Fine Tuning do BERT no IMDB

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Instruções:

Treinar e medir a acurácia de um modelo BERT (ou variantes) para classificação binária usando o dataset do IMDB (20k/5k amostras de treino/validação).

Importante:

- [x] Deve-se implementar o próprio laço de treinamento.
- [x] Implementar o acumulo de gradiente.

Dicas:

- BERT geralmente costuma aprender bem uma tarefa com poucas épocas (de 3 a 5 épocas). Se tiver demorando mais de 5 épocas para chegar em 80% de acurácia, ajuste os hiperparametros.
- Solução para erro de memória:
 - [x] Usar bfloat16 permite quase dobrar o batch size

Opcional:

• Pode-se usar a função trainer da biblioteca Transformers/HuggingFace para verificar se seu laço de treinamento está correto. Note que ainda assim é obrigatório implementar o laço próprio.

```
In [ ]:
          import os # Manipular arquivos
          import random # Operações randômicas
          import pickle # Serializar/deserializar backups
          import time # Medição de tempo
          import string # Operações com strings
          from concurrent.futures import ThreadPoolExecutor # Parelização
          from typing import Tuple, List, Dict, Optional # Type hints
          import numpy as np # Operações vetoriais
          import matplotlib.pyplot as plt # Plots
          import tqdm
          import torch # ML
          from torch.utils.data import Dataset, DataLoader # Preparação de dados
              import wandb # Logging
          except:
              wandb = None
```

Fixando a seed

```
def reset_seeds(seed:int=123):
    random.seed(seed)
    np.random.seed(seed)
    torch.manual_seed(seed)
In []: reset_seeds()
```

Preparando Dados

Primeiro, fazemos download do dataset:

```
if not os.path.isfile("aclImdb.tgz"):
    !curl -LO http://files.fast.ai/data/aclImdb.tgz
    !tar -xzf aclImdb.tgz
```

Carregando o dataset

Criaremos uma divisão de treino (20k exemplos) e validação (5k exemplos) artificialmente.

```
texts.append(f.read())
              return texts
In [ ]:
          executor = ThreadPoolExecutor(max workers=4)
          folders = ['aclImdb/train/pos', 'aclImdb/train/neg', 'aclImdb/test/pos', 'aclImdb/test/neg']
          futures = []
          for folder in folders:
              future = executor.submit(load_texts, folder)
              futures.append(future)
          all_texts = []
          for future in futures:
             texts = future.result()
             all_texts.append(texts)
          executor.shutdown()
          x_train_pos = all_texts[0]
          x_train_neg = all_texts[1]
          x_test_pos = all_texts[2]
          x_test_neg = all_texts[3]
In [ ]:
         x_train = x_train_pos + x_train_neg
          x_test = x_test_pos + x_test_neg
          y_train = [True] * len(x_train_pos) + [False] * len(x_train_neg)
         y_test = [True] * len(x_test_pos) + [False] * len(x_test_neg)
In [ ]:
          # Embaralhamos o treino para depois fazermos a divisão treino/valid.
          c = list(zip(x_train, y_train))
          random.shuffle(c)
          x_train, y_train = zip(*c)
          x_valid = x_train[-max_valid:]
          y_valid = y_train[-max_valid:]
          x_train = x_train[:-max_valid]
          y_train = y_train[:-max_valid]
In [ ]:
          print(len(x_train), 'amostras de treino.')
          print(len(x_valid), 'amostras de desenvolvimento.')
          print(len(x_test), 'amostras de teste.')
         20000 amostras de treino.
         5000 amostras de desenvolvimento.
         25000 amostras de teste.
In [ ]:
         print('3 primeiras amostras treino:')
          for x, y in zip(x_train[:3], y_train[:3]):
             print(y, x[:100])
          print('3 últimas amostras treino:')
          for x, y in zip(x_train[-3:], y_train[-3:]):
             print(y, x[:100])
          print('3 primeiras amostras validação:')
          for x, y in zip(x_valid[:3], y_test[:3]):
             print(y, x[:100])
          print('3 últimas amostras validação:')
          for x, y in zip(x_valid[-3:], y_valid[-3:]):
              print(y, x[:100])
         3 primeiras amostras treino:
         False POSSIBLE SPOILERS<br /><br />The Spy Who Shagged Me is a muchly overrated and over-hyped sequel. Int
         False The long list of "big" names in this flick (including the ubiquitous John Mills) didn't bowl me over
         True Bette Midler showcases her talents and beauty in "Diva Las Vegas". I am thrilled that I taped it and
         3 últimas amostras treino:
         False I was previously unaware that in the early 1990's Devry University (or was it ITT Tech?) added Film
         True The story and music (George Gershwin!) are wonderful, as are Levant, Guetary, Foch, and, of course,
         True This is my favorite show. I think it is utterly brilliant. Thanks to David Chase for bringing this i
         3 primeiras amostras validação:
         True Why has this not been released? I kind of thought it must be a bit rubbish since it hasn't been. How
         True I was amazingly impressed by this movie. It contained fundamental elements of depression, grief, lon
         True photography was too jumpy to follow. dark scenes hard to see.<br/>
'>-kbr />Had good story line too bad
         3 últimas amostras validação:
         True In the early to mid 1970's, Clifford Irving proposed to write the ultimate biography of Howard Hughe
         True An ultra-modern house in an affluent neighborhood appears to be the cause of each of its inhabitants
         True Some of the best movies that are categorized as "comedies" actually blur between comedy and drama. '
In [ ]:
          GOOD_MOVIE = 1 #True
```

