

MOTOR SPECIFICATIONS

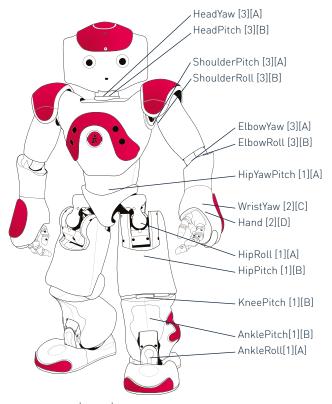
Motor type Brush DC Coreless

POSITION OF MOTORS

		Motor	Reduction Ratio
Head joints	HeadYaw	Туре 3	Туре А
	HeadPitch	Туре 3	Туре В
Arm joints	ShoulderPitch	Туре 3	Туре А
	ShoulderRoll	Туре 3	Type B
	ElbowYaw	Type 3	Туре А
	ElbowRoll	Type 3	Type B
	WristYaw	Type 2	Type C
	Hand	Type 2	Type D
Leg joints	HipYawPitch	Type 1	Туре А
	HipRoll	Type 1	Туре А
	HipPitch	Type 1	Туре В
	KneePitch	Type 1	Туре В
	AnklePitch	Type 1	Туре В
	AnkleRoll	Type 1	Туре А

DESCRIPTION OF THE MOTORS

	Motor type 1	Motor type 2	Motor type 3
Model	22NT82213P	17N88208E	16GT83210E
No load speed	8300rpm ±10%	8400rpm ±12%	10700rpm ±10%
Stall torque	68mNm ±8%	9.4mNm ±8%	14.3mNm ±8%
Continuous torque	16.1mNm max	4.9mNm max	6.2mNm max



Legend: Joint Name[Motor Type][Reductor Type]

Speed Reduction Ratio TYPE A

	Motor type 1	Motor type 3
Reduction ratio	201.3	150.27

Speed Reduction Ratio TYPE C

	Motor type 2
Reduction ratio	50.61

Speed Reduction Ratio TYPE B

	Motor type 1	Motor type 3
Reduction ratio	130.85	173.22

Speed Reduction Ratio TYPE D

	Motor type 2
Reduction ratio	36.24

CERTIFICATIONS & APPROVALS

Region	Classification	Electromagnetic compatibility	EN 301-1 / EN 301 489-17 / EN 300 328 EN 62311 : 2008 / FCC PART15, Class B
Europe	CE (Attestation of conformity)		
USA	FCC	Safety	IEC 60950-1 : 2005 (2nd edition)