Arm® Development Studio

Version 2021.1

Debugger Command Reference

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Arm® Development Studio

Debugger Command Reference

Release Information

Document History

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Progressive terminology commitment

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This document includes terms that can be offensive. We will replace these terms in a future issue of this document.

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Contents
Arm® Development Studio Debugger Command Reference

Preface

This preface introduces the *Arm® Development Studio Debugger Command Reference*.

It contains the following:

- *About this book* on page 6.

About this book

This book contains a full list of Arm® Debugger commands with usage instructions and examples.

Using this book

This book is organized into the following chapters:

Chapter 1 Arm Debugger commands

Arm Debugger commands are a comprehensive set of commands to debug embedded applications. This is an overview of the conformance and usage rules for Arm Development Studio Debugger commands and describes how to use each of the commands with examples.

Chapter 2 CMM-style commands supported by the debugger

Describes how to use each of the commands with examples.

Chapter 3 GNU Free Documentation License Details

Glossary

The Arm® Glossary is a list of terms used in Arm documentation, together with definitions for those terms. The Arm Glossary does not contain terms that are industry standard unless the Arm meaning differs from the generally accepted meaning.

See the *Arm Glossary* for more information.

Typographic conventions

italic

Introduces special terminology, denotes cross-references, and citations.

bold

Highlights interface elements, such as menu names. Denotes signal names. Also used for terms in descriptive lists, where appropriate.

`monospace`

Denotes text that you can enter at the keyboard, such as commands, file and program names, and source code.

`monospace`

Denotes a permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.

`monospace italic`

Denotes arguments to monospace text where the argument is to be replaced by a specific value.

`monospace bold`

Denotes language keywords when used outside example code.

`<and>`

Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example:

```
MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>
```

SMALL CAPITALS

Used in body text for a few terms that have specific technical meanings, that are defined in the *Arm® Glossary*. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and UNPREDICTABLE.

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- The product revision or version.
- An explanation with as much information as you can provide. Include symptoms and diagnostic procedures if appropriate.

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- The title *Arm Development Studio Debugger Command Reference*.
- The number 101471_2021.1_00_en.
- If applicable, the page number(s) to which your comments refer.
- A concise explanation of your comments.

Arm also welcomes general suggestions for additions and improvements.

Note

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Other information

- *Arm® Developer*.
- *Arm® Documentation*.
- *Technical Support*.
- *Arm® Glossary*.

Chapter 1
Arm Debugger commands

Arm Debugger commands are a comprehensive set of commands to debug embedded applications. This is an overview of the conformance and usage rules for Arm Development Studio Debugger commands and describes how to use each of the commands with examples.

It contains the following sections:

1.1 Conformance and usage rules for Arm Debugger commands

This section contains the following subsections:

1.1.1 Syntax of Arm Debugger commands

Arm Debugger commands accept arguments and flags. A flag acts as an optional switch and is specified using a forward slash character. Where a command supports flags, the flags are described as part of the command syntax.

```
command [<argument>] [/<flag>]...
```

Note

- Commands are not case sensitive.
- Abbreviations are underlined.
- When you specify an address as an argument to a command, you can also specify the *address space* on page 1-17, for example `N:0x80000000`. If you do not specify the address space, Arm Debugger assumes the current address space.

In commands that use `/<flag>`, the position of `/<flag>` should generally be as shown in the command syntax. The commands you submit to the debugger must follow these rules:

- Each command line can contain only one debugger command.
- When referring to symbols, you must use the same case as the source code.

You can execute the commands by entering them in the debugger command-line console or by running debugger script files. Alternatively, in the IDE, you can open the **Development Studio** perspective where you can use the menus, icons, and toolbars provided, or you can enter Arm Debugger commands in the **Commands** view.

The debugger requires enough letters to uniquely identify the command you enter. Many commands have alternative names, or aliases, that you might find easier to remember. For example, `backtrace` and `where` are aliases for the `info stack` command.

Some command names and aliases can be abbreviated. For example, `info stack` can be abbreviated to `i s`. The syntax definition for each command shows how it can be abbreviated by underlining it for example:

`info stack`.

In the syntax definition of each command:

- square brackets `[...]` enclose optional parameters
- braces `{...}` enclose required parameters
- a vertical pipe `|` indicates alternatives from which you must choose one
- parameters that can be repeated are followed by an ellipsis `(...)`.

Do not type square brackets, braces, or the vertical pipe. Replace parameters in italics with the value you want. When you supply more than one parameter, use the separator as shown in the syntax definition for each command. If a parameter is a name that includes spaces, enclose it in double quotation marks.

You can add descriptive comments to either the end of a command or on a separate line. You can use the # character to identify a descriptive comment.

1.1.2 Usage of special characters and environment variables in paths within Arm Development Studio

List of characters and variables that you can use for path shortcuts in Arm Debugger commands.

When specifying paths, you can use any of the following:

- a tilde character (~) at the start of a path to refer to your home directory
- an environment variable, for example:
  - `%LOG_DIRECTORY%`
  - `${LOG_DIRECTORY}`
  - `$LOG_DIRECTORY`
- a backslash () or forward slash (/) as a directory separator.

Related references

1.3.132 set escapes-in-filenames on page 1-130

1.1.3 Expressions within Arm Development Studio

Some Arm Development Studio commands accept expressions. There are many types of expressions accepted by the debugger that enable you to extend the operation of a command. For example, binary mathematical expressions, references to module names, or calls to functions.

Usage of $ character to access registers and variables within Arm Development Studio expressions

In an expression you can access the content of registers by using the $ character and the register name, for example:

```
print 4+$R0 # add 4 to the content of R0 register and print result
```

Results from the `print` commands are recorded in debugger variables. Other commands, such as breakpoint or watchpoint creating commands, the `start` command, and the `memory` command, also use debugger variables to record the ID of the new resource. Each of these debugger variables is assigned a number and can be used subsequently in expressions by using the $ character.

You can access print results or resource IDs using the debugger variables:

$

Print result or ID in the last assigned debugger variable.

$$

Print result or ID in the second-to-last debugger variable.

$<n>

Print result or ID in the debugger variable with number *n*.

You can also use the following debugger variables:

$cwd

Current working directory.

$cdir

Current compilation directory.

$entrypoint

Entry point of the current image.

$idir

Current image directory.

$sdir

Current script directory.

$datetime

Current date and time in string format.

$timems

Number of milliseconds since 1st Jan 1970.

$pid

Current operating system process ID.

$thread

Current thread ID for a multi-threaded application.

$core

Current processor ID for Symmetric MultiProcessing (SMP) systems.

$vmid

Current Virtual Machine ID (VMID) for systems that support hypervisor / virtual machine debugging.

Note

- `$thread` is uniquely assigned by the debugger for the current context reported by the OS awareness plugin. If no OS awareness plugin is loaded, `$thread` tracks the current core, `$core`.
- `$pid` is assigned for the debugger for the current context by the OS awareness plugin. If no OS awareness plugin is loaded, `$pid` tracks the current core, `$core`.

Related references

1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11
1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15
1.3.31 echo on page 1-72
1.3.138 set print on page 1-134
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1.3.2 advance on page 1-52

Related information

About OS Awareness

1.1.4 Built-in functions within Arm Development Studio expressions

In an Arm Debugger expression, you can use built-in functions to provide more functionality.

You can use the following built-in functions within Arm Debugger expressions:

int strcmp(const char *str1, const char *str2);

Compares two strings and returns an integer.

Return values are:

<0

Indicates that the second argument string value comes after the first argument string value in the machine collating sequences, `str1 < str2`.

0

Indicates that the two strings are identical in content.

>0

Indicates that the first argument string value comes after the second argument string value in the machine collating sequences, `str2 < str1`.

int strncmp(const char *str1, const char *str2, size_t n);

Compares at most *n* characters of two strings and returns an integer.

Return values are:

<0

Indicates that the second argument string value comes after the first argument string value in the machine collating sequences, `str1 < str2`.

0

Indicates that the two strings are identical in content.

>0

Indicates that the first argument string value comes after the second argument string value in the machine collating sequences, `str2 < str1`.

char *strcpy(char *str1, const char *str2);

Copies `str2` to `str1` including "`\0`" and returns `str1`.

char *strncpy(char *str1, const char *str2, size_t n);

Copies at most *n* characters of `str2` to `str1` including "`\0`" and returns `str1`. If `str2` has fewer than n characters then fill with "`\0`".

void *memcpy(void *s, const void *cs, size_t n);

Copies at most *n* characters from `cs` to `s` and returns `s`.

Examples

```
break main.c:45 if strcmp(myVar, "10") == 0     # Set conditional breakpoint that stops
                                                # when strings are identical
```

Related references

1.1.3 Expressions within Arm Development Studio on page 1-10

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.31 echo on page 1-72

1.3.138 set print on page 1-134

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1.3.6 break on page 1-58

1.3.195 thread, core on page 1-162

1.3.216 x on page 1-178

1.1.5 Usage of wildcards within Arm Debugger expressions

You can use wildcards to enhance your pattern matching in Arm Debugger expressions.

The following types of wildcard pattern matching can be used:

- Globs. This is the default.
- Regular expressions.

You can use the Arm Debugger command `set wildcard-style` to change the default setting.

Usage of globs within Arm Debugger expressions

Globs are a mechanism for examining the contents of strings, and can be used to search variables for strings matching specific patterns.

Commands that support wildcards can use globs with the following syntax:

`*`

Specifies zero or more characters

`?`

Specifies only one character

`\\`

Specifies an escape character to match on strings containing either `*` or `?`

`[<character>]`

Specifies a range of characters. You can use `!<character>` to match characters that are not listed in the range.

Examples

This is an example of Globs where a wildcard is expected:

```
info functions m* # List all functions starting with m
```

Usage of regular expressions within Arm Development Studio

Commands that support wildcards can use regular expressions.

The exact regular expression syntax supported is described in a book called *Mastering Regular Expressions*.

Examples

This is an example of regular expressions where a wildcard is expected:

```
info functions m.*   # List all functions starting with m
```

Related references

1.3.148 set wildcard-style on page 1-141

1.3.185 show wildcard-style on page 1-155

Related information

Jeffrey E. F.Friedl, Mastering Regular Expressions. ISBN 0-596-52812-4

Related references

Usage of globs within Arm Debugger expressions on page 1-13

Usage of regular expressions within Arm Development Studio on page 1-13

1.1.6 Usage of regular expressions in the C expression parser within Arm Development Studio

The C expression parser in Arm Debugger supports regular expressions. Regular expressions are a mechanism for examining the contents of strings, and can be used to search variables for strings

matching specific patterns. The debugger extends C expression syntax to support regular expressions using the =~ and !~ operators in the style of Perl, as shown in the following examples:

This example evaluates to 1 if the regular expression that uses =~ matches anywhere in the string and 0 if it does not match:

```
expression =~ regular_expression
```

This example evaluates to 0 if the regular expression that uses !~ matches anywhere in the string and 1 if it does not match:

```
expression !~ regular_expression
```

Where:

`expression`

is any expression of type `char *` or `char[]`. For example, a variable name.

`regular_expression`

is a regular expression in the form `/regex/modifiers` or `m/regex/modifiers`.

For example, if `str` is a variable of type char*, the following are valid expressions:

```
str =~ /abc/
```

```
((char *) void_pointer) !~ m/abc/i
```

The exact regular expression syntax supported is described by the *Mastering Regular Expressions* book in the chapter discussing Java regex support. An exception to this is the parsing of the handling of modifiers. The following modifiers are supported by the debugger:

`i`

Enable case insensitive matching.

`m`

Multiline mode (^ and $ match embedded newline).

`s`

Dotall mode (. matches line terminators).

`x`

Comments mode (permit whitespace and comments).

Related information

Jeffrey E. F.Friedl, Mastering Regular Expressions. ISBN 0-596-52812-4

1.1.7 Usage of the scoping resolution operator

In Arm Development Studio, the :: (scope resolution) operator is a global identifier for variable or function names that are out of scope. The expression evaluator supports scoping operations using the scope resolution, member and member pointer operators. This can be used to reference variables and functions within images, files, namespaces, or classes.

The following is an example which references `image.axf` created using `demo.c` below:

```
static int FILE_STATIC_VARIABLE = 20;
class OuterClass
{
  public:
  OuterClass(int i)
  {
    value = i;
  }
  class InnerClass
  {
    public:
```

```
    int demoFunction()
    {
       return 25;
    }
  };
  void increment()
  {
    value++;
  }
  int value;
};
namespace NAME_SPACE_OUTER
{
  const int TEST_VAR = 20;
  namespace NAME_SPACE_INNER
  {
    const int TEST_VAR = 19;
    int nameSpaceFoo ()
    {
      return 60;
    }
  };
};
int main()
{
  OuterClass oc(14);
  OuterClass *ptr_oc = &oc;
  ptr_oc->increment();
}
```

You can query this example by using any of the following expressions:

```
OuterClass::InnerClass::demoFunction
"image.axf"::main
"image.axf"::"demo.c"::FILE_STATIC_VARIABLE
"demo.c"::FILE_STATIC_VARIABLE
NAME_SPACE_OUTER::TEST_VAR
NAME_SPACE_OUTER::NAME_SPACE_INNER::TEST_VARNAME_SPACE_OUTER::NAME_SPACE_INNER::TEST_VAR
```

If you set a breakpoint at `ptr_oc->increment()` and run to it, then the following expressions can also be used to query the instances of the outer class:

```
oc.value
ptr_oc->valueptr_oc->value
```

1.1.8 Usage of printf() style format string within Arm Development Studio

Certain commands use `printf()` style format strings to specify how to format values. For example the and commands specify how to format floating-point values. It works in a similar way to the ANSI C standard library function `printf()`.

Format string syntax

The commands specify the format using a string. If there are no `%` characters in the string, the message is written out and any arguments are ignored. The `%` symbol is used to indicate the start of an argument conversion specification.

The syntax of the format string is:

`%[flag...][fieldwidth][precision]format`

where:

`flag`

An optional conversion modification flag.

`"-"`

result is left-justified

`"#"`

result uses a conversion-dependent alternate form

"+"

result includes a sign

" "

result includes a leading space for positive values

"0"

result is zero-padded

","

result includes locale-specific grouping separator

"("

result encloses negative numbers in parentheses.

fieldwidth

An optional minimum field width specified in decimal.

precision

An optional precision specified in decimal, with a preceding **.** (period character) to identify it.

format

The possible conversion specifier characters are:

%

A literal **%** character.

a, A, e, E, f, g, or G

Results in a decimal number formatted using scientific notation or floating point notation. The capital letter forms use a capital **E** in scientific notation rather than an **e**.

d or u

Results in a decimal integer. **d** indicates a signed integer. **u** indicates an unsigned integer.

h or H

Results in a Hexadecimal character in lower or upper case.

x or X

Results in an unsigned Hexadecimal character in lower or upper case.

o

Results in an octal integer.

c or C

Results in a Unicode character in lower or upper case.

s

Results in a string.

b or B

Results in a string containing either "true" or "false" in lower or upper case.

n

Results in a platform-specific line separator.

`t` or `T`

Prefix for date and time conversion specifier characters. For example:

`"%ta %tb %td %tT"` results in "Sun Jul 2016:17:00"

Related references

1.1.3 Expressions within Arm Development Studio on page 1-10
1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11
1.3.31 echo on page 1-72
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1.3.216 x on page 1-178

1.1.9 Address space prefixes

Use address space prefixes in Arm Debugger to refer to different address spaces. You can use these address space prefixes for various debugging activities.

Default

If no address space prefix is specified, then the debugger defaults to the current address space.

Syntax

```
<address_space_prefix>[<parameter>=<value>,<parameter>=<value>,...]:<address>
```

Parameters

address_space_prefix

The address space prefix. Address spaces can vary on different targets. The availability of an address space depends on what architecture features are implemented, such as security extensions.

The following address space prefixes might be available for Armv7-based processors:

- `S:` This corresponds to the Secure address space.
- `H:` This corresponds to the hypervisor address space.
- `N:` This corresponds to the Non-secure address space.
- `SP:` This corresponds to Secure World physical memory.
- `NP:` This corresponds to Non-secure World physical memory.

