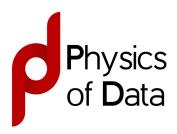
Statistical Models and Inference - Part I

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AA 2023/2024 - Stat Lect. 5





Data Modeling

- we perform experiments and make observations to learn about a phenomenon
- to interpret data, we have to model them

Inference

- make general statements about a phenomenon through a model, using noisy and incomplete data
- must describe both the Phenomenon (i.e. Model) and the Measurement Process
- ➤ Key to Data Modeling: use data together with generative model (theory) and measurement model (experimental practice) to derive consistent probabilistic inferences

Data Modeling

- given some data, D, we usually want to perform three actions:
- ▷ parameter estimation: for a specific Model H, with parameters θ , infere the values of model parameters, i.e. $P(\theta \mid D \mid H)$, the parameter posterior pdf
- ightharpoonup model comparison: given a set of models $\{H_j\}$, find out which one is best supported by data. This means finding $P(H_j|D)$, the model posterior probability
- prediction: given a model H, inferred from the data, predict new data at some new location (in the parameter space or time)

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Bayesian Model Comparison

- we start by looking at model comparison for the simple case of models with no parameters
- \triangleright using our data D, we look for $P(H \mid D)$
- since $H \cdot \overline{H} = 0$ and $H + \overline{H} = \Omega$, we can write

$$P(D) = P(DH) + P(D\overline{H})$$

= $P(D \mid H) P(H) + P(D \mid \overline{H}) P(\overline{H})$

• our quantity of interest, $P(H \mid D)$, is related to Bayes' theorem by

$$P(H \mid D) = \frac{P(D \mid H) P(H)}{P(D)} = \frac{P(D \mid H) P(H)}{P(D \mid H) P(H) + P(D \mid \overline{H}) P(\overline{H})}$$
$$= \frac{1}{1 + \frac{P(D \mid \overline{H}) P(\overline{H})}{P(D \mid H) P(H)}} = \frac{1}{1 + \frac{1}{R}}$$

• with $R = \frac{P(D \mid H) \ P(H)}{P(D \mid \overline{H}) \ P(\overline{H})}$ the posterior odd ratio of the models

Bayesian Model Comparison

it is easy to demonstrate that

$$\frac{P(H \mid D)}{P(\overline{H} \mid D)} = R = \frac{P(D \mid H) P(H)}{P(D \mid \overline{H}) P(\overline{H})}$$

- in order to determine $P(H \mid D)$, we need three quantities:
- $\triangleright P(D \mid H)$: the probability of measuring D when H is true
- $\triangleright P(D \mid \overline{H})$: the probability of measuring D when H is not true (i.e. false)
- ho P(H): the probability that H is true, independently of the data (and, of course, $P(\overline{H}) = 1 P(H)$) $\Rightarrow P(H)$ tells us how probable the model is
- but, shouldn't we have information to tell us that \underline{H} is more likely than $\overline{\underline{H}}$, we could set

$$P(H) = P(\overline{H})$$

• and R becomes the Bayes factor

$$BF = \frac{P(D \mid H)}{P(D \mid \overline{H})}$$

• i.e. the ratio of the probability of the data under each model

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Bayesian Model Comparison

• should we have more models, $\{H_j\}$, with $\sum P(H_j) = 1$, the probability of data becomes

$$P(D) = \sum_{j} P(D \mid H_{j}) P(H_{j})$$

• and the posterior probability of model # 1, H₁, becomes

$$P(H_1 \mid D) = \frac{P(D \mid H_1) P(H_1)}{P(D)}$$

 if we do not have a complete set of models, we cannot compute the posterior probabilities, but we can still compute the odds ratio or Bayes factor between any two models

$$BF = \frac{P(D \mid H_1)}{P(D \mid H_2)}$$
 and $R = \frac{P(D \mid H_1) P(H_1)}{P(D \mid H_2) P(H_2)}$

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Example

Problem

- a test for a disease is 90% reliable
- the probability of testing positive, in absence of the disease, is 0.07
- we know that among people aged 40 to 50 with no symptoms 8 in 1000 have the disease
- Q: if a person in his/her 40 tests positive, what is the probability that he/she has the disease?

