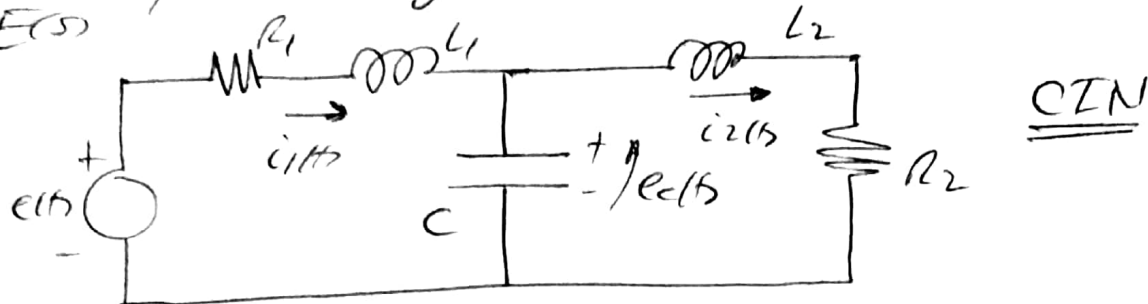


# Ejemplos de Resolución de Sistemas Lineales

Ejemplo #1 Obtenga las transferencias  $\frac{I_1(s)}{E(s)}$ ,  $\frac{I_2(s)}{E(s)}$  y

$\frac{E_c(s)}{E(s)}$  para el siguiente circuito eléctrico



Se considera:  $X(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix} = \begin{bmatrix} i_1(t) \\ i_2(t) \\ e_c(t) \end{bmatrix}$

$$e = R_1 x_1 + L_1 \dot{x}_1 + x_3 \rightarrow \dot{x}_1 = -\frac{R_1}{L_1} x_1 - \frac{1}{L_1} x_3 + \frac{1}{L_1} e$$

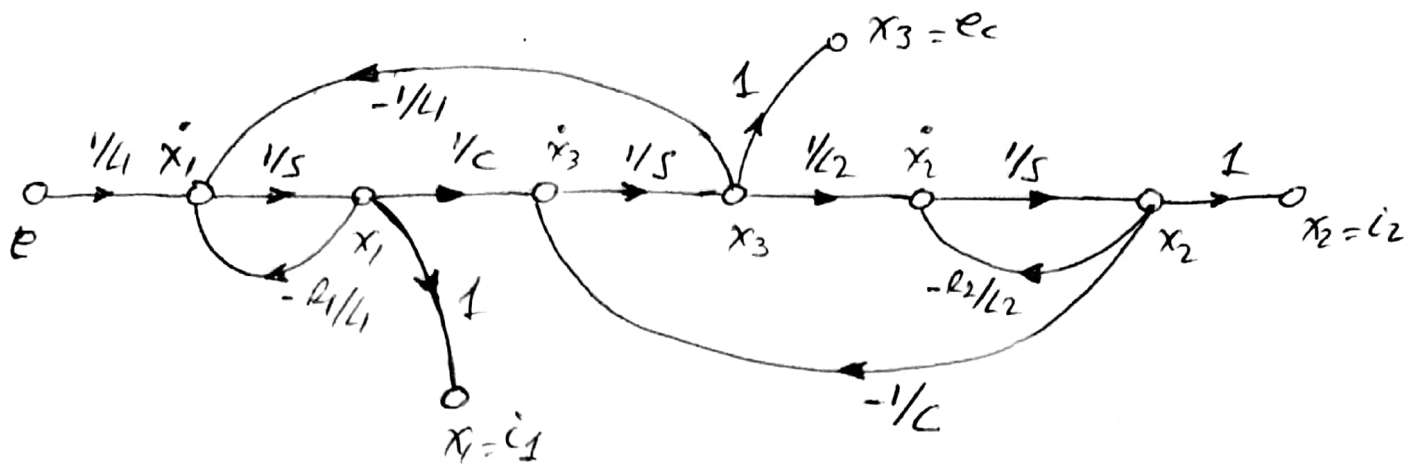
$$x_3 = L_2 \dot{x}_2 + R_2 x_2 \rightarrow \dot{x}_2 = -\frac{R_2}{L_2} x_2 + \frac{1}{L_2} x_3$$

$$C \dot{x}_3 = x_1 - x_2 \rightarrow \dot{x}_3 = \frac{1}{C} x_1 - \frac{1}{C} x_2$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} -R_1/L_1 & 0 & -1/L_1 \\ 0 & -R_2/L_2 & 1/L_2 \\ 1/C & -1/C & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 1/L_1 \\ 0 \\ 0 \end{bmatrix} e \quad (1)$$

$$\begin{bmatrix} i_1(t) \\ i_2(t) \\ e_c(t) \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} e$$