for path in os.listdir(folder):

BAD_MOVIE = 0 #False

with open(os.path.join(folder, path), encoding="utf8") as f:

Tokenizador

Preparamos o tokenizador para uso. No caso vamos utilizar o tokenizador preparado para o modelo BERT (é o mesmo do DistilBERT):

Dataset e Dataloader

Definimos o dataset para realizar a tokenização e manipular os dados:

```
In [ ]:
         class IMDB_Dataset(Dataset):
             Dataset for sentiment analisys
              Input: tokenized review and mask (for padding).
             Output: if is a good (1) or bad (0) review.
              def __init__(self, x_data:List[str], y_data:List[bool], tokenizer) -> None:
                  Creates a new dataset.
                  Args:
                      x_data (List[str]): dataset reviews.
                     y_data (List[bool]): dataset targets.
                      tokenizer: tokenizer to encode reviews.
                  super().__init__()
                  self._x_data = tokenizer(x_data,
                                           return_tensors="pt", #Return as torch tensor
                                           padding=True, #Add padding to small sequences
                                           return_token_type_ids=False, #Don't return sequence mask (only one sequence)
                                           truncation=True) #Truncate big sentences (max = 512 tokens, with CLS and SEP)
                  self._y_data = torch.tensor(y_data, dtype=torch.float32)
                  self._size = len(self._y_data)
                  self.max_len = 512
              def __len__(self) -> int:
                  Gets the size of the dataset.
                  Returns:
                      int: dataset size.
                  return self._size
                  __getitem__(self, idx:int) -> Tuple[torch.Tensor, torch.Tensor, torch.Tensor]:
                  Gets a item of the dataset.
                  Args:
                      idx (int): data index.
                  Returns:
                      torch.Tensor: dataset input.
                      torch. Tensor: dataset attention mask.
                      torch.Tensor: dataset target.
                  x_data = self._x_data["input_ids"][idx]
                  mask = self._x_data["attention_mask"][idx]
                  if self.max_len != 512:
                      x_data = x_data[:self.max_len]
                      x_{data}[-1] = BERT_SEP
                      mask = mask[:self.max_len]
```

```
return x_data, mask, self._y_data[idx]
```

```
In []:
    datasets = {}

    xs = [x_train, x_valid, x_test]
    ys = [y_train, y_valid, y_test]
    names = ["train", "val", "test"]

    for i in range(3):
        dataset = IMDB_Dataset(xs[i], ys[i], tokenizer)
        datasets[names[i]] = dataset
```

Para evitar precisamos realizar várias vezes a tokenização durante o desenvolvimento, podemos serializar o dataset para posteriormente deserializá-lo:

```
In []: file_name = "datasets.bin"
    with open(file_name, "wb") as file:
        pickle.dump(datasets, file)

In []: file_name = "datasets.bin"
    with open(file_name, "rb") as file:
        datasets = pickle.load(file)
```

E defimos uma função para criar os dataloaders a partir dos datasets e batch size:

E uma função para alterar o tamanho das sequências que serão geradas:

```
def set_max_len(datasets:Dict[str, IMDB_Dataset], max_len):
    for name in datasets:
        datasets[name].max_len = max_len
```