Background information

- we build the following propositions:
- D: a person is tested positive
- H: a person has the disease
- and probabilities
- $P(D \mid H) = 0.9$
- $P(D \mid \overline{H}) = 0.07$
- -P(H) = 0.008

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Example - analytical solution

we build

$$R = \frac{P(D \mid H) \ P(H)}{P(D \mid \overline{H}) \ P(\overline{H})} = \frac{9 \cdot 10^{-1} \times 8 \cdot 10^{-3}}{7 \cdot 10^{-2} \times (1 - 8 \cdot 10^{-3})} = 0.1035$$

therefore

$$P(H \mid D) = \frac{1}{1 + 1/R} = 0.094$$

- even though a positive test result is quite probable (assuming the person has the disease), it is very unlikely that he/she has the disease
- what is decisive in the computation of $P(H \mid D)$ is the ratio between

$$P(D H) = P(D | H) P(H) = 7.2 \cdot 10^{-3}$$

(positive result, assuming the disease is present)

and

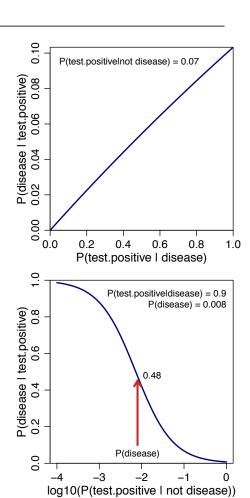
$$P(D \overline{H}) = P(D | \overline{H}) P(\overline{H}) = 7 \cdot 10^{-2}$$

(positive result, assuming the disease is absent)

Example - R solution

```
post <- function(p.d.m, p.d.notm, p.m) {</pre>
   p.notm <-1 - p.m
   odds.ratio <- (p.d.m * p.m) /
                  (p.d.notm * p.notm)
   p.m.d \leftarrow 1/(1 + 1/odds.ratio)
}
p.d.m \leftarrow seq(0, 1, 0.01) \# True positive
p.d.notm < -0.07
                         # False positive
p.m < -0.008
                           # Disease Prior
p.m.d <- post(p.d.m, p.d.notm, p.m)</pre>
plot(p.d.m, p.m.d, type='1', lwd=2, col='navy')
                                 # True positive
p.d.m < -0.9
p.d.notm <- 10^seq(-4,0, 0.02) # False positive
p.m < -0.008
                                 # Disease Prior
p.m.d <- post(p.d.m, p.d.notm, p.m)</pre>
plot(log10(p.d.notm), p.m.d, type='l', col='navy')
```

 only once the false positive rate drops below the base rate (P(H)) does the test starts to be useful



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Occam's Razor

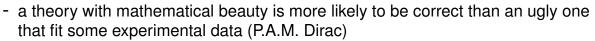
Look at the picture

- Q₁ How many boxes are in the picture?
- Q2 How many boxes are in the vicinity of the tree?

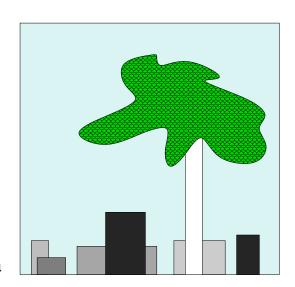
What is Occam's Razor

- If several explanations are compatible with a set of observation, Occam's razor advises us to buy the simplest.
- Accept the simplest explanation that fits the data





 choerent inference, embodied by bayesian probability, automatically embodies Occam's razor, quantitatively



Model comparison and Occam's Razor

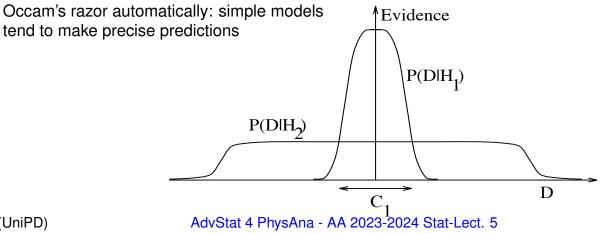
- we evaluate the plausibility of two alternative theories: H_1 and H_2
- we derived the probability ratio between the two theories as

$$\frac{P(H_1 \mid D)}{P(H_2 \mid D)} = \frac{P(D \mid H_1) \ P(H_1)}{P(D \mid H_2) \ P(H_2)}$$

• how is this related to Occam's razor when H_1 is a simpler model than H_2 ? the ratio

$$\frac{P(D \mid H_1)}{P(D \mid H_2)}$$

which depends on the data embodies



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Example

(1)

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• we have a sequence of numbers:

we want to predict the next two numbers in the sequence

Answer₁: 15 and 19

i.e. add 4 to the previous number

the sequence is an arithmetic progression

Answer₂: -19.9 and 1043.8

i.e. we apply $-x^3/11 + 9x^2/11 + 23/11$ to the previous number

→ the sequence is generated by a cubic function

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Example

- let's compare the two models: H_q (geometric) versus H_c (cubic)
- in general, an arithmetic progression is more frequent than a cubic, but since this would out a bias in the ratio $P(H_g)/P(H_c)$, we assume they have equal probabilities
- let's compute $P(D \mid H_g)$:

$$P(D \mid H_g) = \frac{1}{101} \frac{1}{101} = 10^{-4}$$

(we have assumed that these number could be anywere in the interval [-50,50])

