







# Implementing Deep Networks with Keras

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#### You have just found Keras.

Keras is a high-level neural networks API, written in Python and capable of running on top of TensorFlow, CNTK, or Theano. It was developed with a focus on enabling fast experimentation. Being able to go from idea to result with the least possible delay is key to doing good research.

Use Keras if you need a deep learning library that:

- Allows for easy and fast prototyping (through user friendliness, modularity, and extensibility).
- Supports both convolutional networks and recurrent networks, as well as combinations of the two.
- Runs seamlessly on CPU and GPU.

Read the documentation at Keras.io.



### Other DL Frameworks

- PyTorch (most diffused, specially in research)
- Tensorflow
- JAX (functional programming)
- □ Theano (deprecated)
- □ Caffe (deprecated)
- □ CNTK (deprecated)
- **...**









## **Guiding Principles**

- User friendliness
  - Easy for easy things
  - Possible to do complex things
- Modularity
  - Modules: neural layers, cost functions, optimizers, activation functions, regularization schemes
- Extensibility
  - Easy to add new modules
- Python-based
  - Interactive environment



## Installing Keras





- Comes pre-packaged with all TensorFlow2 installations
  - You can access it as follows:

```
import tensorflow as tf
tf.keras.[any keras object]
```

Recently, the PyTorch support has been implemented too



### TensorFlow2 Installation

#### Two (main) ways of installing

- anaconda (especially on Windows it is simpler)
- pip (described on official website)

#### Anaconda installation (CPU version, simple but slow):

- 1. Assuming you already have Anaconda/Python 3
- conda create -n tensorflow\_env tensorflow
- 3. conda activate tensorflow\_env

#### Anaconda installation (GPU version, requires an NVIDIA compatible GPU):

- conda create -n tensorflow\_gpuenv tensorflow-gpu
- conda activate tensorflow\_gpuenv
- Could require to install (or fix issues with) CUDA and CuDNN libraries

#### Tensorflow and Jupyter:

Jupyter could use a different environment than the TensorFlow one



## Alternative: use Google Colab

#### Requirements:

- Google account
- Internet connection

# [ ] from google.colab import drive drive.mount('/content/gdrive') ☐→ Go to this URL in a browser: https://accounts.google.com/o/ Enter your authorization code: .......... Mounted at /content/gdrive

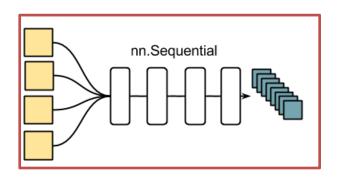
#### Getting started:

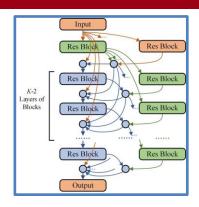
- Go to your Google Drive and create a new notebook (New -> More -> Google Colaboratory) or upload one
- Once you have opened it with Google Colaboratory, go to Edit -> Notebook Settings and select GPU
- Many python libraries available, run !pip list to check
- Mount your Google Drive to access files from it
- Start coding!





## Sequential vs. Functional Models





- Two ways to build Keras models: sequential and functional
- The sequential API allows you to create models layer-by-layer
  - Each layer is connected to the previous and next
  - Write your neural network in a few lines of code
  - It does not allow you to create complex models
- The functional API allows you to create models that have a lot more flexibility
  - In fact, you can connect each layer to any other layer
  - Creating complex networks becomes possible



## The Easy Way

- Instantiate a sequential model
- Stack some layers
- Configure/tune the learning process
- Iterate on the training data
- Evaluate performance
- Generate predictions



#### 30s to Keras

Instantiate a sequential model

```
from tensorflow.keras import Sequential

model = Sequential()
```

#### 30s to Keras

#### Stack some layers

```
from tensorflow.keras.layers import Dense

model.add(Dense(units=64, activation='relu', input_dim=100))
model.add(Dense(units=10, activation='softmax'))
```

- Add one layer after the other (order matters!)
- Specify input for first layer (for the others it is the output of the previous one)



#### Configure/tune the learning process

- Notice the difference between loss (used for NN optimization) and metrics
- Can use pre-defined settings ('..') or manually specify optimizer parameters (...modularity and extensibility...)



