joint distribution over observed data x and latent variables Z.

$$p(x, z | \alpha) = \overbrace{p(x | z, \alpha)}^{\text{likelihood}} \underbrace{p(z | \alpha)}_{\text{prior}}$$

The likelihood and prior are often standard distributions (Gaussian, Bernoulli) with simple dependence on conditioning information.

## Recap: Variational Inference

#### Objective

$$\max_{q(z)} \mathbb{E}\left[\log p(x,z)\right] + \mathbb{H}\left(q(z)\right)$$

- ▶ The ELBO is a lower bound on log p(x)
- ▶ Mean field assumption:  $q(z) = \prod_{i=1}^{N} q(z_i)$

#### Deep Generative Models

First Attempt: Log-linear Models

#### Feature-rich Generative Models

Let us assume that z has internal structure (features). How can we exploit that?

#### First Idea

Make  $p(x|z, \alpha)$  a log-linear model.

- Only discrete data
- ► Trainable with EM if we can efficiently enumerate  $\mathcal{X}$  and  $\mathcal{Z}$ .

### Log-linear Model

Let us treat z as observed.

$$p(x|z, \alpha = w) = \frac{\exp\left(w^{\top} f(x, z)\right)}{\sum_{x \in \mathcal{X}} \exp\left(w^{\top} f(x, z)\right)}$$

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Weight Gradient

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#### Weight Gradient

$$\frac{d}{dw}\log p(x|z,w) = f(x,z) - \mathbb{E}\left[f(X,z)|z,w\right]$$

Updates need to be performed iteratively.

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#### Model

$$p(x, z | w) = \underbrace{\frac{\exp\left(w^{\top} f(x, z)\right)}{\sum_{x \in \mathcal{X}} \exp\left(w^{\top} f(x, z)\right)}}_{p(x|z, w)} \times \underbrace{p(z)}_{arbitrary}$$

$$p(z|x,w) = \frac{p(x,z|w)}{p(x|w)}$$

$$p(z|x,w) = \frac{p(x,z|w)}{p(x|w)} = \frac{p(x,z|w)}{\sum_{z} p(x,z|w)} =$$

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$$\frac{d}{dw}\mathbb{E}_{p(z|x,w)}\left[\log p(x,z|w)\right] =$$

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$$\frac{d}{dw} \mathbb{E}_{\rho(z|x,w)} \left[ \log \rho(x,z|w) \right] = \\ \mathbb{E}_{\rho(z|x,w)} \left[ f(x,Z)|x,w \right] - \mathbb{E}_{\rho(z|x,w)} \left[ \mathbb{E} \left[ (f(X,Z)|Z,w) \right] \right]$$

Weight Gradient (treat p(z|x, w) as fixed)

$$\frac{d}{dw} \mathbb{E}_{p(z|x,w)} \left[ \log p(x,z|w) \right] = \\ \mathbb{E}_{p(z|x,w)} \left[ f(x,Z)|x,w \right] - \mathbb{E}_{p(z|x,w)} \left[ \mathbb{E} \left[ (f(X,Z)|Z,w) \right] \right]$$

#### Procedurally

$$\mathsf{E\_count}(f(x,z)) - \{ \mathsf{E\_count}(f(x,z)) \times \mathbb{E}[f(X,z)|z,w] \}$$

#### **EM**

E-step 
$$p(z|x, w) = \frac{p(x, z|w)}{\sum_{z} p(x, z|w)}$$
 in  $\mathcal{O}(|\mathcal{X}| \times |\mathcal{Z}|)$ 

M-step Iteratively optimise w to match  $E_{count}(x, z)$  with  $E_{count}(x, z) \times \mathbb{E}[X|z, w]$ 

#### Restrictions

- Only log-linear models
- Scales badly

#### Deep Generative Models

Second Attempt: Wake-Sleep

## Wake-sleep Algorithm

- Generalise latent variables to Neural Networks
- Train generative neural model
- Use variational inference! (kind of)

#### 2 Neural Networks:

A generation network to model the data (the one we want to optimise) – parameters:  $\theta$ 

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- An inference (recognition) network (to model the latent variable) – parameters: λ
- Original setting: binary hidden units
- ▶ Training is performed in a "hard EM" fashion