The following address space prefixes might be available for Armv8-based processors when in the AArch32 execution state:

- `S:` This corresponds to the EL3, Secure EL1, and Secure EL0 translation regimes.
- `H:` This corresponds to the EL2 translation regime. This is a Non-secure address space.
- `N:` This corresponds to the Non-secure EL1 and Non-secure EL0 translation regimes.
- `SP:` This corresponds to Secure World physical memory.
- `NP:` This corresponds to Non-secure World physical memory.

The following address space prefixes might be available for Armv8-based processors when in the AArch64 execution state:

- `EL3:` This corresponds to the EL3 translation regime. This is a secure address space.
- `EL2S:` This corresponds to the Secure EL2 translation regime.
- `EL2N:` This corresponds to the Non-secure EL2 translation regime.
- `EL1S:` This corresponds to the Secure EL1 and Secure EL0 translation regimes.
- `EL1N:` This corresponds to the Non-secure EL1 and Non-secure EL0 translation regimes.
- `SP:` This corresponds to Secure World physical memory.
- `NP:` This corresponds to Non-secure World physical memory.

parameter

Optional. The parameter you want to specify.

When you are using an address space as part of an expression, you can use memory parameters to specify additional behavior. Use the *info memory-parameters* on page 1-89 command to see the available parameters.

value

The value that you want to set for the parameter.

address

There address where you want to apply the operation.

Example: break command with address space prefix for Armv7

This example sets an execution breakpoint in the main function in the secure address space.

```
break S:main
```

Example: add-symbol-file command with address space prefix for Armv8

This example loads additional debug information into the secure physical address space.

```
add-symbol-file foo.axf SP:0
```

Example: x command with address space prefix for Armv8

This example displays the content of the memory at address `0x80000000` in the secure EL1 and EL0 translation regimes.

```
x EL1S:0x80000000
```

Example: Address space parameters with the set command

```
set*((int*)SP<verify=0>:0x8000)=0x1234
```

This command writes an integer, `0x1234`, to the secure physical address, `0x8000`, but does not verify the write.

Related references

1.3.61 info memory-parameters on page 1-89

1.3.6 break on page 1-58

1.3.1 add-symbol-file on page 1-51

1.3.216 x on page 1-178

1.2.19 Set on page 1-39

Related information

About address spaces

Related references

1.1.1 Syntax of Arm Debugger commands on page 1-9

1.1.2 Usage of special characters and environment variables in paths within Arm Development Studio on page 1-10

1.1.3 Expressions within Arm Development Studio on page 1-10

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1.1.7 Usage of the scoping resolution operator on page 1-14

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.1.9 Address space prefixes on page 1-17

1.2 Arm Debugger commands listed in groups

Displays all the commands in functional groups according to specific tasks.

This section contains the following subsections:

1.2.1 Breakpoints and watchpoints

List of all the Arm Debugger commands that enable you to control the starting and stopping of the debugger using breakpoints and watchpoints.

awatch

Sets a watchpoint for a data symbol. The debugger stops the target when the memory at the specified address is read or written.

break

Sets an execution breakpoint at a specific location.

break-script

Assigns a script file to a specific breakpoint. The script executes when the breakpoint is triggered.

break-set-property

Updates the properties of an existing breakpoint.

break-stop-on-threads, break-stop-on-cores

Applies an existing breakpoint to one or more threads or processors.

break-stop-on-vmid

Applies an existing hardware breakpoint to a Virtual Machine (VM).

clear

Deletes a breakpoint at a specific location.

clearwatch

Deletes a watchpoint at a specific location.

condition

Sets a stop condition for a specific breakpoint or watchpoint.

delete breakpoints

Deletes one or more breakpoints or watchpoints.

disable breakpoints

Disables one or more breakpoints or watchpoints.

enable breakpoints

Enables one or more breakpoints or watchpoints by number.

hbreak

Sets a hardware execution breakpoint at a specific location.

ignore

Sets the ignore counter for a breakpoint or watchpoint condition.

info breakpoints, info watchpoints

Displays information about the status of all breakpoints and watchpoints.

info breakpoints capabilities, info watchpoints capabilities

Displays a list of parameters that you can use with breakpoint and watchpoint commands for the current connection.

resolve

Re-evaluates the specified breakpoints or watchpoints and those with addresses that can be resolved are set.

rwatch

Sets a watchpoint for a data symbol. The debugger stops the target when the memory at the specified address is read.

set breakpoint

Controls the automatic behavior of breakpoints and watchpoints.

silence

Disables the printing of stop messages for a specific breakpoint.

tbreak

Sets an execution breakpoint at a specific location and deletes the breakpoint when it is hit.

thbreak

Sets a hardware execution breakpoint at a specific location and deletes the breakpoint when it is hit.

unsilence

Enables the printing of stop messages for a specific breakpoint.

watch

Sets a watchpoint for a data symbol. The debugger stops the target when the memory at the specified address is written.

watch-set-property

Updates the properties of an existing watchpoint.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.6 break on page 1-58
1.3.41 hbreak on page 1-78
1.3.193 tbreak on page 1-159
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1.3.212 watch on page 1-175
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1.2.2 Execution control

List of all the Arm Debugger commands that enable you to control the starting and stopping of the debugger.

advance

Sets a temporary breakpoint at the specified address and calls the debugger `continue` command. Use the `advance` command to halt execution at a particular point in your code, for example a specific function, source code line number, or instruction memory address.

continue

Continues running the target.

finish

Continues running the device to the next instruction after the selected stack frame finishes.

handle

Controls the handler settings for one or more signals or exceptions.

info signals, info handle

Displays information about the handling of signals or processor exceptions.

interrupt, stop

Interrupts the target and stops the application if it is running.

next

Steps through an application at the source level stopping at the first instruction of each source line but stepping over all function calls.

nexti

Steps through an application at the instruction level but stepping over all function calls.

nexts

Steps through an application at the source level stopping at the first instruction of each source statement but stepping over all function calls.

reset

Performs a reset on the target.

run

Starts running the target.

set blocking-run-control

Controls whether run control operations such as stepping and running are blocked until the target stops or released immediately.

set debug-from

Specifies the address of the temporary breakpoint for subsequent use by the `start` command.

set step-mode

Controls the default behavior of the `step` and `steps` commands.

show blocking-run-control

Displays the setting for blocking run control operations such as stepping and running.

show debug-from

Displays the setting for the expression that is used by the `start` command to set a temporary breakpoint.

show step-mode

Displays the step setting for functions without debug information.

start

Sets a temporary breakpoint, calls the debugger `run` command, and then deletes the temporary breakpoint when it is hit. By default, the temporary breakpoint is set at the address of the global function `main()`.

step

Steps through an application at the source level stopping on the first instruction of each source line including stepping into all function calls.

stepi

Steps through an application at the instruction level including stepping into all function calls.

steps

Steps through an application at the source level stopping on the first instruction of each source statement (for example, statements in a `for()` loop) including stepping into all function calls.

thread, core

Displays information about the current thread or processor.

thread apply, core apply

Switches control to a specific thread or processor to execute a debugger command and then switches back to the original state.

wait

Instructs the debugger to wait until the target stops.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.188 start on page 1-156
1.3.119 set blocking-run-control on page 1-123
1.3.156 show blocking-run-control on page 1-144
1.3.124 set debug-from on page 1-126
1.3.161 show debug-from on page 1-146
1.3.18 continue on page 1-65
1.3.2 advance on page 1-52
1.3.80 interrupt, stop on page 1-97
1.3.211 wait on page 1-175
1.3.110 reset on page 1-116
1.3.190 step on page 1-157
1.3.191 stepi on page 1-158
1.3.192 steps on page 1-159
1.3.99 next on page 1-110
1.3.100 nexti on page 1-111
1.3.101 nexts on page 1-111
1.3.195 thread, core on page 1-162
1.3.196 thread apply, core apply on page 1-163
1.3.142 set step-mode on page 1-139
1.3.179 show step-mode on page 1-153
1.3.71 info signals on page 1-94
1.3.56 info handle on page 1-86
1.3.40 handle on page 1-77

1.2.3 Tracing

List of all the Arm Debugger commands that can be used to capture trace.

trace start

Starts the trace capture on the specified trace capture device.

trace stop

Stops the trace capture on the specified trace capture device.

trace clear

Clears the trace on the specified trace capture device.

trace list

Lists the trace capture devices and trace sources.

trace info

Displays details about trace capture devices and trace sources.

trace dump

Dumps raw trace data to a directory, along with target trace configuration metadata, from a trace capture device or a trace source.

trace report

Produces a trace report, containing the decoded trace data, for the currently selected core.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.197 trace clear on page 1-164
1.3.198 trace dump on page 1-164
1.3.199 trace info on page 1-165
1.3.200 trace list on page 1-166
1.3.201 trace report on page 1-166
1.3.202 trace start on page 1-169
1.3.203 trace stop on page 1-170

1.2.4 Scripts

List of all the Arm Debugger commands that can be used to control the debugger using script files.

define

Enables you to derive new user-defined commands from existing commands.

document

Enables you to add integrated help for a new user-defined command.

newvar

Declares and initializes a new debugger convenience variable.

end

Enables you to terminate conditional blocks when using the define, if, and while commands.

if

Enables you to write scripts that conditionally execute debugger commands.

source

Loads and runs a script file to control and debug your target.

while

Enables you to write scripts with conditional loops that execute debugger commands.

usecase help

Displays help for a use case script.

usecase list

Lists use case scripts.

usecase run

Runs a use case script.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.19 define on page 1-65
1.3.27 document on page 1-70
1.3.34 end on page 1-73
1.3.43 if on page 1-81
1.3.215 while on page 1-177
1.3.187 source on page 1-155
1.3.98 newvar on page 1-110
1.3.208 usecase help on page 1-172
1.3.209 usecase list on page 1-173
1.3.210 usecase run on page 1-174

1.2.5 Call stack

List of all the Arm Debugger commands that display information about the call stack and others that control the current position in the call stack.

down

Moves and displays the current frame pointer down the call stack towards the bottom frame.

down-silently

Moves the current frame pointer down the call stack towards the bottom frame.

frame

Sets the current frame pointer in the call stack and also displays the function name and source line number for the specified frame.

info frame

Displays stack frame information at the selected position.

info stack, backtrace, where

Displays a numbered list of the calling stack frames including the function names and source line numbers.

select-frame

Moves the current frame pointer in the callstack.

set backtrace

Controls the default behavior when using the info `info stack` command.

show backtrace

Displays the behavior settings for use with the `info stack` command.

up

Moves and displays the current frame pointer up the call stack towards the top frame.

up-silently

Moves the current frame pointer up the call stack towards the top frame.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.118 set backtrace on page 1-122
1.3.73 info stack, backtrace, where on page 1-94
1.3.155 show backtrace on page 1-144
1.3.39 frame on page 1-77
1.3.54 info frame on page 1-86
1.3.28 down on page 1-70
1.3.29 down-silently on page 1-70
1.3.206 up on page 1-171
1.3.207 up-silently on page 1-172
1.3.115 select-frame on page 1-120

1.2.6 Operating System (OS)

List of all the Arm Debugger commands that enable you to debug applications running on a target with an operating system.

sharedlibrary

Loads symbols from shared libraries.

nosharedlibrary

Discards all loaded shared library symbols.

info os

Displays the current state of the Operating System (OS) support. If OS support is enabled, also lists all available OS data tables.

info os-log

Displays the contents of the Operating System (OS) log buffer for connections that support this feature.

info os-modules

Displays a list of loadable kernel modules for connections that support this feature.

info os-version

Displays the version of the Operating System (OS)for connections that support this feature.

info processes

Displays information about the user space processes.

info sharedlibrary

Displays the names of the loaded shared libraries, the base address, and whether the debug symbols of the shared libraries are loaded or not.

info threads

Displays information about the available threads.

set auto-solib-add

Controls the automatic loading of shared library symbols.

set os

Controls Operating System (OS) settings in the debugger. An OS-aware connection must be established before you can use this command.

set solib-search-path

Specifies additional directories to search for shared library symbols.

set stop-on-solib-events

Controls whether the debugger stops execution when a shared object is loaded or unloaded.

set sysroot, set solib-absolute-prefix

Specifies the system root directory to search for shared library symbols.

show auto-solib-add

Displays the automatic setting for use when loading shared library symbols.

show os

Displays the Operating System (OS) control settings.

show solib-search path

Displays the search paths in use by the debugger when searching for shared libraries.

show stop-on-solib-events

Displays the debugger setting that controls whether execution stops when shared library events occur.

show sysroot, show solib-absolute-prefix

Displays the system root directory in use by the debugger when searching for shared library symbols.

thread apply, core apply

Switches control to a specific thread or processor to execute a debugger command and then switches back to the original state.

thread, core

Displays information about the current thread or processor.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.149 sharedlibrary on page 1-142
1.3.102 nosharedlibrary on page 1-112
1.3.70 info sharedlibrary on page 1-93
1.3.136 set os on page 1-132
1.3.174 show os on page 1-150
1.3.145 set sysroot on page 1-140
1.3.140 set solib-absolute-prefix on page 1-137
1.3.182 show sysroot on page 1-154
1.3.177 show solib-absolute-prefix on page 1-152
1.3.117 set auto-solib-add on page 1-122
1.3.154 show auto-solib-add on page 1-144
1.3.141 set solib-search-path on page 1-138
1.3.178 show solib-search-path on page 1-152
1.3.195 thread, core on page 1-162
1.3.143 set stop-on-solib-events on page 1-139
1.3.180 show stop-on-solib-events on page 1-153
1.3.196 thread apply, core apply on page 1-163
1.3.76 info threads on page 1-95

1.3.67 info processes on page 1-91
1.3.62 info os on page 1-89
1.3.63 info os-log on page 1-90
1.3.64 info os-modules on page 1-90
1.3.65 info os-version on page 1-91

1.2.7 Files

List of Arm Debugger commands that enable you to control the loading and unloading of executable images on to a target and debug information into the debugger.

add-symbol-file

Loads additional debug information into the debugger.

append

Reads data from memory or the result of an expression and appends it to an existing file.

cd

Changes the current working directory.

directory

Defines additional directories to search for source files.

discard-symbol-file

Discards debug information relating to a specific file.

dump

Reads data from memory or the result of an expression and writes it to a file.

file, symbol-file

Loads debug information from an image into the debugger and records the entry point address for future use by the `run` and `start` commands.

info files, info target

Displays information about the loaded image and symbols.

info sources

Displays the names of the source files used in the current image being debugged.

load

Loads an image on to the target and records the entry point address for future use by the `run` and `start` commands.

loadfile

Loads debug information into the debugger, an image on to the target and records the entry point address for future use by the `run` and `start` commands.

pwd

Displays the current working directory.

reload-symbol-file

Reloads debug information from an already loaded image into the debugger using the same settings as the original load operation.

restore

Reads data from a file and writes it to memory.

set substitute-path

Modifies the search paths used by the debugger when it executes any of the commands that look up and display source code.

show directories

Displays the list of directories to search for source files.

show substitute-path

Displays the search path substitution rules in use by the debugger when searching for source files.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.82 load on page 1-98
1.3.83 loadfile on page 1-99
1.3.35 file, symbol-file on page 1-74
1.3.109 reload-symbol-file on page 1-116
1.3.1 add-symbol-file on page 1-51
1.3.3 append on page 1-54
1.3.112 restore on page 1-118
1.3.72 info sources on page 1-94
1.3.14 cd on page 1-63
1.3.107 pwd on page 1-115
1.3.22 directory, set directories on page 1-67
1.3.162 show directories on page 1-146
1.3.144 set substitute-path on page 1-140
1.3.181 show substitute-path on page 1-153

1.2.8 Data

List of all the Arm Debugger commands that enables you to display source code, expressions, variables, functions, classes, memory, and other data.

disassemble

Displays the disassembly for the function surrounding a specific address or the disassembly for a specific address range.

info address

Displays the location of a symbol.

info classes

Displays C++ class names.

info functions

Displays the name and data types for all functions.

info locals

Displays all local variables for the current stack frame.

info members

Displays the name and data types for all class member variables that are accessible in the function corresponding to the selected stack frame.

info symbol

Displays the symbol name at a specific address.

info variables

Displays the name and data types for all global and static variables.

list

Displays lines of source code surrounding the current or specified location.

set listsize

Modifies the default number of source lines that the `list` command displays.

set variable

Evaluates an expression and assigns the result to a variable, register or memory.

show listsize

Displays the number of source lines that the `list` command displays.

whatis

Displays the data type of an expression.

x

Displays the content of memory at a specific address.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.25 disassemble on page 1-69
1.3.147 set variable on page 1-141
1.3.214 whatis on page 1-177
1.3.216 x on page 1-178
1.3.45 info on page 1-82
1.3.50 info classes on page 1-84
1.3.55 info functions on page 1-86
1.3.58 info locals on page 1-87
1.3.59 info members on page 1-87
1.3.71 info signals on page 1-94
1.3.56 info handle on page 1-86
1.3.74 info symbol on page 1-95
1.3.77 info variables on page 1-96
1.3.81 list on page 1-97
1.3.134 set listsize on page 1-132
1.3.172 show listsize on page 1-149

1.2.9 Memory group

List of all the Arm Debugger commands that controls memory accesses and displays information about specific memory regions.

append

Reads data from memory or the result of an expression and appends it to an existing file.

assemble

Writes assembler instructions to memory.

delete memory

Deletes one or more user-defined memory regions.

disable memory

Disables one or more user-defined memory regions.

disassemble

Displays the disassembly for the function surrounding a specific address or the disassembly for a specific address range.

dump

Reads data from memory or the result of an expression and writes it to a file.

enable memory

Enables one or more user-defined memory regions.

info memory

Displays the currently defined memory regions.

info mem-params

Displays the memory parameters applicable to an address space.

memory

Defines a memory region and specifies its attributes and size.

memory auto

Resets the memory regions to the default target settings and discards all user-defined regions.

memory debug-cache

Controls the caching by the debugger for all memory regions.

memory fill

Writes a specific pattern of bytes to memory.

memory set

Writes to memory.

memory set_typed

Writes a list of values to memory.

restore

Reads data from a file and writes it to memory.

x

Displays the content of memory at a specific address.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.86 memory on page 1-100
1.3.3 append on page 1-54
1.3.4 assemble on page 1-55
1.3.21 delete memory on page 1-67
1.3.33 enable memory on page 1-73
1.3.24 disable memory on page 1-68

1.3.60 info memory on page 1-88
1.3.61 info memory-parameters on page 1-89
1.3.87 memory auto on page 1-102
1.3.30 dump on page 1-71
1.3.89 memory fill on page 1-103
1.3.90 memory set on page 1-104
1.3.25 disassemble on page 1-69
1.3.91 memory set_typed on page 1-106
1.3.88 memory debug-cache on page 1-103
1.3.112 restore on page 1-118
1.3.216 x on page 1-178

1.2.10 Cache

List of all the Arm Debugger commands that provide information on the available caches.

cache flush

Flushes the caches of the current CPU.

cache list

Lists the caches and related information available for the current core. The output is implementation defined.

cache print

Provides a structured view of the cache data in the current core. The output is implementation defined.

Enter `help` followed by a command name for more information on a specific command.

Related references
1.3.12 cache list on page 1-62
1.3.13 cache print on page 1-62
1.3.11 cache flush on page 1-62

1.2.11 Registers

List of all the Arm Debugger commands that provide register information.

info all-registers

Displays the name and content of grouped registers for the current stack frame.

info registers

Displays the name and content of all application level registers for the current stack frame.

Enter `help` followed by a command name for more information on a specific command.

Related references
1.3.46 info all-registers on page 1-82
1.3.68 info registers on page 1-91

1.2.12 mmu

List of all the Arm Debugger commands that provide information on the Memory Management Unit.

mmu list tables

Lists the available translation tables and their associated parameters.

mmu list translations

Lists the available translations and their associated parameters.

mmu list memory-maps

Lists the available memory maps and their associated parameters.

mmu print

Prints the contents of a translation table.

mmu translate

Performs translations between virtual and physical addresses.

mmu memory-map

Prints the memory map.

set mmu use-cache-for-phys-reads

Instructs the debugger to, where possible, ensure that the translation table entries it reads from physical memory are coherent with the contents of data caches.

show mmu use-cache-for-phys-reads

Displays the MMU setting that controls the coherency between translation table memory reads and cache data.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.92 mmu list memory-maps, mpu list memory-maps on page 1-106
1.3.93 mmu list tables, mpu list tables on page 1-107
1.3.94 mmu list translations on page 1-107
1.3.97 mmu translate on page 1-109
1.3.95 mmu memory-map, mpu memory-map on page 1-107
1.3.96 mmu print, mpu print on page 1-108
1.3.135 set mmu use-cache-for-phys-reads on page 1-132
1.3.173 show mmu use-cache-for-phys-reads on page 1-149

1.2.13 MMU list

`mmu list` commands in Arm Debugger.

mmu list tables

Lists the available translation tables and their associated parameters.

mmu list translations

Lists the available translations and their associated parameters.

mmu list memory-maps

Lists the available memory maps and their associated parameters.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.92 mmu list memory-maps, mpu list memory-maps on page 1-106
1.3.93 mmu list tables, mpu list tables on page 1-107
1.3.94 mmu list translations on page 1-107

1.2.14 mpu

List of all the Arm Debugger commands that provide information on the Memory Protection Unit.

mpu list tables

Lists the available translation tables and their associated parameters.

mpu list memory-maps

Lists the available memory maps and their associated parameters.

mpu print

Prints the contents of a translation table.

mpu memory-map

Prints the memory map.

set idau-region

Specifies the Implementation Defined Attribution Unit (IDAU) region parameters for each memory range.

show idau-region

Displays the currently specified Implementation Defined Attribution Unit (IDAU) region parameters.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.92 mmu list memory-maps, mpu list memory-maps on page 1-106

1.3.93 mmu list tables, mpu list tables on page 1-107

1.3.95 mmu memory-map, mpu memory-map on page 1-107

1.3.96 mmu print, mpu print on page 1-108

1.2.15 mpu list

`mpu list` commands in Arm Debugger.

mpu list tables

Lists the available translation tables and their associated parameters.

mpu list memory-maps

Lists the available memory maps and their associated parameters.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.92 mmu list memory-maps, mpu list memory-maps on page 1-106

1.3.93 mmu list tables, mpu list tables on page 1-107

1.2.16 Display

List of all the Arm Debugger commands that enable you to display specific output on the command-line.

echo

Displays only textual strings.

output

Displays only the result of an expression.

print, inspect

Displays the output of an expression (128 character limit) and also records the result in a new debugger variable, `$<n>`, where `<n>` is a number.

set print

Controls the current debugger print settings.

show print

Displays the debugger print settings.

x

Displays the content of memory at a specific address.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.31 echo on page 1-72
1.3.103 output on page 1-112
1.3.106 print, inspect on page 1-114
1.3.138 set print on page 1-134
1.3.175 show print on page 1-150
1.3.216 x on page 1-178

1.2.17 Information

List of all the Arm Debugger commands that enables you to display information about breakpoints, watchpoints, running processors, variables, functions, classes, registers, memory regions, stack frames, and other data.

info address

Displays the location of a symbol.

info all-registers

Displays the name and content of grouped registers for the current stack frame.

info breakpoints, info watchpoints

Displays information about the status of all breakpoints and watchpoints.

info breakpoints capabilities, info watchpoints capabilities

Displays a list of parameters that you can use with breakpoint and watchpoint commands for the current connection.

info capabilities

Displays a list of capabilities for the target device that is currently connected to the debugger.

info classes

Displays C++ class names.

info cores

Displays information about the running processors.

info files, info target

Displays information about the loaded image and symbols.

info flash

Displays information about the flash devices on the current target.

info frame

Displays stack frame information at the selected position.

info functions

Displays the name and data types for all functions.

info inst-sets

Displays the available instruction sets.

info locals

Displays all local variables for the current stack frame.

info members

Displays the name and data types for all class member variables that are accessible in the function corresponding to the selected stack frame.

info memory

Displays the currently defined memory regions.

info mem-params

Displays the memory parameters applicable to an address space.

info os

Displays the current state of the Operating System (OS) support. If OS support is enabled, also lists all available OS data tables.

info os-log

Displays the contents of the Operating System (OS) log buffer for connections that support this feature.

info os-modules

Displays a list of loadable kernel modules for connections that support this feature.

info os-version

Displays the version of the Operating System (OS)for connections that support this feature.

info overlays

Displays information about the currently loaded overlays.

info processes

Displays information about the user space processes.

info registers

Displays the name and content of all application level registers for the current stack frame.

info semihosting

Displays semihosting information.

info sharedlibrary

Displays the names of the loaded shared libraries, the base address, and whether the debug symbols of the shared libraries are loaded or not.

info signals, info handle

Displays information about the handling of signals or processor exceptions.

info sources

Displays the names of the source files used in the current image being debugged.

info stack, backtrace, where

Displays a numbered list of the calling stack frames including the function names and source line numbers.

info symbol

Displays the symbol name at a specific address.

info threads

Displays information about the available threads.

info variables

Displays the name and data types for all global and static variables.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.46 info all-registers on page 1-82
1.3.47 info breakpoints on page 1-83
1.3.78 info watchpoints on page 1-96
1.3.62 info os on page 1-89
1.3.63 info os-log on page 1-90
1.3.64 info os-modules on page 1-90
1.3.65 info os-version on page 1-91
1.3.67 info processes on page 1-91
1.3.68 info registers on page 1-91
1.3.69 info semihosting on page 1-92
1.3.70 info sharedlibrary on page 1-93
1.3.71 info signals on page 1-94
1.3.56 info handle on page 1-86
1.3.72 info sources on page 1-94
1.3.73 info stack, backtrace, where on page 1-94
1.3.74 info symbol on page 1-95
1.3.76 info threads on page 1-95
1.3.77 info variables on page 1-96
1.3.57 info inst-sets on page 1-87
1.3.49 info capabilities on page 1-84
1.3.50 info classes on page 1-84
1.3.51 info cores on page 1-85
1.3.58 info locals on page 1-87
1.3.59 info members on page 1-87
1.3.60 info memory on page 1-88
1.3.61 info memory-parameters on page 1-89
1.3.52 info files on page 1-85
1.3.75 info target on page 1-95

1.2.18 log

List of all the Arm Debugger commands that enable you to control runtime messages from the debugger.

log config

Specifies the type of logging configuration to output runtime messages from the debugger.

log file

Specifies an output file to receive runtime messages from the debugger.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.84 log config on page 1-99

1.3.85 log file on page 1-100

1.2.19 Set

List of all the Arm Debugger commands that enable you to control the default debugger settings.

set

`set` is an alias for `set variable`.

set arm

Controls the behavior of the debugger when selecting the instruction set for disassembly and setting breakpoints.

set auto-solib-add

Controls the automatic loading of shared library symbols.

set backtrace

Displays the behavior settings for use with the `info stack` command.

set blocking-run-control

Controls whether run control operations such as stepping and running are blocked until the target stops or released immediately.

set breakpoint

Controls the automatic behavior of breakpoints and watchpoints.

set case-insensitive-source-matching

Controls the case sensitivity of debugger file matching operations.

set cde-coprocessors

Specify the coprocessors that are associated with the Arm Custom Datapath Extension (CDE).

set debug-agent

Sets an internal configuration parameter for the debug agent.

set debug-from

Specifies the address of the temporary breakpoint for subsequent use by the `start` command.

set directories

Defines additional directories to search for source files.

set dtsl-options

Sets a parameter in the DTSL configuration.

set dtsl-temporary-directory

Specifies the path for the temporary directory to store trace data.

set elf cache-uninitialized-sections

Controls whether the debugger caches uninitialized sections.

set elf load-segments-at-p_paddr

Enables loading to the specified load offset + `p_paddr` when loading segments of ELF images to the target.

set elf zero-extra-segment-bytes

Enables zeroing of bytes from `p_filesz` to `p_memsz` when loading segments of ELF images to the target.

set endian

Specifies the byte order for use by the debugger.

set escape-strings

Controls how special characters in strings are printed on the debugger command-line.

set escapes-in-filenames

Controls the use of special characters in paths.

set idau-region

Specifies the Implementation Defined Attribution Unit (IDAU) region parameters for each memory range.

set listsize

Modifies the default number of source lines that the `list` command displays.

set mmu use-cache-for-phys-reads

Instructs the debugger to, where possible, ensure that the translation table entries it reads from physical memory are coherent with the contents of data caches.

set os

Controls operating system (OS) settings in the debugger. An OS-aware connection must be established before you can use this command.

set overlays enabled

Enables or disables overlay support.

set print

Controls the current debugger print settings.

set semihosting

Controls the semihosting settings in the debugger.

set solib-search-path

Specifies additional directories to search for shared library symbols.

set step-mode

Controls the default behavior of the `step` and `steps` commands.

set stop-on-solib-events

Controls whether the debugger stops execution when a shared object is loaded or unloaded.

set substitute-path

Modifies the search paths used by the debugger when it executes any of the commands that look up and display source code.

set sysroot, set solib-absolute-prefix

Specifies the system root directory to search for shared library symbols.

set trust-ro-sections-for-opcodes

Controls whether the debugger can read opcodes from read-only sections of images on the host workstation rather than from the target itself.

set variable

Evaluates an expression and assigns the result to a variable, register, or memory.

set wildcard-style

Specifies the type of wildcard pattern matching you can use for examining the contents of strings.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.147 set variable on page 1-141
1.3.116 set arm on page 1-121
1.3.117 set auto-solib-add on page 1-122
1.3.118 set backtrace on page 1-122
1.3.119 set blocking-run-control on page 1-123
1.3.120 set breakpoint on page 1-123
1.3.121 set case-insensitive-source-matching on page 1-124
1.3.122 set cde-coprocessors on page 1-125
1.3.123 set debug-agent on page 1-126
1.3.124 set debug-from on page 1-126
1.3.22 directory, set directories on page 1-67
1.3.125 set dtsl-options on page 1-127
1.3.126 set dtsl-temporary-directory on page 1-127
1.3.127 set elf cache-uninitialized-sections on page 1-128
1.3.128 set elf load-segments-at-p_paddr on page 1-128
1.3.129 set elf zero-extra-segment-bytes on page 1-129
1.3.130 set endian on page 1-129
1.3.131 set escape-strings on page 1-130
1.3.132 set escapes-in-filenames on page 1-130
1.3.134 set listsize on page 1-132
1.3.136 set os on page 1-132
1.3.138 set print on page 1-134
1.3.139 set semihosting on page 1-135
1.3.145 set sysroot on page 1-140
1.3.140 set solib-absolute-prefix on page 1-137
1.3.141 set solib-search-path on page 1-138
1.3.142 set step-mode on page 1-139
1.3.143 set stop-on-solib-events on page 1-139
1.3.144 set substitute-path on page 1-140
1.3.146 set trust-ro-sections-for-opcodes on page 1-140
1.3.148 set wildcard-style on page 1-141
1.3.135 set mmu use-cache-for-phys-reads on page 1-132

1.2.20 set elf

`set elf` commands in Arm Debugger.

set elf cache-uninitialized-sections

Controls whether the debugger caches uninitialized sections.

set elf load-segments-at-p_paddr

Enables loading to the specified load offset + `p_paddr` when loading segments of ELF images to the target.

set elf zero-extra-segment-bytes

Enables zeroing of bytes from `p_filesz` to `p_memsz` when loading segments of ELF images to the target.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.127 set elf cache-uninitialized-sections on page 1-128
1.3.128 set elf load-segments-at-p_paddr on page 1-128
1.3.129 set elf zero-extra-segment-bytes on page 1-129

1.2.21 show group

List of all the Arm Debugger commands that enable you to view the default debugger settings.

show

Displays the debugger settings.

show architecture

Displays the architecture of the target.

show arm

Displays the instruction set settings in use by the debugger for disassembly and setting breakpoints.

show auto-solib-add

Displays the automatic setting for use when loading shared library symbols.

show backtrace

Displays the behavior settings for use with the `info stack` command.

show blocking-run-control

Displays the setting for blocking run control operations such as stepping and running.

show breakpoint

Displays the breakpoint and watchpoint behavior settings.

show case-insensitive-source-matching

Displays the case sensitivity setting for the debugger file matching operations.

show cde-coprocessors

Displays the encoding associated with each coprocessor.

show debug-agent

Displays the value of an internal configuration parameter for the debug agent.

show debug-from

Displays the setting for the expression that is used by the `start` command to set a temporary breakpoint.

show directories

Displays the list of directories to search for source files.

show dtsl-options

Displays the value of a parameter in the DTSL configuration.

show dtsl-temporary-directory

Displays the current path for the temporary directory which stores trace data.

show elfcache-uninitialized-sections

Displays the debugger setting that controls whether uninitialized sections are cached.

show elf load-segments-at-p_paddr

Displays the debugger setting that controls the location for loading segments of ELF images.

show elf zero-extra-segment-bytes

Displays the debugger setting that controls zeroing of bytes when loading segments of ELF images to the target.

show endian

Displays the byte order setting in use by the debugger.

show escape-strings

Displays the setting for controlling how special characters in strings are printed on the debugger command line.

show escapes-in-filenames

Displays the setting for controlling the use of special characters in paths.

show listsize

Displays the number of source lines that the `list` command displays.

show idau-region

Displays the currently specified Implementation Defined Attribution Unit (IDAU) region parameters.

show mmu use-cache-for-phys-reads

Displays the MMU setting that controls the coherency between translation table memory reads and cache data.

show os

Displays the Operating System (OS) control settings.

show print

Displays the debugger print settings.

show semihosting

Displays the semihosting settings in the debugger.

show solib-search-path

Displays the search paths in use by the debugger when searching for shared libraries.

show step-mode

Displays the step setting for functions without debug information.

show stop-on-solib-events

Displays the debugger setting that controls whether execution stops when shared library events occur.

show substitute-path

Displays the search path substitution rules in use by the debugger when searching for source files.

show sysroot, show solib-absolute-prefix

Displays the system root directory in use by the debugger when searching for shared library symbols.

show trust-ro-sections-for-opcodes

Displays the debugger setting that controls whether the debugger can read opcodes from read-only sections of images on the host workstation rather than from the target itself.

show version

Displays the version number of the debugger.

show wildcard-style

Displays the wildcard style for pattern matching.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.151 show on page 1-143
1.3.152 show architecture on page 1-143
1.3.153 show arm on page 1-143
1.3.154 show auto-solib-add on page 1-144
1.3.155 show backtrace on page 1-144
1.3.156 show blocking-run-control on page 1-144
1.3.157 show breakpoint on page 1-145
1.3.158 show case-insensitive-source-matching on page 1-145
1.3.160 show debug-agent on page 1-146
1.3.161 show debug-from on page 1-146
1.3.162 show directories on page 1-146
1.3.163 show dtsl-options on page 1-147
1.3.164 show dtsl-temporary-directory on page 1-147
1.3.165 show elf cache-uninitialized-sections on page 1-147
1.3.166 show elf load-segments-at-p_paddr on page 1-147
1.3.167 show elf zero-extra-segment-bytes on page 1-148
1.3.168 show endian on page 1-148
1.3.169 show escape-strings on page 1-148
1.3.170 show escapes-in-filenames on page 1-149
1.3.172 show listsize on page 1-149
1.3.174 show os on page 1-150
1.3.175 show print on page 1-150
1.3.176 show semihosting on page 1-151
1.3.178 show solib-search-path on page 1-152

1.3.179 show step-mode on page 1-153
1.3.180 show stop-on-solib-events on page 1-153
1.3.181 show substitute-path on page 1-153
1.3.182 show sysroot on page 1-154
1.3.177 show solib-absolute-prefix on page 1-152
1.3.183 show trust-ro-sections-for-opcodes on page 1-154
1.3.184 show version on page 1-154
1.3.185 show wildcard-style on page 1-155
1.3.173 show mmu use-cache-for-phys-reads on page 1-149

1.2.22 show elf

`show elf` commands in Arm Debugger.

`show elf cache-uninitialized-sections`

Displays the debugger setting that controls whether uninitialized sections are cached.

`show elf load-segments-at-p_paddr`

Displays the debugger setting that controls the location for loading segments of ELF images.

`show elf zero-extra-segment-bytes`

Displays the debugger setting that controls zeroing of bytes when loading segments of ELF images to the target.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.165 show elf cache-uninitialized-sections on page 1-147
1.3.166 show elf load-segments-at-p_paddr on page 1-147
1.3.167 show elf zero-extra-segment-bytes on page 1-148

1.2.23 flash

List of all the Arm Debugger commands that controls flash accesses and displays information about specific flash devices.

flash load

Loads sections from an image into one or more flash devices.

flash load-multiple

Simultaneously load multiple flash image sections from multiple images, to one or more flash devices.

info flash

Displays information about the flash devices on the current target.

Enter `help` followed by a command name for more information on a specific command.

——— **Note** ———

To use this command you must check that flash device support is available for your target. If it is not available, you must write your own flash algorithm for this command to work. For details on how to do this, see the *Flash programming chapter* in the *Arm Development Studio User Guide*. To see an example of what Arm Debugger expects, see the following file in your Arm Development Studio installation folder:

`<installation_directory>/examples/Bare-metal_examples_Armv7.zip/flash_algo-STM32F10x`.

———————————

Related references

1.3.53 info flash on page 1-85

1.3.37 flash load on page 1-75

1.3.38 flash load-multiple on page 1-76

1.2.24 Support

List of all the miscellaneous Arm Debugger commands.

define

Enables you to derive new user-defined commands from existing commands.

help

Displays help information for a specific command or a group of commands listed according to specific debugging tasks.

info capabilities

Displays a list of capabilities for the target device that is currently connected to the debugger.

info inst-sets

Displays the available instruction sets.

pause

Pauses the execution of a script for a specified period of time.

preprocess

Displays the preprocessed expression, not the evaluated expression.

quit, exit

Quits the debugger session.

set arm

Controls the behavior of the debugger when selecting the instruction set for disassembly and setting breakpoints.

set endian

Specifies the byte order for use by the debugger.

set semihosting

Controls the semihosting settings in the debugger.

shell

Runs a shell command within the debug session.

show architecture

Displays the architecture of the target.

show arm

Displays the instruction set settings in use by the debugger for disassembly and setting breakpoints.

show semihosting

Displays the semihosting settings in the debugger.

show version

Displays the version number of the debugger.

show endian

Displays the byte order setting in use by the debugger.

stdin

Specifies semihosting input requested by application code.

unset

Modifies the current debugger settings.

Enter `help` followed by a command name for more information on a specific command.

Related references

1.3.105 preprocess on page 1-114
1.3.104 pause on page 1-113
1.3.150 shell on page 1-142
1.3.108 quit, exit on page 1-116
1.3.184 show version on page 1-154
1.3.152 show architecture on page 1-143
1.3.116 set arm on page 1-121
1.3.153 show arm on page 1-143
1.3.130 set endian on page 1-129
1.3.168 show endian on page 1-148
1.3.139 set semihosting on page 1-135
1.3.176 show semihosting on page 1-151
1.3.189 stdin on page 1-157
1.3.204 unset on page 1-170

1.3 Arm Debugger commands listed in alphabetical order

Displays all the commands in alphabetical order.

This section contains the following subsections:

1.3.1 add-symbol-file

Loads additional debug information into the debugger.

Syntax

```
add-symbol-file <filename> [<offset>] [-s <section> <address>]...
```

Where:

<filename>

Specifies the image, shared library, or Operating System (OS) module.

Note

Shared library and OS modules depend on connections that support loading these types of files. This option pends the file until the library or OS module is loaded.

<offset>

Specifies the offset that is added to all addresses within the image. If `<offset>` is not specified then the default for:

- An image is zero.
- A shared library is the load address of the library. If the application has not currently loaded the specified library then the request is pended until the library is loaded and the offset can be determined.

s

For relocatable objects, this specifies the address to which a section was relocated.

<section>

Specifies the name of the relocated section.

<address>

Specifies the address of the section. This can be either an address or an expression that evaluates to an address. You can also specify the address space.

You can use the `info files` command to display information about the loaded files.

Examples

```
add-symbol-file myFile.axf                    # Load symbols at entry point+0x0000
add-symbol-file myLib.so                      # Pends symbol file for shared library
add-symbol-file myModule.ko                   # Pends symbol file for OS module
add-symbol-file myFile.axf 0x2000             # Load symbols at entry point+0x2000
add-symbol-file relocate.o -s .text 0x1000 -s .data 0x2000
                                              # Load symbols from relocate.o with
                                              # section .text relocated to 0x1000 and
                                              # section .data relocated to 0x2000
add-symbol-file vmlinux N:0                   # Load symbols at the non-secure address 0x00
add-symbol-file vmlinux EL2N:0x4080000000     # Load symbols for the non-secure address
space EL2N:0x4080000000
```

Related references

1.2.7 Files on page 1-29

1.3.2 advance

Sets a temporary breakpoint at the specified address and calls the debugger **continue** command. Use the `advance` command to halt execution at a particular point in your code, for example a specific function, source code line number, or instruction memory address.

Execution continues until it hits the temporary breakpoint (or until execution halts for another reason, for example the end of the program is reached).

Temporary breakpoints are deleted when hit.

Syntax

```
advance [-p] [<filename>:]<line_num>
```

```
advance [-p] [<filename>:]<function>
advance [-p] [<filename>:]<label>
advance [-p] *<address>
advance +<offset> | -<offset>
```

Where:

-p

Creates pending breakpoints for unrecognized locations.

By default, specifying an unrecognized breakpoint location (for example, a non-existent function name) results in an error.

The `-p` option creates pending breakpoints for unrecognized locations instead. This is useful when debugging shared libraries. Shared libraries are loaded on demand, so locations are unrecognized until the library is loaded. For more information, see *Pending breakpoints and watchpoints*.

Note

If you want to debug a shared library, you must load debug symbols from the shared library as well as the application itself. For more information, see *About debugging shared libraries*.

<filename>

Sets a temporary breakpoint on a function, label, or line number in the specified source file.

Functions and labels are usually unique, so the debugger can identify the breakpoint location from the name alone.

However, if you have ambiguous function or label names in your source code, for example static functions named `myfunc` in both `file_a.c` and `file_b.c`, use the filename to identify the precise function. For example, `advance file_a.c:myfunc`.

<line_num>

Sets a breakpoint at the specified line number in the source file `<filename>`.

If no `<filename>` is specified, the debugger assumes the source file containing the current location.

<function>

Sets a breakpoint on the specified function name.

<label>

Sets a breakpoint on the specified assembly label.

Note

You can only set breakpoints on labels that are present in the executable image. Toolchains might not preserve all symbol names in the final image by default. For example, when using Arm Compiler 5 you must specify either the `KEEP` assembler directive or the `armasm --keep` option to retain local symbols.

***<address>**

Sets a breakpoint at the specified address. Specify either an address (for example `advance *0x8000024C`) or an expression that evaluates to an address (for example `advance *$R4+64` or `advance *$PC+256`). For more information about expressions, see *Expressions within Arm Development Studio* on page 1-10.

+<offset> | -<offset>

Sets a breakpoint on the source code line offset from the current location by the specified amount.

Usage

The `advance` command returns control as soon as the target is running. You can use the `wait` command to block the debugger from returning control until, for example, the application completes or a breakpoint is hit. This is useful if you are scripting Arm Development Studio commands and do not want subsequent commands to run until after the breakpoint has been reached.

Examples

```
advance func1                  # To set a temporary breakpoint at func1, then resume execution
advance -p lib.c:foo           # To set a temporary breakpoint on function foo() in lib.c,
then resume execution.
                               # If lib.c is unrecognized (for example, if lib.c is compiled
to a shared library),
                               # the debugger creates a pending breakpoint.
```

Related references

1.2.2 Execution control on page 1-22

1.3.18 continue on page 1-65

1.3.211 wait on page 1-175

1.1.3 Expressions within Arm Development Studio on page 1-10

Related information

KEEP directive - (armasm)

-keep command-line option (armasm)

About debugging shared libraries

Pending breakpoints and watchpoints

1.3.3 append

Reads data from memory or the result of an expression and appends it to an existing file.

Syntax

`append [<format>] memory <filename> <start_address> {<end_address> | +<size>}`

`append [<format>] value <filename> <expression>`

Where:

`<format>`

Specifies the output format:

`binary`

Binary. This is the default setting.

`<filename>`

Specifies the file.

`<start_address>`

Specifies the start address for the memory.

`<end_address>`

Specifies the inclusive end address for the memory.

`+<size>`

Specifies the size of the region.

<expression>

Specifies an expression that is evaluated and the result is returned.

Examples

```
append memory myFile.bin 0x8000 0x8FFF  # Append content of memory 0x8000-0x8FFF
                                        # to binary file myFile.bin
append value myFile.bin myArray         # Append content of myArray
                                        # to binary file myFile.bin
```

Related references

1.2.7 Files on page 1-29

1.2.9 Memory group on page 1-31

1.1.3 Expressions within Arm Development Studio on page 1-10

1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.4 assemble

Writes assembler instructions to memory.

The debugger performs inline assembly of the instructions between the **assemble** and `end` commands, using the specified instruction set, and then writes them to the specified memory location.

This command is useful for making small changes to your code without recompiling. For larger code changes or to make use of a wider set of assembler directives you must use the standalone assembler tool provided by your compiler toolchain.

Note

The assemble command does not change the processor state. You must ensure that the processor is in the correct state to execute the new instructions.

Syntax

```
assemble <address> [<InstructionSet>] # comment

[<Instruction>] ; comment

...

end # comment
```

Where:

<address>

Specifies the address to write the first instruction to. Subsequent instructions are written to following memory.

<InstructionSet>

Specifies the instruction set to assemble to. This can be:

- ARM
- Thumb
- A32
- T32
- A64

You can only specify an instruction set that is available for the processor. If you do not specify the instruction set, it defaults to the instruction set state at the specified address.

<Instruction>

Assembler instruction to write to memory. You can specify multiple instructions. Each instruction must be on a separate line.

You can also specify supported directives. The supported directives are:

- ARM
- THUMB
- CODE32
- CODE16
- A64
- DCB
- DCD
- DCDU
- DCDO
- DCFD
- DCFDU
- DCFS
- DCFSU
- DCI
- DCQ
- DCQU
- DCW
- DCWU

Note

The syntax for the instructions and directives follows the Arm assembly language syntax.

<end>

Specifies the end of the `assemble` command. The list of assembler instructions are written to memory only when you enter `end`.

<comment>

For comments after an `assemble` or `end` command, use the hash `#` character at the beginning of your comment.

For comments after an instruction or directive, use the semicolon `;` character at the beginning of your comment.

Examples

```
assemble $pc ARM    # Assemble the following Arm instructions
    ADD r1,r2,r3    ; Write the A32 add instruction to address $PC
    SUB r2,r3,r4    ; Write the A32 sub instruction to address $PC+4
    DMB             ; Write Data Memory Barrier to $PC+8
    THUMB           ; Assemble the following Thumb instructions
    MOVS r0,#10     ; Write T32 move instruction to $PC+12
end                 # End of the assemble command

assemble 0x00008000 # Assemble the following directives
    DCB 0,1,2,3     ; Write four bytes to 0x00008000
    DCD 7,8         ; Write two words to 0x00008004 and 0x00008008
end                 # End of the assemble command
```

Related references

1.2.9 Memory group on page 1-31

Related information

Arm Compiler armasm User Guide

Syntax of source lines in assembly language

1.3.5 awatch

Sets a watchpoint for a data symbol. The debugger stops the target when the memory at the specified address is read or written.

This command records the ID of the watchpoint in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the watchpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Watchpoints are only supported on scalar values.

