## Neural networks and face images

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September 22, 2022

## 1 Introduction

This assignment gives you an opportunity to apply neural network learning to the problem of face recognition. You will experiment with a neural network program to train a sunglasses recognizer, a face recognizer, and a pose recognizer.

You will not need to do significant amounts of coding for this assignment, and you should not let the size of this document scare you, but training your networks will take time for slow machines. It is recommended that you read the assignment in its entirety first, and start early.

## 1.1 The face images

The image data can be found in our LMS with a filename **faces.tar.Z**. Decompress it and you should have a folder called **faces**. If not, then place all the files in a folder called **faces**. **IMPORTANT**: **Place the folder faces inside the directory where you saved all your codes**.

This directory contains 20 subdirectories, one for each person, named by userid. Each of these directories contains several different face images of the same person.

You will be interested in the images with the following naming convention: <userid>\_<pose>\_<expression>\_<eyes>\_<scale>.pgm

- **<userid>** is the user id of the person in the image, and this field has 20 values: an2i, at33, boland, bpm, ch4f, cheyer, choon, danieln, glickman, karyadi, kawamura, kk49, megak, mitchell, night, phoebe, saavik, steffi, sz24, and tammo.
- **<pose>** is the head position of the person, and this field has 4 values: straight, left, right, up.
- **<expression>** is the facial expression of the person, and this field has 4 values: neutral, happy, sad, angry.
- <eyes> is the eye state of the person, and this field has 2 values: open, sunglasses.
- <scale> is the scale of the image, and this field has 3 values: 1, 2, and 4. 1 indicates a full-resolution image (128 columns × 120 rows); 2 indicates a half-resolution image (64 × 60); 4 indicates a quarter-resolution image (32 × 30). For this assignment, you will be using the quarter-resolution images for experiments, to keep training time to a manageable level.

If you've been looking closely in the image directories, you may notice that some images have a .bad suffix rather than the .pgm suffix. As it turns out, 16 of the 640 images taken have glitches due to problems with the camera setup; these are the .bad images. Some people had more glitches than others, but everyone who got "faced" should have at least 28 good face images (out of the 32 variations possible, discounting scale).

## 1.2 Viewing the face images

You can view the images from the folder and get to know how the naming convention and the image inside it looks like.

## 1.3 The neural network and image access code

We're supplying C code for a **three-layer fully-connected feedforward neural network** which uses the **backpropagation** algorithm to tune its weights. Make sure that you have a C compiler installed in your system. To make life as easy as possible, we're also supplying you with an **image package** 

for accessing the face images, as well as the top-level program for training and testing, as a skeleton for you to modify. To help explore what the nets actually learn, you'll also find a utility program for visualizing hidden-unit weights as images.

The codes are located in our LMS. Copy all of the files in this area to your own directory, and type make. Note: take care to use cp \* instead of cp \*.\* in order to ensure that you get the Makefile. When the compilation is done, you should have one executable program: facetrain. Briefly, facetrain takes lists of image files as input, and uses these as training and test sets for a neural network. facetrain can be used for training and/or recognition, and it also has the capability to save networks to files.

Details of the routines, explanations of the source files, and related information can be found in Section 3 of this handout.

## 2 The Assignment

#### 2.1 Required

Turn in a short write-up or screenshot (whichever is required) of your answers to the questions found in the following sequence of initial experiments. If there is a question in a particular number, provide your short-write answer or screenshot (whichever is required). For those steps without questions, skip them and just leave them blank.

Place everything in a word or pdf file and submit to our LMS with filename familyname\_faces.pdf (e.g. gamot\_faces.pdf)

- 1. You might want to review how to issue commands using the command line. If you have taken CS 125, or Introduction to Operating Systems, then you have had experience in basic terminal commands. Open a terminal or command line and navigate to the directory where you saved all the codes.
- 2. On that directory, type **make** and press Enter. You might see warning signs, but you should not see errors. In the event of errors, please email rtgamot@up.edu.ph and report the error so that we can figure it out. Provide a screenshot for the output of the **make** command.