De las Ec. de Estados y Slide, se puede armar el Diagrama de Flujo de Estados



$$\Delta = 1 + \frac{R_1}{sL_1} + \frac{1}{s^2L_2C} + \frac{R_2}{sL_2} + \frac{1}{s^2LC} + \frac{R_1R_2}{s^2L_1L_2} + \frac{R_1}{s^3L_1L_2C} + \frac{R_2}{s^3L_1L_2C}$$

$$\Delta = \frac{s^3L_1L_2C + s^2L_2C + sL_1 + s^2LCR_2 + sL_2 + sCR_1R_2 + R_1 + R_2}{s^3L_1L_2C}$$

$$\Delta = \frac{s^3L_1L_2C + s^2C(L_2R_1 + L_1R_2) + s(L_1 + L_2 + CR_1R_2) + R_1 + R_2}{s^3L_1L_2C}$$

$$\frac{I_1(s)}{E(s)} = \frac{\frac{1}{sL_1} \left( 1 + \frac{R_2}{sL_2} + \frac{1}{s^2L_2C} \right)}{\Delta} = \frac{\frac{s^2L_2C + sCR_2 + 1}{s^3L_1L_2C}}{\Delta}$$

$$\frac{I_1(s)}{E(s)} = \frac{s^2L_2C + sCR_2 + 1}{s^3L_1L_2C + s^2C(L_2R_1 + L_1R_2) + s(L_1 + L_2 + CR_1R_2) + R_1 + R_2} \quad (2)$$

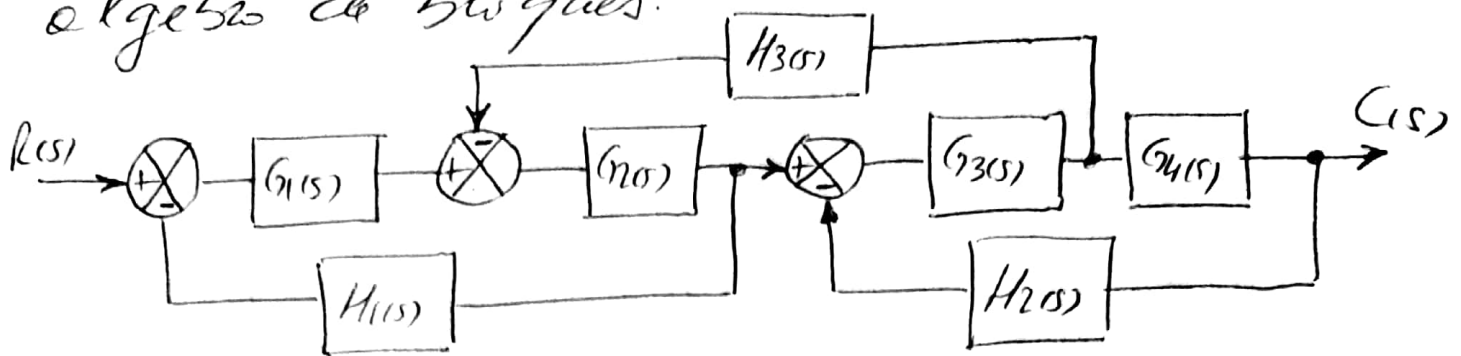
$$\frac{I_2(s)}{E(s)} = \frac{\frac{1}{s^3L_1L_2C}}{\Delta}, \text{ or } \frac{1}{s^3L_1L_2C \Delta}$$

$$\frac{I_2(s)}{E(s)} = \frac{1}{s^3L_1L_2C + s^2C(L_2R_1 + L_1R_2) + s(L_1 + L_2 + CR_1R_2) + R_1 + R_2} \quad (3)$$

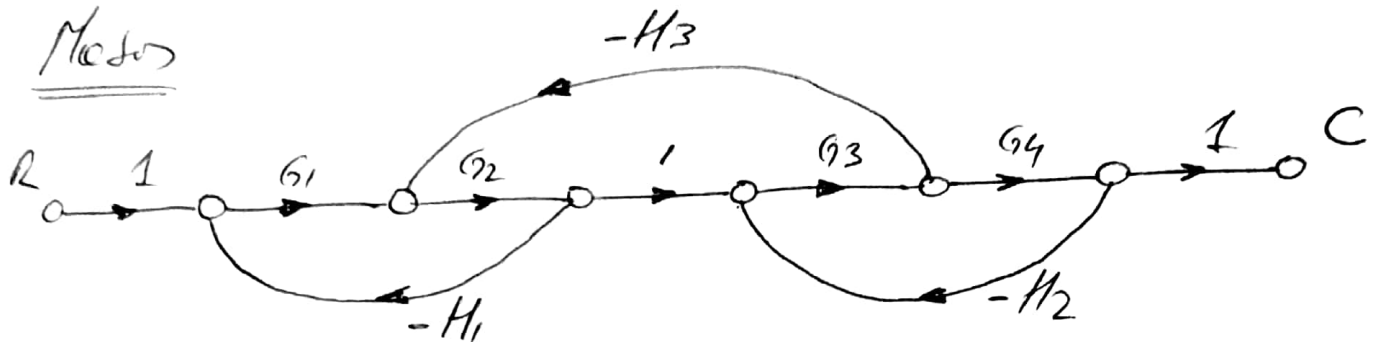
$$\frac{E_c(s)}{E(s)} = \frac{\frac{1}{s^2LC} \left( 1 + \frac{R_2}{sL_2} \right)}{\Delta} = \frac{\frac{sL_2 + R_2}{s^3L_1L_2C}}{\Delta}$$

$$\frac{E_c(s)}{E(s)} = \frac{sL_2 + R_2}{s^3L_1L_2C + s^2C(L_2R_1 + L_1R_2) + s(L_1 + L_2 + CR_1R_2) + R_1 + R_2} \quad (4)$$

Ejemplo #2 Resolver por Método y verificar mediante álgebra de bloques.



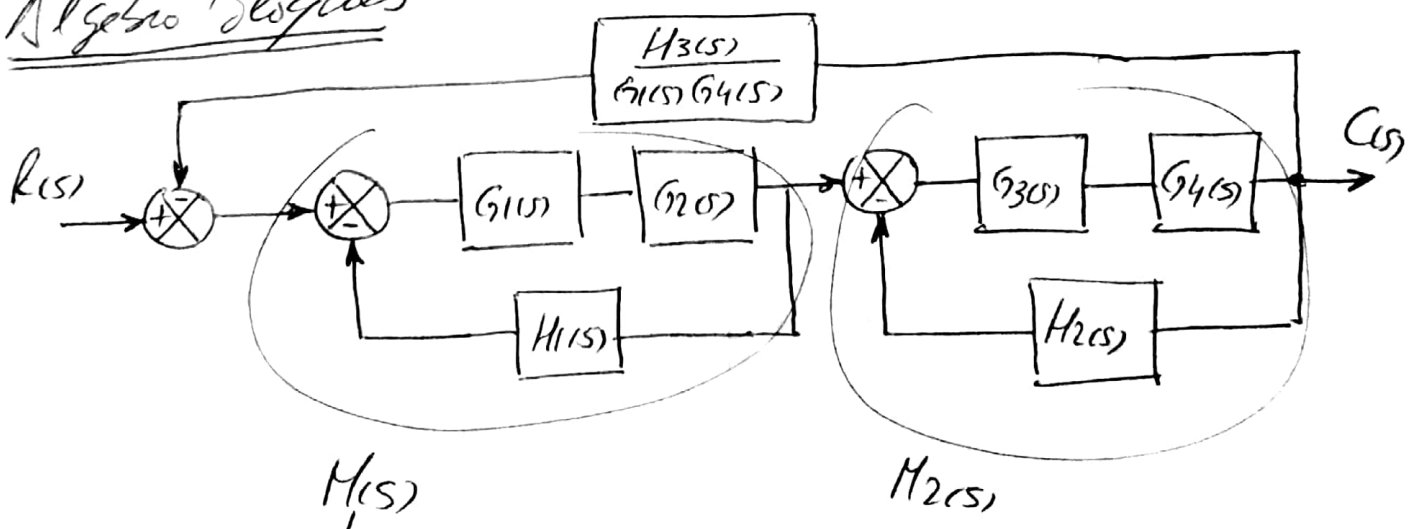
Método



$$\Delta = 1 + G_1 G_2 H_1 + G_2 G_3 H_3 + G_3 G_4 H_2 + G_1 G_2 G_3 G_4 H_1 H_2$$

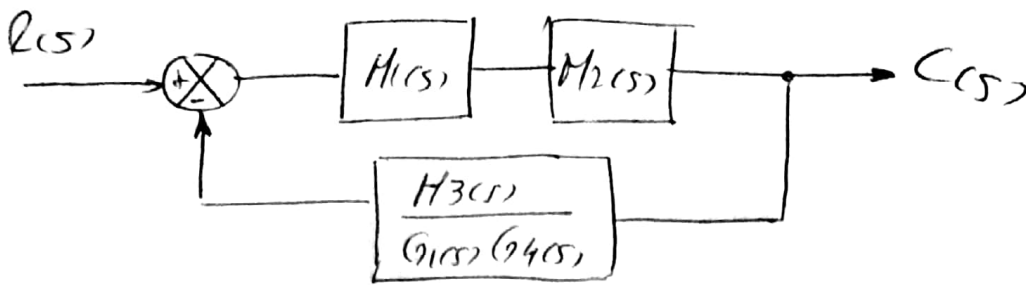
$$\frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4}{1 + G_1 G_2 H_1 + G_2 G_3 H_3 + G_3 G_4 H_2 + G_1 G_2 G_3 G_4 H_1 H_2} \quad (5)$$

Álgebra de Bloques



$$M_1(s) = \frac{G_1 G_2}{1 + G_1 G_2 H_1} ; \quad M_2(s) = \frac{G_3 G_4}{1 + G_3 G_4 H_2}$$

En consecuencia, se tiene que:



$$\frac{C(s)}{R(s)} = \frac{H_1 H_2}{1 + H_1 H_2 \frac{H_3}{G_1 G_4}} = \frac{\frac{G_1 G_2}{1 + G_1 G_2 H_1} \cdot \frac{G_3 G_4}{1 + G_3 G_4 H_2}}{1 + \frac{G_1 G_2}{1 + G_1 G_2 H_1} \cdot \frac{G_3 G_4}{1 + G_3 G_4 H_2} \cdot \frac{H_3}{G_1 G_4}}$$