#### □ Iterate on the training data

```
x_train and y_train can be numpy arrays, like in scikit-learn
```

```
model.fit(x_train, y_train, epochs=5, batch_size=32)
```

```
model.train_on_batch(x_batch, y_batch)
```

- fit: runs the whole training procedure
- train\_on\_batch: perform a single step



#### 30s to Keras

Evaluate performance

loss\_and\_metrics = model.evaluate(x\_test, y\_test, batch\_size=128)

#### 30s to Keras

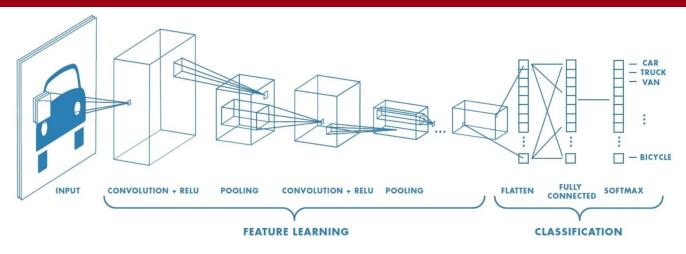
Generate predictions

```
classes = model.predict(x test, batch size=128)
```

- The end
  - Simple but limited... More advanced example with functional model in the notebook



#### Keras: Build a CNN



#### Typical layers in a Convolutional Neural Network

- Convolutional
- 2. Pooling
- 3. Fully connected
- 4. Activations (ReLU, Softmax, ...)

## I/O: Tensors

Tensor: typed multi-dimensional array (From TensorFlow)

#### Input shape

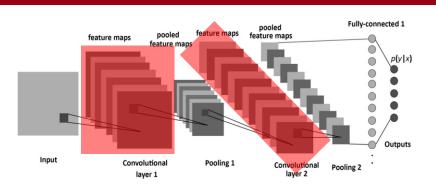
```
4D tensor with shape: (samples, channels, rows, cols) if data_format='channels_first' or 4D tensor with shape: (samples, rows, cols, channels) if data_format='channels_last'.
```

#### Output shape

```
4D tensor with shape: (samples, filters, new_rows, new_cols) if data_format='channels_first' or 4D tensor with shape: (samples, new_rows, new_cols, filters) if data_format='channels_last'. rows and cols values might have changed due to padding.
```



## 2D Convolutional Layers in Keras



2D convolution layer (e.g. spatial convolution over images).

This layer creates a convolution kernel that is convolved with the layer input to produce a tensor of outputs. If <a href="use\_bias">use\_bias</a> is True, a bias vector is created and added to the outputs. Finally, if <a href="activation">activation</a> is not <a href="None">None</a>, it is applied to the outputs as well.

When using this layer as the first layer in a model, provide the keyword argument <a href="input\_shape">input\_shape</a> (tuple of integers, does not include the sample axis), e.g. <a href="input\_shape=(128, 128, 3)">input\_shape=(128, 128, 3)</a> for 128x128 RGB pictures in data format="channels last".



## Conv2D Arguments

#### **Arguments**

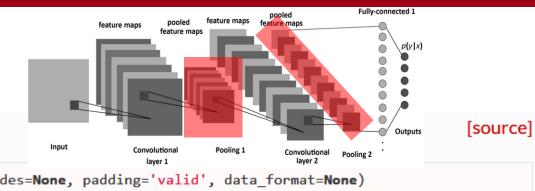
- filters: Integer, the dimensionality of the output space (i.e. the number of output filters in the convolution).
- **kernel\_size**: An integer or tuple/list of 2 integers, specifying the width and height of the 2D convolution window. Can be a single integer to specify the same value for all spatial dimensions.
- **strides**: An integer or tuple/list of 2 integers, specifying the strides of the convolution along the width and height. Can be a single integer to specify the same value for all spatial dimensions. Specifying any stride value != 1 is incompatible with specifying any dilation\_rate value != 1.
- padding: one of "valid" or "same" (case-insensitive). Note that "same" is slightly inconsistent across backends with strides != 1, as described here
- data\_format: A string, one of \_channels\_last (default) or \_channels\_first . The ordering of the dimensions in the inputs.

