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# Attention-based U-Net for segmentation

Deep Learning - Topic 7

Emanuelle PASSOS MARTINS, Nathan YGÉ

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# SUMMARY

**1. Introduction**

**2. Methodology**

**3. Results**

**4. Conclusion**

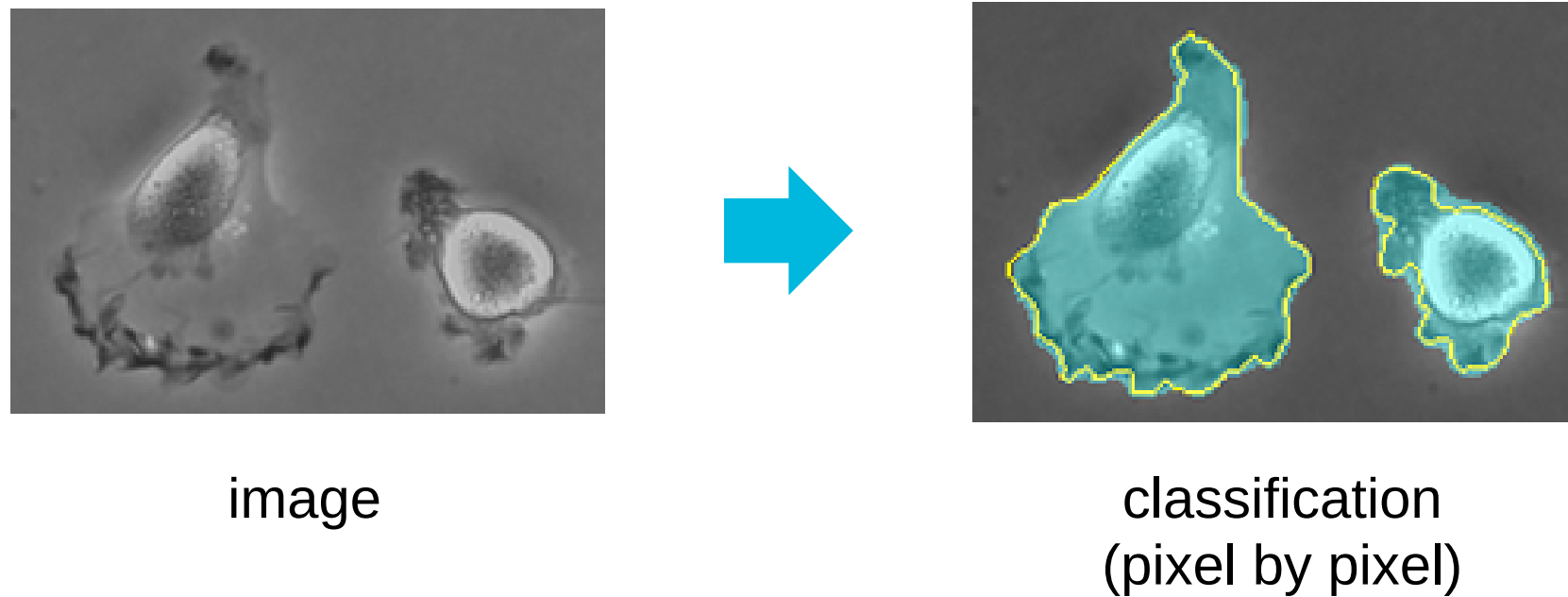
**5. References**



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# 1. Introduction

## Segmentation of medical images with deep learning:



- CNN-based architectures, such as U-Net, have demonstrated strong performance in automating this task.
  - Variations in organ size, shape, and location across patients
- Cascaded frameworks:
- Define a region of interest (ROI)
  - Make predictions on this ROI
- **High computational demand due to full-image processing!**