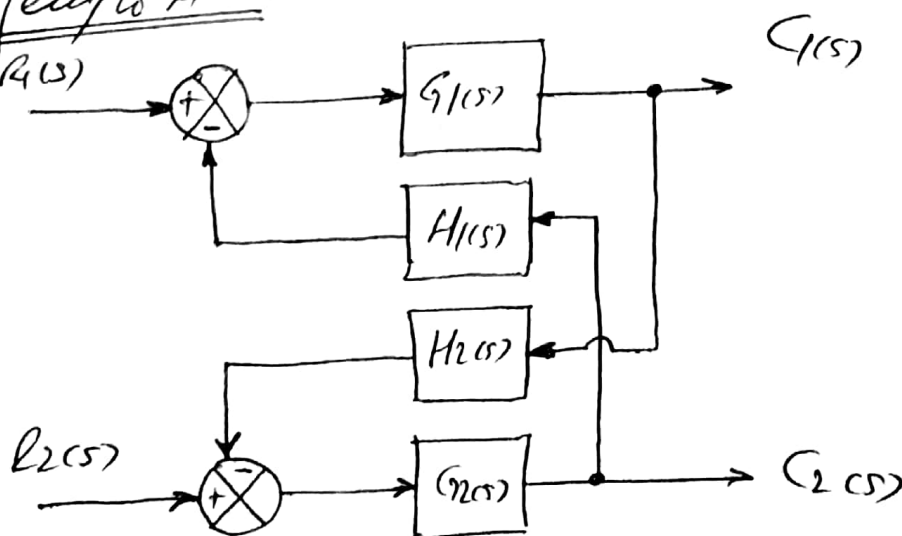
$$\frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4}{(1 + G_1 G_2 H_1)(1 + G_3 G_4 H_2) + G_2 G_3 H_3}$$

$$\frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4}{1 + G_3 G_4 H_2 + G_1 G_2 H_1 + G_1 G_2 H_1 G_3 G_4 H_2 + G_2 G_3 H_3}$$

$$\frac{C(s)}{R(s)} = \frac{G_1 G_2 G_3 G_4}{1 + G_1 G_2 H_1 + G_2 G_3 H_3 + G_3 G_4 H_2 + G_1 G_2 G_3 G_4 H_1 H_2} \quad (6)$$

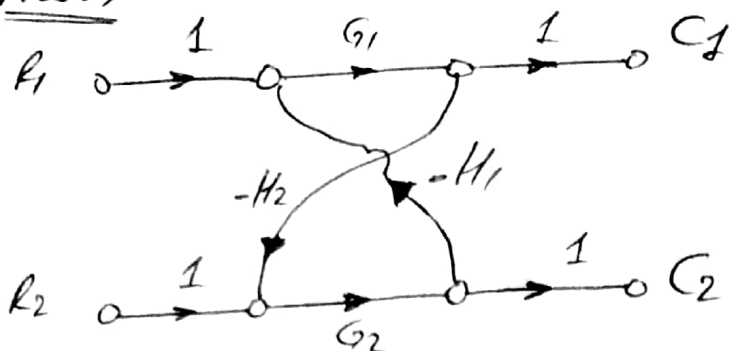
Las Ecs (5) y (6) son iguales.

### Ejemplo # 3



Calcule  $C_1(s)$  y  $C_2(s)$ .

Modelo



$$\Delta = 1 - G_1 G_2 H_1 H_2$$

$$C_1 \Big|_{R_1} = \frac{G_1}{\Delta} R_1 ; \quad C_1 \Big|_{R_2} = \frac{-G_1 G_2 H_1}{\Delta} R_2$$

$$C_1 = C_1 \Big|_{R_1} + C_1 \Big|_{R_2} = \frac{G_1 R_1}{\Delta} - \frac{G_1 G_2 H_1 R_2}{\Delta} ; \text{ con lo cual}$$

$$C_1(s) = \frac{G_1(s) R_1(s) - G_1(s) G_2(s) H_1(s) R_2(s)}{1 - G_1(s) G_2(s) H_1(s) H_2(s)} \quad (7)$$

$$C_2 \Big|_{R_2} = \frac{G_2}{\Delta} R_2 ; \quad C_2 \Big|_{R_1} = \frac{-G_1 G_2 H_2 R_1}{\Delta} \Rightarrow$$

$$C_2(s) = C_2 \Big|_{R_2} + C_2 \Big|_{R_1} = \frac{G_2 R_2}{\Delta} - \frac{G_1 G_2 H_2 R_1}{\Delta} \Rightarrow$$

$$C_2(s) = \frac{G_2(s) R_2(s) - G_1(s) G_2(s) H_2(s) R_1(s)}{1 - G_1(s) G_2(s) H_1(s) H_2(s)} \quad (8)$$

Resoluci3n:

De la figura del Ejemplo #3, se tiene que:

$$C_1 = G_1(R_1 - H_1 C_2) ; \quad C_1 + G_1 H_1 C_2 = G_1 R_1 \quad (a)$$

$$C_2 = G_2(R_2 - H_2 C_1) ; \quad G_2 H_2 C_1 + C_2 = G_2 R_2 \quad (b)$$

$$\text{De (a) y (b)} \rightarrow \begin{bmatrix} 1 & G_1 H_1 \\ G_2 H_2 & 1 \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} G_1 R_1 \\ G_2 R_2 \end{bmatrix}$$

$$C = \frac{\det \begin{bmatrix} G_1 R_1 & G_1 H_1 \\ G_2 R_2 & 1 \end{bmatrix}}{\det \begin{bmatrix} 1 & G_1 H_1 \\ G_2 H_2 & 1 \end{bmatrix}} = \frac{G_1 R_1 - G_1 G_2 H_1 R_2}{1 - G_1 G_2 H_1 H_2} \quad (9)$$