  \_channels\_last corresponds to inputs with shape (batch, height, width, channels) while \_channels\_first corresponds to inputs with shape (batch, channels, height, width). It defaults to the \_image\_data\_format value found in your Keras config file at \_~/.keras/keras.json . If you never set it, then it will be "channels\_last".
- dilation\_rate: an integer or tuple/list of 2 integers, specifying the dilation rate to use for dilated convolution. Can be a single integer to specify the same value for all spatial dimensions. Currently, specifying any dilation\_rate value != 1 is incompatible with specifying any stride value != 1.
- activation: Activation function to use (see activations). If you don't specify anything, no activation is applied (ie. "linear" activation:
   a(x) = x).
- use\_bias: Boolean, whether the layer uses a bias vector.
- kernel\_initializer: Initializer for the kernel weights matrix (see initializers).
- bias\_initializer: Initializer for the bias vector (see initializers).
- kernel\_regularizer: Regularizer function applied to the kernel weights matrix (see regularizer).
- bias\_regularizer: Regularizer function applied to the bias vector (see regularizer).
- activity\_regularizer: Regularizer function applied to the output of the layer (its "activation"). (see regularizer).
- kernel\_constraint: Constraint function applied to the kernel matrix (see constraints).
- bias\_constraint: Constraint function applied to the bias vector (see constraints).

- The argument list is huge!
- Specify only the desired arguments
- Rely on default values for the others



## **Pooling Layers**



#### MaxPooling2D

keras.layers.MaxPooling2D(pool\_size=(2, 2), strides=None, padding='valid', data\_format=None)

Max pooling operation for spatial data.

#### Arguments

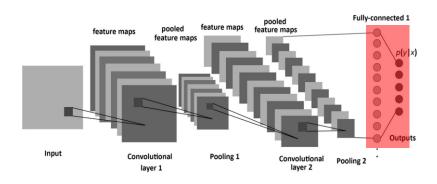
- **pool\_size**: integer or tuple of 2 integers, factors by which to downscale (vertical, horizontal). (2, 2) will halve the input in both spatial dimension. If only one integer is specified, the same window length will be used for both dimensions.
- strides: Integer, tuple of 2 integers, or None. Strides values. If None, it will default to pool\_size.
- padding: One of "valid" or "same" (case-insensitive).
- data\_format: A string, one of channels\_last (default) or channels\_first. The ordering of the dimensions in the inputs.

  channels\_last corresponds to inputs with shape (batch, height, width, channels) while channels\_first

  corresponds to inputs with shape (batch, channels, height, width). It defaults to the image\_data\_format value found in your Keras config file at ~/.keras/keras.json. If you never set it, then it will be "channels last".



## Dense (Fully Connected) <u>Layers</u>



Just your regular densely-connected NN layer.

Dense implements the operation: output = activation(dot(input, kernel) + bias) where activation is the element-wise activation function passed as the activation argument, kernel is a weights matrix created by the layer, and bias is a bias vector created by the layer (only applicable if use\_bias is True).

• **Note**: if the input to the layer has a rank greater than 2, then it is flattened prior to the initial dot product with kernel.