## Manual annotation

a tedious and  
error-prone task

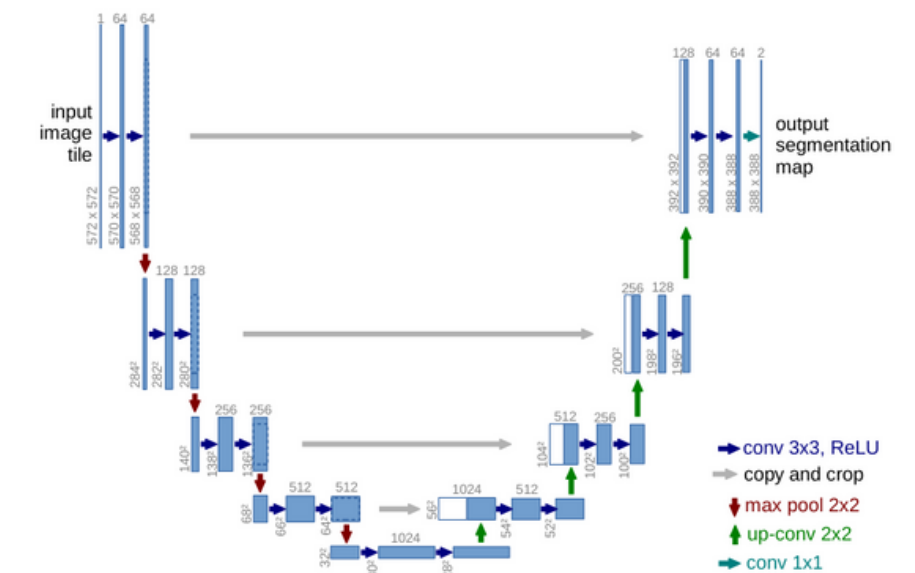


Figure 1 - Example of U-Net architecture

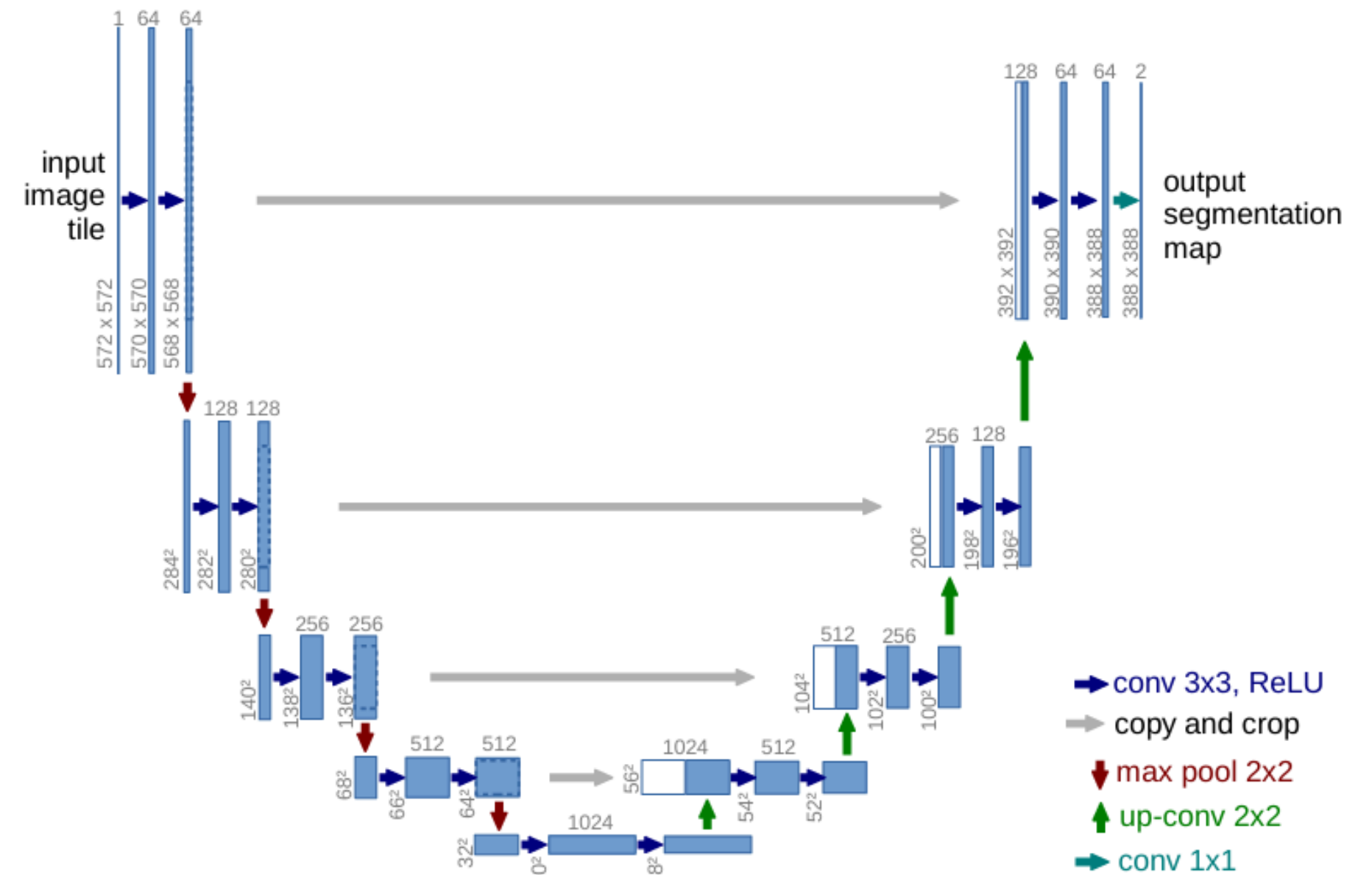
## How does the U-Net work?

### Contracting path

- Convolutional layers
- Activation function (ReLU)
- Pooling layers

### Expanding path

- Up-convolutional layers
- Concatenation / skip connections
- Convolutional layers + ReLU
- Final 1x1 convolution layer, followed by an activation layer (sigmoid)



## Attention U-Net

Attention gates (AGs) **automatically adapt their attention toward target structures!**

- No large number of parameters nor computational demand

The AG receives two main inputs:

- Feature map from the encoder (high detail)
- Gating signal from the decoder (lower resolution)
  - “where to look” without getting stuck on small irrelevant details

These two signals are combined in each AG to generate an attention map, filtering the relevant pixels.