## Wake-sleep Training

#### Wake Phase

- Use inference network to sample hidden unit setting z from  $q(z|x,\lambda)$
- Update generation parameters  $\theta$  to maximize liklelihood of data given latent state  $p(x|z,\theta)$

## Wake-sleep Training

#### Wake Phase

- Use inference network to sample hidden unit setting z from  $q(z|x,\lambda)$
- ▶ Update generation parameters  $\theta$  to maximize liklelihood of data given latent state  $p(x|z, \theta)$

#### Sleep Phase

- Produce dream sample  $\tilde{x}$  from random hidden unit z
- Update inference parameters  $\lambda$  to maximize probability of latent state  $q(z|\tilde{x},\lambda)$

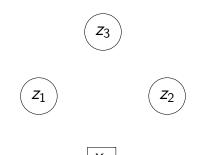
## Wake Phase Objective

Assumes latent state z to be fixed random draws from  $q(z|x,\lambda)$ .

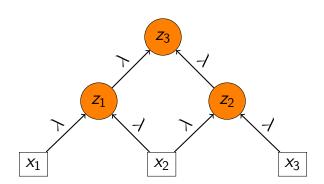
$$\max_{\theta} \log p(x|z,\theta)$$

This is simply supervised learning with imputed latent data!

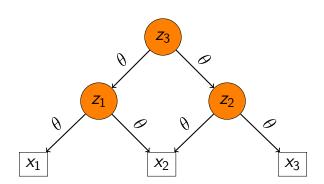
# Wake Phase Sampling



# Wake Phase Sampling



## Wake Phase Update

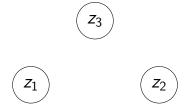


## Sleep Phase Objective

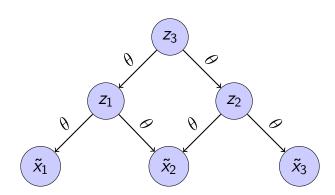
Assumes fake data  $\tilde{x}$  and latent variables z to be fixed random draw from  $p(x, z|\theta)$ .

$$\min_{\lambda} \; \mathbb{E}_{q(z|\tilde{x},\lambda)} \left[ \log p(\tilde{x},z|\theta) \right] + \mathbb{H} \left( q(z|\tilde{x},\lambda) \right)$$

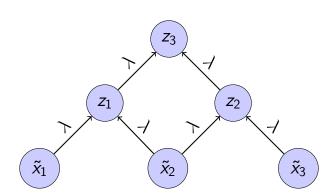
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## Sleep Phase Update



## Wake-sleep Algorithm

#### **Advantages**

- Simple layer-wise updates
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#### **Advantages**

- Simple layer-wise updates
- Amortised inference: all latent variables are inferred from the same weights  $\lambda$

#### **Drawbacks**

- Inference and generative networks are trained on different objectives
- Inference weights  $\lambda$  are updated on fake data  $\tilde{x}$
- Generative weights are bad initially, giving wrong signal to the updates of  $\lambda$

#### Deep Generative Models

☐ This is how we do: Variational Autoencoders

#### Goal

Define model  $p(x, z|\theta) = p(x|z, \theta)p(z)$  where the likelihood  $p(x|z, \theta)$  is given by a neural network. (We fix p(z) for simplicity.)

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#### **Problem**

 $p(x) = \int p(x|z,\theta)p(z)dz$  is hard to compute.

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#### **Problem**

$$p(x) = \int \underbrace{p(x|z,\theta)}_{\substack{\text{highly} \\ \text{non-linear}}} p(z) dz \text{ is hard to compute.}$$

$$\log p(x) \geq \frac{\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x,z|\theta)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}{\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x,z|\theta)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}$$

$$\begin{split} \log p(x) & \geq \underbrace{\mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x,z|\theta) \right] + \mathbb{H} \left( q(z|x,\lambda) \right)}_{\text{ELBO}} \\ & = \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) + \log p(z) \right] + \mathbb{H} \left( q(z|x,\lambda) \right) \end{split}$$

$$\log p(x) \ge \underbrace{\mathbb{E}_{q(z|x,\lambda)} \left[\log p(x,z|\theta)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}_{\text{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta) + \log p(z)\right] + \mathbb{H}\left(q(z|x,\lambda)\right)}_{\text{E}_{q(z|x,\lambda)} \left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)}$$