The availability of watchpoints depends on your target. In the case of Linux application debug using *gdbserver*, the availability of watchpoints also depends on the Linux kernel version and configuration.

The address of the instruction that triggers the watchpoint might not be the address shown in the PC register. This is because of pipelining effects.

Syntax

```
awatch [-d] [-p][-w <width>] {[<filename>:]<symbol> | *<address>} [vmid <number>] [if <condition>]
```

Where:

`-d`

Creates the watchpoint disabled.

`-p`

Specifies whether or not the resolution of an unrecognized watchpoint location results in a pending watchpoint being created.

`-w <width>`

Specifies the width to watch at the given address, in bits. Accepted values are: 8, 16, 32, and 64 if supported by the target. This parameter is optional.

The width defaults to:

- 32 bits for an address.
- The width corresponding to the type of the symbol or expression, if entered.

`<filename>`

Specifies the file.

`<symbol>`

Specifies a global/static data symbol. For arrays or structs you must specify the element or member.

`*<address>`

Specifies the address. This can be either an address or an expression that evaluates to an address.

`vmid <number>`

Specifies the Virtual Machine ID (VMID) to apply the watchpoint to. This can be either an integer or an expression that evaluates to an integer. Applicable only on targets which support hypervisor / virtual machine debugging.

`if <condition>`

Specifies the condition which must evaluate to true at the time the watchpoint is triggered for the target to stop. You can create several conditional watchpoints, but when a conditional watchpoint is enabled, no other watchpoints (regardless of whether they are conditional) can be enabled.

Examples

```
awatch myVar1                        # Set read/write watchpoint on myVar1
awatch *0x80D4                       # Set read/write watchpoint on address 0x80D4
awatch myVar1 if myVar1 == 2         # Set read/write watchpoint on myVar1 which
                                     # will only be hit if myVar1 evaluates to 2
awatch myVar1 if $LR & 0xFF == 0x12 # Set read/write watchpoint on myVar1 which
                                     # will only be hit if ($LR & 0xFF) evaluates
                                     # to 0x12 when myVar1 is accessed
```

Related references

1.3.212 watch on page 1-175
1.3.114 rwatch on page 1-119
1.3.16 clearwatch on page 1-64
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.6 break

Sets an execution breakpoint at a specific location. You can also specify a conditional breakpoint by using an `if` statement that stops only when the conditional expression evaluates to true.

This command records the ID of the breakpoint in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the breakpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$` respectively.

Note

Breakpoints that are set within a shared object or kernel module become pending when the shared object or kernel module is unloaded.

Use `set breakpoint` to control the automatic breakpoint behavior when using this command.

Syntax

```
break [-d] [-p] [[<filename>:] <location> | *<address>][[thread|core] <number>...]
[if <expression>]
```

Where:

`-d`

Disables the breakpoint immediately after creation.

`-p`

Specifies whether or not the resolution of an unrecognized breakpoint location results in a pending breakpoint being created.

`<filename>`

Specifies the file.

`<location>`

Specifies the location:

`<line_num>`

is a line number.

`<function>`

is a function name.

`<label>`

is a label name.

+<offset> | -<offset>

Specifies the line offset from the current location.

***<address>**

Specifies the address. This can be either an address or an expression that evaluates to an address.

<number>

Specifies one or more threads or processors to apply the breakpoint to. You can use `$thread` to refer to the current thread. If `<number>` is not specified then all threads are affected.

<expression>

Specifies an expression that is evaluated when the breakpoint is hit.

If no arguments are specified then a breakpoint is set at the current PC.

You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

Examples

```
break *0x8000                       # Set breakpoint at address 0x8000
break *0x8000 thread $thread        # Set breakpoint at address 0x8000 on
                                    # current thread
break *0x8000 thread 1 3            # Set breakpoint at address 0x8000 on
                                    # threads 1 and 3
break main                          # Set breakpoint at address of main()
break SVC_Handler                   # Set breakpoint at address of label SVC_Handler
break +1                            # Set breakpoint at address of next source line
break my_File.c:main                # Set breakpoint at address of main() in my_File.c
break my_File.c:10                  # Set breakpoint at address of line 10 in my_File.c
break function1 if x>0          # Set conditional breakpoint that stops when x>0
break *0x80000000 if $thread==32    # Set conditional breakpoint that stops execution
                                    # when thread ID is 32.
break *0x80000000 if $pid==928      # Set conditional breakpoint that stops execution
                                    # when process ID is 928.
```

Related references

1.3.41 hbreak on page 1-78
1.3.193 tbreak on page 1-159
1.3.194 thbreak on page 1-161
1.3.111 resolve on page 1-117
1.3.15 clear on page 1-63
1.2.1 Breakpoints and watchpoints on page 1-20
1.1.3 Expressions within Arm Development Studio on page 1-10
1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11
1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.7 break-script

Assigns a script file to a specific breakpoint. The script executes when the breakpoint is triggered.

Syntax

`break-script <number> [<filename>]`

Where:

<number>

Specifies the breakpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

<filename>

Specifies the script file that you want to execute when the specified breakpoint is triggered. If <filename> is not specified then the currently assigned <filename> is removed from the breakpoint.

Usage

Be aware of the following when using scripts with breakpoints:

- You must not assign a script to a breakpoint that has sub-breakpoints. If you do, the debugger attempts to execute the script for each sub-breakpoint. If this happens, an error message is displayed.
- Take care with the commands you use in a script that is attached to a breakpoint. For example, if you use the **quit** command in script, the debugger disconnects from the target when the breakpoint is hit.
- If you put the `continue` command at the end of a script, this has the same effect as setting the **Continue Execution** checkbox on the **Breakpoint Properties** dialog box.

Examples

```
break-script 1 myScript.ds     # Run myScript.ds when breakpoint 1 is triggered
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.8 break-set-property

Updates the properties of an existing breakpoint.

Syntax

```
break-set-property <number> <property>
```

Where:

<number>

Specifies the breakpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints.

<property>

Specifies the property to set. The valid properties are:

if[<expression>]

Specifies an expression that is evaluated when the breakpoint is hit. If the value of the expression evaluates to true, then the debugger stops the target, otherwise execution resumes. If no expression is specified then the breakpoint condition is deleted.

<core[id]>

The current core ID. You can use `info cores`, `info processes`, or `info threads` to display the ID numbers.

<thread[id]>

The current thread ID. You can use `info cores`, `info processes`, or `info threads` to display the ID numbers.

Note

This command supports other <properties> depending on your target. Use the `info breakpoints capabilities` command to display a list of <properties> that you can use for the current connection.

Examples

```
break-set-property 4 if myVar1 == 2   # Update the 'if' property of breakpoint 4,
                                      # meaning the breakpoint will only be hit if
                                      # myVar1 evaluates to 2
```

1.3.9 break-stop-on-threads, break-stop-on-cores

Applies an existing breakpoint to one or more threads or processors.

Syntax

`break-stop-on-threads <number> [<id>]...`

`break-stop-on-cores <number> [<id>]...`

Where:

`<number>`

Specifies the breakpoint number. This is a unique breakpoint number assigned by the debugger when it is set. You can use `info breakpoints` to display the breakpoint numbers and status.

`<id>`

Specifies one or more threads or processors to apply the breakpoint to. You can use `$thread` or `$core` to refer to the current thread or processor. If `<id>` is not specified then apply the breakpoint to all threads or processors. You can use `info cores`, or `info threads` to display the `<id>` numbers.

Examples

```
break-stop-on-threads 1 2              # Apply breakpoint 1 to thread 2
break-stop-on-threads 4 9 11           # Apply breakpoint 4 to threads 9 and 11
break-stop-on-cores 4                  # Apply breakpoint 4 to all processors
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.10 break-stop-on-vmid

Applies an existing hardware breakpoint to a Virtual Machine (VM).

Syntax

`break-stop-on-vmid <number> [<vmid>]`

Where:

`<number>`

Specifies the hardware breakpoint number. This is a unique breakpoint number assigned by the debugger when it is set. You can use `info breakpoints` to display the breakpoint numbers and status.

`<vmid>`

Specifies the Virtual Machine ID (VMID) to apply the breakpoint to. This can be either an integer or an expression that evaluates to an integer. If `<vmid>` is not specified then the VM effect is removed from the breakpoint.

Examples

```
break-stop-on-vmid 1 2      # Apply hardware breakpoint 1 to vmid 2
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.11 cache flush

Flushes the caches of the current CPU. This might affect the caches of the other CPUs depending on the cache hierarchy. The precise behavior is implementation defined.

Note

This command might be slow depending on the size of the caches and the available flush methods.

Syntax

```
cache flush
```

Examples

```
cache flush     # Flush the caches of the current CPU.
```

Related references

1.2.10 Cache on page 1-33

Related information

About debugging MMUs

1.3.12 cache list

Lists the caches and related information available for the current core. The output is implementation defined.

Syntax

```
cache list
```

Note

The availability of the command and the available caches depend on the specific device that the debugger is connected to.

Examples

```
cache list      # Lists the available caches and views. An example output is:
                        L1D:
                          L1 data cache, size=32k, views: [tags, tlb]
                          ...
                        L1I:
                          L1 instruction cache, size=2k, views: [tags, tlb]
                          ...
```

Related references

1.2.10 Cache on page 1-33

1.3.13 cache print

Provides a structured view of the cache data in the current core. The output is implementation defined.

Syntax

```
cache print <cache> [<view>]...
```

Where:

<cache>

Specifies the cache name.

<view>

Specifies the view name for the selected cache. For each cache, views provide access to different sets of data, or data presented in different formats.

Note

The availability of the command and the available caches depend on the specific device that the debugger is connected to.

Examples

```
cache print L1D        # Prints L1 data cache. An example output is:
                                tags:
                                  ...
                                tlb:
                                  ...

cache print L1D tags   # Prints L1 data cache. An example output is:
                                tags:
                                  ...
```

Related references

1.2.10 Cache on page 1-33

1.3.14 cd

Changes the current working directory.

Syntax

`cd <dir>`

Where:

<dir>

Specifies the directory.

Examples

```
cd "\usr\source"     # Change the current working directory
```

Related references

1.2.7 Files on page 1-29

1.3.15 clear

Deletes a breakpoint at a specific location.

Syntax

`clear [[<filename>:]<location> | *<address>]`

Where:

<filename>

Specifies the file.

<location>

Specifies the location:

<line_num>

is a line number.

<function>

is a function name.

<label>

is a label name.

+<offset> | -<offset>

is a line offset from the current location.

***<address>**

Specifies the address. This can be either an address or an expression that evaluates to an address.

If no arguments are specified then the breakpoint at the current PC is deleted.

Examples

```
clear *0x8000        # Clear breakpoint at address 0x8000
clear main           # Clear breakpoint at address of main()
clear SVC_Handler    # Clear breakpoint at address of label SVC_Handler
clear +1             # Clear breakpoint at address of next source line
clear my_File.c:main # Clear breakpoint at address of main() in my_File.c
clear my_File.c:10   # Clear breakpoint at address of line 10 in my_File.c
```

Related references

1.3.6 break on page 1-58
1.3.41 hbreak on page 1-78
1.3.193 tbreak on page 1-159
1.3.194 thbreak on page 1-161
1.3.111 resolve on page 1-117
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.16 clearwatch

Deletes a watchpoint at a specific location.

Syntax

```
clearwatch [[<filename>:]<symbol> | *<address>]
```

Where:

<filename>

Specifies the file.

<symbol>

Specifies a global/static data symbol. For arrays or structs you must specify the element or member.

***<address>**

Specifies the address. This can be either an address or an expression that evaluates to an address.

Examples

```
clearwatch *0x8000         # Clear watchpoint at address 0x8000
clearwatch my_File.c:myVar # Clear watchpoint at address of myVar in my_File.c
```

Related references

1.3.212 watch on page 1-175
1.3.114 rwatch on page 1-119
1.3.5 awatch on page 1-57
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.17 condition

Sets a stop condition for a specific breakpoint or watchpoint. If the value of a specific expression evaluates to true then the debugger stops the target otherwise execution resumes.

Syntax

```
condition <number> [<expression>]
```

Where:

<number>

Specifies the breakpoint or watchpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

<expression>

Specifies an expression that is evaluated when the breakpoint or watchpoint is hit. If no `<expression>` is specified then the breakpoint or watchpoint condition is deleted.

Examples

```
condition 1 myVar<5     # Set break condition myVar<5 for breakpoint number 1
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.18 continue

Continues running the target. `fg` is an alias for the `continue` command.

Note

Control is returned as soon as the target is running. You can use the **wait** command to block the debugger from returning control until either the application completes or a breakpoint is hit.

Syntax

```
continue [<count>]
```

Where:

<count>

Specifies the number of times to ignore the breakpoint or watchpoint at the current location.

Examples

```
continue          # Continue running target
continue 5        # Continue running target, ignoring current breakpoint 5 times
```

Related references

1.2.2 Execution control on page 1-22

1.3.2 advance on page 1-52

1.3.19 define

Enables you to derive new user-defined commands from existing commands.

User-defined commands accept arguments separated by whitespace.

Syntax

```
define <cmd>
```

```
...
end
```

Where:

<cmd>

Specifies the command name followed by one or more debugger commands. Enter each debugger command on a new line and terminate the `define` command by using the `end` command. You can use arguments by using `$arg0...$argn`, or `$argv` for all arguments.

Note

Existing built in commands cannot be redefined.

Examples

```
# Define add-args command to print sum of first 3 arguments

define add-args
    print $arg0+$arg1+$arg2
end

# Define echo-all command to echo all arguments
define echo-all
    echo $argv
end
```

Related references

1.2.4 Scripts on page 1-25

1.3.20 delete breakpoints

Deletes one or more breakpoints or watchpoints.

Syntax

```
delete [breakpoints] <number>...
```

Where:

<number>

Specifies the breakpoint or watchpoint number. This is the number assigned by the debugger when it is set. You can use info breakpoints to display the number and status of all breakpoints and watchpoints.

Note

Multiple-statements on a single line of source code are assigned sub-numbers, for example `n.n`. You can specify all multiple-statement breakpoints by specifying `n.0` or individually by specifying `n.n`.

If no `number` is specified, then all breakpoints and watchpoints are deleted.

Examples

```
delete breakpoints 1          # Delete breakpoint number 1
delete breakpoints 1 2        # Delete breakpoints number 1 and 2
delete breakpoints            # Delete all breakpoints and watchpoints
delete breakpoints $          # Delete breakpoint whose number is in the
                              # most recently created debugger variable
```

Related references

1.3.120 set breakpoint on page 1-123
1.3.23 disable breakpoints on page 1-68
1.3.47 info breakpoints on page 1-83

1.3.78 info watchpoints on page 1-96
1.3.49 info capabilities on page 1-84
1.3.48 info breakpoints capabilities on page 1-83
1.3.79 info watchpoints capabilities on page 1-97
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.21 delete memory

Deletes one or more user-defined memory regions.

Syntax

`delete memory <number>...`

Where:

`<number>`

Specifies the region number. This is the number assigned by the debugger when the region is set. You can use `info mem` to display the number and status of all regions.

Examples

```
delete memory 1               # Delete region number 1
delete memory 1 2             # Delete regions number 1 and 2
delete memory $               # Delete memory region whose number is in
                              # the most recently created debugger variable
```

Related references

1.2.9 Memory group on page 1-31

1.3.22 directory, set directories

Defines additional directories to search for source files. If you use this command without an argument then the search directories are reset to the default settings. You can use the `show` command to display the current settings.

Syntax

`directory [<path>]...`

`set directories [<path>]...`

Where:

`<path>`

Specifies an additional directory to search for source files. This is appended to the beginning of the list.

Multiple directories can be specified but must be separated with either:

- a space
- a colon (Unix)
- a semi-colon (Windows).

Default

The default directories for searching are:

- compilation directory, *$cdir*
- current working directory, *$cwd*
- current image directory, *$idir*.