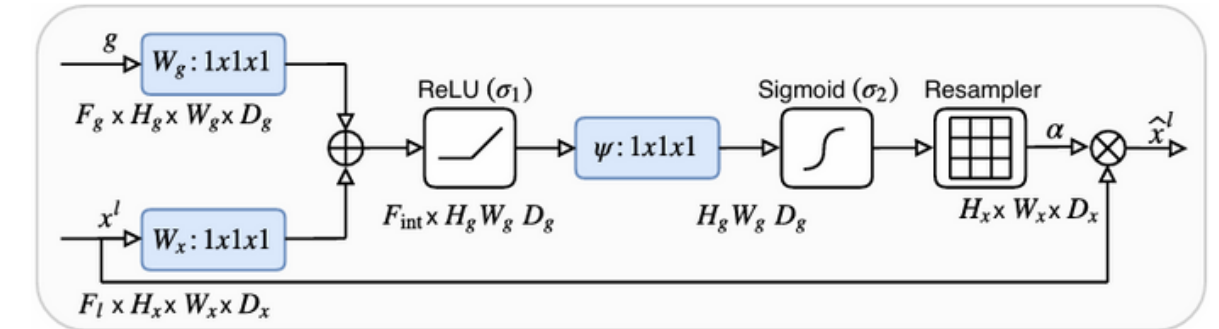


Figure 2 - Attention gate

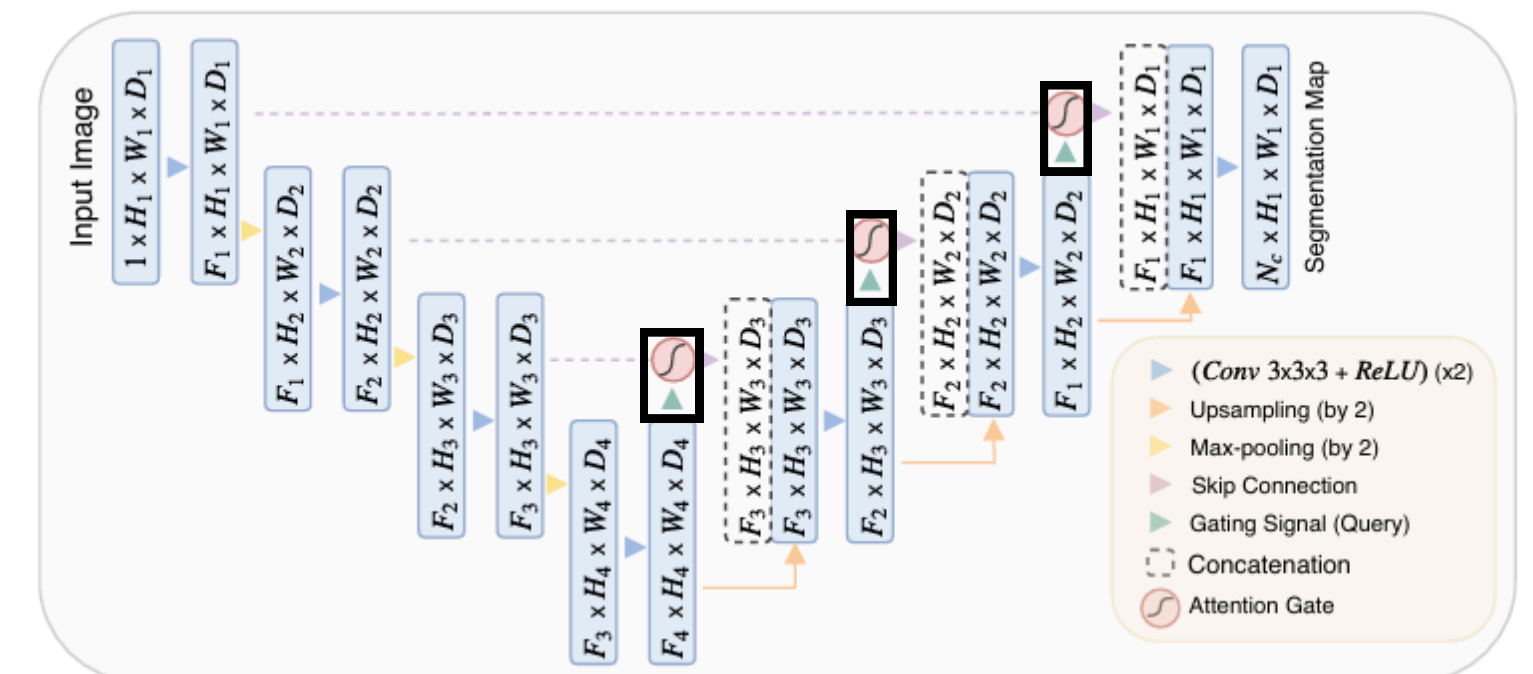


Figure 3 - Attention U-Net segmentation model

## 2. Methodology

## Preprocessing

### ① split

- **20** T2 MRI abdominal images + masks

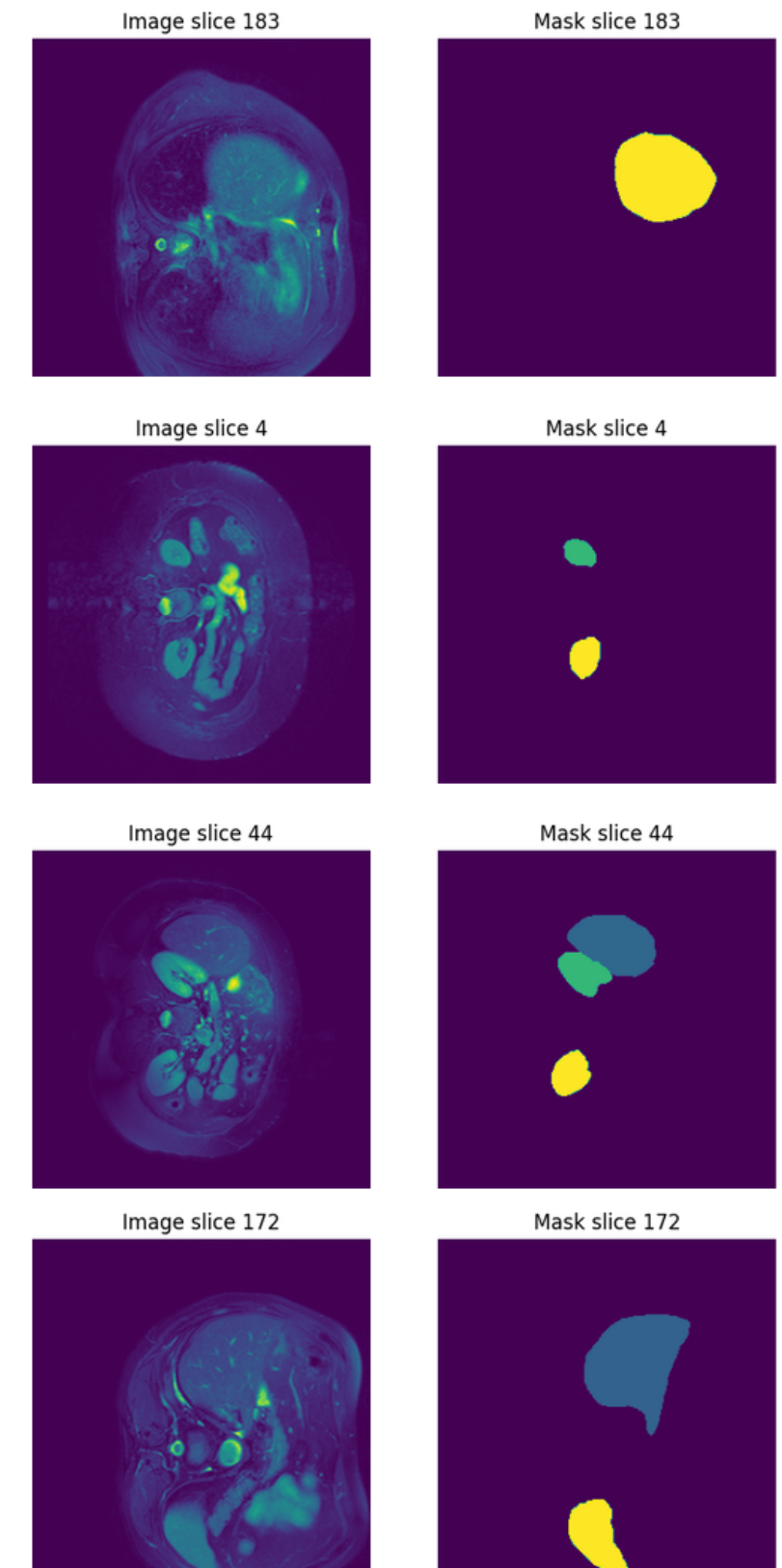
- Train: 12 patients
- Validation: 4 patients
- Test: 4 patients

### ② data transformation: 2D into 3D slices

### ③ Train: slice weights based on the present classes to correct class imbalance

- 5 classes
  - Background
  - Liver
  - Left kidney
  - Right kidney
  - Spleen

```
Fréquence des pixels dans le masque 3D complet:  
Classe 0.0: 2227580 pixels (94.4171 %)  
Classe 80.0: 100875 pixels (4.2756 %)  
Classe 160.0: 11883 pixels (0.5037 %)  
Classe 240.0: 11851 pixels (0.5023 %)  
Classe 255.0: 7107 pixels (0.3012 %)
```