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$$\frac{d}{d\theta} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \overbrace{\mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right)}^{constant}$$

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$$= \mathbb{E}_{q(z|x,\lambda)} \left[ \frac{d}{d\theta} \log p(x|z,\theta) \right]$$

$$\overset{\mathsf{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{d}{d\theta} \log p(x|z_i,\theta)$$

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Note:  $q(z|x,\lambda)$  does not depend on  $\theta$ .

$$\frac{d}{d\lambda}\left[\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda)\mid\mid p(z)\right)\right]$$

$$\frac{d}{d\lambda} \left[ \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] - \mathsf{KL} \left( q(z|x,\lambda) \mid\mid p(z) \right) \right]$$

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The first term again requires approximation by sampling

$$\frac{d}{d\lambda} \mathbb{E}_{q(z|x,\lambda)} \left[ \log p(x|z,\theta) \right] \\ = \frac{d}{d\lambda} \int q(z|x,\lambda) \log p(x|z,\theta) dz$$

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MC estimator non-differentiable

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#### MC estimator non-differentiable

• Sampling z neglects  $\frac{d}{d\lambda}q(z|x,\lambda)$ 

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#### MC estimator non-differentiable

- ▶ Sampling z neglects  $\frac{d}{d\lambda}q(z|x,\lambda)$
- ▶ Differentiating  $q(z|x, \lambda)$  breaks the expectation

#### Reparametrisation trick

Find a transformation  $h: z \mapsto \epsilon$  such that  $\epsilon$  does not depend on  $\lambda$ .

- $h(z, \lambda)$  needs to be invertible
- $h(z, \lambda)$  needs to be differentiable

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- $h(z, \lambda)$  needs to be differentiable
- $h(z,\lambda) = \epsilon$
- $h^{-1}(\epsilon,\lambda)=z$

#### **Affine property**

$$Ax + b \sim \mathcal{N}\left(\mu + b, A\Sigma A^{T}\right) \text{ for } x \sim \mathcal{N}\left(\mu, \Sigma\right)$$

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#### **Gaussian transformation**

$$h(z,\lambda) = \frac{z - \mu(x,\lambda)}{\sigma(x,\lambda)} = \epsilon \sim \mathcal{N}(0, 1)$$
  
 $h^{-1}(\epsilon,\lambda) = \mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon \quad \epsilon \sim \mathcal{N}(0, 1)$ 

$$= \frac{d}{d\lambda} \int q(z|x,\lambda) \log p(x|z,\theta) dz$$

$$= \frac{d}{d\lambda} \int q(z|x,\lambda) \log p(x|z,\theta) dz$$

$$= \frac{d}{d\lambda} \int q(\epsilon) \log \left( p(x|h^{-1}(\epsilon,\lambda),\theta) \right) d\epsilon$$

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$$= \int q(\epsilon) \frac{d}{d\lambda} \left[ \log p(x|h^{-1}(\epsilon,\lambda),\theta) \right] d\epsilon$$

## Inference Network Gradient

$$= \int q(\epsilon) \frac{d}{dz} \log p(x| \overbrace{h^{-1}(\epsilon, \lambda)}^{=2}, \theta) \times \frac{d}{d\lambda} h^{-1}(\epsilon, \lambda) d\epsilon$$

## Inference Network Gradient

$$= \int q(\epsilon) \frac{d}{dz} \log p(x| \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}, \theta) \times \frac{d}{d\lambda} h^{-1}(\epsilon, \lambda) d\epsilon$$

$$= \mathbb{E}_{q(\epsilon)} \left[ \frac{d}{dz} \log p(x| \overbrace{h^{-1}(\epsilon, \lambda)}^{=z}, \theta) \times \frac{d}{d\lambda} h^{-1}(\epsilon, \lambda) \right]$$

## Inference Network Gradient

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$$\stackrel{\text{MC}}{\approx} \frac{1}{S} \sum_{i=1}^{S} \frac{d}{dz} \log p(x|\widehat{h^{-1}(\epsilon,\lambda)}, \theta) \times \frac{d}{d\lambda} h^{-1}(\epsilon,\lambda)$$

## Derivatives of Gaussian transformation

Recall:

$$h^{-1}(\epsilon,\lambda) = \mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon$$
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This gives us 2 gradient paths.