• to compute $P(D \mid H_c)$, we use the same probability distribution for evaluating the coefficients

$$P(D \mid H_c) = \left(\frac{1}{101}\right) \left(\frac{4}{101} \frac{1}{50}\right) \left(\frac{4}{101} \frac{1}{5}\right) \left(\frac{2}{101} \frac{1}{50}\right) = 2.5 \cdot 10^{-12}$$

• the ratio favours the geometric hypothesis H_g

$$P(D \mid H_g)/P(D \mid H_c) = 40 \cdot 10^6/1$$

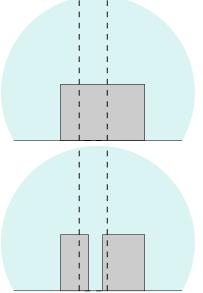
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Occam's Razor and the box/boxes behind the tree

- let's go back to our example:
- Q₁ Are there one or two boxes behind the tree ?
- H₁ says there is one box with four free parameters (three coordinates and colour)
- H₂ says there are two boxes (eight free parameters)
- putting some constraint on the colour (any of 16 values) and of the possible height (20 values in pixels), we get:

$$\frac{P(D \mid H_1)P(H_1)}{P(D \mid H_2)P(H_2)} = \frac{\frac{1}{20} \frac{1}{20} \frac{1}{20} \frac{1}{16}}{\frac{1}{20} \frac{1}{20} \frac{1}{16} \frac{1}{20} \frac{1}{20} \frac{1}{20} \frac{1}{16}} = \frac{1000}{1}$$



the more complex model has four extra parameters for size and colours: it has to pay two big Occam factors (1/20 and 1/6) for the suspicious coincidence that the two boxes have exactly the same colour and exact height

D. J. C. MacKay, *Information Theory, Inference, and Learning Algorithms*, Cambridge University Press, 2003

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Data Modeling with Parametric Models

- generative model: theory predicting observable data from model parameters
- the model just studied did not have any parameter: it was either true or false
- the simplest generative model is a straight line

$$f(x; a, b) = a + b \cdot x$$

but our measurements will differ from the model due to noise

$$y = f(x; a, b) + \epsilon$$

- and the noise model we call it the measurement model has also parameters
- given our set of data $D = \{y_j\}$ at specified values $\{x_j\}$, we want to infer the values of the parameters for the generative model
- in some cases we want to find the best set of parameters that predicts the data
- but data are noisy → there is no unique solution
- we look for the probability distributions of the parameters, $P(\theta \mid D \mid H)$, also called parameter posterior pdf. Thanks to Bayes' theorem

$$P(\theta \mid D H) = \frac{P(D \mid \theta H) P(\theta \mid H)}{P(D \mid H)}$$

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The Likelihood

- $P(D \mid \theta \mid H)$ is the Likelihood probability
- it is a key function since it describes both the phenomenon and the data
- it tells us the probability of getting the data we measured, given some value of the parameters
- H specifies:

the equation for the straight line f(x; a, b)

- a generative model \leftarrow

-

- a measurement model \leftarrow how the measurement of y at a given x differs from f(x; a, b) due to noise
- the measurement model describes ϵ in $y = f(x; a, b) + \epsilon$
- example: Gaussian distribution with variance σ^2 . The Likelihood for any measurement is

$$P(y \mid \theta \mid H) = \frac{1}{\sigma \sqrt{2\pi}} \exp\left(-\frac{(y - f(x; a, b))^2}{2\sigma^2}\right)$$

- telling us that the measurement has a Gaussian distribution about the true value
- $\theta = \theta(a, b; \sigma)$ is the union of the generative and measurements models

- $P(\theta \mid H)$ is the Prior probability
- it encapsulates all the information we have, independent of the data
- it is called Prior because is the background information we have before obtaining the Data
- different people may have different information, or different opinion on what prior information is important
- this is not a weakness of inference
- it just reflects reality: we do not only use our immediate measurements to reach scientific conclusions

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The Posterior

- $P(\theta \mid DH)$ is the Posterior probability
- it is the pdf over the model parameters, given data and background information
- from Bayes' theorem

