



Software Engineering 2022W E2: Use Case Analysis



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Schedule

Topic	Date	Туре	Lecturer
E1: Familiarize with Dronology	5-Oct-22	Individual	Wesley
E2: Use Case Analysis	12-Oct-22	Individual	Luciano
E3: Tracing Use Cases to EARS Requirements	19-Oct-22	Team	Cosmina
E4: Requirements Engineering Mission Planning	9-Nov-22	Individual	Wesley/Cosmina
E5: Define Architecture and Design	16-Nov-22	Team	Luciano
E6: Define Mission Planning Extension	30-Nov-22	Individual	Cosmina
E7: Mission Planning Cost Estimation	7-Dec-22	Individual	Wesley
E8: Quality Assurance	14-Dec-22	Team	Luciano
E9: Test Case Design	11-Jan-23	Individual	Wesley
E10: In-class exercise	18-Jan-23	Individual	Wesley





E2: Use Case Analysis

- Learning goal
 - Understand the functionality of Dronology;
 - Model the use cases and actors of the system;
- Input (available on moodle)
 - Dronology Dataset;
 - Use Case Paper;
- Output
 - Use Case diagram;





Goal

- Each member of the team must create one use case diagram from one
 of the use case scenarios (part of the dronology dataset on Moodle);
- Members of the same group cannot model the same use cases.



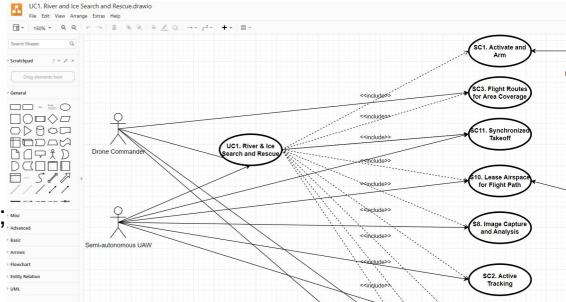


Tool

 Use case diagram(s) should be modeled using http://diagrams.net/

Export the diagram as a PDF file;

File > Export as > PDF

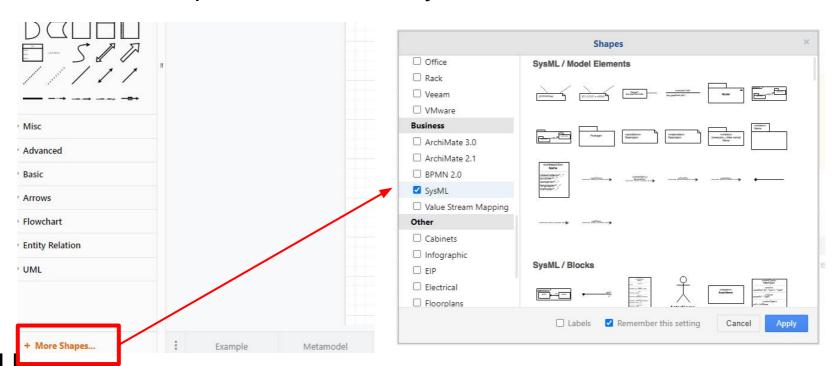






Tool

- Make sure to use the SysML shapes
 - More Shapes > Business > SysML





Main use case

Use Case: River Search and Rescue		
ID	UC1	
Description	Multiple UAVs dispatched to search for victim in river.	
Primary Actor	Drone Commander (human)	
Supporting Actors	Semi-autonomous UAV (UAV)	
Stakeholders and Interests	Emergency responders, FAA regulators, public	
Pre-Conditions	(1) DroneResponse is running, (2) Multiple UAVs with cameras, (3) Victim in river	
Success end condition:	The victim is found by a UAV and actively tracked until rescued.	
Failure end condition:	The victim is not found or the victim is found but not actively tracked.	
Trigger	The Drone Commander activates the search.	

Ma	in Success Scenario	Linked Use Case:
1	UAVs are placed in their launch positions.	
2	UAVs are activated and armed.	ActivateAndArm
3	Emergency responders initiate the dynamic generation of flight routes for the targeted area.	AreaCoverage
4	The DroneResponse commander issues a command to start the flight.	
5	The UAVs tasked with search perform synchronized takeoff.	Î
6	The UAVs lease airspace and fly their assigned flight routes.	<u>LeaseAirspace</u>
7	While flying their assigned routes, the UAVs perform image capture and oboard analysis.	<u>ImageCapture</u>
8	When a potential victim is detected by a UAV at a confidence level above [victim_detected] threshold a [victim_detection] event is raised.	
9	DroneResponse forwards the event to all UIs registered to receive victim_detection alerts.	
10	The UAVs coordinate their response and one is selected and switches to active tracking mode.	ActiveTracking
11	DroneResponse requests victim confirmation from the human operator.	<u>VictimConfirm</u>
12	The UAV receives confirmation from the human operator that the victim sighting is valid.	
13	DroneResponse automatically sends the GPS coordinates to the mobile_rescue system.	
14	A UAV tasked with delivering a flotation device performs item deliver	ItemDelivery
15	Human responders arrive at the scene.	
16	The Drone Commander end the flight.	EndFlight



