HW3

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PROBLEM 1

The Optimization problem can be formulated as

$$\min_{A_{12},A_{21}} \sum_{i} (\hat{p}_i - p_i^{obs})^2$$

```
In [1]: # Importing Libraries
    import torch as t
    from torch.autograd import Variable
    import numpy as np
```

```
In [2]: # Calculation Of Saturation Pressure

p_sat14=10**(7.43155 - 1554.679/(20+240.337))
p_satw=10**(8.071 - 1730.63/(20+233.426))

p_g=[ 28.1 , 34.4 , 36.7 , 36.9 , 36.8 , 36.7 , 36.5 , 35.4 , 32.9 , 27.7 , 17.5 x_g=[ 0.0 , 0.1 , 0.2 , 0.3 , 0.4 , 0.5 , 0.6 , 0.7 , 0.8 , 0.9 , 1.0 ]
```

```
In [3]: # Saturation Pressure

print("Saturation Pressure of 1,4 dioxane is", p_sat14)
print("Saturation Pressure of water is", p_satw)
```

Saturation Pressure of 1,4 dioxane is 28.824099527405245 Saturation Pressure of water is 17.460784103526855

```
In [4]: #Functions
        # Pressure
        def p(a,x1):
            x2=1-x1
            return x1 * t.exp(a[0]* ( (a[1]*x2)/(a[0]*x1 + a[1]*x2) ) * p_satw +\
                                        x2 * t.exp(a[1]* ( (a[0]*x1)/(a[0]*x1 + a[1]*x2)
        # Total sum
        def TS(a):
            t=0
            for i in range(len(x_g)):
                xi=x_g[i]
                P=p(a,xi)
                t += (P-p g[i])**2
            return t
        # Step
        def 1(a):
            s=0.1
            while TS(a-s*a.grad) > TS(a)-s*(0)*np.matmul(a.grad, a.grad):
                s=.25*s
            return s
```

```
In [5]: # Assuming initial values for A12 and A21 as 2 & 1.
    a = Variable(t.tensor([2.0, 1.0]), requires_grad=True)

# Error
    e = 150

# Gradient Descent
while e > 0.15:
    obj=TS(a)
    obj.backward()
    step=1(a)
    e = t.linalg.norm(a.grad)
    with t.no_grad():
        a -= step * a.grad
        a.grad.zero_()

print('Final value of a is ' + str(a.data.numpy()))
print('The value of objective function is ' + str(obj.data.numpy()))
```

Final value of a is [1.9594604 1.6896328] The value of objective function is 0.67127305

```
In [6]: # Comparison between given data and modelled data
        print('Given P
                              Modelled P')
        for i in range(0,11):
                                          + str(p(a.data,x_g[i]).item()))
            print(str(p g[i]) + '
        Given P
                       Modelled P
        28.1
                     28.824098587036133
        34.4
                     34.64482498168945
        36.7
                     36.45182800292969
        36.9
                     36.86505126953125
        36.8
                     36.87146759033203
        36.7
                     36.747562408447266
        36.5
                     36.3885498046875
        35.4
                     35.38287353515625
        32.9
                     32.94468688964844
        27.7
                     27.723770141601562
        17.5
                     17.460784912109375
```

The modelled pressures fit very well with the values given in the data.

PROBLEM 2

In [7]: # Importing Libraries

```
import numpy as np
        import sklearn.gaussian_process as gp
        from scipy.stats import norm
        from scipy.optimize import minimize
In [8]: # EXPECTED IMPROVEMENT function.
        def expected improvement(x, gaussian process, evaluated loss, greater is better=#
            x_to_predict = x.reshape(-1, n_params)
            mu, sigma = gaussian process.predict(x to predict, return std=True)
            if greater_is_better:
                loss optimum = np.max(evaluated loss)
            else:
                loss_optimum = np.min(evaluated_loss)
            scaling_factor = (-1) ** (not greater_is_better)
            # In case sigma equals zero
            with np.errstate(divide='ignore'):
                Z = scaling_factor * (mu - loss_optimum) / sigma
                expected improvement = scaling factor * (mu - loss optimum) * norm.cdf(Z)
                expected improvement[sigma == 0.0] == 0.0
            return -1 * expected improvement
```

```
In [9]: # HYPERPARAMETER function.
        def sample_next_hyperparameter(acquisition_func, gaussian_process, evaluated_loss
                                        bounds=(0, 10), n restarts=25):
            best_x = None
            best_acquisition_value = 1
            n params = bounds.shape[0]
            for starting_point in np.random.uniform(bounds[:, 0], bounds[:, 1], size=(n_r
                res = minimize(fun=acquisition_func,
                                x0=starting_point.reshape(1, -1),
                                bounds=bounds,
                                method='L-BFGS-B',
                                args=(gaussian_process, evaluated_loss, greater_is_better]
                if res.fun < best acquisition value:</pre>
                    best_acquisition_value = res.fun
                    best_x = res.x
            return best x
```

```
In [10]: # BAYESIAN OPTIMIZATION function.
         def bayesian_optimisation(n_iters, sample_loss, bounds, x0=None, n_pre_samples=5)
                                    gp params=None, random search=False, alpha=1e-5, epsilo
             x_list = []
             y_list = []
             n params = bounds.shape[0]
             if x0 is None:
                 for params in np.random.uniform(bounds[:, 0], bounds[:, 1], (n_pre_sample
                     x_list.append(params)
                     y list.append(sample loss(params))
             else:
                 for params in x0:
                     x list.append(params)
                     y list.append(sample loss(params))
             xp = np.array(x list)
             yp = np.array(y list)
             # Create the GP
             if gp_params is not None:
                 model = gp.GaussianProcessRegressor(**gp_params)
             else:
                 kernel = gp.kernels.Matern()
                 model = gp.GaussianProcessRegressor(kernel=kernel,
                                                      alpha=alpha,
                                                      n restarts optimizer=10,
                                                      normalize y=True)
             for n in range(n_iters):
                 model.fit(xp, yp)
                 # Sample next hyperparameter
                 if random_search:
                     x random = np.random.uniform(bounds[:, 0], bounds[:, 1], size=(random
                     ei = -1 * expected_improvement(x_random, model, yp, greater_is_better
                      next_sample = x_random[np.argmax(ei), :]
                 else:
                      next sample = sample next hyperparameter(expected improvement, model)
                                                                greater_is_better=True, bour
                 # Duplicates will break the GP. In case of a duplicate, we will randomly
                 if np.any(np.abs(next_sample - xp) <= epsilon):</pre>
                      next_sample = np.random.uniform(bounds[:, 0], bounds[:, 1], bounds.sk
                 # Sample loss for new set of parameters
                 cv_score = sample_loss(next_sample)
                 # Update lists
                 x list.append(next sample)
                 y list.append(cv score)
```

```
# Update xp and yp
xp = np.array(x_list)
yp = np.array(y_list)
return xp, yp
```

```
In [12]: # Solution
print('Value of X1 and X2 is \t', z1[100])
print('Value of minimized function is \t', z2[100])
```

Value of X1 and X2 is [0.04588308 -0.76349676] Value of minimized function is 0.9991121097405781