$$\frac{dh^{-1}(\epsilon,\lambda)}{d\mu(x,\lambda)} = \frac{d}{d\mu(x,\lambda)} [\mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon] = 1$$
$$\frac{dh^{-1}(\epsilon,\lambda)}{d\sigma(x,\lambda)} = \frac{d}{d\sigma(x,\lambda)} [\mu(x,\lambda) + \sigma(x,\lambda) \odot \epsilon] = \epsilon$$

## Gaussian KL

**ELBO** 

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

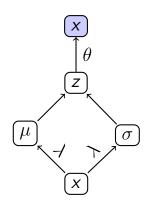
## Gaussian KL

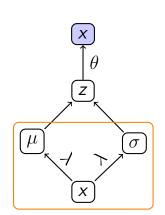
#### **ELBO**

$$\mathbb{E}_{q(z|x,\lambda)}\left[\log p(x|z,\theta)\right] - \mathsf{KL}\left(q(z|x,\lambda) \mid\mid p(z)\right)$$

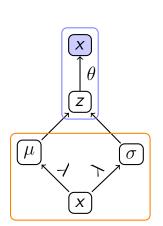
Analytical computation of  $- KL(q(z|x, \lambda) || p(z))$ :

$$\frac{1}{2}\sum_{i=1}^{N}\left(1+\log\left(\sigma_{i}^{2}\right)-\mu_{i}^{2}-\sigma_{i}^{2}\right)$$

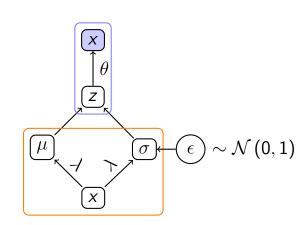




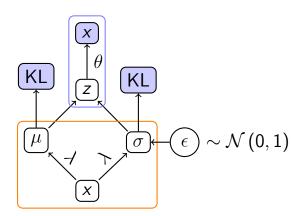
generation model



generation model







## Example

- Data: binary mnist
- Likelihood: product of Bernoullis
  - Let  $\phi = \sigma(NN(z))$
  - $\prod_{i=1}^{N} p(x_i|\phi) = \prod_{i=1}^{N} \phi^{x_i} \times (1-\phi)^{1-x_i}$
- ▶ Prior over z:  $\mathcal{N}(0,1)$
- $q(z|x,\lambda) = \mathcal{N}\left(\mu(x,\lambda), \sigma(x,\lambda)^2\right)$
- $\mu(x,\lambda) = \mathsf{NN}_{\mu}(x;\lambda)$

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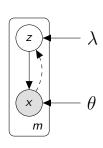
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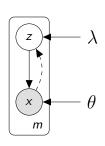
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- $q(z|x,\lambda) = \mathcal{N}\left(\mu(x,\lambda), \sigma(x,\lambda)^2\right)$
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#### Mean Field assumption

Variational approximation factorises over latent dimensions.

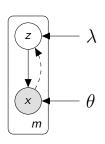


▶ approximate posterior  $q(z|x,\lambda) = \mathcal{N}(\mu(x,\lambda), \sigma(x,\lambda)^2)$ 

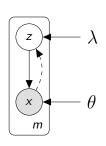


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  - $\mu(x,\lambda) = \mathsf{NN}_{\mu}(x;\lambda)$ e.g.  $\mu(x,\lambda) = W^{(u)}x + b^{(u)}$



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- ▶ approximate posterior  $q(z|x, \lambda) = \mathcal{N}(\mu(x, \lambda), \sigma(x, \lambda)^2)$ 
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- $\lambda = (W^{(u)}, W^{(v)}, b^{(u)}, b^{(v)})$

### Variational Autoencoder

#### **Advantages**

- Backprop training
- Easy to implement
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### Variational Autoencoder

#### **Advantages**

- Backprop training
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#### **Drawbacks**

- Discrete latent variables are difficult
- Optimisation may be difficult with several latent variables

## Summary

- ▶ When  $|\mathcal{X}|$  and  $|\mathcal{Z}|$  are not too large, we can do EM with features
- Otherwise use VI with simple approximation
- Wake-Sleep: train inference and generation networks with separate objectives
- VAE: train both networks with same objective
- Reparametrisation
  - ▶ Transform parameter-free variable  $\epsilon$  into latent value z
  - Update parameters with stochastic gradient estimates

### Literature I