### **Activations and Softmax**

- Activations (e.g. ReLU, tanh, ...)
  - As standalone layers
  - Embedded in forward layers
- Softmax activation often at the end of the last fully connected layer

```
from keras.layers import Activation, Dense

model.add(Dense(64))
model.add(Activation('tanh'))

This is equivalent to:

model.add(Dense(64, activation='tanh'))
```



## Compiling a Model

- Compiling a model means configuring the learning process
- A model can be compiled by providing
  - An optimizer
  - A loss function
  - A list of metrics
- The choices depend on the considered problem
  - Binary classification
  - Multi-class classification
  - Regression

```
# For a multi-class classification problem
model.compile(optimizer='rmsprop',
              loss='categorical crossentropy',
              metrics=['accuracy'])
# For a binary classification problem
model.compile(optimizer='rmsprop',
              loss='binary crossentropy',
              metrics=['accuracy'])
# For a mean squared error regression problem
model.compile(optimizer='rmsprop',
              loss='mse')
# For custom metrics
import keras.backend as K
def mean_pred(y true, y pred):
    return K.mean(y pred)
model.compile(optimizer='rmsprop',
              loss='binary crossentropy',
              metrics=['accuracy', mean pred])
```



## **Optimizers**

```
from keras import optimizers

model = Sequential()
model.add(Dense(64, kernel_initializer='uniform', input_shape=(10,)))
model.add(Activation('softmax'))

sgd = optimizers.SGD(lr=0.01, decay=1e-6, momentum=0.9, nesterov=True)
model.compile(loss='mean_squared_error', optimizer=sgd)
```

You can either instantiate an optimizer before passing it to model.compile(), as in the above example, or you can call it by its name. In the latter case, the default parameters for the optimizer will be used.

```
# pass optimizer by name: default parameters will be used
model.compile(loss='mean_squared_error', optimizer='sgd')
```

SGD [source]

```
keras.optimizers.SGD(lr=0.01, momentum=0.0, decay=0.0, nesterov=False)
```



## Loss Function (1)

- Loss Function
  - a.k.a. objective function
  - a.k.a. optimization score function
- Measures the distance between actual and desired output
  - Drives the training process
- Depends on the task / output type
  - Classification vs regression



## Loss Function (2)

- Can be selected from a set of predefined functions, or user-defined
- Good starting points
  - Classification: categorical/binary cross entropy
  - Regression: mean square error (L2)

one-hot representation

**Note**: when using the <u>categorical\_crossentropy</u> loss, your targets should be in categorical format (e.g. if you have 10 classes, the target for each sample should be a 10-dimensional vector that is all-zeros except for a 1 at the index corresponding to the class of the sample). In order to convert *integer targets* into *categorical targets*, you can use the Keras utility <u>to\_categorical</u>:

```
from keras.utils.np_utils import to_categorical
categorical_labels = to_categorical(int_labels, num_classes=None)
```

#### Losses

Usage of loss functions

Available loss functions

mean\_squared\_error

mean\_absolute\_error

mean\_absolute\_percentage\_error

mean\_squared\_logarithmic\_error

squared\_hinge

hinge

categorical\_hinge

logcosh

categorical\_crossentropy

sparse\_categorical\_crossentropy

binary\_crossentropy

kullback\_leibler\_divergence

poisson

cosine\_proximity



#### Metrics

"A metric function is similar to a loss function, except that the results from evaluating a metric are not used when training the model"

Available metrics

binary\_accuracy

categorical\_accuracy

sparse\_categorical\_accuracy

top\_k\_categorical\_accuracy

sparse\_top\_k\_categorical\_accuracy

Custom metrics



#### Resources

- Getting started with Keras
  - o https://keras.io/getting-started/sequential-model-guide/
  - https://blog.keras.io/keras-as-a-simplified-interface-to-tensorflow-tutorial.html
- Focus on optimization algorithms
  - https://towardsdatascience.com/types-of-optimization-algorithms-used-in-neural-networks-and-ways-to-optimize-gradient-95ae5d39529f
- Metrics
  - https://machinelearningmastery.com/custom-metrics-deep-learning-keras-python/
- Selected MNIST example
  - https://yashk2810.github.io/Applying-Convolutional-Neural-Network-on-the-MNISTdataset/
  - https://elitedatascience.com/keras-tutorial-deep-learning-in-python
  - https://github.com/keras-team/keras/blob/master/examples/mnist\_cnn.py
- Interactive examples of NN
  - o GitHub MilesCranmer/awesome-ml-demos: Curated list of interactive ML demos