## Training + Evaluation

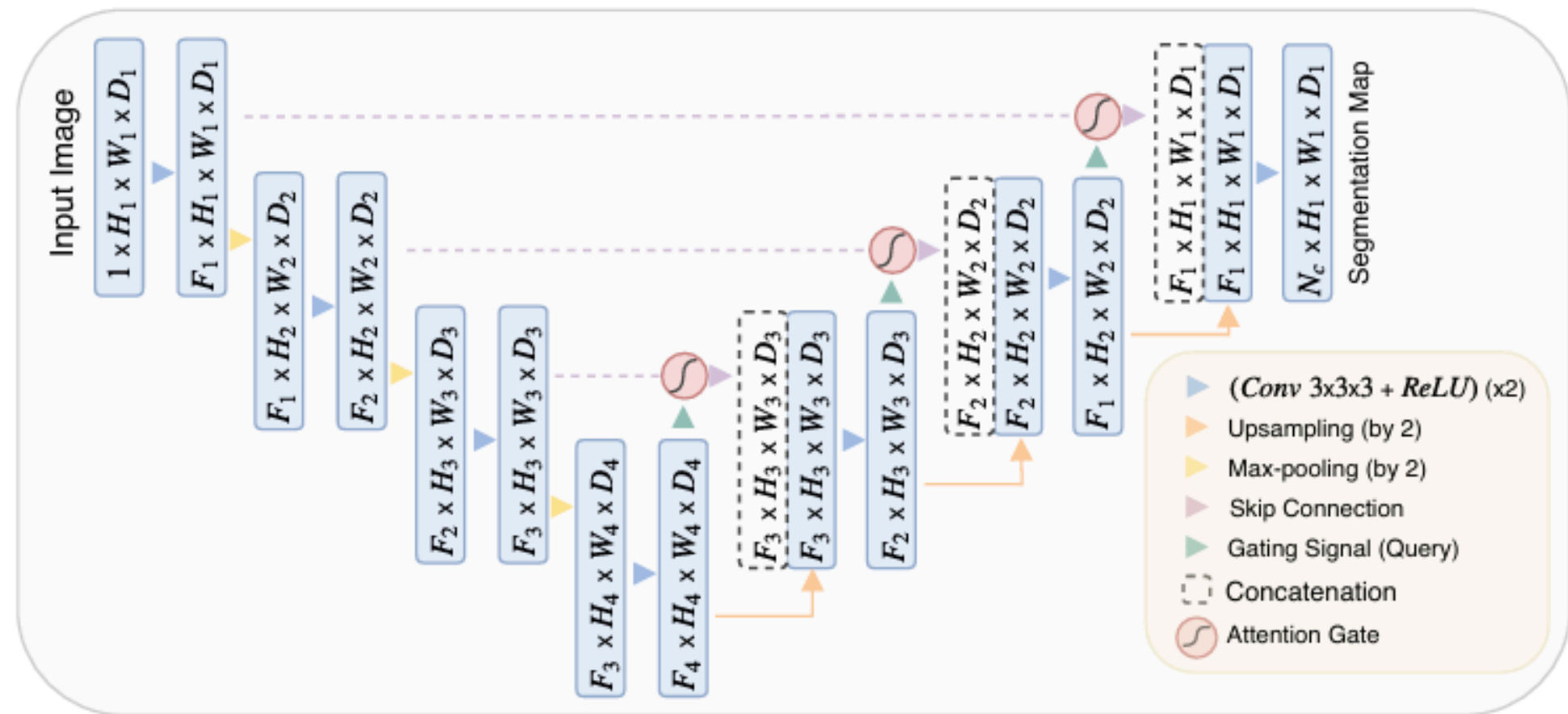
- U-Net
- U-Net with attention gate

### Best configuration:

- Epochs = 40
- Batch size = 4
- Patience = 10
- Optimizer = Adam
- Learning rate =  $1e-4$

## Loss

- Cross-entropy
- Focal loss
- Dice loss



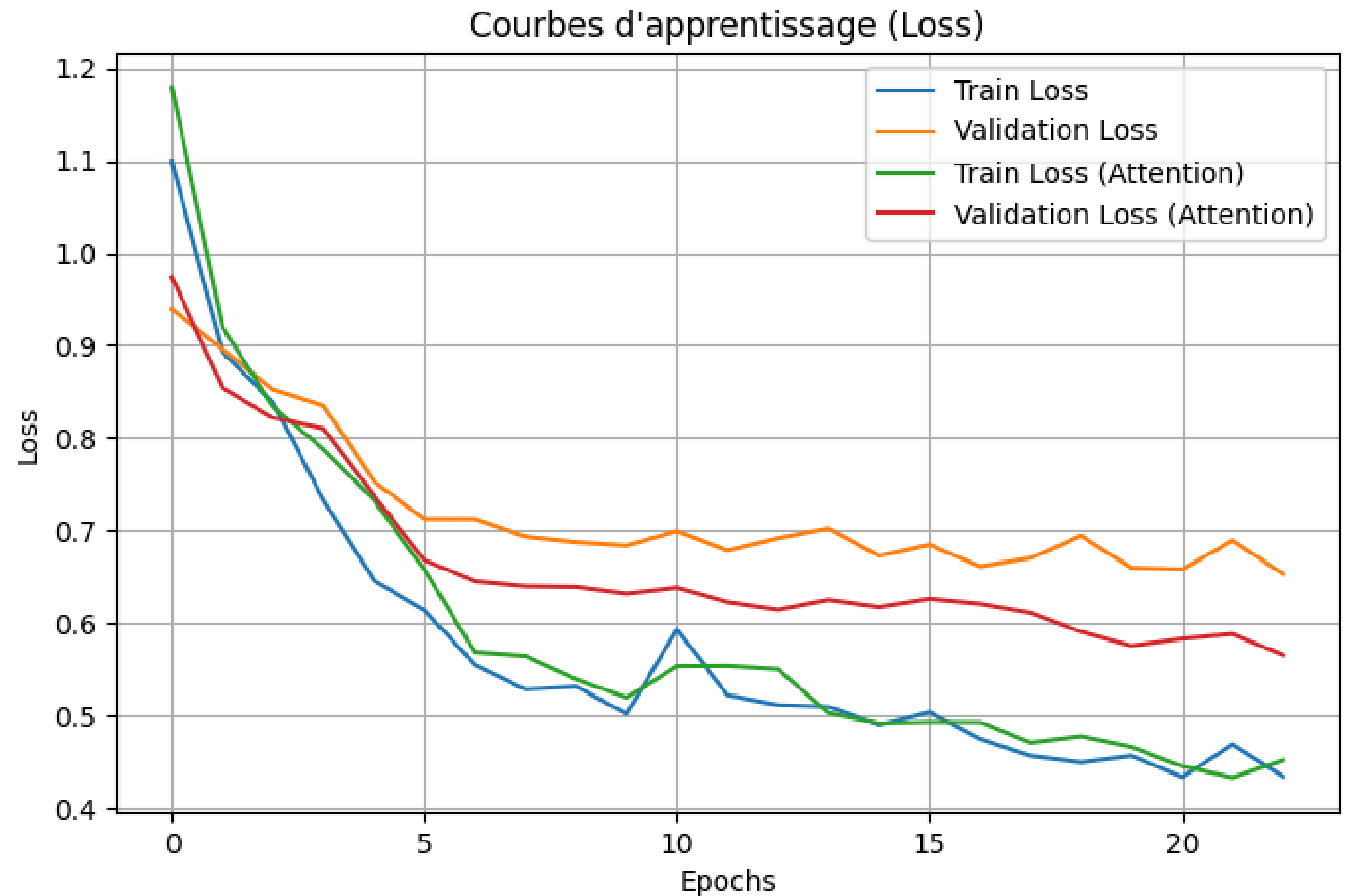
## Metrics

- Dice score (per class, multiclass)
- Average Symmetric Surface Distance (ASSD)
- Hausdorff distance