Examples

```
directory "\usr\source"      # Add directory to search list
directory "\usr" "\My Src"   # Add two directories to search list,
```

```
                                # first takes precedence
directory                       # Reset to the default directories
```

Related references

1.2.7 Files on page 1-29

1.2.19 Set on page 1-39

1.3.23 disable breakpoints

Disables one or more breakpoints or watchpoints.

Syntax

`disable [breakpoints] <number>...`

Where:

`<number>`

Specifies the breakpoint or watchpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

Note

Multiple-statements on a single line of source code are assigned sub-numbers, for example `<n.n>`. You can specify all multiple-statement breakpoints by specifying `<n>.0` or individually by specifying `<n.n>`.

If no `<number>` is specified, then all breakpoints and watchpoints are disabled.

Note

The breakpoints sub-command is optional.

Examples

```
disable breakpoints 1           # Disable breakpoint number 1
disable breakpoints 1 2         # Disable breakpoints number 1 and 2
disable breakpoints             # Disable all breakpoints and watchpoints
disable breakpoints $           # Disable the breakpoint whose number is in the
                                # most recently created debugger variable
```

Related references

1.3.120 set breakpoint on page 1-123

1.3.20 delete breakpoints on page 1-66

1.3.47 info breakpoints on page 1-83

1.3.78 info watchpoints on page 1-96

1.3.49 info capabilities on page 1-84

1.3.48 info breakpoints capabilities on page 1-83

1.3.79 info watchpoints capabilities on page 1-97

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.24 disable memory

Disables one or more user-defined memory regions.

Syntax

`disable memory <number>...`

Where:

<number>

Specifies the region number. This is the number assigned by the debugger when the region is set. You can use `info memory` to display the number and status of all regions.

Examples

```
disable memory 1              # Disable region number 1
disable memory 1 2            # Disable regions number 1 and 2
disable memory $              # Disable memory region whose number is in
                              # the most recently created debugger variable
```

Related references

1.2.9 Memory group on page 1-31

1.3.25 disassemble

Displays the disassembly for the function surrounding a specific address or the disassembly for a specific address range.

Syntax

`disassemble [<address> [<address> | +<size>]]`

Where:

<address>

Specifies an expression that evaluates to an address. Two `<address>` arguments specify an inclusive address range. If no `<address>` argument is specified then the debugger displays the disassembly for the function surrounding the program counter for the current frame.

+<size>

Specifies the size of the region.

Examples

```
disassemble               # Display disassembly for current function
disassemble 0x8140 0x8157 # Display disassembly for address range 0x8140-0x8157
disassemble 0x8140 +0x18  # Display disassembly for address range 0x8140-0x8157
disassemble 0xC0040AC0    # Display disassembly for address range 0xC0040AC0-0xC0040ADC
```

Related references

1.2.9 Memory group on page 1-31

1.3.26 discard-symbol-file

Discards debug information relating to a specific file.

Syntax

`discard-symbol-file <filename>`

Where:

<filename>

Specifies the image, shared library, or Operating System (OS) module.

Note

Shared library and OS modules depend on connections that support loading these types of files.

You can use the `info files` command to display information about the loaded files.

Examples

```
discard-symbol-file myFile.axf         # Discard symbols relating to myFile.axf
discard-symbol-file myLib.so           # Discard symbols relating to shared library
discard-symbol-file myModule.ko        # Discard symbols relating to OS module
```

1.3.27 document

Enables you to add integrated help for a new user-defined command.

Syntax

```
document <cmd>

...

end
```

Where:

<cmd>

Specifies the user-defined command name. Enter the description on one of more lines of text and terminate the `document` command by using the `end` command.

Examples

```
# Documentation for the new user-defined add-args command

document add-args
    This user-defined command prints the sum of the first 3 arguments
end
```

Related references

1.2.4 Scripts on page 1-25

1.3.28 down

Moves and displays the current frame pointer down the call stack towards the bottom frame. It also displays the function name and source line number for the specified frame.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

```
down [<offset>]
```

Where:

<offset>

Specifies a frame offset from the current frame pointer in the call stack. If no `<offset>` is specified then the default is one.

Examples

```
down     # Move and display information 1 frame down from current frame pointer
down 2   # Move and display information 2 frames down from current frame pointer
```

Related references

1.2.5 Call stack on page 1-26

1.3.29 down-silently

Moves the current frame pointer down the call stack towards the bottom frame.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

```
down-silently [<offset>]
```

Where:

<offset>

Specifies a frame offset from the current frame pointer in the call stack. If no `<offset>` is specified then the default is one.

Examples

```
down-silently                # Move 1 frame down from current frame pointer
down-silently 2              # Move 2 frames down from current frame pointer
```

Related references

1.2.5 Call stack on page 1-26

1.3.30 dump

Reads data from memory or the result of an expression and writes it to a file.

Syntax

```
dump [<format>] memory <filename> [-r] <start_address> {<end_address> | <+size>}
```

```
dump [<format>] value <filename> [-r] <expression>
```

Where:

<format>

Specifies the output format:

binary

Binary. This is the default.

elf

32-bit Arm ELF.

elf64

64-bit Arm ELF.

ihex

Intel Hex-32.

srec

Motorola 32-bit (S-records).

vhx

Byte oriented hexadecimal (Verilog Memory Model).

<filename>

Specifies the file to write to. Specify `-r` to overwrite an existing file.

-r

Use this option with `<filename>` to overwrite an existing file.

<start_address>

Specifies the start address for the memory.

<end_address>

Specifies the inclusive end address for the memory.

<size>

Specifies the size of the region.

<expression>

Specifies an expression that is evaluated to an address and the data from that address is written to the file.

Examples

```
dump memory myFile.bin 0x8000 0x8FFF     # Write content of memory 0x8000-0x8FFF
                                         # to binary file myFile.bin
dump srec value myFile.m32 &myArray      # Write contents of myArray to
                                         # Motorola 32-bit file myFile.m32
```

Related references

1.2.9 Memory group on page 1-31

1.3.31 echo

Displays only textual strings.

Backslashes can be used as follows:

- C escape sequences, for example, "\n" can be used to print a new line.
- Leading and trailing spaces are not displayed unless escaped with a backslash.
- Quoted strings are printed literally including the quote marks.

Syntax

```
echo <string>
```

Where:

<string>

Specifies a string of characters.

Examples

```
echo "   initializing..."    # Display: "   initializing..." (includes quotes)
echo Stage 1\n               # Display: Stage 1 (followed by a new line)
echo \       Init               # Display:    Init (includes leading spaces)
echo 4+4                     # Display: 4+4
```

Related references

1.2.16 Display on page 1-35

1.1.3 Expressions within Arm Development Studio on page 1-10

1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.32 enable breakpoints

Enables one or more breakpoints or watchpoints by number.

Syntax

`enable [breakpoints] [<number>...]`

Where:

`<number>`

Specifies the breakpoint or watchpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

Note

Multiple-statements on a single line of source code are assigned sub-numbers, for example `<n.n>`. You can specify all multiple-statement breakpoints by specifying `<n>.0` or individually by specifying `<n.n>` .

If no `<number>` is specified then all breakpoints and watchpoints are disabled.

Note

The breakpoints sub-command is optional.

Examples

```
enable breakpoints 1           # Enable breakpoint number 1
enable breakpoints 1 2         # Enable breakpoints number 1 and 2
enable breakpoints             # Enable all breakpoints and watchpoints
enable breakpoints $           # Enable the breakpoint whose number is in the
                               # most recently created debugger variable
```

1.3.33 enable memory

Enables one or more user-defined memory regions.

Syntax

`enable memory <number>...`

Where:

`<number>`

Specifies the region number. This is the number assigned by the debugger when the region is set. You can use `info memory` to display the number and status of all regions.

Examples

```
enable memory 1              # Enable region number 1

enable memory 1 2            # Enable regions number 1 and 2
enable memory $              # Enable memory region whose number is in
                             # the most recently created debugger variable
```

Related references

1.2.9 Memory group on page 1-31

1.3.34 end

Enables you to terminate conditional blocks when using the define, if, and while commands.

Examples

```
# Define a while loop containing commands to conditionally execute

# myVar is a variable in the application code
while myVar<10
    step
```

```
    wait
    x
    set myVar++
end
```

Related references

1.2.4 Scripts on page 1-25

1.3.35 file, symbol-file

Loads debug information from an image into the debugger and records the entry point address for future use by the `run` and `start` commands. Subsequent use of the `file` command discards existing information before loading the new debug information. The debug information is loaded when required by the debugger.

If you want to append debug information instead of replacing it, you can use the `add-symbol-file` command.

Note

This command does not set the PC register.

Syntax

```
file [<filename>] [<offset>] [-s <section> <address>]...
```

```
symbol-file [<filename>] [<offset>] [-s <section> <address>]...
```

Where:

`<filename>`

Specifies the image. If no `<filename>` is specified then the debug information is discarded.

`<offset>`

Specifies the offset that is added to all addresses within the image. If `<offset>` is not specified then the default for:

- An image is zero.
- A shared library is the load address of the library. If the application has not loaded the specified library then the request is pended until the library is loaded and the offset can be determined.

`-s`

For relocatable objects, this specifies the address to which a section was relocated.

`<section>`

Specifies the name of the relocated section.

`<address>`

Specifies the address of the section. This can be either an address or an expression that evaluates to an address. You can also specify the address space.

Examples

```
file "myFile.axf"                       # Load debug information on demand.
file "images\myFile.axf"                # Load debug information on demand.
file                                    # Discard debug information.
file "myFile.axf" -s .text 0x1000 -s .data 0x2000
                                        # Load debug information on demand with
                                        # section .text relocated to 0x1000 and
                                        # section .data relocated to 0x2000.
file "vmlinux" N:0                      # Load debug information for the non-secure address
0x00
file "vmlinux" EL2N:0x4080000000        # Load debug information for the non-secure address
space EL2N:0x4080000000
```

Related references

1.2.7 Files on page 1-29

1.3.36 finish

Continues running the device to the next instruction after the selected stack frame finishes.

Syntax

`finish [<n>]`

Where:

`<n>`

Specifies the number of stack frames to finish executing. The default is one.

Examples

```
finish                # Continues running until the current stack frame finishes
finish 5              # Continues running until 5 stack frames finish
```

1.3.37 flash load

Loads sections from an image into one or more flash devices.

Note

To use this command you must check that flash device support is available for your target. If it is not available, you must write your own flash algorithm for this command to work. For details on how to do this, see the *Flash programming chapter* in the *Arm Development Studio User Guide*. To see an example of what Arm Debugger expects, see the following file in your Arm Development Studio installation folder:

`<installation_directory>/examples/Bare-metal_examples_Armv7.zip/flash_algo-STM32F10x`.

`flash load <filename> [<device> [:parameter=<value>]...]...`

Where:

`<filename>`

Specifies the image.

`<device>`

Specifies the flash device name. Use this option to restrict the load to the specified device only.

`<parameter>`

Specifies a parameter or comma separated list of parameters to override.

If no `device` is specified then all devices can be loaded. This is dependent on the sections in the image that correspond to the flash device regions.

You can use `info flash` to display information about the flash devices on the current target.

Examples

```
flash load "foo.axf"    # loads the file to flash

flash load "foo.axf" MainFlash:ramAddress=0x20000100,ramSize=0xFF00
                        # Loads the file to a flash device and overrides the parameters
```

Related references

1.2.23 flash on page 1-45

1.3.38 flash load-multiple

Load multiple images on to your target.

When loading multiple images on to your target, before it writes the images to flash memory, `flash load-multiple` checks that there are no overlaps in the memory address ranges that are specified in the image files. Arm recommends using this option instead of running the `flash load` command multiple times, to prevent data corruption. With the `flash load` command, the debugger does not check for memory overlap and you might accidentally overwrite the existing data.

Note

To use this command you must check that flash device support is available for your target. If it is not available, you must write your own flash algorithm for this command to work. For details on how to do this, see the *Flash programming chapter* in the *Arm Development Studio User Guide*. To see an example of what Arm Debugger expects, see the following file in your Arm Development Studio installation folder:

`<installation_directory>/examples/Bare-metal_examples_Armv7.zip/flash_algo-STM32F10x`.

Syntax

```
flash load-multiple "<image>"<device_parameters> "<another_image>"<device_parameters>
```

For each image, you can optionally provide device parameter information. If you do not provide device parameter information, the image is loaded on to all flash devices on the target, using the default values for each device.

`<device_parameters>` uses the following syntax:

```
@<device_name>:<parameter1>=<value>,<parameter2>=<value>|
@<device_name>:<parameter3>=<value>
```

Note

- You must not have any spaces between an image and its associated device parameters. Spaces are used to indicate a new image.

Parameters

The parameters vary between the different targets. Use `info flash` to find out which device parameters are available on your target.

Examples: flash load-multiple

Consider the following command:

```
flash load-multiple "image1.axf"@MainFlash "image2.axf"@OtherFlash:ramAddress=0x2
image3.axf
```

First, the debugger checks that there are no overlaps between the memory address ranges that are specified in each image. If there is an overlap, an error is reported in the console and the operation is terminated.

If there is no overlap, this command does the following:

- Loads `image1.axf` on to the `MainFlash` device only, using the default values for this device.
- Loads `image2.axf` on to the `OtherFlash` device only, starting at RAM address `0x2`.
- Loads `image3.axf` on to all available devices, using the default values for each device.

Consider another command:

```
flash load-multiple image4.axf image5.axf@Device2|Device3
image6.axf@Device4:size=512,type=2
```

If there are no overlaps in the memory address ranges, this command does the following:

- Loads `image4.axf` on to all available devices, using the default values for each device.
- Loads `image5.axf` on to `Device2` and `Device3` only, using the default values for both devices.
- Loads `image6.axf` on to `Device4` only, and overrides the default values for `size` and `type`.

Restrictions

- Images must be valid `.axf` files.
- You must specify one or more images when you use this command.
- Image paths can be relative or absolute.
- If there is an overlap between the memory address ranges that are specified in the images, an error is reported in the console.

Related references

1.3.37 flash load on page 1-75
1.3.53 info flash on page 1-85

1.3.39 frame

Sets the current frame pointer in the call stack and also displays the function name and source line number for the specified frame.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

```
frame [<number>]
```

Where:

`<number>`

Specifies the frame number. The default is the current frame.

Examples

```
frame 1          # Move to and display information for stack frame 1
frame            # Display stack frame information at current frame pointer
```

Related references

1.2.5 Call stack on page 1-26

1.3.40 handle

Controls the handler settings for one or more signals or exceptions. The default handler settings depend on the type of debug activity. For example, by default on a Linux kernel connection, all signals are handled by Linux on the target. You can use *info handle* to display the current settings.

When connected to an application running on a remote target using gdbserver, the debugger handles Unix signals but on bare-metal it handles processor exceptions.

Syntax

```
handle [<name>]...<keyword>...
```

Where:

`<name>`

Specifies the signal or processor exception name.

`<keyword>`

Specifies the following keywords:

noprint

Disables the print property so the occurrence of an event is not indicated at all. Using the `noprint` keyword implies the properties of the `nostop` keyword as well.

nostop

Disables the stop property so the occurrence of an event does not stop execution.

print

Enables the print property. The debugger prints a message and continues execution when the event occurs. When using `gdbserver` the debugger can only print if `stop` is enabled.

stop

Enables the stop and print properties. The debugger stops execution and prints a message when the event occurs. Using the `stop` keyword implies the properties of the `print` keyword as well.

If no `name` is specified then all handler settings are modified.

Examples

```
handle SVC stop       # When an SVC exception occurs, stop execution and
                      # print a message.
handle IRQ print      # When an IRQ exception occurs, print a message, but
                      # continue execution.
handle IRQ noprint    # When an IRQ exception occurs, do not print a message.
handle noprint nostop # Do not stop execution at any event and do not print
                      # a message.
```

Related references

1.2.2 Execution control on page 1-22

1.3.56 info handle on page 1-86

1.3.41 hbreak

Sets a hardware execution breakpoint at a specific location. You can also specify a conditional breakpoint by using an *if* statement that stops only when the conditional expression evaluates to true.