Preparação do modelo

Prepamos o modelo a ser utilizado, que é um modelo BERT com uma camada adicional para realizar a classificação, que recebe como entrada o embedding final relacionado ao token CLS:

```
Returns:
    torch.Tensor: inference result.
bert_output = self.bert(input_ids=input_ids, attention_mask=attention_masks)
c_vector = bert_output.last_hidden_state[:, 0]
y = self.dropout(c_vector)
y = self.linear(y)
return y
```

Treino

Nesta seção iremos realizar o treino, iniciando pela definição de algumas funções auxiliares.

Funções auxiliares

Returns:

torch. Tensor: resulting loss. torch.Tensor: resulting accuracy

device = next(iter(model.parameters())).device

```
Iremos definir três funções auxiliares: uma para calcular a perplexidade a partir da loss, outra para printar informações e uma final para calcular a loss:
In [ ]:
          def ppl(loss:torch.Tensor) -> torch.Tensor:
              Computes the perplexity from the loss.
                  loss (torch.Tensor): loss to compute the perplexity.
              Returns:
                  torch. Tensor: corresponding perplexity.
              return torch.exp(loss)
In [ ]:
          def print_info(loss_value:torch.Tensor, epoch:int, total_epochs:int,
                         time:float=0.0, accuracy:Optional[float]=None):
             Prints the information of a epoch.
              Args:
                  loss_value (torch.Tensor): epoch loss.
                  epoch (int): epoch number.
                  total_epochs (int): total number of epochs.
                  time (float, optional): time to run the epoch. Don't print if is 0.0. Defaults to 0.0.
                  accuracy (float, optional): epoch accuracy.
              ppl_value = ppl(loss_value)
              print(f'Epoch [{epoch+1}/{total_epochs}], \
                      Loss: {loss_value.item():.4f}, \
                      Perplexity: {ppl_value.item():.4f}', end="")
              if accuracy is not None:
                  print(f', Accuracy: {100*accuracy:.4f}%')
              if time != 0:
                  print(f", Elapsed Time: {time:.2f} sec")
              else:
                  print("")
In [ ]:
          MODE_TRAIN = 0
          MODE_EVALUATE = 1
          def compute_loss(model:torch.nn.Module, loader:DataLoader,
                           criterion:torch.nn.Module, mode:int = MODE_EVALUATE,
                           optimizer:Optional[torch.optim.Optimizer]=None,
                           accumulation_steps:Optional[int] = 1) -> Tuple[torch.Tensor, torch.Tensor]:
              .....
              Computes the loss from a model across a dataset.
              If in train mode also runs optimizer steps.
              Args:
                  model (torch.nn.Module): model to evaluate.
                  loader (DataLoader): dataset.
                  criterion (torch.nn.Module): loss function to compute.
                  mode (int): mode of the computation.
                              If MODE_EVALUATE, computes without gradient, in eval mode and detachs loss.
                              If MODE_TRAIN, computes with gradient and in train mode.
                              Default is MODE_EVALUATE.
                  optimizer (torch.optim.Optimizer, optional): optimizer to use in the train mode.
```

```
if mode == MODE_EVALUATE:
    model.eval()
    torch.set_grad_enabled(False)
elif mode == MODE_TRAIN:
    model.train()
    torch.set_grad_enabled(True)
    optimizer.zero grad()
    raise ValueError(f"Unknown mode: {mode}.")
batch_index = 0
total_loss = torch.tensor(0, dtype=torch.float32, device=device)
correct = torch.tensor(0, dtype=torch.float32, device=device)
n = 0
for inputs, masks, targets in tqdm.tqdm(loader):
    inputs = inputs.to(device)
    masks = masks.to(device)
    targets = targets.reshape(-1)
    targets = targets.to(device)
    logits = model(inputs, masks)
    logits = logits.view(-1, logits.shape[-1])
    loss : torch.Tensor = criterion(logits.squeeze(), targets)
    total_loss += loss*targets.size(0)
    predicted = torch.round(torch.sigmoid(logits.squeeze()))
    correct += (predicted == targets).sum().item()
    n += targets.size(0)
    if mode == MODE_TRAIN:
        loss /= accumulation_steps
        loss.backward()
        if ((batch_index+1) % accumulation_steps == 0) or (batch_index+1 == len(loader)):
            optimizer.step()
            optimizer.zero_grad()
    batch_index += 1
total loss /= n
accuracy = correct / n
torch.set_grad_enabled(True)
accuracy = accuracy.detach()
total_loss = total_loss.detach()
return total_loss, accuracy
```

Inicialização

Começamos o processo de treino inicializando as variáveis.