Posterior ∝ Likelihood × Prior

• the proportionality is through $P(D \mid H)$, a normalization factor which is independent of θ . Therefore:

$$P(\theta \mid D H) = \frac{1}{7}P(D \mid \theta H)P(\theta \mid H)$$

- with $Z = P(D \mid H)$
- from a conceptual point of view, inference is really that strightforward
- Bayesian inference is the process of improving our knowledge of the model paramaters by using the data
- we update the Prior using the Likelihood to obtain the Posterior

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The Evidence

- $P(D \mid H)$ is the Evidence
- is the denominator of Bayes's equation and it gives the probability of observing the Data D, assuming the model H to be true, for any values of θ

$$P(D \mid H) = \int P(D \mid \theta H) P(\theta \mid H) d\theta$$

- evidence plays a key role in model comparison
- as a normalization constant, it is very important if we want to compute certain quantities from the posterior
- sometimes the integral can be calculated analytically, but for many real-world problems, we have to resort to numerical integration → Markov Chain Monte Carlo

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Bayesian Inference of repeated Bernoulli trials

Bayesian analysis of coin tossing

Problem

- we have a coin and we toss it *n* times
- the coin lands heads in r of them
- Q is the coin fair ? (i.e. $\pi = \frac{1}{2}$)

Comment

- no definitive answer exists
- only a probabilistic answer can be provided
- we are looking for

$$P(\pi \mid n, r, H)$$

• from Bayes' theorem

$$P(\pi \mid n, r, H) = \frac{P(r \mid \pi, n, H) P(\pi \mid H)}{P(r \mid n, H)}$$

Comment: *n* is not part of the Prior since it is independent of the number of coin tosses

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Coin tossing model and probabilities

Our Measurement Model

- π : probability of getting heads in one toss
- π is constant in all the tosses
- all tosses are independent

The Likelihood

• the appropriate Likelihood is the binomial distribution

$$P(r \mid \pi, n, H) = \binom{n}{r} \pi^r (1 - \pi)^{n-r}$$
 with $r \le n$

Comment: *n* is part of the data, but it is on the right side since it is fixed before starting to collect data

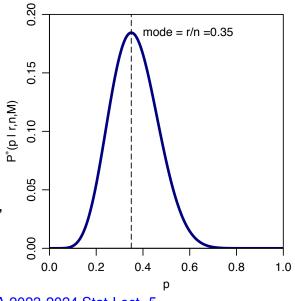
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Coin tossing: a uniform Prior

- let's adopt a uniform prior, $P(\pi \mid H) \sim \mathcal{U}(0, 1)$
- the Posterior pdf is simply proportional to the Likelihood

$$P(\pi \mid r, n, H) = \frac{1}{Z} \pi^{r} (1 - \pi)^{n-r} = \frac{1}{Z} P^{*} (\pi \mid r, n, H)$$

- the normalization factor Z (i.e. the evidence $P(r \mid n, H)$ does not depend on π
- the mode is at r/n



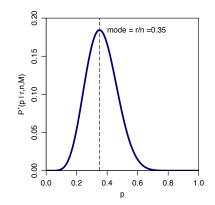
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Uniform Prior

Comments

- the curve is not binomial in π , but it is binomial in r
- the posterior is not-normalized: the integral over π is not unity
- we need the normalization factor only if we want to calculate expected values: i.e. mean and variance
 - given the un-normalized posterior pdf, $P^*(\pi \mid r, n, H)$,



$$E[\pi] = \int_{0}^{1} \pi \cdot P(\pi \mid r, n, H) d\pi = \frac{1}{Z} \int_{0}^{1} \pi \cdot \pi^{r} (1 - \pi)^{n-r} d\pi$$

with

$$Z = \int_{0}^{1} P^{*}(\pi \mid r, n, H) d\pi \approx \sum_{j} P^{*}(\pi_{j} \mid r, n, H) \Delta \pi_{j}$$

estimated using numerical integration

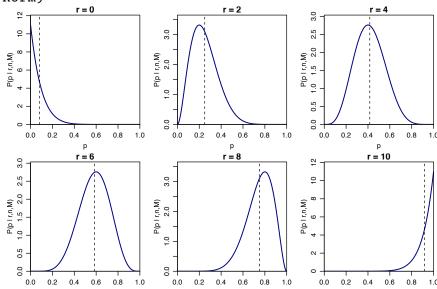
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Uniform Prior

- interval [0, 1] is divided into n.sample intervals
- un-normalized pdf is evaluated at the center of each point
- a grid of probability is created
- with the normalized posterior, the expected value is computed