This command records the ID of the breakpoint in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the breakpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Note

The number of hardware breakpoints is processor limited. If you run out of hardware breakpoints, then delete or disable one that you no longer use.

Note

Breakpoints that are set within a shared object or kernel module become pending when the shared object or kernel module is not loaded.

You can use **info breakpoints capabilities** to display a list of parameters that you can use with breakpoint commands for the current connection.

Syntax

```
hbreak [-d] [-p][{[<filename>:]<location>|*<address>}] [[{thread|core}]<number>...]
[vmid <vmid>] [context <contextid>] [if <expression>]
```

Where:

-d

Disables the breakpoint immediately after creation.

-p

Specifies whether or not the resolution of an unrecognized breakpoint location results in a pending breakpoint being created.

<filename>

Specifies the file.

<location>

Specifies the location:

<line_num>

Is a line number.

<function>

Is a function name.

<label>

Is a label name.

{+<offset> | -<offset>}

Specifies the line offset from the current location.

***<address>**

Specifies the address. This can be either an address or an expression that evaluates to an address.

<number>

Specifies one or more threads or processors to apply the breakpoint to. You can use `$thread` to refer to the current thread. If `<number>` is not specified then all threads are affected.

<vmid>

Specifies the Virtual Machine ID (VMID) to apply the breakpoint to. This can be either an integer or an expression that evaluates to an integer.

<contextid>

Specifies the context ID to apply the breakpoint to. This can be either an integer or an expression that evaluates to an integer. You can only use the context parameter if your hardware supports it and your application makes use of the CONTEXTIDR register. For more information, see CONTEXTIDR in the *Arm Architecture Reference Manual* .

<expression>

Specifies an expression that is evaluated when the breakpoint is hit.

If no arguments are specified, then a hardware breakpoint is set at the current PC.

Examples

```
hbreak *0x8000                # Set breakpoint at address 0x8000
hbreak *0x8000 thread $thread # Set breakpoint at address 0x8000 on current thread
hbreak *0x8000 thread 1 3     # Set breakpoint at address 0x8000 on threads 1 and 3
hbreak main                   # Set breakpoint at address of main()
hbreak SVC_Handler            # Set breakpoint at address of label SVC_Handler
hbreak +1                     # Set breakpoint at address of next source line
hbreak my_File.c:main         # Set breakpoint at address of main() in my_File.c
hbreak my_File.c:8            # Set breakpoint at address of line 8 in my_File.c
hbreak function1 if x>0       # Set conditional breakpoint that stops at address of
```

```
                                  # function1() when x>0
hbreak context 257 0x80000000 # Set conditional breakpoint at address 0x80000000
                              # that stops when CONTEXTIDR=257
```

Related references

1.3.6 break on page 1-58
1.3.193 tbreak on page 1-159
1.3.194 thbreak on page 1-161
1.3.111 resolve on page 1-117
1.3.15 clear on page 1-63
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.42 help

Displays help information for a specific command or a group of commands listed according to specific debugging tasks.

Syntax

`help [{<command> | <group>}]`

Where:

`<command>`

Specifies an individual command.

`<group>`

Specifies a group name for specific debugging tasks:

`group_breakpoints`

Displays the breakpoint and watchpoint commands.

`group_cache`

Displays the cache commands.

`group_data`

Displays the commands that displays source data.

`group_display`

Displays the output and print settings commands.

`group_files`

Displays the commands that interact with files.

`group_flash`

Displays the flash commands.

`group_info`

Displays the program information commands.

`group_log`

Displays the message logging commands.

`group_memory`

Displays the commands that interact with memory.

`group_mmu`

Displays the MMU commands.

group_mpu

Displays the MPU commands.

group_os

Displays the operating system commands.

group_registers

Displays the register commands.

group_running

Displays the target execution and stepping group.

group_scripts

Displays the commands for use in script files.

group_set

Displays the set commands for debugger settings.

group_show

Displays the show commands for debugger settings.

group_stack, **stack**

Displays the call stack commands.

group_support

Displays the supporting commands.

Examples

```
help load                 # Display help information for load command
help print                # Display help information for print command
help group_breakpoints    # Display group of breakpoint and watchpoint commands
help group_files          # Display group of file commands
```

1.3.43 if

Enables you to write scripts that conditionally execute debugger commands.

Syntax

```
if <condition>
...
else
...
end
```

Where:

<condition>

Specifies a conditional expression. Follow the if statement with one or more debugger commands that execute when the expression evaluates to true.

Note

The `else` statement is optional and the debugger commands that follow it only execute when `<condition>` evaluates to false.

Enter each debugger command on a new line and terminate the `if` command by using the `end` command.

Examples

```
# Define an if statement containing commands to conditionally execute

if $pc==0x80000
    break
    info stack full
end
```

Related references

1.2.4 Scripts on page 1-25

1.3.44 ignore

Sets the ignore counter for a breakpoint or watchpoint condition.

Syntax

`ignore <number> <count>`

Where:

`<number>`

Specifies the breakpoint or watchpoint number. This is the number assigned by the debugger when it is set.

`<count>`

Specifies the number of times to ignore the specified breakpoint or watchpoint. The ignore counter is incremented only when the condition evaluates to true.

You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

Examples

```
ignore 2 3     # Ignore breakpoint 2 for 3 hits
ignore $ 3     # Ignore breakpoint, whose number is in the
               # most recently created debugger variable, for 3 hits
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.45 info

Displays the location of a symbol.

Syntax

`info address <symbol>`

Where:

`<symbol>`

Specifies the symbol.

Examples

```
info address mySymbol # Display location of symbol
```

1.3.46 info all-registers

Displays the name and content of grouped registers for the current stack frame.

Unless you specify otherwise, the registers listed by this command are the full set made available by the target, including co-processor and floating-point registers where available. You can use the `inforegisters` command to display a subset of registers that are most useful when debugging C/C++ applications. When application code calls a function it is common for any existing register values to be

saved, so that the registers can be used by the callee function for other purposes. The original register values are then restored when the function returns. When displaying register values the debugger tries to show the value of the actual registers prior to each function call, according to the currently selected stack frame. A consequence of this is that some registers might be shown with undefined values because the debugger is unable to determine the actual value.

Syntax

`info all-registers [<group>]`

Where:

`<group>`

Specifies a group name for a specific register. If no `<group>` is specified then all registers and groups are displayed.

Examples

```
info all-registers                # Display info for all registers
info all-registers USR            # Display info for all user mode registers
```

Related references

1.2.11 Registers on page 1-33

1.2.17 Information on page 1-36

1.3.47 info breakpoints

Displays information about the status of all breakpoints and watchpoints.

Note

This command sets a default address variable to the location of the last breakpoint or watchpoint listed. Some commands, such as `x`, use this default value if no address is specified.

Syntax

`info breakpoints`

Examples

```
info breakpoints            # Display status for all breakpoints and watchpoints
```

Related references

1.3.120 set breakpoint on page 1-123

1.3.23 disable breakpoints on page 1-68

1.3.20 delete breakpoints on page 1-66

1.3.49 info capabilities on page 1-84

1.3.48 info breakpoints capabilities on page 1-83

1.3.79 info watchpoints capabilities on page 1-97

1.2.1 Breakpoints and watchpoints on page 1-20

1.2.17 Information on page 1-36

1.3.78 info watchpoints on page 1-96

1.3.48 info breakpoints capabilities

Displays a list of parameters that you can use with breakpoint and watchpoint commands for the current connection.

Syntax

```
info breakpoints capabilities
```

Examples

```
info breakpoints capabilities     # Display list of parameters for current connection
```

Related references

1.3.120 set breakpoint on page 1-123
1.3.23 disable breakpoints on page 1-68
1.3.20 delete breakpoints on page 1-66
1.3.47 info breakpoints on page 1-83
1.3.78 info watchpoints on page 1-96
1.3.49 info capabilities on page 1-84
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.49 info capabilities

Displays a list of capabilities for the target device that is currently connected to the debugger. For more information, see the documentation for your target.

Syntax

```
info capabilities
```

Examples

```
info capabilities      # Display target device capabilities
```

Related references

1.3.120 set breakpoint on page 1-123
1.3.23 disable breakpoints on page 1-68
1.3.20 delete breakpoints on page 1-66
1.3.47 info breakpoints on page 1-83
1.3.78 info watchpoints on page 1-96
1.3.48 info breakpoints capabilities on page 1-83
1.3.79 info watchpoints capabilities on page 1-97
1.2.1 Breakpoints and watchpoints on page 1-20
1.2.17 Information on page 1-36

1.3.50 info classes

Displays C++ class names.

Syntax

```
info classes [<expression>]
```

Where:

<expression>

Specifies a class name or a wildcard expression. You can use wildcard expressions to enhance your pattern matching. If no <expression> is specified then all classes are displayed.

Examples

```
info classes                  # Display info for all classes
info classes m*               # Display info for names starting with m
                              # (use when set wildcard-style=glob)
```

```
info classes my_class[0-9]+    # Display info for names with my_class followed
                               # by a number (use when set wildcard-style=regex)
```

Related references

1.2.17 Information on page 1-36

1.3.51 info cores

Displays information about the running processors. It shows the number (a unique number assigned by the debugger), name, current state, and related stack frame including the function names and source line number.

Syntax

`info cores`

Examples

```
info cores     # Display all processors
```

Related references

1.2.17 Information on page 1-36

1.3.52 info files

Displays information about the loaded image and symbols.

Syntax

`info files`

Examples

```
info files      # Display information for loaded image and symbols
```

Related references

1.2.17 Information on page 1-36
1.3.75 info target on page 1-95

1.3.53 info flash

Displays information about the flash devices on the current target.

Note

To use this command, you need to check that flash device support is available for your target. If it is not available, you need to write your own flash algorithm for this command to work. For details on how to do this, see the *Flash programming chapter* in the *Arm Development Studio User Guide*. To see an example of what the debugger expects, locate the following file in your Arm Development Studio installation folder:

`.../examples/Bare-metal_examples_Armv7.zip/flash_algo-STM32F10x`.

Syntax

`info flash`

Examples

```
info flash      # Display information about the current flash devices.
```

Related references

1.2.23 flash on page 1-45

1.3.54 info frame

Displays stack frame information at the selected position.

- Stack frame address.
- Current PC address.
- Saved PC address.
- Calling frame address.
- Source language.
- Frame arguments and associated addresses.
- Address of the local variables.
- Stack pointer address for the previous frame.
- Saved registers and associated location.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

`info frame [<number>]`

Where:

`<number>`

Specifies the frame number.

If no arguments are specified, then the stack frame information for the current frame pointer is displayed.

Examples

```
info frame 1          # Display information for stack frame 1
info frame            # Display information for stack frame at current location
```

Related references

1.2.5 Call stack on page 1-26

1.3.55 info functions

Displays the name and data types for all functions.

Syntax

`info functions [<expression>]`

Where:

`<expression>`

Specifies a function name or a wildcard expression. You can use wildcard expressions to enhance your pattern matching.

If no `<expression>` is specified then all functions are displayed.

Examples

```
info functions                # Display info for all functions
info functions m*             # Display info for names starting with m
                              # (use when set wildcard-style=glob)
info functions my_func[0-9]+  # Display info for names with my_func followed
                              # by a number (use when set wildcard-style=regex)
```

1.3.56 info handle

Displays information about the handling of signals or processor exceptions.

When connected to an application running on a remote target using `gdbserver`, the debugger handles Unix signals but on bare-metal it handles processor exceptions.

Syntax

```
info handle [<name>]
```

Where:

<name>

Specifies the signal name. If no `<name>` is specified then all handler settings are displayed.

Examples

```
info handle                     # Display info for all signals
info handle IRQ                 # Display info for IRQ signal
```

Related references

1.2.2 Execution control on page 1-22

1.3.40 handle on page 1-77

1.2.17 Information on page 1-36

1.3.71 info signals on page 1-94

1.3.57 info inst-sets

Displays the available instruction sets.

Syntax

```
info inst-sets
```

Examples

```
info inst-sets      # Display available instruction sets
```

Related references

1.2.17 Information on page 1-36

1.3.58 info locals

Displays all local variables for the current stack frame.

Syntax

```
info locals
```

Examples

```
info locals     # Display all local variables for the current stack frame
```

Related references

1.2.17 Information on page 1-36

1.3.59 info members

Displays the name and data types for all class member variables that are accessible in the function corresponding to the selected stack frame.

Syntax

```
info members [<expression>]
```

Where:

<expression>

Specifies the name of a class member or a C expression that evaluates to a struct, union, or class variable. If no <expression> is specified, then all members of the current function identified by this pointer are displayed.

Note

Using high compiler optimization levels such as `-O2` with `--debug` can produce a less than satisfactory debug view because the mapping of object code to source code is not always clear. If the compiler optimizes away the this pointer, then using the `info members` command without an expression produces an error.

Examples

```
info members                    # Display members for the current function
info members my_Struct[0-9]+    # Display members for matching struct variables
```

Related references

1.2.17 Information on page 1-36

1.3.60 info memory

Displays the currently defined memory regions.

This command also shows the currently defined attributes for the memory regions. When you specify an address as an argument to a command, you can also specify the attributes defined for the memory region if needed.

Syntax

`info memory`

You can define new memory regions using the `memory` command. To discover the additional set of attributes applicable for a region of address space, you can use the `info memory-parameters` command.

Examples

```
info memory              # Display attributes for all memory regions

Num Enb Low Addr        High Addr       Attributes                          Description
1:  y   SP:0x0000000000 SP:0xFFFFFFFFFF rw, nocache, verify                 Memory accessed
using secure world physical addresses
2:  y   S:0x00000000    S:0xFFFFFFFF    rw, nocache, verify                 Memory accessed
using secure world addresses
8:  y   S:0x80000000    S:0x80001DCB    cache
[EXEC]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
9:  y   S:0x80001DCC    S:0x80001E33    cache
[EXEC]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
10: y   S:0x80001E34    S:0x8000229F    cache
[EXEC]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
11: y   S:0x800022A0    S:0x8000429F    cache
[ARM_LIB_HEAP]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
12: y   S:0x800042A0    S:0x8000829F    cache
[ARM_LIB_STACK]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
13: y   S:0x800082A0    S:0x8000869F    cache
[IRQ_STACKS]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
14: y   S:0x80500000    S:0x805FFFFF    cache
[PAGETABLES]C:\Arm_DS_Workspace\smp_primes_A15x2-CoreTile\primes.axf
3:  y   NP:0x0000000000 NP:0xFFFFFFFFFF rw, nocache, verify                 Memory accessed
using normal world physical addresses
4:  y   N:0x00000000    N:0xFFFFFFFF    rw, nocache, verify                 Memory accessed
using normal world addresses
5:  y   H:0x00000000    H:0xFFFFFFFF    rw, nocache, verify                 Memory accessed
via hypervisor address
6:  y   APB:0x00000000  APB:0xFFFFFFFF  rw, nobp, nohbp, nocache, noverify  APB bus accessed
via AP_1
7:  y   AHB:0x00000000  AHB:0xFFFFFFFF  rw, nobp, nohbp, nocache, noverify  AHB bus accessed
via AP_0
```

Related references

1.2.9 Memory group on page 1-31

1.2.17 Information on page 1-36

1.3.61 info memory-parameters

Displays the memory parameters applicable to an address space.

Syntax

`info memory-parameters`

`info mem-params`

Operation

When using the debugger to interact with target memory, you can specify the memory address using an expression. The debugger also allows other aspects of the memory operation to be controlled using extra parameters within the expression. Different address spaces support different parameters. You can use the `info memory-parameters` command to list the parameters applicable to an *address space* on page 1-17.

Example: info mem-params command

Enter `info mem-params`. The output looks similar to this:

```
Address Space | Parameter | Description
------------------------------------------------------------------------------------------------
------------------------------------------------------------------------
N:            | width     | Specifies the access width used to perform the access, note that
this is independent from the total amount of data read.
              | verify    | Controls whether or not a write operation must verify the value
written by reading the value back and comparing it to the value written.
------------------------------------------------------------------------------------------------
------------------------------------------------------------------------
NP:           | width     | Specifies the access width used to perform the access, note that
this is independent from the total amount of data read.
              | verify    | Controls whether or not a write operation must verify the value
written by reading the value back and comparing it to the value written.
------------------------------------------------------------------------------------------------
------------------------------------------------------------------------
S:            | width     | Specifies the access width used to perform the access, note that
this is independent from the total amount of data read.
              | verify    | Controls whether or not a write operation must verify the value
written by reading the value back and comparing it to the value written.
------------------------------------------------------------------------------------------------
------------------------------------------------------------------------
SP:           | width     | Specifies the access width used to perform the access, note that
this is independent from the total amount of data read.
              | verify    | Controls whether or not a write operation must verify the value
written by reading the value back and comparing it to the value written.
```

Related references

1.2.9 Memory group on page 1-31
1.2.17 Information on page 1-36
1.3.147 set variable on page 1-141
1.1.9 Address space prefixes on page 1-17

Related information

About address spaces
About debugging caches

1.3.62 info os

Displays the current state of the Operating System (OS) support. If OS support is enabled, also lists all available OS data tables. To print the contents of a data table, pass its name as an argument.

Note

A connection must be established with your target before you can use this command. You can use the `set os` command to control operating system support in the debugger.

Syntax

`info os [<data-table>]`

Where:

`<data-table>`

Specifies the data table name.

Examples

```
info os               # Displays the current state of the OS support and lists all
available OS data tables.
info os tasks         # Displays the contents of the 'tasks' data table, where 'tasks' is
the name of an available data table.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.17 Information on page 1-36

1.3.63 info os-log

Displays the contents of the Operating System (OS) log buffer for connections that support this feature. On Linux, this is the contents of the kernel `dmesg` log.