Definimos se será realizado o logging utilizando o wandb:

```
In [ ]: use_wandb = True
```

Checamos se existe uma GPU disponível:

```
# Verifica se há uma GPU disponível e define o dispositivo para GPU se possível, caso contrário, usa a CPU device = torch.device('cuda' if torch.cuda.is_available() else 'cpu') device
```

```
Out[]: device(type='cuda')
```

Definimos os parâmetros de treino. No caso os parâmetros a seguir são do melhor treino, enquanto que todas as variações testadas podem ser encontradas em https://api.wandb.ai/links/eltoncn/2exfkyeh.

```
In [ ]:
         accumulation_steps = 2 # Passos de acumulação de gradiente
          batch size = 16 # Tamanho de um batch
          dropout_rate = 0.1 # Taxa de dropout para a camada adicional
         lr = 2.5e-5 # Taxa de treinamento
         n_epoch = 5 # Quantidade de epochs
          optimizer_class = torch.optim.Adam # Otimizador
          seq_len = 512 # Tamanho de uma sequência
          weight_decay = 0 # Regularização L2
          config = {
              "accumulation_steps": accumulation_steps,
              "batch_size": batch_size,
              "dropout_rate": dropout_rate,
              "lr": lr,
              "n_epoch": n_epoch,
              "optimizer_class": optimizer_class.__name__,
```

```
"seq_len" : seq_len,
    "weight_decay": weight_decay,
}
if use_wandb:
   run = wandb.init(project="IA024-04-BERT_IMDB", config=config)
   run_name = run.name
   run_id = run.id
   model_name = f"{run_name}-{run_id}.bin"
else:
   #get random name using config
   seed = 0
    for name in config:
        if isinstance(config[name], int) or isinstance(config[name], float):
            seed += config[name]
        else:
            for c in config[name]:
                seed += ord(c)
   reset_seeds(seed)
   model_name = ''.join(random.choice(string.ascii_uppercase + string.digits) for _ in range(5))
```

wandb version 0.16.6 is available! To upgrade, please run: \$ pip install wandb --upgrade

Tracking run with wandb version 0.15.8

Run data is saved locally in d:\Github\IA024\05-BERT\wandb\run-20240409_125232-rf89flxi

Syncing run **splendid-field-10** to Weights & Biases (docs)

View project at https://wandb.ai/eltoncn/IA024-04-BERT_IMDB

View run at https://wandb.ai/eltoncn/IA024-04-BERT_IMDB/runs/rf89flxi

Reiniciamos as sementes:

```
In [ ]:
         reset_seeds()
```

Criamos o modelo, loss, otimizador e dataloaders:

```
In [ ]:
         model = BinaryClassifierBERT(dropout_rate)
          model.to(device, dtype=torch.bfloat16)
          criterion = torch.nn.BCEWithLogitsLoss()
          optimizer = optimizer_class(model.parameters(), lr=lr, weight_decay=weight_decay)
          set_max_len(datasets, seq_len)
          dataloaders = create_dataloaders(datasets, batch_size)
```

Using cache found in C:\Users\eltsu/.cache\torch\hub\huggingface_pytorch-transformers_main

Treino

E finalmente podemos realizar o processo de treino em si:

```
In [ ]:
         #Informações antes da primeira epoch
         prev_loss, prev_accuracy = compute_loss(model, dataloaders["val"], criterion, MODE_EVALUATE)
         print_info(prev_loss, -1, n_epoch, 0, prev_accuracy)
        100% | 313/313 [01:31<00:00, 3.41it/s]
        Epoch [0/5],
                                Loss: 0.7207,
                                                         Perplexity: 2.0559, Accuracy: 49.4600%
```

```
In [ ]:
         hist = {}
         hist["loss_train"] = []
         hist["loss_val"] = []
         hist["ppl_train"] = []
          hist["ppl_val"] = []
          hist["accuracy_train"] = []
          hist["accuracy_val"] = []
          for epoch in range(n_epoch):
              start_time = time.time()
             loss_train, accuracy_train = compute_loss(model, dataloaders["train"], criterion, MODE_TRAIN, optimizer, accumulation_steps)
             end_time = time.time()
             epoch_duration = end_time - start_time
             ppl_train = ppl(loss_train)
             print_info(loss_train, epoch, n_epoch, epoch_duration, accuracy_train)
             #Validation stats
             loss_val, accuracy_val = compute_loss(model, dataloaders["val"], criterion, MODE_EVALUATE)
             ppl_val = ppl(loss_val)
             print("VAL ", end="")
             print_info(loss_val, epoch, n_epoch, accuracy=accuracy_val)
             #Save history
```

