

.STM32746G-EVAL2_OS3 vPublic

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STM32746G-EVAL2 Example Project Read-Me

The provided example project for which this Read-Me was made utilizes the ST STM32746G-EVAL2 (STM32F746) evaluation board from the STM32F7x Family. The MCU found on this development board conforms with the ARM_Cortex_M7 architecture.

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Project Download

Download Link	Micrium_STM32746G-EVAL2_OS3.zip
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Toolchain IDE Versions

IDE/Toolchain	Version
IAR EW for ARM	7.40.3
Atollic TrueSTUDIO	6.0.0
STM32CubeF7 Libraries	1.0.4

Micrium Product Versions

Product	Version
μC/CPU	1.31.00
μC/LIB	1.38.02
μC/OS-III	3.06.00

Hardware Setup

1. Have the board connected via the **ST-LINK** into the board debugging input (**CN21**).
2. Power will be provided by the ST-Link debugger.
3. On the board, make sure to select jumper STlk on JP13.

Loading & Running The Project on the Board

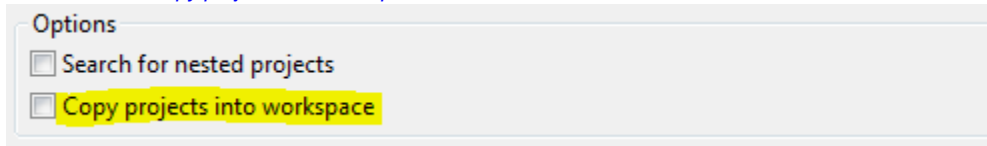
Make sure to open the example project workspace using the mentioned IDE(s) version or newer.

IAR Embedded Workbench™

1. Click on [File→Open→Workspace...](#)
2. Navigate to the directory where the workspace is located: `$\Micrium\Examples\ST\STM32746G-EVAL2\OS3\IAR\OS3.eww`
3. Click [Open](#).
4. For safety, clean the project by clicking on [Project→Clean](#) (if available).
5. Compile the project by clicking on [Project→Make](#).
6. Make sure your hardware setup (as previously described) is correct.
7. Download the code to the board by clicking on [Project→Download and Debug](#).
8. Run the project by clicking on [Debug→Go](#). To stop the project from running, click on [Debug→Stop Debugging](#).

Atollic TrueSTUDIO™

1. Click on [File→Import...](#)
2. Select [Existing Projects into Workspace](#).
3. Navigate to the directory where the workspace is located: `$\Micrium\Examples\ST\STM32746G-EVAL2\OS3\TrueSTUDIO`
4. Click [OK](#).
5. Make sure the "Copy projects into workspace" check-box is unchecked.



6. Make sure that the project has been selected under the [Projects](#) check-box.
7. Click [Finish](#).
8. For safety, clean the project by clicking on [Project→Clean](#) (if available).
9. Compile the project by clicking on [Project→Build All](#). The project should build successfully.
10. Make sure your hardware setup (as previously described) is correct.
11. Download the code to the board by right-clicking inside the project directory and selecting [Debug As→Embedded C/C++ Application](#).
 - a. Select the appropriate interface inside the [Debugger Tab](#) (if needed).
12. Run the project by clicking on [Run→Resume](#). To stop the project from running click on [Run→Terminate](#).

µC/OS-III

```

void main (void)
{
    ...
    OSInit(&os_err);                                     /* Initialize
uC/OS-III                                             */          (1)

    ...
    OSTaskCreate(&AppTaskStartTCB,                      /* Create the
start task                                           */          (2)
                "App Task Start",
                AppTaskStart,
                0,
                APP_CFG_TASK_START_PRIO,
                &AppTaskStartStk[0],
                APP_CFG_TASK_START_STK_SIZE / 10u,
                APP_CFG_TASK_START_STK_SIZE,
                0u,
                0u,
                0,
                (OS_OPT_TASK_STK_CHK | OS_OPT_TASK_STK_CLR),
                &os_err);

    OSStart(&os_err);                                     /* Start
multitasking                                           */          (3)
}

static void AppTaskStart (void *p_arg)
(4)
{
    ....

    while (DEF_TRUE) {                                   /* Task body,
always as an infinite loop.                             */          (5)
        ...
(6)

        OSTimeDlyHMSM( 0u, 0u, 0u, 500u,
(7)
                        OS_OPT_TIME_HMSM_STRICT,
                        &os_err);
    }
}

```

Listing - app.c

(1)
OSInit() initializes uC/OS-III and must be called prior to calling OSStart(), which actually starts multitasking.

(2)
OSTaskCreate() creates a task to be managed by uC/OS-III. Tasks can be created either prior to the start of multitasking or by a running task. In this case, the task "AppStartTask" gets created.

(3)
OSStart() starts multitasking under uC/OS-III. This function is typically called from the startup code but after calling OSInit().

(4)

AppTaskStart is the startup task created in (2).

(5)

A task must be written as an infinite loop and must not return.

(6)

In most examples, there is hardware dependent code such as LED blink, etc.

(7)

OSTimeDlyHMSM() allows AppTaskStart to delay itself for a user-specified amount of time (500ms in this case). Rescheduling always occurs when at least one of the parameters is nonzero. Placing a break-point here can ensure that uC/OS-III is running, it should get hit periodically every 500 milliseconds.