- 3. Obtain the training and test set data (files with extension .list) from our LMS and save it in the directory where you saved the codes.
- 4. The code you have been given is currently set up to learn to recognize the person with userid "glickman". Modify this code (you need to determine which source code you should modify) to implement a "kawamura" recognizer; i.e., train a neural net which, when given an image as input, indicates whether the face in the image is kawamura or not. Refer to the beginning of Section 3 for an overview of how to make changes to this code.
- 5. Train a network using the default learning parameter settings (learning rate 0.3, momentum 0.3) for 75 epochs, except for changing the hidden units appropriately according to what was edited in the previous item (if need be) with the following command:

```
./facetrain -n kawa.net -t straightrnd_train.list
```

- -1 straightrnd\_test1.list
- -2 straightrnd\_test2.list -e 75

Please provide a screenshot of the output of the command above.

Please note that the above command should be typed continuously in the command line

facetrain's arguments are described in Section 3.1.1, but a short description is in order here. kawa.net is the name of the network file which will be saved when training is finished. straightrnd\_train.list, straightrnd\_test1.list, and straightrnd\_test2.list are text files which specify the training set (70 examples) and two test sets (34 and 52 examples), respectively.

This command creates and trains your net on a randomly chosen sample of 70 of the 156 "straight" images, and tests it on the remaining 34 and 52 randomly chosen images, respectively. One way to think of this test strategy is that roughly  $\frac{1}{3}$  of the images (straightrnd\_test2.list) have been held over for testing. The remaining  $\frac{2}{3}$  have been used for a train and cross-validate strategy, in which  $\frac{2}{3}$  of these are being used for as a training set (straightrnd\_train.list) and  $\frac{1}{3}$  are being used for the validation set to decide when to halt training (straightrnd\_test1.list).

- 6. What code did you modify (Provide a screenshot for this)? What was the maximum classification accuracy achieved on the training set? How many epochs did it take to reach this level? How about for the validation set? The test set? Note that if you run it again on the same system with the same parameters and input, you should get exactly the same results because, by default, the code uses the same seed to the random number generator each time. You will need to read Section 3.1.2 carefully in order to be able to interpret your experiments and answer these questions.
- 7. Now, redo steps #4 to # 6 to learn to recognize "mitchell" but this time, use as training file "all\_train.list" and then "all\_test1.list" for test 1 and "all\_test2.list" for test 2. Please see step #5 as guide on what command to provide to train and test the network. You can also review Section 3.1.1 for the meaning of the options of the program facetrain.

Please provide screenshots/answers to questions similar to what were asked in steps #4 to #6 in this section.

- 8. Now, implement a 1-of-4 expression recognizer; i.e. implement a neural net that accepts an image as input, and outputs the expression of the person. To do this, you will need to implement a different output encoding (since you must now be able to distinguish among 4 expressions). (Hint: leave learning rate and momentum at 0.3, and use number of hidden units equal to the number of expressions).
- 9. As before, train the network, this time for 100 epochs:
  - ./facetrain -n exp.net -t straighteven\_train.list
  - -1 straighteven\_test1.list
  - -2 straighteven\_test2.list -e 100

Please provide a screenshot of the output of the command above.

Please note that the above command should be typed continuously in the command line

The difference between the

straightrnd\_\*.list and the straighteven\_\*.list sets is that while the former divides the images purely randomly among the training and test sets, the latter ensures a relatively even distribution of each individual's images over the sets. Because we have only 7 or 8 "straight" images per individual, failure to distribute them evenly would result in testing our network the most on those faces on which it was trained the least.

- 10. Which parts of the code was it necessary to modify this time (Provide a screenshot for this)? What was the maximum classification accuracy achieved on the training set? How many epochs did it take to reach this level? How about for the validation and test set?
- 11. Now let's take a closer look at which images the net may have failed to classify:

```
./facetrain -n exp.net -T -1 straighteven_test1.list
-2 straighteven_test2.list
```

Please note that the above command should be typed continuously in the command line

Do there seem to be any particular commonalities between the misclassified images? Please explain not by checking the quality of the images but by digging deep and checking the training and test lists and discussing from there. Please DO NOT provide answers in the lines of "because the images were blurry", "because the person looks asian" or "because the person has bangs".

- 12. Implement a pose recognizer; i.e. implement a neural net which, when given an image as input, indicates whether the person in the image is looking straight ahead, up, to the left, or to the right. You will also need to implement a different output encoding for this task. (Hint: leave learning rate and momentum at 0.3, and use 6 hidden units).
- 13. Train the network for 100 epochs, this time on samples drawn from all of the images:

```
./facetrain -n pose.net -t all_train.list -1 all_test1.list
-2 all_test2.list -e 100
```

Since the pose-recognizing network should have substantially fewer weights to update than the face-recognizing network, even those of you with slow machines can get in on the fun of using all of the images. In this case, 260 examples are in the training set, 140 examples are in test1, and 193 are in test2.