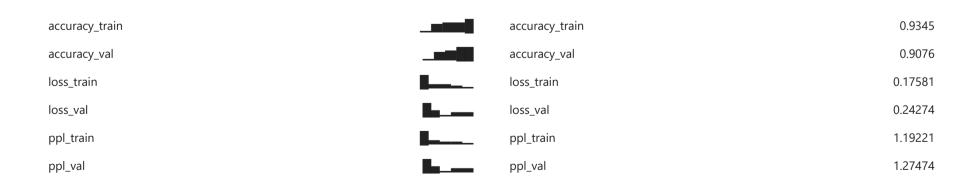
```
hist["loss_train"].append(loss_train.item())
   hist["loss_val"].append(loss_val.item())
   hist["ppl_train"].append(ppl_train.item())
   hist["ppl_val"].append(ppl_val.item())
   hist["accuracy_train"].append(accuracy_train.item())
   hist["accuracy_val"].append(accuracy_val.item())
   log = {
        "loss_train": loss_train.item(),
        "loss_val": loss_val.item(),
        "ppl_train": ppl_train.item(),
        "ppl_val": ppl_val.item(),
        "accuracy_train": accuracy_train.item(),
        "accuracy_val": accuracy_val.item()
   }
   if use wandb:
       wandb.log(log)
for key in hist:
   hist[key] = np.array(hist[key])
if use_wandb:
   wandb.finish()
```

```
100%| 1250/1250 [16:49<00:00, 1.24it/s]
                                              Perplexity: 1.4183, Accuracy: 83.9650%
Epoch [1/5],
                      Loss: 0.3495,
, Elapsed Time: 1010.84 sec
100%| 313/313 [01:23<00:00, 3.76it/s]
VAL Epoch [1/5],
                          Loss: 0.2565,
                                                  Perplexity: 1.2923, Accuracy: 89.6200%
100% | 1250/1250 [16:01<00:00, 1.30it/s]
                      Loss: 0.2370,
                                              Perplexity: 1.2675, Accuracy: 90.5150%
Epoch [2/5],
, Elapsed Time: 962.81 sec
100%| 313/313 [01:22<00:00, 3.79it/s]
VAL Epoch [2/5],
                          Loss: 0.2462,
                                                  Perplexity: 1.2791, Accuracy: 90.4800%
100%| 1250/1250 [16:32<00:00, 1.26it/s]
Epoch [3/5],
                      Loss: 0.2137,
                                              Perplexity: 1.2382, Accuracy: 91.5900%
, Elapsed Time: 993.92 sec
100%| 313/313 [01:27<00:00, 3.58it/s]
VAL Epoch [3/5],
                          Loss: 0.2374,
                                                  Perplexity: 1.2680, Accuracy: 90.6200%
100% | 1250/1250 [16:47<00:00, 1.24it/s]
Epoch [4/5],
                      Loss: 0.1924,
                                              Perplexity: 1.2121, Accuracy: 92.6150%
, Elapsed Time: 1008.03 sec
100%| 313/313 [01:26<00:00, 3.62it/s]
VAL Epoch [4/5],
                         Loss: 0.2417,
                                                  Perplexity: 1.2734, Accuracy: 90.7400%
100%| 1250/1250 [16:27<00:00, 1.27it/s]
Epoch [5/5],
                      Loss: 0.1758,
                                              Perplexity: 1.1922, Accuracy: 93.4500%
, Elapsed Time: 988.82 sec
100%| 313/313 [01:28<00:00, 3.54it/s]
VAL Epoch [5/5],
                          Loss: 0.2427,
                                                  Perplexity: 1.2747, Accuracy: 90.7600%
```

Waiting for W&B process to finish... (success).

