

# TARGETMAV

Barbarian's Team

# OUR TEAM



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# CHALLENGE

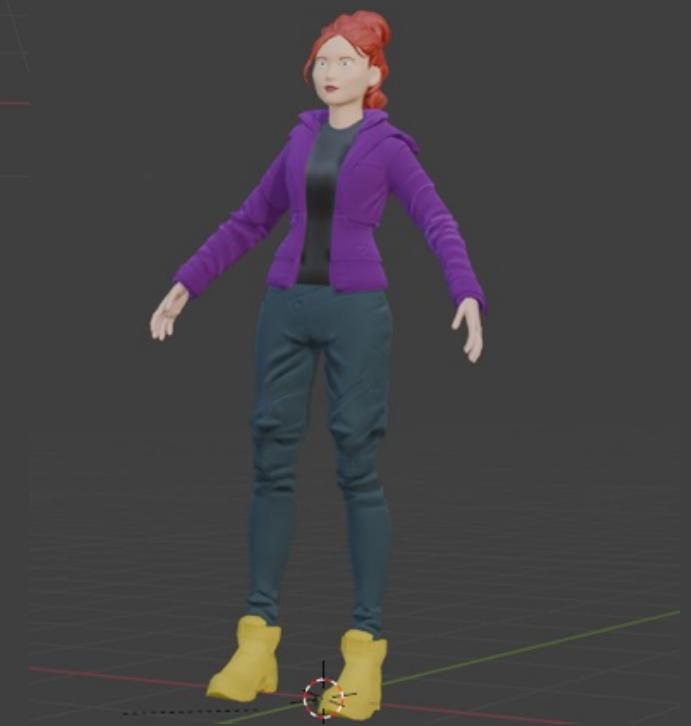
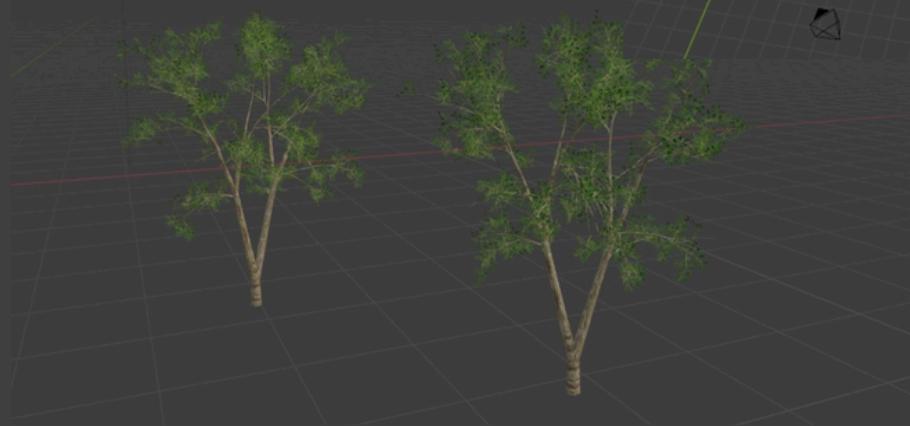
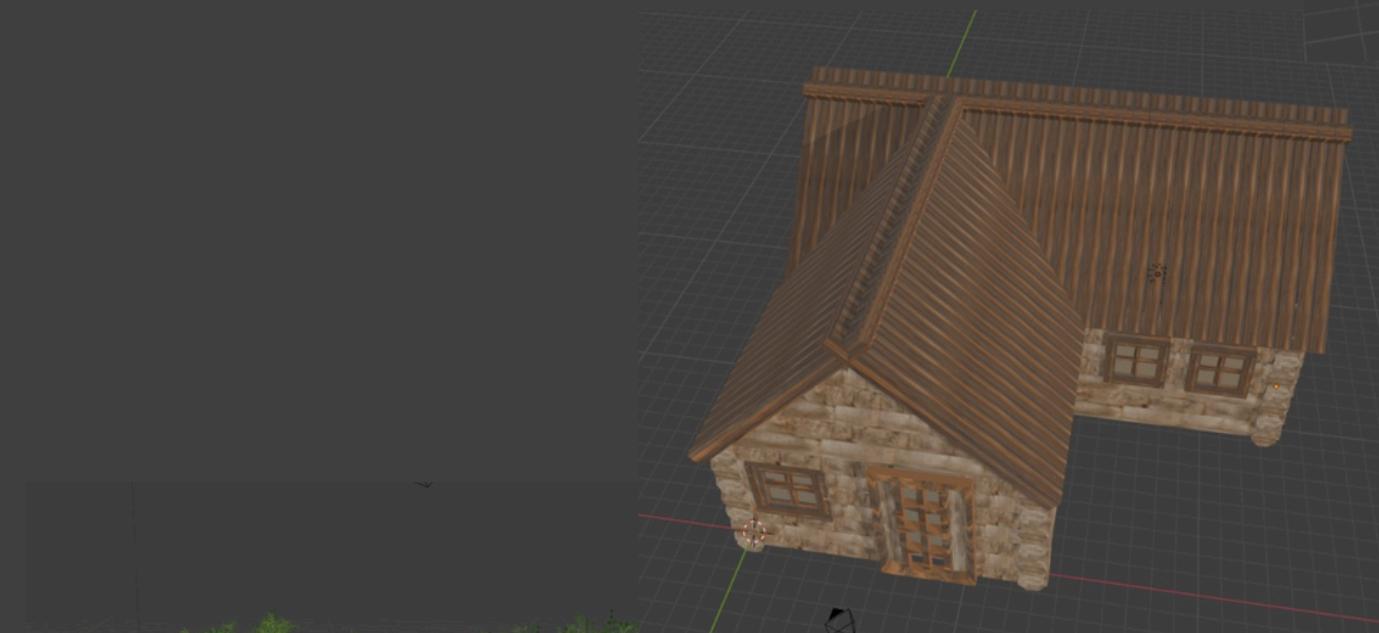
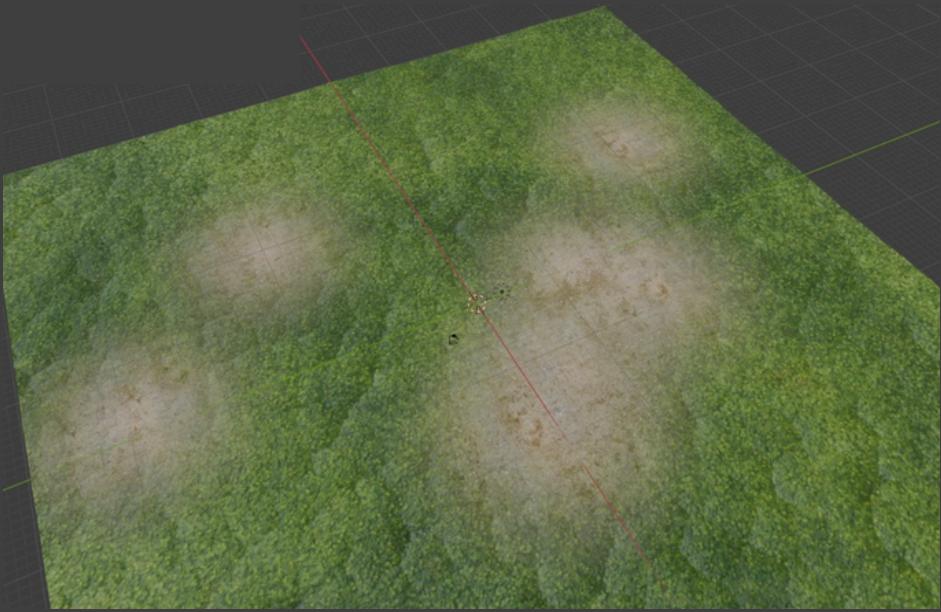
Find a person in a  $10,000 \text{ m}^2$  open field with a textual description of the person and its whereabouts with a MAV autonomously, and land in a 2 meter radius near the person

# OUR SOLUTION

Using a MAV of three drones with a multi-agent system patrols the designated area, analyzing people and matching them to a given textual description using an LLM; when the best match is found, the drone alerts the others, halts their movement, and the closest drone lands within a 2 meter radius of the person.



# 3D MODELS



# COMPONENTS INVOLVED

## LandingController:

Handles Safe Landing

## DroneAgent:

Flight Controller

## PersonDescriptor:

Sends Description of people seen (Tags and Characteristics)

## SearchCoordinator:

Manages Mission State, Decisions, Callbacks and Winner

## OllamaLLMComparer:

Communication between MAS and LLM

## DroneProximitySensor:

Proximity Trigger

# PROTOTYPE DEMO

# CONCLUSION





**THANK YOU!**