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Coin tossing: a Beta Prior

- given a random coin, we may believe the coin is fair, or close to fair
- an appropriate probability density function is the Beta distribution

$$P\left(\pi \mid r, n, H\right) = \frac{1}{B(\alpha, \beta)} \pi^{\alpha - 1} (1 - \pi)^{\beta - 1} \quad \text{with } \alpha > 0, \beta > 0$$

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Note: for $\alpha = \beta = 1$ we get a uniform distribution

- if $\alpha = \beta$ the function is symmetric, and the mean and mode are 0.5
- the larger α (when $\alpha \geq 1$), the narrower the distribution

Beta(10,10)

mode = 0.5
mean = 0.5

(W d)d
(S) - (O) -

• multiplying the Prior by the likelihood, and absorbing the terms not depending on π in the constant term Z, we get

$$P(\pi \mid r, n, H) = \frac{1}{Z} \pi^{r} (1 - \pi)^{n-r} \times \pi^{\alpha - 1} (1 - \pi)^{\beta - 1}$$
$$= \frac{1}{Z} \pi^{r+\alpha - 1} (1 - \pi)^{n-r+\beta - 1}$$

- multiplying the Posterior with this Likelihood, we get the same form for the Posterior (another Beta distribution)
- the normalization constant is

$$Z = B(r + \alpha, n - r + \beta)$$

- we say the Prior and Posterior are conjugate distributions
- the Prior is the conjugate Prior for this Likelihood function

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Beta Prior

• if we start with a Beta Prior with parameters α_p and β_p , and then measure r heads in n tosses, the Posterior is a Beta functions with parameters

$$\alpha = \alpha_p + r$$
 and $\beta = \beta_p + n - r$

mean and mode for the Posterior are

mean =
$$\frac{\alpha_p + r}{\alpha_p + \beta_p + n}$$
 and mode = $\frac{\alpha_p + r - 1}{\alpha_p + \beta_p + n - 2}$

• if we compare the result with that obtained with a Uniform Prior $(\mathcal{U}(0,1) \sim \text{Beta}(\alpha=1,\beta=1))$, we get

$$mean = \frac{1+r}{2+n} \quad and \quad mode = \frac{r}{n}$$

Beta Prior vs Uniform Prior

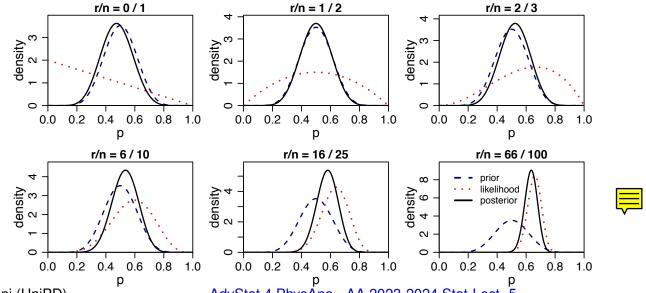
```
n < -10;
alpha.prior <- 10;</pre>
                       beta.prior <- 10</pre>
n.sample \leftarrow 2000;
                      delta.p <- 1/n.sample</pre>
p <- seq(from=1/(2*n.sample),</pre>
          by=1/n.sample, length.out=n.sample)
par(mfrow=c(3,3))
for(r in seq(from=0, to=10, by=2)) {
                                                        0.0
                                                           0.2
                                                               0.4
                                                                 0.6
                                                                     8.0
                                                                                0.2
                                                                                   0.4
                                                                                      0.6
                                                                                         8.0
  post.beta <- dbeta(x=p,</pre>
                                                                                    r = 8
                         alpha.prior+r,
                         beta.prior+n-r)
  plot(p, post.beta, type="l", lwd=1.5,
        col='firebrick3', ...)
  p.mean.b <- delta.p*sum(p*post.beta)</pre>
  abline(v=p.mean.b,
           col='firebrick3',lty=2)
                                                        0.0
                                                           0.2
                                                               0.4
                                                                        1.0
                                                                                0.2
                                                                                   0.4 0.6
  # overplot posterior with Unif Prior
                                                                                    r = 10
  post.unif <- dbinom(x=r, size=n, prob=p)</pre>
  lines(p,
         post.unif/(delta.p*sum(post.unif)))
  p.norm.u <- post.unif/</pre>
                 (delta.p*sum(post.unif))
  p.mean.u <- delta.p*sum(p*p.norm.u)</pre>
  abline(v=p.mean.u, col="grey60", lty=2)
                                                                  0.6
                                                                     0.8
                                                                                0.2
                                                                                   0.4
}
                                                        0.0
```

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Posterior evolution with data size