For more information please refer to [uC/OS-III Users' Guide](#).

μC/Probe

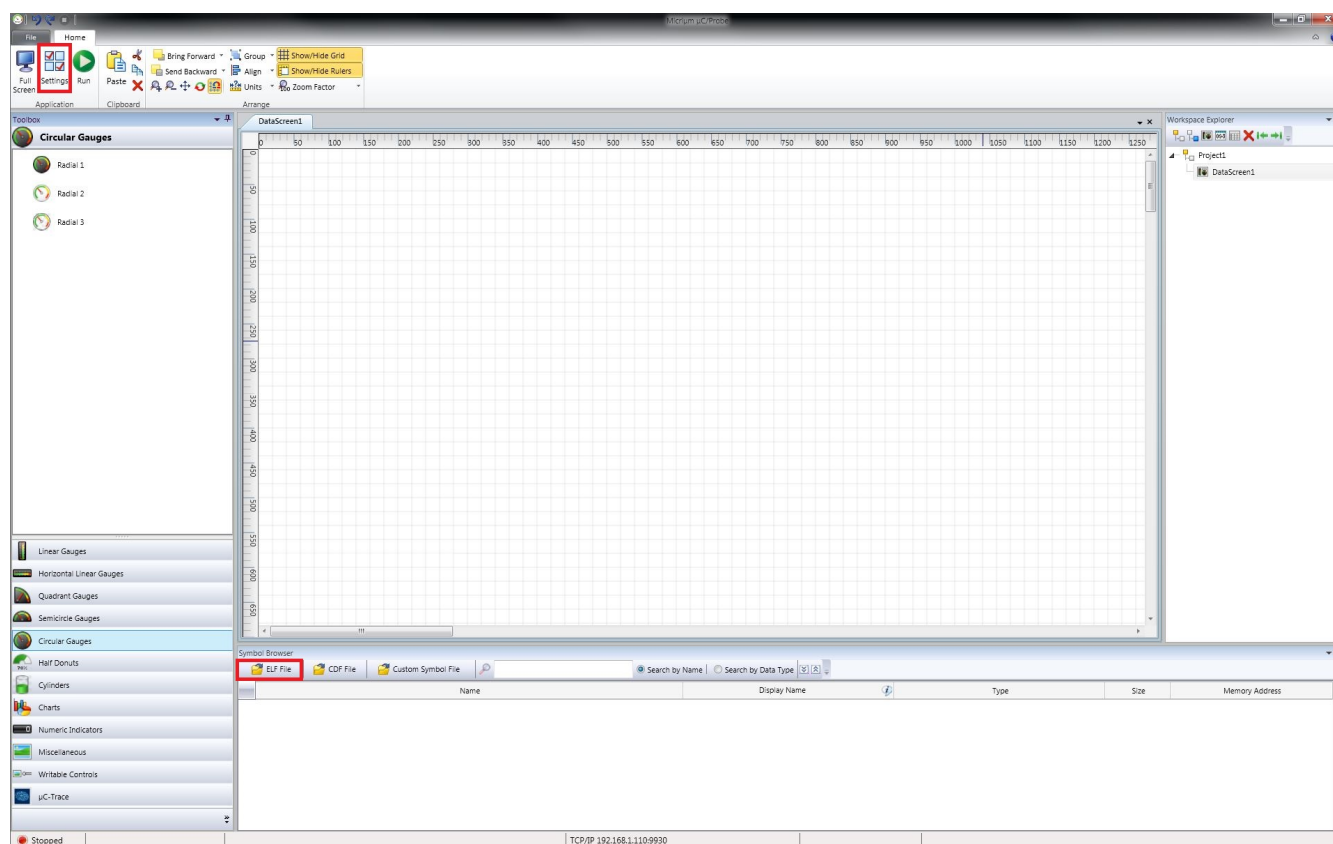
μC/Probe, is a Micrium Windows™ application to graphically view the internals of any embedded system. This example project includes a pre-configured μC/Probe workspace that can be found at:

`$\Micrium\Examples\ST\STM32746G-EVAL2\OS3\<IDE>\OS3.wsp`

Please compile the project (as described earlier in this document) prior to opening a pre-configured μC/Probe workspace.

In order for μC/Probe to display symbols, an **ELF file** that is generated by the compiler is required. After the example project has compiled, look for the ELF file that is usually found inside the compiler auto-generated binaries folder.

The following image shows where the **ELF file** (highlighted in **RED**) button is found to search for the project's ELF file.



If creating a new μC/Probe workspace, you must configure μC/Probe with the proper communication protocol used in your project. The following communication protocols are currently available for this example project:

Running with J-Link

When running a Micrium example project that is using the J-Link debugger to interface with μ C/Probe, there is no additional set-up necessary other than to configure μ C/Probe's settings to "J-Link".

In μ C/Probe's settings, under the [Communication](#) tab, select [J-Link](#) under the [Interfaces](#) section and configure the [Speed](#) and [Interface Mode](#) you desire that suits your project's needs. Along with the J-Link settings, μ C/Probe also allows you to change the endianness of the device, how to receive statistics, and the rate at which the data collection is done.

The following image illustrates how the settings should look:

