



ENGR 21:

Computer Engineering Fundamentals

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Lecture 21
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Polynomial Interpolation

Finding a straight line through 2 points is the simplest kind of polynomial interpolation

1. Write down the equation of a line

$$y = a_0 + a_1 x$$

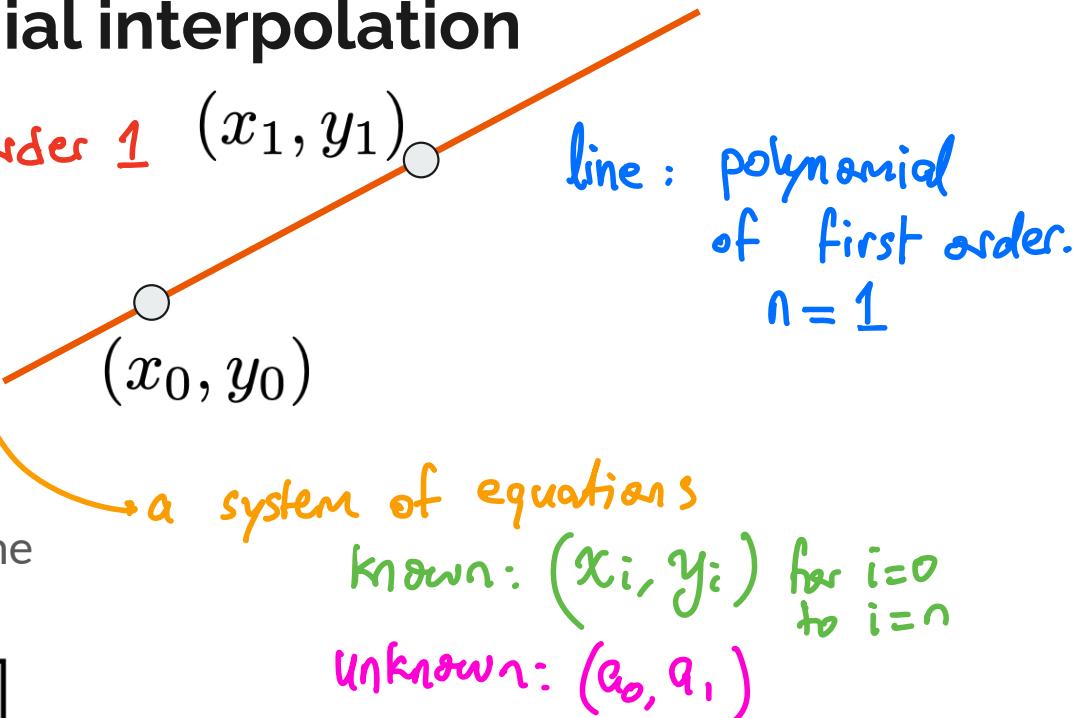
2. Plug in the data points

2 equations
2 points

$$\left. \begin{array}{l} y_0 = a_0 + a_1 x_0 \\ y_1 = a_0 + a_1 x_1 \end{array} \right\}$$

3. Solve simultaneous equations for the two unknowns

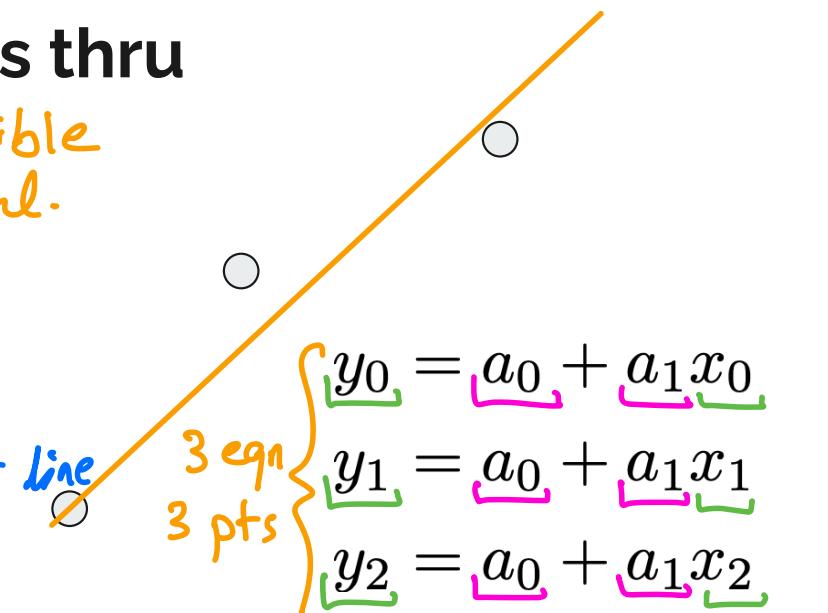
$$\begin{bmatrix} 1 & x_0 \\ 1 & x_1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \end{bmatrix}$$