- the outcome of only few coin flips tells us little about the fairness of a coin.
 Our state of knowledge after the analysis of the data is strongly dependent on what we knew or assumed a priori
- as the evidence grows, we are eventually bought to the same conclusions irrespective of our initial beliefs
- the posterior pdf is then dominated by the likelihood function
- the choice of the prior becomes largely irrelevant



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Posterior Evolution, R code

```
alpha.prior <- 10; beta.prior</pre>
                                     <- 10
                                                                     r/n = 2/3
Nsamp < -200
delta.p <- 1/Nsamp</pre>
                                                       density
p \leftarrow seq(from=1/(2*Nsamp),
          by=1/Nsamp,
          length.out=Nsamp)
p.prior <- dbeta(x=p,</pre>
                  alpha.prior,
                  beta.prior)
                                                                 0.2
                                                                           0.6
                                                                                8.0
                                                                      0.4
                                                            0.0
                                                                         р
n.str <- readline("Enter_n_extractions:_")</pre>
n.seq <- as.numeric(unlist(strsplit(n.str, ",")))</pre>
# Loop over the vector
for (n in n.seq) {
  r \leftarrow as.integer((2/3) * n)
  p.like <- dbinom(x=r, size=n, prob=p)</pre>
  p.like <- p.like/(delta.p*sum(p.like))</pre>
  p.post <- dbeta(x=p, shape1=alpha.prior+r, shape2=beta.prior+n-r)</pre>
  plot(p, p.prior, type="l", xlim=c(0,1), ...)
  lines(p, p.like, col='firebrick3',lwd=2, lty=3)
  lines(p, p.post, lwd=1.5)
  title(main=paste("r/n<sub>u</sub>=",r,"/",n), line=0.3, cex.main=1.2)
```

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Parameters best estimates and reliability

- once the posterior is determined, we wish to summarize our inference on a parameter with two numbers:
- the best estimates
- and a measure of its reliability
- probability distribution associated with the parameter ⇒ a measure of how much we believe the result lies in the neighborhood of that point
- Best estimate → maximum of the posterior pdf

$$\theta_{\circ} = \text{MAX} \{ P(\theta \mid D, H) \}$$

which means

$$\left. \frac{dP}{d\theta} \right|_{\theta_{\circ}} = 0$$
 and $\left. \frac{d^2P}{d\theta^2} \right|_{\theta_{\circ}} < 0$

• to get a measurement of the reliability of our 'best estimate', we need to look at the spread of the posterior pdf around θ_{\circ}

Parameters best estimates and reliability

- let's consider a Taylor expansion of the posterior pdf around θ_{\circ}
- rather than working with the pdf, the calculations will be done with the natural logarithm

$$L = \ln P(\theta \mid D, H)$$

$$= L(\theta_{\circ}) + \frac{1}{2} \frac{d^{2}P}{d\theta^{2}} \Big|_{\theta_{\circ}} (\theta - \theta_{\circ})^{2} + \dots$$

Comments

- $L(\theta_{\circ})$ is a constant and tells us nothing about the slope of the posterior pdf
- the linear term in $(\theta \theta_{\circ})$ is missing since we are expanding about a maximum
- the quadratic term is the dominant factor and it determines the width of the pdf
- ignoring higher order contributions and taking the exponential of the Taylor expansion

$$P(\theta \mid D, H) \sim A \exp \left[\frac{1}{2} \left. \frac{d^2 P}{d\theta^2} \right|_{\theta_o} (\theta - \theta_o)^2 \right]$$

with A, a normalization constant

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Parameters best estimates and reliability

we have approximated our posterior pdf by a Gaussian distribution

$$P(\theta \mid \theta_{\circ}, \sigma) = \frac{1}{\sigma \sqrt{2\pi}} \exp \left[-\frac{1}{2} \frac{(\theta - \theta_{\circ})^{2}}{\sigma^{2}} \right]$$

• comparing the two functions, we get

$$\left. \frac{d^2 L}{d\theta^2} \right|_{\theta_o} = -\frac{1}{\sigma^2} \quad \Rightarrow \quad \sigma = \left(-\left. \frac{d^2 L}{d\theta^2} \right|_{\theta_o} \right)^{-1/2}$$

• our inference about the quantity of interest is

$$\theta = \theta_{\circ} \pm \sigma$$

- with:
- θ_{\circ} our best estimate for θ
- σ a measurement of its reliability
- for a Gaussian distribution

$$P(|\theta - \theta_{\circ}| \le \sigma \mid DH) \sim 0.67$$

$$P(|\theta - \theta_{\circ}| \le 2\sigma \mid DH) \sim 0.95$$

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• the Posterior is

$$P(\pi \mid r, n, H) \propto \pi^{r} (1 - \pi)^{n-r}$$

taking the natural logarithm

$$L = const + r \ln \pi + (n - r) \ln (1 - \pi)$$

$$\frac{dL}{d\pi} = \frac{r}{\pi} - \frac{n-r}{1-\pi} \quad \text{and} \quad \frac{d^2L}{d\pi^2} = -\frac{r}{\pi^2} - \frac{n-r}{(1-\pi)^2}$$