Identifying Actors

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		Listanii II.
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 Understanding the connection between main use case and supporting use cases

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		Supporting Use Case: Activate and Arm
ID		SC1
Description		The UAV is prepped for flight, activated by turning 'safety' off, and finally armed.
Pri	mary Actor RPIC - remote pilot in control (human), DroneResponse (syste Semi-autonomous UAVs (UAV)	
Su	pporting Actors	Technicians
Sta	keholders and Interests	General public
Pre	e-Conditions	UAV has prepped for flight and airworthy. Placed at launch position.
Su	ccess end condition:	The UAV passes arming checks and is armed for flight
Fai	lure end condition:	The UAV takes off without adequate arming checks
Tri	gger	An arming command is issued
Ma	in Success Scenario	
1	The RPIC deactivates the	UAV's safety switch.
2	DroneResponse issues an arming command.	
3	The UAV executes all prearming tests.	
4	The UAV passes prearming tests.	
5	The UAV arms.	
6	The UAV's status is set to	o MISSION mode (PX4=MISSION, Ardupilot=GUIDED/STABILIZED)
7	The UAV's automated pilot notifies DroneResponse that the UAV is armed for flight.	

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Supporting Actors	Technicians
Stakeholders and Interests	General public
Pre-Conditions	UAV has prepped for flight and airworthy. Placed at launch position.
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Failure end condition:	The UAV takes off without adequate arming checks
Trigger	An arming command is issued

Main Success Scenario

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6	The UAV's status is set to MISSION mode (PX4=MISSION, Ardupilot=GUIDED/STABILIZED)
7	The UAV's automated pilot notifies DroneResponse that the UAV is armed for flight.

Supporting Use Case: Generate Flight Routes for Area Coverage				
ID	SC3			
Description	Define a coverage area and allocate routes to UAV(s)			
Primary Actor	Drone Commander (human), DroneResponse (system), Semi-autonomous UAV (UAV)			
Supporting Actors				
Stakeholders and Interests				
Pre-Conditions	UAVs are active and armed, DroneResponse is active			
Success end condition:	Search routes planned and allocated to UAVs for an efficient search			
Failure end condition:	Ineffective search routes provide low coverage or inefficient search			
Trigger	User selects the option to mark a region and generate routes dynamically			

Main Success Scenario

1.	The brone commander selects the reature to mark a region on the currently displayed map.	
2	The Drone Commander marks a polygon shape on the map.	
	DroneResponse analyzes the shape and size of the drawn polygon for feasibility of generating routes and the polygon is accepted as viable for route generation.	_
4	The Drone Commander specifies the number of UAVs N that will participate in the mission.	_

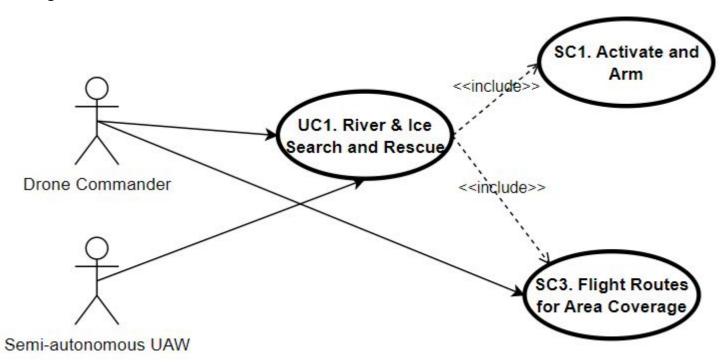
DroneResponse dynamically generates an efficent set of N flight routes that optimize coverage of

- 5 the marked area whilst minimizing flight times.

 6 DroneResponse assigns the flight routes to N available UAVs.
- 7 The use case ends once flight routes have been generated and assigned.



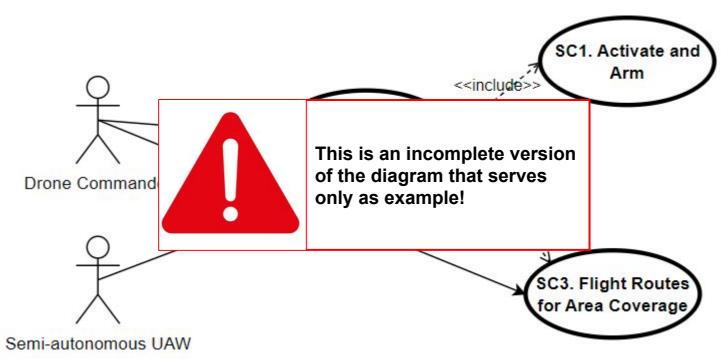
Creating the diagram







Creating the diagram







Hand-in Procedure and Grading Criteria

- Deadline: 18.10.2022 23:59
- Hand-in procedure
 - Use case diagram should be uploaded on Moodle as a PDF file.
 - Make sure to name the file with the following format:
 - UCX_Use_Case_Name_StudentLastName_StudentFirstName.pdf (Replace X for the number of the use case)
- Grading Criteria
 - Correctness use the UML use case notation correctly
 - Completeness no missing use cases or actors in the diagram