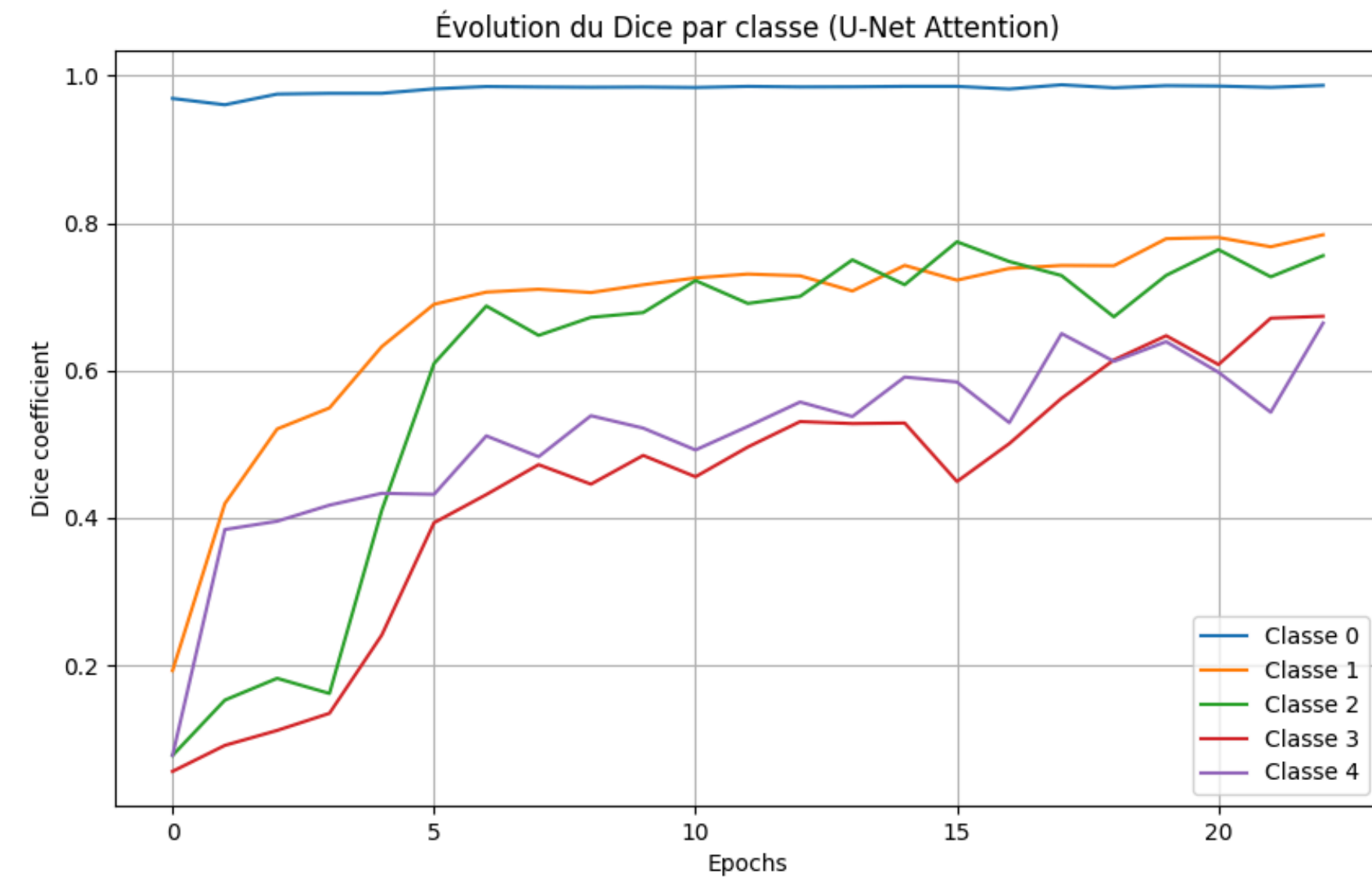
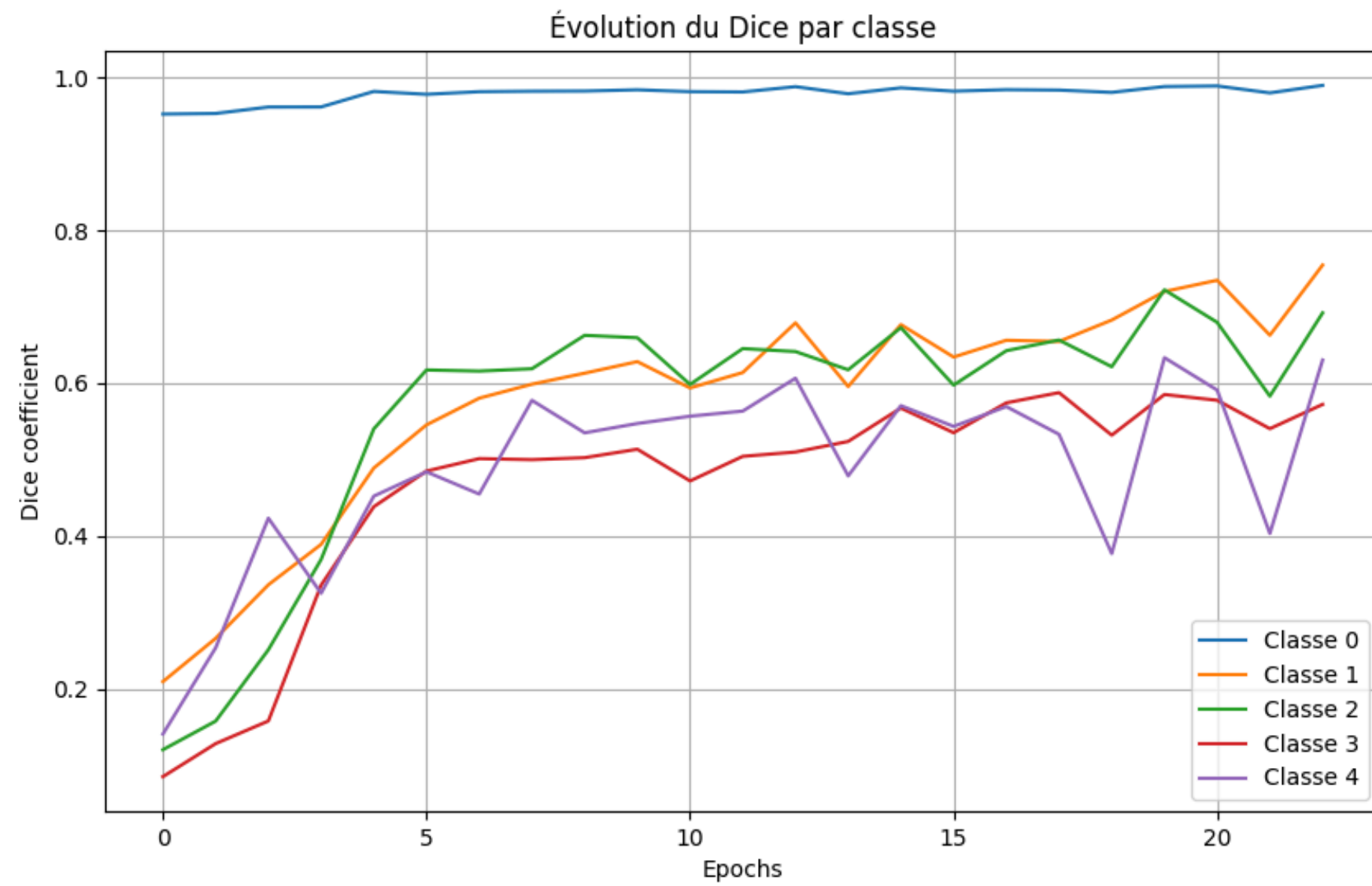
# 3. Results

## Train and validation losses

it has **similar train loss**  
BUT  
**different validation loss** meaning it  
generalize better