• from the request of a maximum

$$\frac{dL}{d\pi} = 0 \quad \Rightarrow \quad \pi_{\circ} = \frac{r}{n}$$

• the reliability is given by the second derivative

$$\left. \frac{d^2 L}{d\pi^2} \right|_{\pi^{\circ}} = -\frac{r}{\pi_{\circ}^2} - \frac{n-r}{(1-\pi_{\circ})^2} = -\frac{n}{\pi_{\circ}(1-\pi_{\circ})}$$

therefore

$$\sigma = \left(-\left.\frac{d^2L}{d\theta^2}\right|_{\theta_0}\right)^{-1/2} = \sqrt{\frac{\pi_0(1-\pi_0)}{n}} = \frac{1}{n}\sqrt{\frac{r(n-r)}{n}}$$

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Parameters estimates, coin example, Beta Prior

• the Posterior is

$$P(\pi \mid r, n, H) \propto \pi^{r+\alpha-1} (1-\pi)^{n-r+\beta-1}$$

taking the natural logarithm

$$L = const + (r + \alpha - 1) \ln \pi + (n - r + \beta - 1) \ln (1 - \pi)$$

$$\frac{dL}{d\pi} = \frac{r + \alpha - 1}{\pi} - \frac{n - r + \beta - 1}{1 - \pi} \quad \text{and} \quad \frac{d^2L}{d\pi^2} = -\frac{r + \alpha - 1}{\pi^2} - \frac{n - r + \beta - 1}{(1 - \pi)^2}$$

from the request of a maximum

$$\frac{dL}{d\pi} = 0$$
 \Rightarrow $\pi_{\circ} = \frac{r + \alpha - 1}{n + \alpha + \beta - 2}$

• the reliability is given by the second derivative

$$\left. \frac{d^2 L}{d\pi^2} \right|_{p_0} = -\frac{r + \alpha - 1}{\pi_0^2} - \frac{n - r + \beta - 1}{(1 - \pi_0)^2} = -(\alpha + \beta + n - 2) \frac{\alpha + r}{\alpha + r - 1}$$

therefore

$$\sigma = \left(-\frac{d^2L}{d\theta^2}\Big|_{\theta_0}\right)^{-1/2} = \frac{1}{\alpha + \beta + n - 2}\sqrt{\frac{\alpha + r - 1}{\alpha + r}}$$

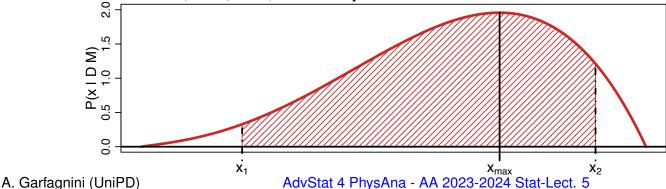
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Asymmetric Posterior pdfs

- our derivation of the reliability of the parameter estimate (i.e. the error) relies on the validity of the quadratic expansion
- this is usually a reasonable approximation
- however there are times when the posterior pdf is markedly asymmetric
- while the maximum of the posterior can still be regarded as giving the best estimate, the concept of symmetric error bars does not seem appropriate
- a good way to express the reliability is through a confidence interval

$$P(x_1 \le x < x_2 \mid D, H) = \int_{x_1}^{x_2} P(x \mid D, H) dx \sim 0.95$$

- Why 95% confidence level ?
- it is traditionally seen as a reasonable value, but nothing stops us from quoting other values, 50%, 70%, 99% or any other value



Assigning Priors

- probabilistic inference provides answers to well-posed problems but
- it does not define our models
- it does not define the priors
- or tell us which data to collect and how
- with the coin example we learned how the posterior pdf depends on both the prior and the likelihood
 - → when data are poor, the prior plays a more dominant role

How do we assign a Prior?

- a prior should incorporate any relevant information we have about the problem
 (→ we implicitly use priors all the time in every day life)
- 2) some principles can help us to adopt an appropriate prior

Principle of insufficient reason

- also called the principle of indifference
- if we have a set of mutually exclusive outcomes, and we do not expect any one of them more likely, we should assign equal probabilities

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Assigning Priors

Maximum Entropy

- it is based on the idea of finding the least informative (most entropic) distribution, given certain information
- example:

if only mean and variance are known, it shows that the Gaussian is the least informative distribution

Empirical Bayes

- priors are estimated from some general properties of the data
- we can take the posterior from one analysis to be the prior of the next analysis, if they involve independent data
- the final posterior will be identical to having combined the two data sets together with the original prior
- let D₁ and D₂ be two independent data sets

$$P(\theta \mid D_1 D_2) \propto P(D_1 D_2 \mid \theta) P(\theta)$$

$$\propto P(D_2 \mid \theta) P(D_1 \mid \theta) \times P(\theta)$$

$$\begin{array}{ccc} \text{likelihood} & \text{posterior} \\ \text{for } D_2 & \text{from } D_1 \end{array}$$

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Exercise: a survey for the next Uni elections

The Problem

- In proximity of the elections for student's representatives in some University board, Anna, Chris and Maggie decide to perform a survey among their classmates to check how strong is their candidate friend
- the aim is to infere the probability that she gets elected

Step 1: choosing the Priors

- Before starting the interviews, they have different opinions about the results of the elections:
- Anna thinks that there will be a 20% chanches that their friend will be elected, and moreover, the probability has a standard deviation of 0.08.
 She therefore assumes a Beta prior such that:

$$E[x] = \frac{a}{a+b} = 0.2$$
 $1 - E[x] = \frac{b}{a+b} = 0.8$ $\frac{0.2 \times 0.8}{a+b+1} = 0.08^2$,

which means a = 4.8 and b = 19.2

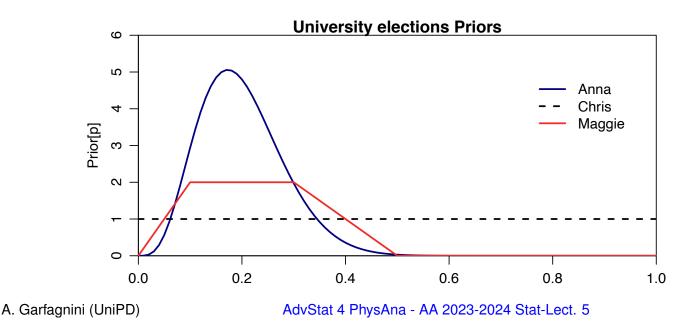
- Chris is a new student and he does not have any feeling how popular their candidate is, therefore he assumes a Uniform prior distribution. For him a = b = 1

Exercise: a survey for the next Uni elections (2)

Step 1: choosing the Priors (cont'd)

Before starting the interviews, they have different opinions about the results of the elections:

 Maggie thinks that the probability distribution is flat, but not over the whole domain. Therefore she assumes a trapezoidal distribution which is flat between 0.1 and 0.3, and goes to zero outside that domain



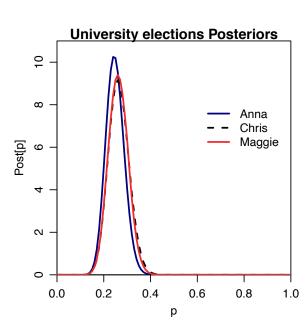
Exercise: a survey for the next Uni elections (3)

Step 2: getting the data

- now they start the survey and decide to interview n = 100 students regularly coming to the University canteen but they do not personally know
- out of the interviewed students, x = 26 claim they will support and vote the candidate

Step 3: computing the Posterior

- Anna and Chris use a Beta prior \rightarrow they get a conjugate prior Beta($\alpha = a + x, \beta = b + n x$)
- Anna has Beta($\alpha = 4.8 + 26, \beta = 19.2 + 74$)
- Chris gets Beta($\alpha = 1 + 26, \beta = 1 + 74$)
- Maggie has to perform a numerical computation of the posterior, given her user-defined Prior



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Exercise: a survey for the next Uni elections (4)

Step 4: computing Credibility Intervals

- given the Posterior distributions, we can compute the mean value and the variance
- by integrating the Posterior distribution, it is possible to compute the Credibility Interval, 95%, as the area between the 2.5% and 97.5%
- Maggie's estimate must be done by numerical integration

	$Post(\alpha, \beta)$	mean	sigma	95% Cr. Int.
Anna	Beta($\alpha = 30.8, \beta = 93.2$)	0.248	0.039	0.177 - 0.328
Chris	Beta($\alpha = 27, \beta = 75$)	0.265	0.043	0.184 - 0.354
Maggie	numerical	0.262	0.042	0.183 - 0.346

95% Credibility Intervals