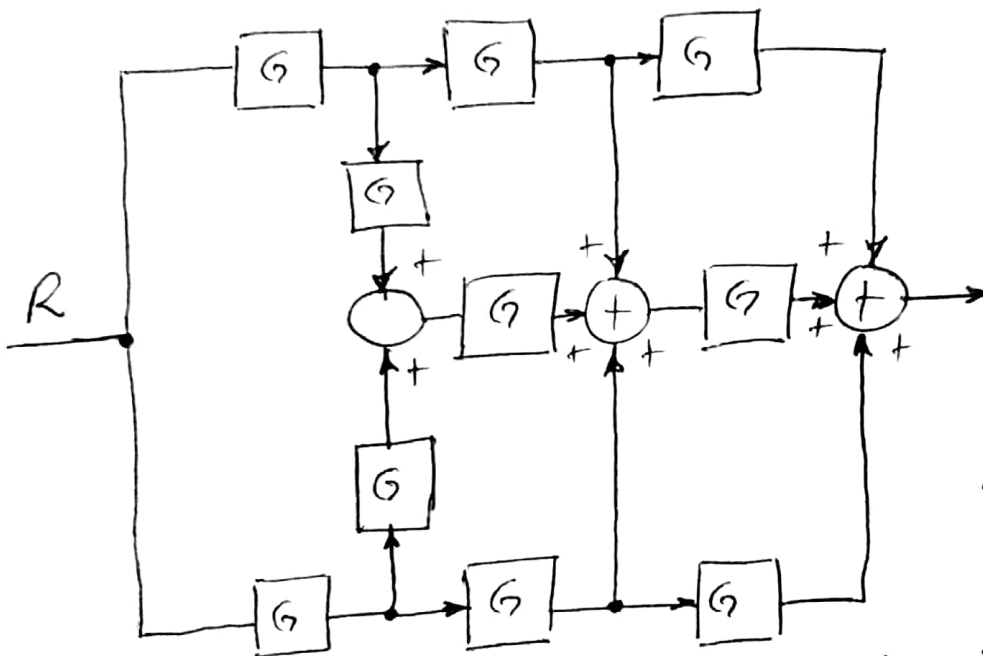


$$C_2 = \frac{\det \begin{bmatrix} 1 & G_1 H_1 \\ G_2 H_2 & G_2 R_2 \end{bmatrix}}{\det \begin{bmatrix} 1 & G_1 H_1 \\ G_2 H_2 & 1 \end{bmatrix}} = \frac{G_2 R_2 - G_1 G_2 H_2 R_1}{1 - G_1 G_2 H_1 H_2} \quad (10)$$

Se observa que  $(7) = (9)$  y  $(8) = (10)$

### Ejemplo #4

Encuentre  $\frac{Y(s)}{R(s)}$  siendo  $G(s) = \frac{1}{s+1}$



No hay LAPOS  
Todos caminos directos!!!

$$\Delta = 1$$

$$\frac{Y}{R} = \frac{\sum P_k \Delta_k}{\Delta} = \frac{G^3 + G^4 + G \cdot G^3 + G^3 + G^4 + G^3}{1} = 4G^3 + 2G^4$$

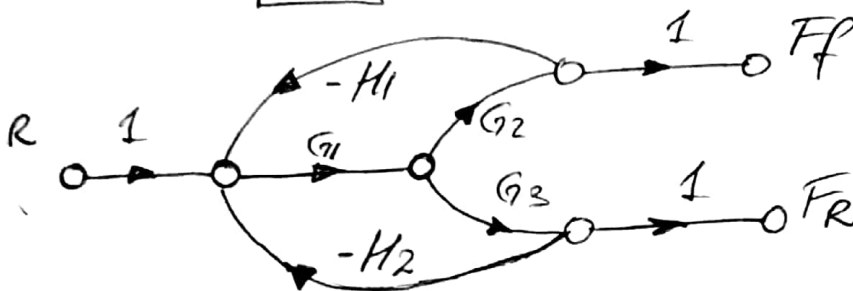
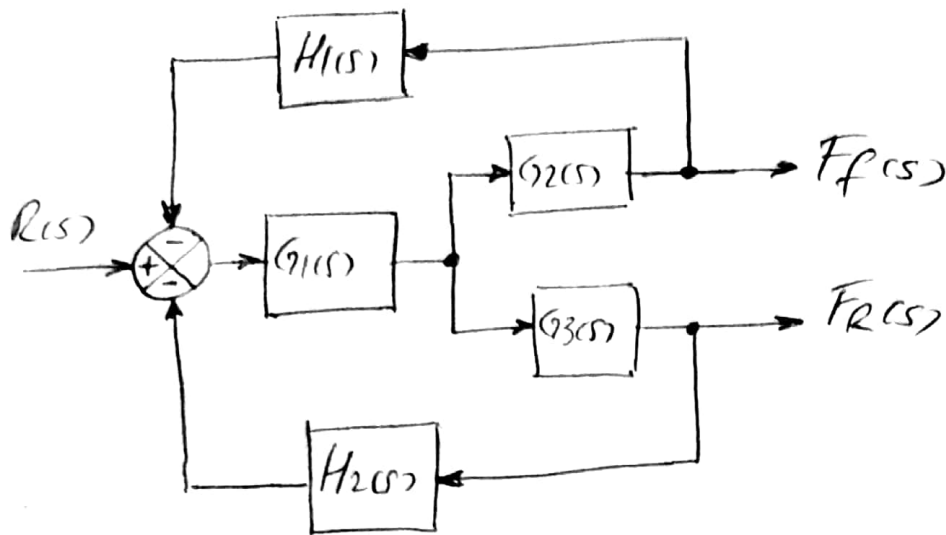
$$\frac{Y}{R} = 2G^3(2+G) = 2 \cdot \frac{1}{(s+1)^3} \left( 2 + \frac{1}{s+1} \right) = \frac{2}{(s+1)^3} \cdot \frac{2(s+1)+1}{s+1}$$

$$\frac{Y}{R} = \frac{2}{(s+1)^3} \cdot \frac{2s+3}{s+1} = \frac{2}{(s+1)^3} \cdot \frac{2(s+3/2)}{(s+1)}$$

$$\frac{Y(s)}{R(s)} = \frac{4(s+3/2)}{(s+1)^4}$$

(11)

Ejemplo #5 Calcular  $\frac{F_f(s)}{R(s)}$  y  $\frac{F_R(s)}{R(s)}$



$$\Delta = 1 + G_1 G_2 H_1 + G_1 G_3 H_2 ; \quad \frac{F_f}{R} = \frac{G_1 G_2}{\Delta} ; \quad \frac{F_R}{R} = \frac{G_1 G_3}{\Delta}$$

$$\frac{F_f(s)}{R(s)} = \frac{G_1(s) G_2(s)}{1 + G_1(s) G_2(s) H_1(s) + G_1(s) G_3(s) H_2(s)} \quad (12)$$

$$\frac{F_R(s)}{R(s)} = \frac{G_1(s) G_3(s)}{1 + G_1(s) G_2(s) H_1(s) + G_1(s) G_3(s) H_2(s)} \quad (13)$$

Ejemplo #6 Calcular la Ec. Dif. del proceso descrito por la siguiente función transferencia, así también como su modelo de estados

$$\frac{Y(s)}{U(s)} = \frac{3(s+2)(s+6)}{s(s+1)(s^2+4s+8)(s+12)}$$

Con ayuda de Matlab (¿qué instrucciones?), se tiene que:

$$\frac{Y(s)}{U(s)} = \frac{3s^2 + 24s + 36}{s^5 + 17s^4 + 72s^3 + 152s^2 + 96s}$$

$$(s^5 + 17s^4 + 72s^3 + 152s^2 + 96s)Y(s) = (3s^2 + 24s + 36)u(s) \xrightarrow{\div}$$

$$y^{(V)}(t) + 17y^{(IV)}(t) + 72y'''(t) + 152y''(t) + 96y'(t) = 3u''(t) + 24u'(t) + 36u(t) \quad (14)$$

$$Y(s) = \frac{\overbrace{3s^2}^{b_2} + \overbrace{24s}^{b_1} + \overbrace{36}^{b_0}}{\underbrace{s^5}_{a_4} + \underbrace{17s^4}_{a_3} + \underbrace{72s^3}_{a_2} + \underbrace{152s^2}_{a_1} + \underbrace{96s}_{a_0}}$$

$$D = [bs] = [0]; \quad B = [0 \ 0 \ 0 \ 0 \ 1]^T;$$

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & -96 & -152 & -72 & -17 \end{bmatrix}$$

$$C = [(b_0 - b_5 a_0)(b_1 - b_5 a_1)(b_2 - b_5 a_2)(b_3 - b_5 a_3)(b_4 - b_5 a_4)]$$

$$C = [36 \ 24 \ 3 \ 0 \ 0] \Rightarrow$$

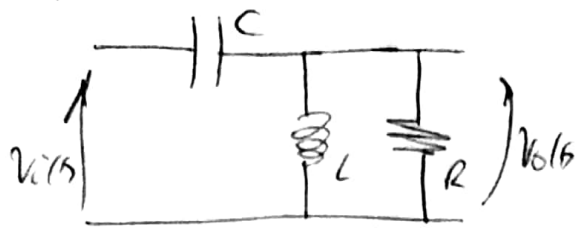
$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \\ \dot{x}_4 \\ \dot{x}_5 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & -96 & -152 & -72 & -17 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} u$$

(15)

$$y = [36 \ 24 \ 3 \ 0 \ 0] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} + [0]u$$