Finding a straight line that goes thru all three points Not possible in general.

- Use 3 data points to attempt a straight line fit to three points.

→ Need a curve, not straight line
→ Let's use quadratic curve.



$$\begin{bmatrix} 1 & x_0 \\ 1 & x_1 \\ 1 & x_2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

Known
Unknown

Finding a quadratic curve that goes **thru** all **three points** order n=2

3 coefficients

$$y = a_0 + a_1 x + a_2 x^2$$

2. Plug in the data points

3 eqns.
3 pts.
3 unknowns

$$y_0 = a_0 + a_1 x_0 + a_2 x_0^2$$

$$y_1 = a_0 + a_1 x_1 + a_2 x_1^2$$

$$y_2 = a_0 + a_1 x_2 + a_2 x_2^2$$

3. Solve simultaneous equations for the three unknowns

$$\begin{bmatrix} 1 & x_0 & x_0^2 \\ 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ y_2 \end{bmatrix}$$

Knowns Unknowns

NOT close by!
exactly pass through
(x_2, y_2)

(x_1, y_1)

(x_0, y_0)

A polynomial of order 2 can "interpolate between" 3 points

Knowns
Unknowns

$$A \vec{x} = \vec{b}$$

3x3 matrix
3x1 vector
3x1 vector

Matrix - vector equation
can be solved with
direct / iterative numerical
methods.

Generalizing Polynomial Interpolation

You can (almost) always find a unique n-degree polynomial that goes through $n+1$ points^{known} using a matrix of size $(n+1) \times (n+1)$

$$\begin{bmatrix} x_0^0 & 1 & x_0^1 & x_0^2 & \cdots & x_0^n \\ x_1^0 & 1 & x_1^1 & x_1^2 & \cdots & x_1^n \\ \vdots & \vdots & \vdots & \ddots & & \vdots \\ x_n^0 & 1 & x_n^1 & x_n^2 & \cdots & x_n^n \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{bmatrix}$$

numpy.linalg.solve(A, b)

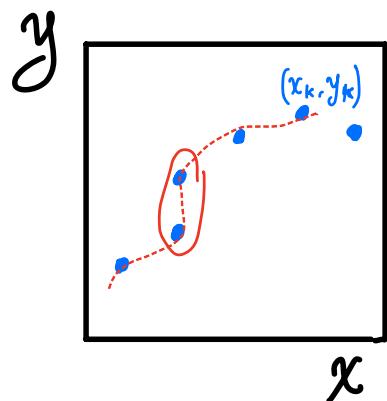
unknowns.
Solve for this

to build $y(x)$, given
 a_0, a_1, \dots, a_n
numpy.polyval

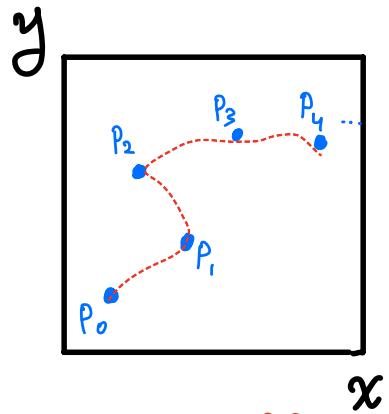
then you have a
function,
 $y(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \dots + a_nx^n$