## Evolution of dice per class



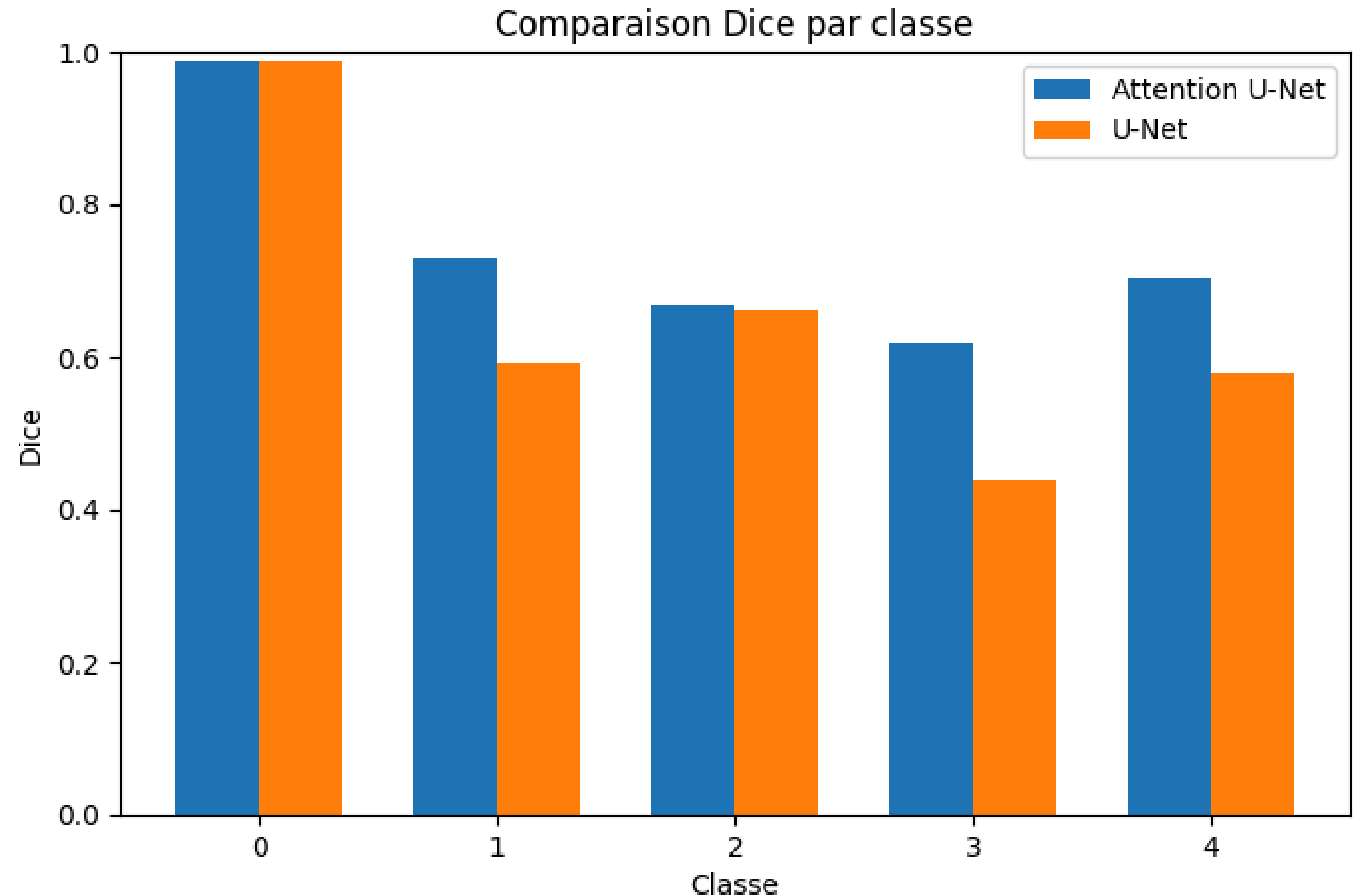
## Evaluation metric DICE

to see in **global** (across all pixels of a class) **if the predicted masks are efficient**

BUT

not looking in local regions

Does not capture local boundary errors or small misalignments

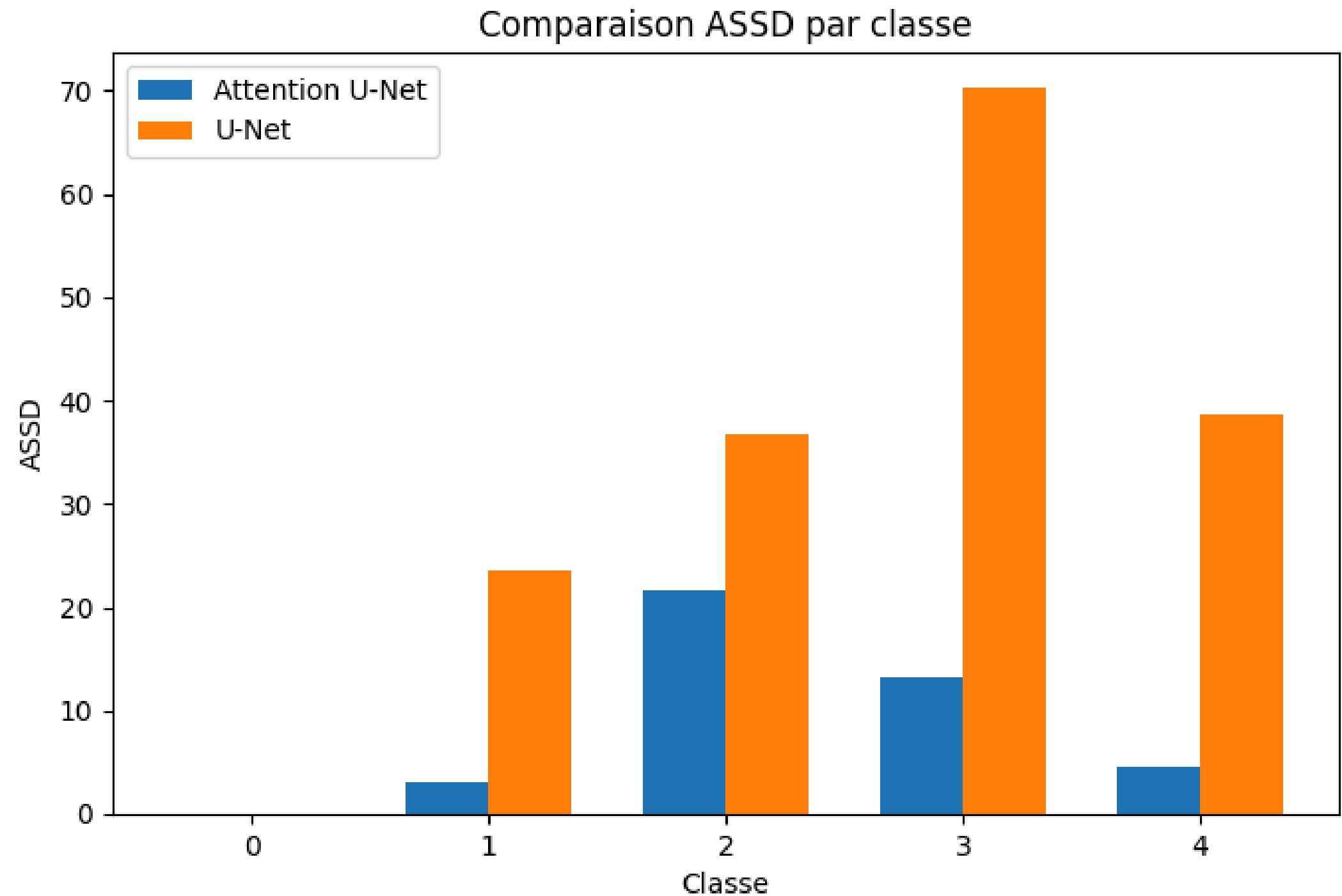


## Evaluation metric ASSD

It computes the **average distance between the edges of the ground truth and the predicted mask** so it is looking specifically on the edges (**contours**)

BUT  
it is an average

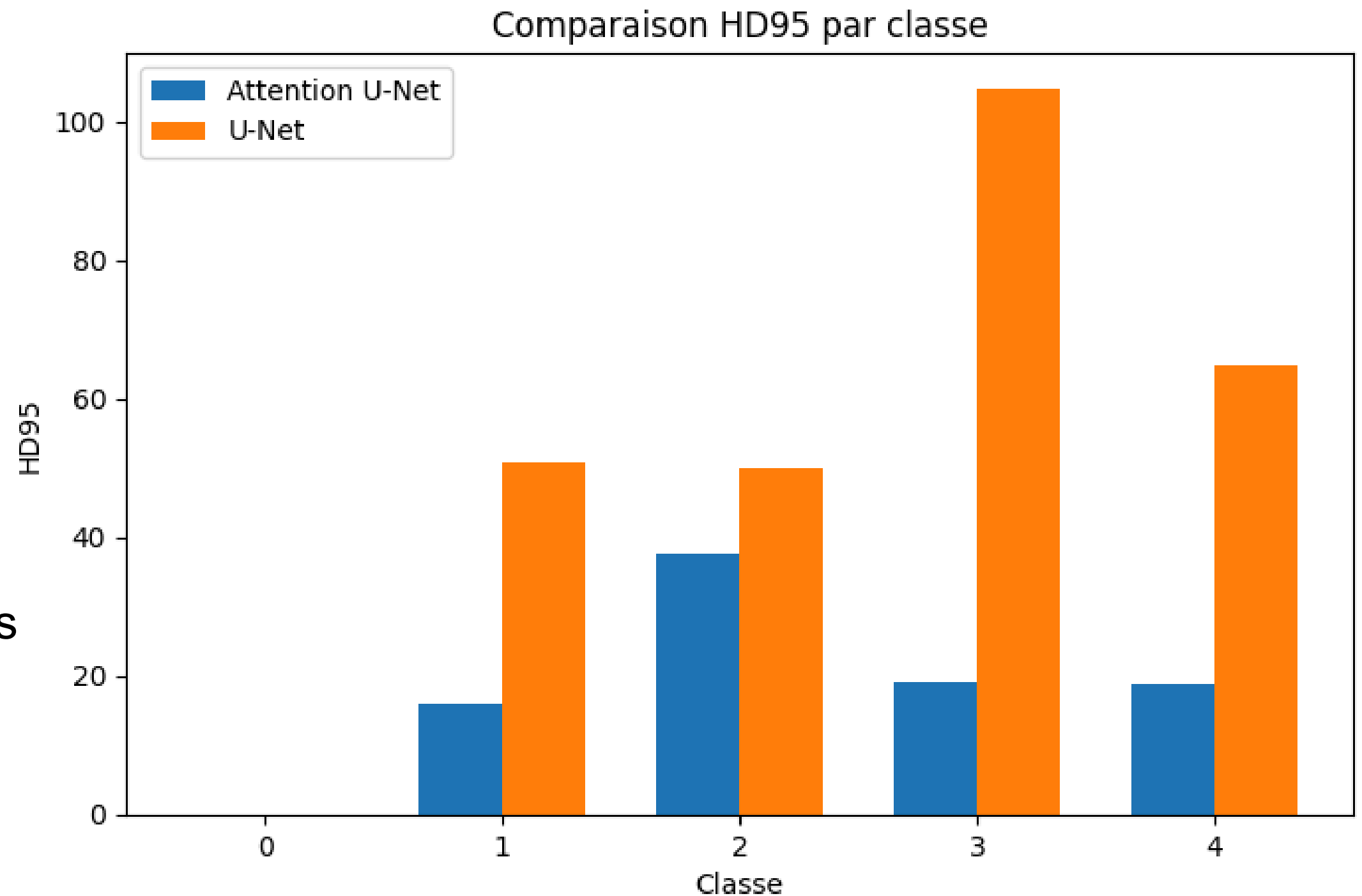
Lower values indicate better alignment



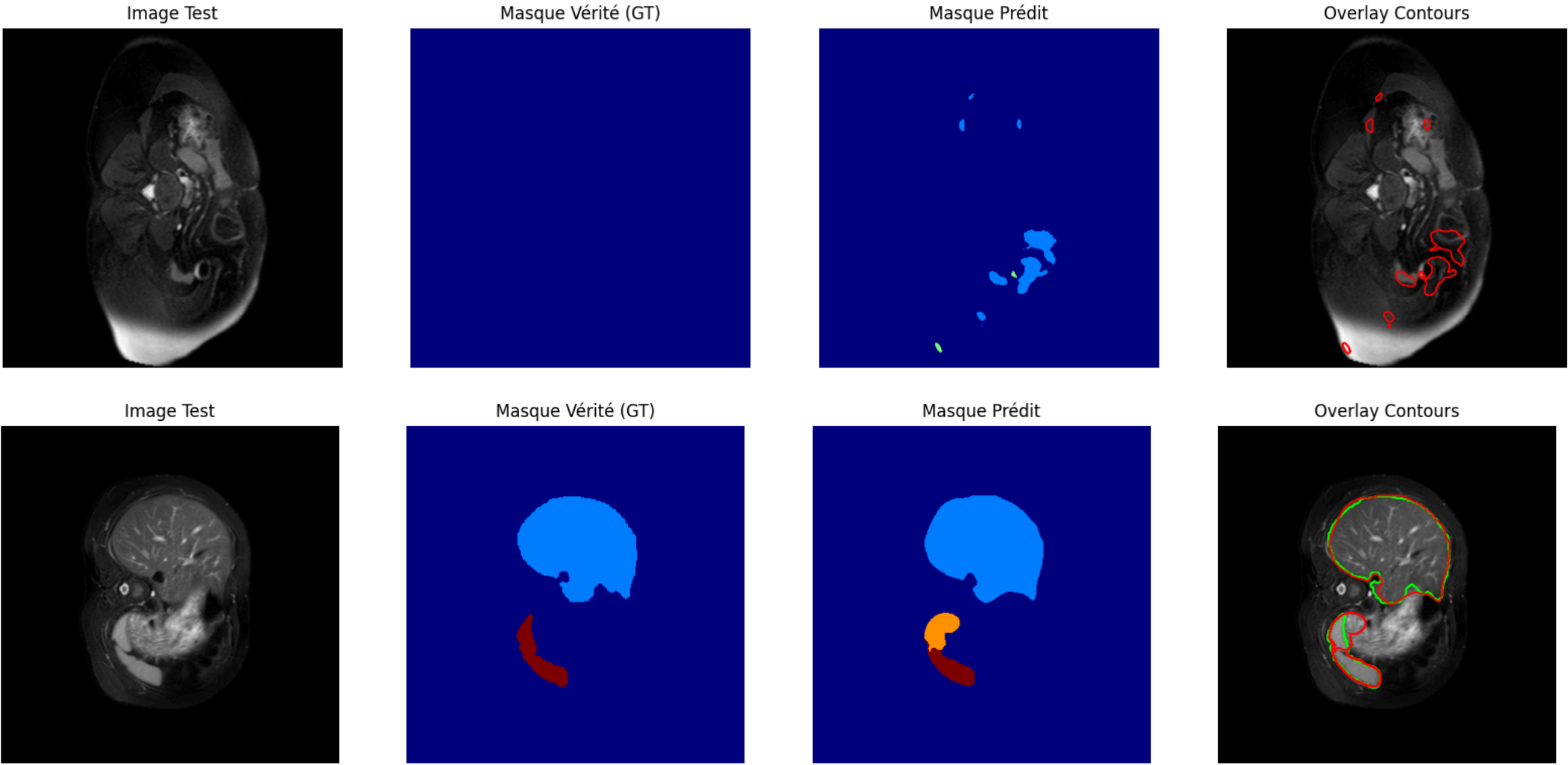
## Evaluation metric HD95

It returns the 95th percentile of the **distances between the edges of the ground truth and the predicted mask**  
SO  
it gives the worst case

It reduces the influence of small outliers

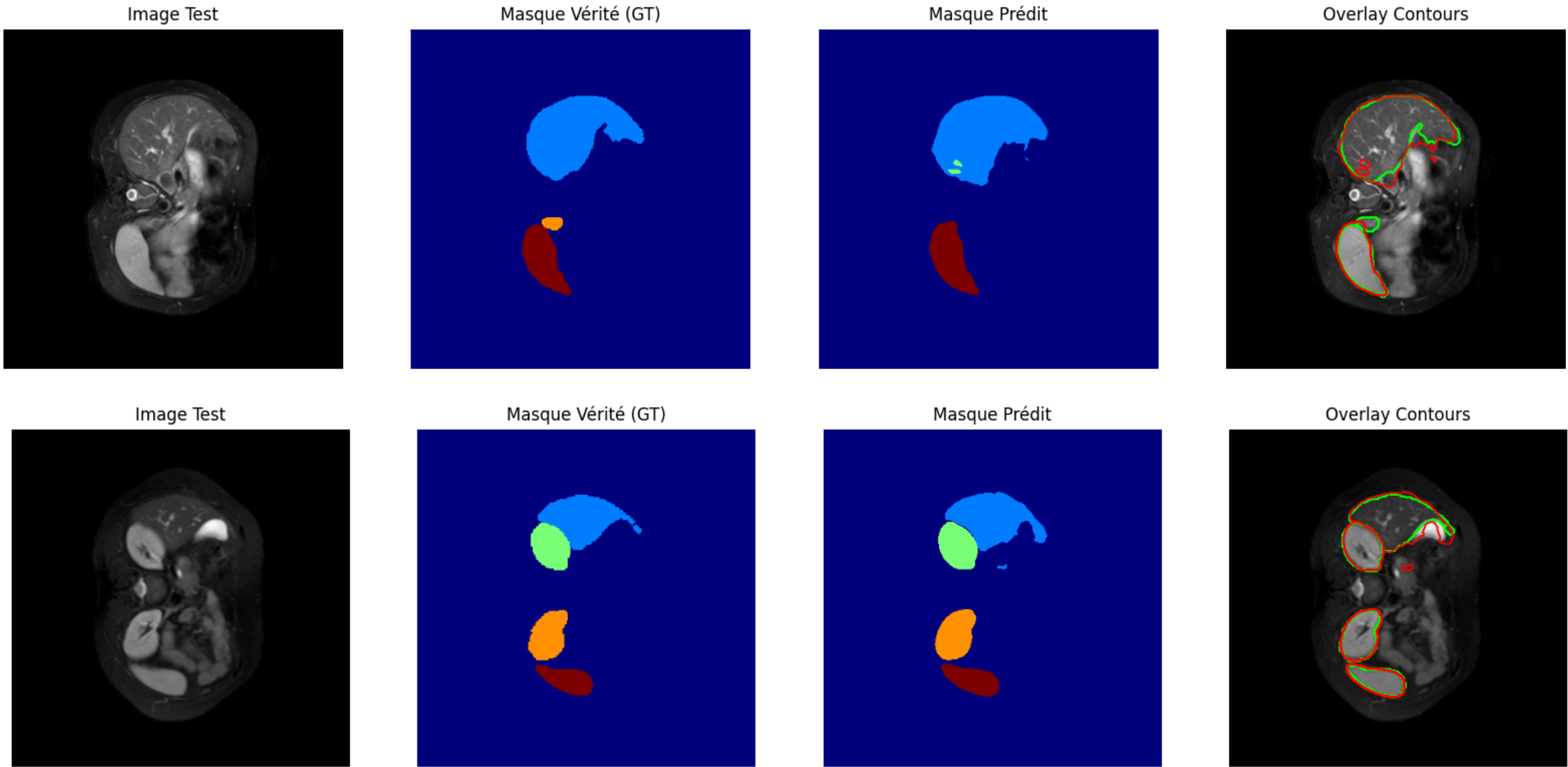


# Predicted mask of the U-Net





# Predicted mask of the Attention U-Net



# 4. Conclusion

- **Computational power and time requirements**

Strategy: using GPU and playing with the parameters.

- **Well organizing implementation details**

Strategy: implementing the model itself was only one part of the work, before and after training, several adjustments were necessary, like taking image and mask together to properly split the dataset, handling the much larger number of background pixels, etc.

- **Optimization of the model to get better performances**

Strategy: trying different parameters and combinations, such as slice weight, combined loss, reducing batch size, and using different metrics to evaluate.

- **Change the complexity of the attention gate ?** as we saw how much it affects the results
- **Change the evaluation metric ?** Use Tversky loss (focuses on FN)
- **Try with a better GPU to increase the batch size ?**
- **Apply data augmentation ?** due to the lack of data
- **Use an unsupervised network to pre-train the encoder ?** because we used only half the dataset

# 5. References

O. Oktay et al., “Attention U-Net: Learning Where to Look for the Pancreas”, 20 mai 2018, arXiv: arXiv:1804.03999. doi: 10.48550/arXiv.1804.03999.

O. Ronneberger, P. Fischer, et T. Brox, “U-Net: Convolutional Networks for Biomedical Image Segmentation”, in *Medical Image Computing and Computer-Assisted Intervention – MICCAI 2015*, vol. 9351, N. Navab, J. Hornegger, W. M. Wells, et A. F. Frangi, Éd., Cham: Springer International Publishing, 2015, p. 234-241. doi: 10.1007/978-3-319-24574-4\_28.

Merci beaucoup  
pour votre attention !

Avez-vous des questions ?