Run history:

Run summary:



View run splendid-field-10 at: https://wandb.ai/eltoncn/IA024-04-BERT_IMDB/runs/rf89flxi

Synced 5 W&B file(s), 0 media file(s), 0 artifact file(s) and 0 other file(s)

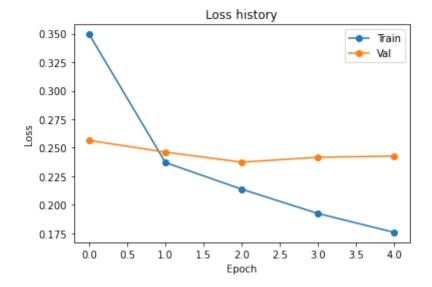
Find logs at: .\wandb\run-20240409_125232-rf89flxi\logs

Plotamos os gráficos das estatísticas obtidas durante o treinamento, onde podemos observar que o modelo conseguiu treinar corretamente, visto que as métricas melhoram pelas épocas; porém com overfitting, já que existe uma discrepância com estagnação ou piora nas métricas de validação:

```
plt.plot(hist["loss_train"], "o-")
plt.plot(hist["loss_val"], "o-")

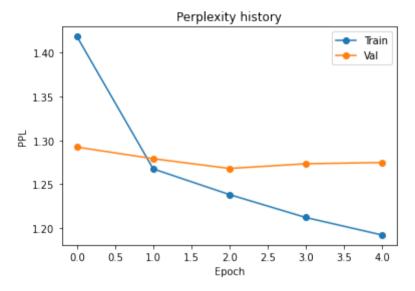
plt.legend(["Train", "Val"])
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.title("Loss history")
```

```
plt.show()
```



```
plt.plot(hist["ppl_train"], "o-")
plt.legend(["Train", "Val"])
plt.xlabel("Epoch")
plt.ylabel("PPL")
plt.title("Perplexity history")

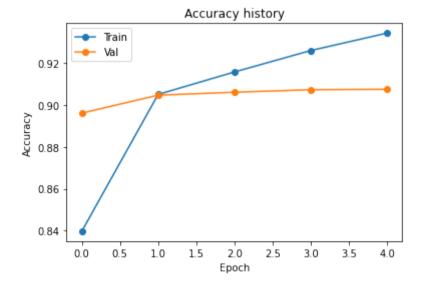
plt.show()
```



```
plt.plot(hist["accuracy_train"], "o-")
plt.plot(hist["accuracy_val"], "o-")

plt.legend(["Train", "Val"])
plt.xlabel("Epoch")
plt.ylabel("Accuracy")
plt.title("Accuracy history")

plt.show()
```



E podemos por fim salvar o modelo para uso posterior:

```
In [ ]: torch.save(model_name)
```

Avaliação

Para avaliação começamos calculando as estatísticas no dataset de teste:

```
test_loss, test_accuracy = compute_loss(model, dataloaders["test"], criterion, mode=MODE_EVALUATE)
test_ppl = ppl(test_loss)
```

```
test_loss.item(), test_ppl.item(), test_accuracy.item()
         100%| | 1563/1563 [07:17<00:00, 3.57it/s]
Out[]: (0.2271283119916916, 1.2549909353256226, 0.9109199643135071)
        Calculamos quantos pesos adicionais foram necessários:
In [ ]:
          n_param_bert = sum([p.numel() for p in model.bert.parameters()])
          n_param = sum([p.numel() for p in model.parameters()])
          n_param-n_param_bert, (n_param-n_param_bert)/n_param_bert
Out[ ]: (769, 1.1796122747906947e-05)
        E verificamos qualitativamente a saída do modelo:
In [ ]:
          tokens = tokenizer('''This must be gambling debt. Because only when someone threatens to break your legs
                                if you don't pay will you go and agree to make a film like this.''',
                              return_tensors="pt",
                              return_token_type_ids=False,
                              truncation=True,)
          with torch.no_grad():
             logits = model(tokens["input_ids"].to(device), tokens["attention_mask"].to(device))
          print("Result:", logits.item())
          print(f"Is this a good movie? {torch.round(logits).item() == GOOD_MOVIE}")
         Result: -2.6875
         Is this a good movie? False
        Podemos observar que ele realizou corretamente a classificação
```