and
 $y(x_k) = y_k$ for all k from 0 to n

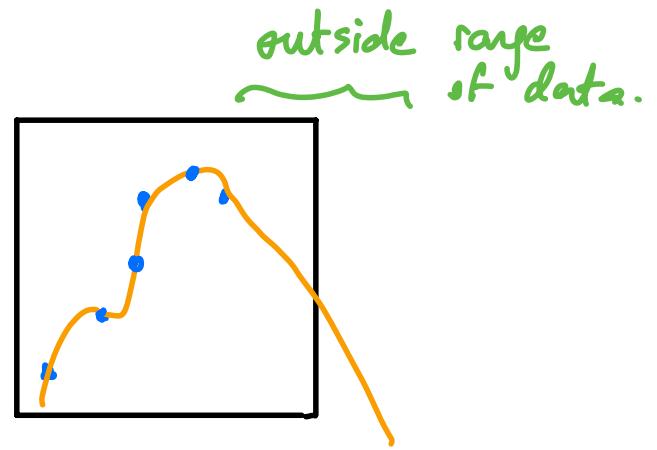
Potential Difficulties with Interpolation Matrices



function would have
to go vertical



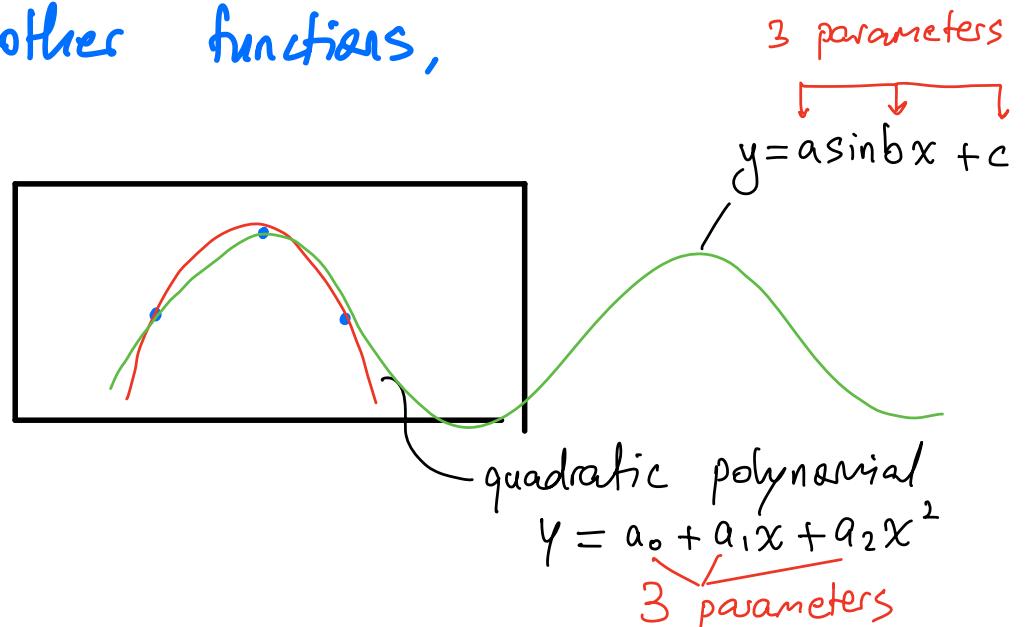
Backtracking



- only works in the region where you have data.
- Bad idea to extrapolate

Polynomial Interpolation

→ Can also interpolate with other functions, not necessarily polynomials.



Interpolating Matrices activity

a single line of code
that solves $A\bar{x} = \bar{b}$

- Download coordinates from course website
- Write code that:
 - Generates the interpolating matrix for these points
 - Solves a linear system for the coefficients
- How would you use these coefficients to write the interpolating function?

```
from numpy.linalg import inv as invert
from numpy import dot
```

numpy.loadtxt

x = dot(inv(A), b)

x
1.0
2.0
2.5
3.0
3.5
4.5
6.0
9.0
9.5
10.0