# Ejemplo #7



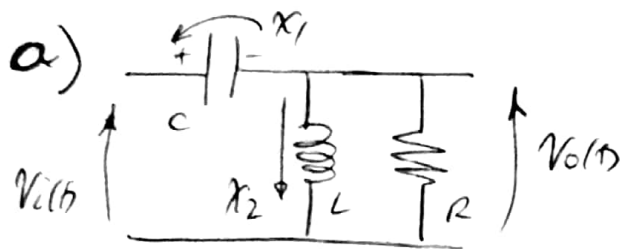
CE:  $V_o(0) = V_o$ ;  $i_L(0) = 40$

Dado el siguiente circuito,  
Se pide

a) Modelo de Estados

b)  $V_o(s)/V_i(s)$  en la columna anteriormente

c) Modelo de Flujo de Estados y cálculo de  $V_o(s)$



$$V_o(s) = V_i - x_1 \quad (I)$$

$$L \dot{x}_2 = V_o = V_i - x_1; \quad \dot{x}_2 = -\frac{1}{L} x_1 + \frac{1}{L} V_i \quad (II)$$

$$C \dot{x}_1 = x_2 + \frac{V_o}{R} = x_2 + \frac{V_i - x_1}{R} = -\frac{x_1}{R} + x_2 + \frac{V_i}{R}$$

$$\dot{x}_1 = -\frac{1}{RC} x_1 + \frac{1}{C} x_2 + \frac{1}{RC} V_i \quad (III) \text{ De } (I), (II) \text{ y } (III)$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} -\frac{1}{RC} & \frac{1}{C} \\ -\frac{1}{L} & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} \frac{1}{RC} \\ \frac{1}{L} \end{bmatrix} V_i$$

$$V_o(s) = \begin{bmatrix} -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 1 \end{bmatrix} V_i$$

b)  $\frac{V_o(s)}{V_i(s)} = C(SI - A)^{-1}B + D$

$$(SI - A) = \begin{pmatrix} S & 0 \\ 0 & S \end{pmatrix} - \begin{pmatrix} -\frac{1}{RC} & \frac{1}{C} \\ -\frac{1}{L} & 0 \end{pmatrix} = \begin{pmatrix} S + \frac{1}{RC} & -\frac{1}{C} \\ \frac{1}{L} & S \end{pmatrix}$$

$$\det(SI - A) = S^2 + \frac{1}{RC}S + \frac{1}{LC}; \quad (SI - A)^{-1} = \frac{\begin{pmatrix} S & \frac{1}{C} \\ -\frac{1}{L} & S + \frac{1}{RC} \end{pmatrix}}{S^2 + \frac{1}{RC}S + \frac{1}{LC}}$$

$$\frac{V_o(s)}{V_i(s)} = C(SI - A)^{-1}B + D = \frac{(-1 \ 0) \begin{pmatrix} S & \frac{1}{C} \\ -\frac{1}{L} & S + \frac{1}{RC} \end{pmatrix} \begin{pmatrix} \frac{1}{RC} \\ \frac{1}{L} \end{pmatrix} + 1}{\det(SI - A)}$$

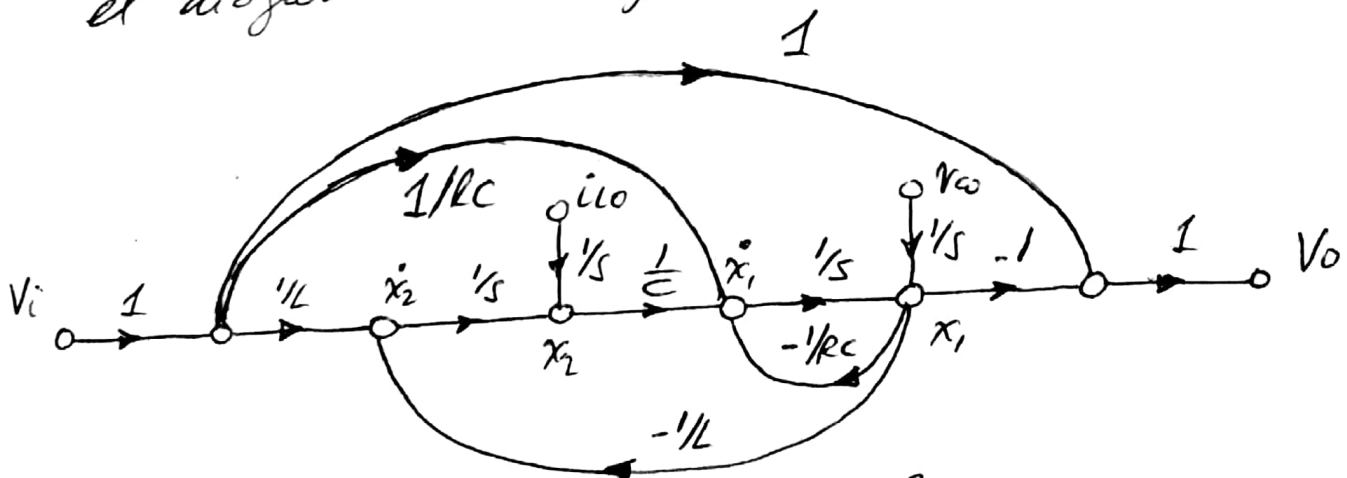
$$\frac{V_o(s)}{V_i(s)} = \frac{(-S \ -\frac{1}{C}) \begin{pmatrix} \frac{1}{RC} \\ \frac{1}{L} \end{pmatrix} + 1}{\det(SI - A)} + 1 = \frac{-\frac{1}{RC}S - \frac{1}{LC}}{S^2 + \frac{1}{RC}S + \frac{1}{LC}} + 1$$

$$\frac{V_o(s)}{V_i(s)} = \frac{\cancel{-\frac{1}{RC}S - \frac{1}{LC}} + \cancel{S^2 + \frac{1}{RC}S + \frac{1}{LC}}}{S^2 + \frac{1}{RC}S + \frac{1}{LC}} \rightarrow$$

