Detecting fire with drones

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Goal

Prevent fires by:

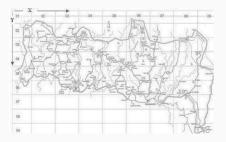
- · Providing tools to help forest guards.
- Using drones to automatically patrol vulnerable areas.



https://upload.wikimedia.org/wikipedia/commons/9/98/Simi_Valley_fire_California_USA.jpg

Step 1 – Build a model

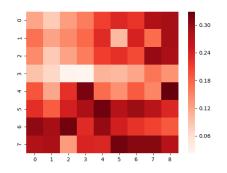
- · Find a dataset. Montesihno Park contains:
 - · Historic information of fire and weather characteristics.
 - · Data distributed in a grid.



• Use supervised machine learning (linear regression) to infer a function for the **probability of fire**.

Step 2 – Help forest guards

Use the **model** and the information from the **sensors** in the park to **build a risk map** with probability of fire.



To be used by forest guards to:

- · distribute available resources,
- · clean the area (e.g., remove dry plants),

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Step 3 – Patrol Automatically

The drone uses the probability of fire to patrol automatically the most vulnerable areas.

DEMO

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The **drone** uses the probability of fire to **patrol automatically the** most vulnerable areas.

DEMO

Future work:

- take pictures, to be checked by the forest guards.
- recognize fire in the pictures using image recognition algorithms.

Summary – What did we do?

- Found a dataset of fires in Mountesihno Park.
- · Processed the data.
- · Built a model of the risk of fire.
- Built a visualization tool for the forest guards.
- · Programmed a patrolling algorithm (using ROS).