- 14. How did you encode your outputs this time (Provide a screenshot for this)? What was the maximum classification accuracy achieved on the training set? How many epochs did it take to reach this level? How about for each test set?
- 15. Now, try taking a look at how backpropagation tuned the weights of the hidden units with respect to each pixel. First type make hidtopgm to compile the utility on your system. Then, to visualize the weights of hidden unit n, type:
  - ./hidtopgm pose.net image-filename 32 30 n

When you open on the image *image-filename* it should display the range of weights, with the lowest weights mapped to pixel values of zero, and the highest mapped to 255. If the images just look like noise, try retraining using facetrain\_init0 (compile with make facetrain\_init0), which initializes the hidden unit weights of a new network to zero, rather than random values.

Provide a screenshot of all images associated with the weights of the hidden units for the expression recognizer.

16. Do the hidden units seem to weight particular regions of the image greater than others? Do particular hidden units seem to be tuned to different features of some sort? Please explain your answer according to each hidden unit and do not just provide a general explanation (e.g. explain hidden unit 1 and how it matches the expression associate with it, etc)

## 3 Documentation

The code for this assignment is broken into several modules:

- pgmimage.c, pgmimage.h: the image package. Supports read/write of PGM image files and pixel access/assignment. Provides an IMAGE data structure, and an IMAGELIST data structure (an array of pointers to images; useful when handling many images). You will not need to modify any code in this module to complete the assignment.
- backprop.c, backprop.h: the neural network package. Supports threelayer fully-connected feedforward networks, using the backpropagation

algorithm for weight tuning. Provides high level routines for creating, training, and using networks. You will not need to modify any code in this module to complete the assignment.

- imagenet.c: interface routines for loading images into the input units of a network, and setting up target vectors for training. You will need to modify the routine load target, when implementing the face recognizer and the pose recognizer, to set up appropriate target vectors for the output encodings you choose.
- facetrain.c: the top-level program which uses all of the modules above to implement a "TA" recognizer. You will need to modify this code to change network sizes and learning parameters, both of which are trivial changes. The performance evaluation routines performance\_on\_imagelist() and evaluate\_performance() are also in this module; you will need to modify these for your face and pose recognizers.
- hidtopgm.c: the hidden unit weight visualization utility. It's not necessary modify anything here, although it may be interesting to explore some of the numerous possible alternate visualization schemes.

Although you'll only need to modify code in imagenet.c and facetrain.c, feel free to modify anything you want in any of the files if it makes your life easier or if it allows you to do a nifty experiment.

#### 3.1 facetrain

#### 3.1.1 Running facetrain

facetrain has several options which can be specified on the command line. This section briefly describes how each option works. A very short summary of this information can be obtained by running facetrain with no arguments.

- -n <network file> this option either loads an existing network file, or creates a new one with the given name. At the end of training, the neural network will be saved to this file.
- -e <number of epochs> this option specifies the number of training epochs which will be run. If this option is not specified, the default is 100.

- -T for test-only mode (no training). Performance will be reported on each of the three datasets specified, and those images misclassified will be listed, along with the corresponding output unit levels.
- -s <seed>- an integer which will be used as the seed for the random number generator. The default seed is 102194 (guess what day it was when I wrote this document). This allows you to reproduce experiments if necessary, by generating the same sequence of random numbers. It also allows you to try a different set of random numbers by changing the seed.
- -S <number of epochs between saves> this option specifies the number of epochs between saves. The default is 100, which means that if you train for 100 epochs (also the default), the network is only saved when training is completed.
- -t <training image list> this option specifies a text file which contains a list of image pathnames, one per line, that will be used for training. If this option is not specified, it is assumed that no training will take place (epochs = 0), and the network will simply be run on the test sets. In this case, the statistics for the training set will all be zeros.
- -1 <test set 1 list> this option specifies a text file which contains a list of image pathnames, one per line, that will be used as a test set. If this option is not specified, the statistics for test set 1 will all be zeros.
- -2 <test set 2 list> same as above, but for test set 2. The idea behind having two test sets is that one can be used as part of the train/test paradigm, in which training is stopped when performance on the test set begins to degrade. The other can then be used as a "real" test of the resulting network.