$$\frac{V_o(s)}{V_i(s)} = \frac{S^2}{S^2 + \frac{1}{RC}S + \frac{1}{LC}}$$

(17)

c) A partir de las Ecs. (16), podemos obtener el diagrama de Flujo de Estados



$$\Delta = 1 + \frac{1}{RC} \frac{1}{s} + \frac{1}{LC} \frac{1}{s^2} = \frac{s^2 LCR + LS + R}{LCs^2}$$

$$\frac{V_o}{V_i} = \frac{\sum_i p_i \Delta_i}{\Delta} = \frac{1 \left( 1 + \frac{1}{RC} \frac{1}{s} + \frac{1}{LC} \frac{1}{s^2} \right) - \frac{1}{RC} \frac{1}{s} - \frac{1}{LC} \frac{1}{s^2}}{\Delta} V_i(s)$$

$$\frac{V_o}{V_i} = \frac{1 \cdot V_i(s)}{\frac{s^2 LCR + LS + R}{LCs^2}} = \frac{(LCs^2) V_i(s)}{s^2 LCR + LS + R} = \frac{\cancel{LC} s^2 V_i(s)}{\cancel{LC} (s^2 + \frac{1}{RC} s + \frac{1}{LC})}$$

$$V_O(s)/V_{i(s)} = \frac{s^2 V_{i(s)}}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} \quad (1P)$$

$$V_O(s)/i_{L0} = \frac{-\frac{Li_0}{s}}{\frac{s^2 LC R + Ls + R}{LC R s^2}} = \frac{-LC R i_{L0}}{LC R (s^2 + \frac{1}{RC}s + \frac{1}{LC})}$$

$$V_O(s)/i_{L0} = \frac{-\frac{1}{C} i_{L0}}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} \quad (1P)$$

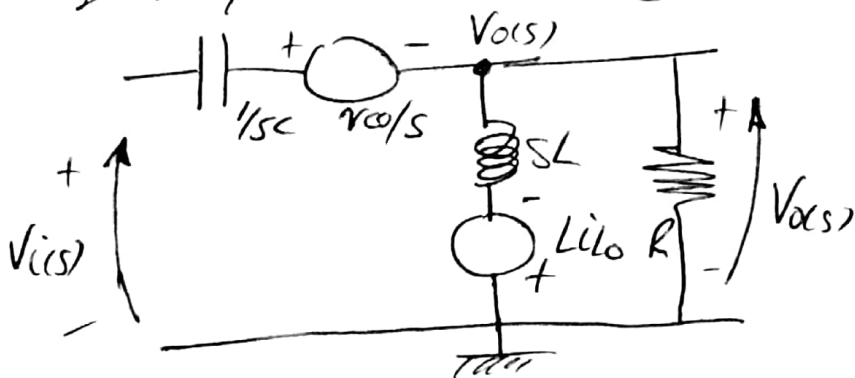
$$V_O(s)/V_{C0} = \frac{-\frac{V_{C0}}{s}}{\frac{s^2 LC R + Ls + R}{LC R s^2}} = \frac{-LC R s V_{C0}}{LC R (s^2 + \frac{1}{RC}s + \frac{1}{LC})}$$

$$V_O(s)/V_{C0} = \frac{-s V_{C0}}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} \quad (2P). \text{ De (1P), (1P) y (2P)}$$

$$V_O(s) = -\frac{s V_{C0} + \frac{i_{L0}}{s}}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} + \frac{s^2}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} V_{i(s)} \quad (21)$$

De (21) puede observarse claramente la componente Natural (Transitoria), así también como la Forzada.

Se verificará la Ec. (21) por Laplace



Se resuelve por Nodos:  
Hay 1 solo nodo que es  $V_O(s)$

$$V_O(s) \left( sC + \frac{1}{sL} + \frac{1}{R} \right) = sC \left( V_{i(s)} - \frac{V_{C0}}{s} \right) - \frac{L i_{L0}}{sL}$$

$$V_o(s) \frac{s^2 LC R + R + SL}{SLR} = \cancel{s} C \frac{s V_{ic}(s) - V_{co}}{\cancel{s}} - \frac{i_{L0} L}{SL}$$

$$V_o(s) = \frac{SLR}{s^2 LC R + SL + R} C s V_{ic}(s) - \frac{SLRC V_{co}}{s^2 LC R + SL + R} - \cancel{\frac{SLR}{s^2 LC + SL + R}} \frac{L i_{L0}}{\cancel{SL}}$$

$$V_o(s) = \frac{s^2 SLRC V_{ic}(s)}{LCR(s^2 + \frac{1}{RC}s + \frac{1}{LC})} - \frac{SLRC V_{co}}{LCR(s^2 + \frac{1}{RC}s + \frac{1}{LC})} - \frac{L i_{L0}}{LCR(s^2 + \frac{1}{RC}s + \frac{1}{LC})}$$

$$V_o(s) = -\frac{s V_{co} + \frac{i_{L0}}{C}}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} + \frac{s^2}{s^2 + \frac{1}{RC}s + \frac{1}{LC}} V_{ic}(s) \quad (22)$$

Se observa que las Ecs. (21) y (22) son iguales.