#### 3.1.2 Interpreting the output of facetrain

When you run facetrain, it will first read in all the data files and print a bunch of lines regarding these operations. Once all the data is loaded, it will begin training. At this point, the network's training and test set performance is outlined in one line per epoch. For each epoch, the following performance measures are output:

<epoch> <delta> <trainperf> <trainerr> <t1perf> <t1err> <t2err>

These values have the following meanings:

- epoch is the number of the epoch just completed; it follows that a value of 0 means that no training has yet been performed.
- delta is the sum of all  $\delta$  values on the hidden and output units as computed during backprop, over all training examples for that epoch.
- trainperf is the percentage of examples in the training set which were correctly classified.
- trainerr is the average, over all training examples, of the error function  $\frac{1}{2}\sum (t_i o_i)^2$ , where  $t_i$  is the target value for output unit i and  $o_i$  is the actual output value for that unit.
- t1perf is the percentage of examples in test set 1 which were correctly classified.
- tlerr is the average, over all examples in test set 1, of the error function described above.
- t2perf is the percentage of examples in test set 2 which were correctly classified.
- t2err is the average, over all examples in test set 2, of the error function described above.

## 3.2 Tips

Although you do not have to modify the image or network packages, you will need to know a little bit about the routines and data structures in them, so that you can easily implement new output encodings for your networks. The following sections describe each of the packages in a little more detail. You can look at imagenet.c, facetrain.c, and facerec.c to see how the routines are actually used.

In fact, it is probably a good idea to look over facetrain.c first, to see how the training process works. You will notice that load\_target() from imagenet.c is called to set up the target vector for training. You will also

notice the routines which evaluate performance and compute error statistics, performance\_on\_imagelist() and evaluate\_performance(). The first routine iterates through a set of images, computing the average error on these images, and the second routine computes the error and accuracy on a single image.

You will almost certainly not need to use all of the information in the following sections, so don't feel like you need to know everything the packages do. You should view these sections as reference guides for the packages, should you need information on data structures and routines.

Another fun thing to do, if you didn't already try it in the last question of the assignment, is to use the image package to view the weights on connections in graphical form; you will find routines for creating and writing images, if you want to play around with visualizing your network weights.

Finally, the point of this assignment is for you to obtain first-hand experience in working with neural networks; it is **not** intended as an exercise in C hacking. An effort has been made to keep the image package and neural network package as simple as possible. If you need clarifications about how the routines work, don't hesitate to ask.

### 3.3 The neural network package

As mentioned earlier, this package implements three-layer fully-connected feedforward neural networks, using a backpropagation weight tuning method. We begin with a brief description of the data structure, a BPNN (BackPropNeuralNet).

All unit values and weight values are stored as doubles in a BPNN.

Given a BPNN \*net, you can get the number of input, hidden, and output units with net->input\_n, net->hidden\_n, and net->output\_n, respectively.

Units are all indexed from 1 to n, where n is the number of units in the layer. To get the value of the kth unit in the input, hidden, or output layer, use net->input\_units[k], net->hidden\_units[k], or net->output\_units[k], respectively.

The target vector is assumed to have the same number of values as the number of units in the output layer, and it can be accessed via net->target. The kth target value can be accessed by net->target[k].

To get the value of the weight connecting the ith input unit to the jth hidden unit, use net->input\_weights[i][j]. To get the value of the weight connecting the jth hidden unit to the kth output unit, use net->hidden\_weights[j][k].

The routines are as follows:

# void bpnn\_initialize(seed) int seed;

This routine initializes the neural network package. It should be called before any other routines in the package are used. Currently, its sole purpose in life is to initialize the random number generator with the input seed.

```
BPNN *bpnn_create(n_in, n_hidden, n_out)
  int n_in, n_hidden, n_out;
```

Creates a new network with  $n_i$  in input units,  $n_i$  hidden units, and  $n_i$  output output units. All weights in the network are randomly initialized to values in the range [-1.0, 1.0]. Returns a pointer to the network structure. Returns NULL if the routine fails.

```
void bpnn_free(net)
    BPNN *net;
```

Takes a pointer to a network, and frees all memory associated with the network.

```
void bpnn_train(net, learning_rate, momentum, erro, errh)
    BPNN *net;
    double learning_rate, momentum;
    double *erro, *errh;
```

Given a pointer to a network, runs one pass of the backpropagation algorithm. Assumes that the input units and target layer have been properly set up. learning\_rate and momentum are assumed to be values between 0.0 and 1.0. erro and errh are pointers to doubles, which are set to the sum of the  $\delta$  error values on the output units and hidden units, respectively.

```
void bpnn_feedforward(net)
     BPNN *net;
```

Given a pointer to a network, runs the network on its current input values.

Given a filename, allocates space for a network, initializes it with the weights stored in the network file, and returns a pointer to this new BPNN. Returns NULL on failure.

```
void bpnn_save(net, filename)
    BPNN *net;
    char *filename;
```

Given a pointer to a network and a filename, saves the network to that file.

#### 3.4 The image package

The image package provides a set of routines for manipulating PGM images. An image is a rectangular grid of pixels; each pixel has an integer value ranging from 0 to 255. Images are indexed by rows and columns; row 0 is the top row of the image, column 0 is the left column of the image.

```
IMAGE *img_open(filename)
    char *filename;
```

Opens the image given by filename, loads it into a new IMAGE data structure, and returns a pointer to this new structure. Returns NULL on failure.

```
IMAGE *img_creat(filename, nrows, ncols)
    char *filename;
    int nrows, ncols;
```

Creates an image in memory, with the given filename, of dimensions nrows × ncols, and returns a pointer to this image. All pixels are initialized to 0. Returns NULL on failure.

```
int ROWS(img)
    IMAGE *img;
```

Given a pointer to an image, returns the number of rows the image has.

```
int COLS(img)
    IMAGE *img;
```

Given a pointer to an image, returns the number of columns the image has.

```
char *NAME(img)
    IMAGE *img;
```

Given a pointer to an image, returns a pointer to its base filename (i.e., if the full filename is /usr/joe/stuff/foo.pgm, a pointer to the string foo.pgm will be returned).

```
int img_getpixel(img, row, col)
   IMAGE *img;
   int row, col;
```

Given a pointer to an image and row/column coordinates, this routine returns the value of the pixel at those coordinates in the image.

```
void img_setpixel(img, row, col, value)
    IMAGE *img;
    int row, col, value;
```

Given a pointer to an image and row/column coordinates, and an integer value assumed to be in the range [0, 255], this routine sets the pixel at those coordinates in the image to the given value.

```
int img_write(img, filename)
    IMAGE *img;
    char *filename:
```

Given a pointer to an image and a filename, writes the image to disk with the given filename. Returns 1 on success, 0 on failure.

```
void img_free(img)
    IMAGE *img;
```

Given a pointer to an image, deallocates all of its associated memory.

```
IMAGELIST *imgl_alloc()
```

Returns a pointer to a new IMAGELIST structure, which is really just an array of pointers to images. Given an IMAGELIST \*il, il->n is the number of images in the list. il->list[k] is the pointer to the kth image in the list.

```
void imgl_add(il, img)
    IMAGELIST *il;
    IMAGE *img;
```

Given a pointer to an imagelist and a pointer to an image, adds the image at the end of the imagelist.

```
void imgl_free(il)
    IMAGELIST *il;
```

Given a pointer to an imagelist, frees it. Note that this does not free any images to which the list points.

```
void imgl_load_images_from_textfile(il, filename)
    IMAGELIST *il;
    char *filename;
```

Takes a pointer to an imagelist and a filename. filename is assumed to specify a file which is a list of pathnames of images, one to a line. Each image file in this list is loaded into memory and added to the imagelist il.

#### 3.5 hidtopgm

hidtopgm takes the following fixed set of arguments: hidtopgm net-file image-file  $x \ y \ n$ 

net-file is the file containing the network in which the hidden unit weights are to be found.

*image-file* is the file to which the derived image will be output.

x and y are the dimensions in pixels of the image on which the network was trained.

n is the number of the target hidden unit. n may range from 1 to the total number of hidden units in the network.

#### 3.6 outtopgm

outtopgm takes the following fixed set of arguments: outtopgm net-file image-file x y n

This is the same as hidtopgm, for output units instead of input units. Be sure you specify x to be 1 plus the number of hidden units, so that you get to see the weight  $w_0$  as well as weights associated with the hidden units. For example, to see the weights for output number 2 of a network containing 3 hidden units, do this:

outtopgm pose.net pose-out2.pgm 4 1 2

net-file is the file containing the network in which the hidden unit weights are to be found.

image-file is the file to which the derived image will be output.

- x and y are the dimensions of the hidden units, where x is always 1 + the number of hidden units specified for the network, and y is always 1.
- n is the number of the target output unit. n may range from 1 to the total number of output units for the network.