Note

A Linux kernel connection must be established and the target stopped before you can use this command.

Syntax

`info os-log`

Examples

```
info os-log     # Displays the OS log buffer
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.17 Information on page 1-36

1.3.64 info os-modules

Displays a list of loadable kernel modules for connections that support this feature.

Note

A connection must be established and operating system support must be enabled within the debugger before a loadable module can be detected. You can use the `set os` command to control operating system support in the debugger.

Syntax

`info os-modules` [-s]

Where:

`-s`

Displays the section information of the modules.

Examples

```
info os-modules     # Displays info for loaded OS modules
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.17 Information on page 1-36

1.3.65 info os-version

Displays the version of the Operating System (OS) for connections that support this feature.

Syntax

```
info os-version
```

Examples

```
info os-version      # Displays the version of the OS
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.17 Information on page 1-36

1.3.66 info overlays

Displays information about the currently loaded overlays. It shows the ID, the load address, exec address, and size for each overlay, and whether it is loaded or not.

Syntax

```
info overlays [functions]
```

Where:

`functions`

Displays the details of functions in the overlay.

Examples

```
info overlays               # Displays the details of overlays in the application.
info overlays functions     # Displays the details of functions in each overlay.
```

1.3.67 info processes

Displays information about the user space processes. It shows the number (a unique number assigned by the debugger), OS ID (pid), OS Parent ID, kind, OS state, current state, and related stack frame including the function names and source line number.

Syntax

```
info processes
```

Examples

```
info processes     # Display all user space processes
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.17 Information on page 1-36

1.3.68 info registers

Displays the name and content of all application level registers for the current stack frame. The registers listed by this command are a subset that are most useful when debugging C/C++ applications. You can use the `info all-registers` command to list the full set of registers.

When application code calls a function it is common for any existing register values to be saved, so that the registers can be used by the callee function for other purposes. The original register values are then restored when the function returns. When displaying register values the debugger tries to show the value of the actual registers prior to each function call, according to the currently selected stack frame. A consequence of this is that some registers might be shown with undefined values because the debugger is unable to determine the actual value.

Syntax

`info registers [<register>]`

Where:

`<register>`

Specifies the register name. If no `<register>` is specified then all application level registers are displayed.

Examples

```
info registers                # Display info for all application level registers
info registers pc             # Display info for PC register
```

Related references

1.2.11 Registers on page 1-33

1.2.17 Information on page 1-36

1.3.69 info semihosting

Displays semihosting information.

Syntax

`info semihosting [server | clients | all]`

Where:

`all`

Displays information on the semihosting server listener port, a list of the connected clients, and the heap and stack. This is the default.

`server`

Displays information on the semihosting server listener port.

`clients`

Displays information on each of the semihosting streams `stdin`, `stdout`, `stderr`. This includes a list of the connected clients.

`heap`

Displays the heap information that the debugger used to initialize the heap.

Note

This information is only displayed if the debugger performs the initialization.

`stack`

Displays the stack information that the debugger used to initialize the stack.

Note

This information is only displayed if the debugger performs the initialization.

Examples

```
info semihosting            # Displays all semihosting information
info semihosting clients    # Display clients info for semihosting streams
```

Related references

1.2.17 Information on page 1-36

1.3.70 info sharedlibrary

Displays the names of the loaded shared libraries, the base address, and whether the debug symbols of the shared libraries are loaded or not.

- You must launch the debugger with `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.
- This command is only supported for Linux application debug, for example, connections using `gdbserver`. It is not supported for Linux kernel debug, for example, connections using JTAG.

Syntax

`info sharedlibrary [/<order>] [/<sort_by>] [/<group>]`

Where:

`/<order>`

Specifies the sorting order:

`a`

Ascending order. This is the default.

`d`

Descending order.

`/<sort_by>`

Specifies the sorting order of the shared objects:

`b`

Sort by base addresses. This is the default.

`n`

Sort by library names.

`/<group>`

Specifies whether to group the debug symbols:

`s`

Group loaded symbols followed by unloaded symbols.

`sn`

Group unloaded symbols followed by loaded symbols.

Examples

```
info sharedlibrary           # Display shared libraries by base address, asc
info sharedlibrary /n        # Display shared libraries by library name, asc
info sharedlibrary /d        # Display shared libraries by base address, desc
info sharedlibrary /n /a /s  # Display shared libraries grouped loaded->unloaded
                             # and by library name, asc
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.17 Information on page 1-36

1.3.71 info signals

Displays information about the handling of signals or processor exceptions.

When connected to an application running on a remote target using `gdbserver`, the debugger handles Unix signals but on bare-metal it handles processor exceptions.

Syntax

`info signals [<name>]`

Where:

`<name>`

Specifies the signal name. If no `<name>` is specified then all handler settings are displayed.

Examples

```
info signals                    # Display info for all signals
info signals IRQ                # Display info for IRQ signal
```

Related references

1.2.2 Execution control on page 1-22
1.2.17 Information on page 1-36
1.3.56 info handle on page 1-86
1.3.40 handle on page 1-77

1.3.72 info sources

Displays the names of the source files used in the current image being debugged. Where possible the names are resolved to the location on the host system.

Syntax

`info sources`

Examples

```
info sources     # Display the names of source files
```

Related references

1.2.7 Files on page 1-29
1.2.17 Information on page 1-36

1.3.73 info stack, backtrace, where

Displays a numbered list of the calling stack frames including the function names and source line numbers. You can use to control the default call stack display settings.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

`info stack [<n> | -<n>] [full]`

`backtrace [<n> | -<n>] [full]`

`where [<n> | -<n>] [full]`

Where:

<n>

Specifies <n> frames from the bottom of the call stack.

-<n>

Specifies <n> frames from the top of the call stack.

full

Specifies the additional display of local variables.

Examples

```
info stack                  # Display call stack
backtrace -5                # Display top 5 frames of the call stack
backtrace full              # Display call stack including local variables
where                       # Display call stack
```

Related references

1.2.5 Call stack on page 1-26

1.2.17 Information on page 1-36

1.3.74 info symbol

Displays the symbol name at a specific address.

Syntax

info symbol <address>

Where:

<address>

Specifies the address.

Examples

```
info symbol 0x8000      # Display symbol name at address0x8000
```

Related references

1.2.17 Information on page 1-36

1.3.75 info target

Displays information about the loaded image and symbols.

Syntax

info target

Examples

```
info target      # Display information for loaded image and symbols
```

Related references

1.2.17 Information on page 1-36

1.3.52 info files on page 1-85

1.3.76 info threads

Displays information about the available threads. It shows the number (a unique number assigned by the debugger), OS ID (pid), OS Parent ID, kind, OS state, current state, and related stack frame including the function names and source line number.

Note

When kernel debugging this command displays kernel threads only. For user space processes you can use the `info processes` command.

Syntax

```
info threads
```

Examples

```
info threads      # Display all threads
```

Related references

1.2.6 Operating System (OS) on page 1-27
1.2.17 Information on page 1-36

1.3.77 info variables

Displays the name and data types for all global and static variables.

Syntax

```
info variables [<expression>]
```

Where:

`<expression>`

Specifies a symbol name or a wildcard expression. You can use wildcard expressions to enhance your pattern matching.

If no `<expression>` is specified, then all global and static variables are displayed.

Examples

```
info variables                # Display info for all variables
info variables num            # Display info for num variable
info variables m*             # Display info for names starting with m
                              # (use when set wildcard-style=glob)
info variables my_var[0-9]+   # Display info for names with my_var followed
                              # by a number (use when set wildcard-style=regex)
```

Related references

1.2.17 Information on page 1-36

1.3.78 info watchpoints

Displays information about the status of all breakpoints and watchpoints.

Note

This command sets a default address variable to the location of the last breakpoint or watchpoint listed. Some commands, such as `x`, use this default value if no address is specified.

Syntax

```
info watchpoints
```

Examples

```
info watchpoints           # Display status for all breakpoints and watchpoints
```

Related references

1.3.120 set breakpoint on page 1-123
1.3.23 disable breakpoints on page 1-68
1.3.20 delete breakpoints on page 1-66
1.3.49 info capabilities on page 1-84
1.3.48 info breakpoints capabilities on page 1-83
1.3.79 info watchpoints capabilities on page 1-97
1.2.1 Breakpoints and watchpoints on page 1-20
1.2.17 Information on page 1-36
1.3.47 info breakpoints on page 1-83

1.3.79 info watchpoints capabilities

Displays a list of parameters that you can use with breakpoint and watchpoint commands for the current connection.

Syntax

`info watchpoints capabilities`

Examples

```
info watchpoints capabilities     # Display list of parameters for current connection
```

Related references

1.3.120 set breakpoint on page 1-123
1.3.23 disable breakpoints on page 1-68
1.3.20 delete breakpoints on page 1-66
1.3.47 info breakpoints on page 1-83
1.3.78 info watchpoints on page 1-96
1.3.49 info capabilities on page 1-84
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.80 interrupt, stop

Interrupts the target and stops the application if it is running.

Syntax

`interrupt`

`stop`

Examples

```
interrupt                  # Interrupt application.
stop                       # Interrupt application.
```

Related references

1.2.2 Execution control on page 1-22

1.3.81 list

Displays lines of source code surrounding the current or specified location. The default listing is 10 lines of source code unless you specify start and finish line numbers. You can use the `set listsize` command to modify the default settings.

Repeated commands display successive source lines in the same direction through the source file.

Syntax

`list [[<filename>:]<location> | + | - | +<offset> | -<offset>]| [*<address>]`

Where:

`<filename>`

Specifies the file.

`<location>`

Specifies the location:

`<line_num>`

is a line number

`<first>, <last>`

are start and finish line numbers

`<function>`

is a function.

`+`

Displays the source lines after the current location.

`-`

Displays the source lines before the current location.

`<offset>`

Specifies the line offset from the current location.

`*<address>`

Specifies the address. This can be either an address or an expression that evaluates to an address.

Default

The default directories for searching are:

- compilation directory, `$cdir`
- current working directory, `$cwd`
- current image directory, `$idir`.

You can use the `directory` command to define additional search directories.

Examples

```
list main           # Set current location to main() and display source
list +3             # Increment current location then display source
list -              # Decrement current location then display source
list *0x8120        # Set current location to address 0x8120 and display source
list 35             # Set current location to line 35 and display source
list dhry_1.c:10,23 # Display source lines 10 to 23 in dhry_1.c
list *main          # Set current location to address of main and display source
```

1.3.82 load

Loads an image on to the target and records the entry point address for future use by the `run` and `start` commands.

The PC register is not set with this command.

Debug information is not loaded with this command. You can use either the `add-symbol-file`, `file`, or `loadfile` command to load debug information.

Syntax

```
load [<filename>][<offset>]
```

Where:

<filename>

Specifies the image. If no `<filename>` is specified then the executable image specified by the previous command is loaded. You can use `info files` to display information about the current image and symbols.

<offset>

Specifies the offset that is added to all addresses within the image.

Examples

```
load "myFile.axf"              # Load image
load "images\myFile.axf"       # Load image
load myFile.axf 0x2000         # Load image with offset 0x2000
load "myV8File.axf" EL3:0x0    # Load image in the EL3 address space with offset 0x0
```

Related references

1.2.7 Files on page 1-29

1.3.83 loadfile

Loads debug information into the debugger, an image on to the target and records the entry point address for future use by the `run` and `start` commands.

The debug information is loaded when required by the debugger.

Note

This command does not set the PC register.

Syntax

```
loadfile <filename> [<offset>]
```

Where:

<filename>

Specifies the image.

<offset>

Specifies the offset that is added to all addresses within the image.

Examples

```
loadfile "myFile.axf"             # Load image and debug information when required
loadfile "images\myFile.axf"      # Load image and debug information when required
loadfile myFile.axf 0x2000        # Load image with offset 0x2000 and load debug
                                  # information when required
loadfile "myV8File.axf" EL3:0x0   # Load image in the EL3 address space with offset 0x0
                                  # and load debug information when required.
```

Related references

1.2.7 Files on page 1-29

1.3.84 log config

Specifies the type of logging configuration to output runtime messages from the debugger.

Syntax

```
log config <option>
```

Where:

<option>

Specifies a predefined logging configuration or a user-defined logging configuration file:

error

Output messages using the predefined ERROR level configuration. This only reports errors.

info

Output messages using the predefined INFO level configuration. This reports errors and other debugger information. This is the default.

debug

Output messages using the predefined DEBUG level configuration. This reports errors and more information than the INFO configuration.

<filename>

Specifies a user-defined logging configuration file to customize the output of messages. The debugger supports log4j configuration files.

You can use this command with the `log file` command to output messages to a file in addition to the console.

Examples

```
log config debug     # Display all debug messages
```

Related references

1.2.18 log on page 1-38

Related information

Log4j in Apache Logging Services

1.3.85 log file

Specifies an output file to receive runtime messages from the debugger.

Syntax

```
log file [<filename>]
```

Where:

<filename>

Specifies the output file. If no `<filename>` is specified then output messages are sent only to the console.

Examples

```
log file myOutput.log     # Output debugger messages to myOutput.log and console
```

Related references

1.2.18 log on page 1-38

1.3.86 memory

Defines a memory region and specifies its attributes and size.

This command records the ID of the memory region in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the status of the memory region. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$` respectively.

User-defined memory regions are higher-numbered, and they override lower-numbered memory regions. Use the `info memory` command to view the available memory regions.

Syntax

`memory <start_address> <end_address> | +<size> [<attributes>]...`

Where:

`<start_address>`

Specifies the start address for the region.

`<end_address>`

Specifies the inclusive end address for the region. You can use `0x0` as a shortcut to represent the end of the address space.

`+<size>`

Specifies the size of the region.

`<attributes>`

Specifies additional attributes:

`<access_mode>`

Specifies the access mode for the region:

`na`

no access

`ro`

read-only

`wo`

write-only

`rw`

read/write. This is the default.

`<width>`

Specifies the access width:

`8`

8-bit

`16`

16-bit

`32`

32-bit

`64`

64-bit.

It is only necessary to specify a specific access width where the memory region is sensitive to this, for example, when accessing some peripherals.

If no `<width>` is specified then the debugger uses any available access width and generally provides the highest performance.

`bp | nobp`

Controls whether or not software breakpoints can be set in the region. `bp` is the default.

`hbp | nohbp`

Controls whether or not hardware breakpoints can be set in the region. `hbp` is the default.

`cache | nocache`

Controls whether the debugger can cache data read from the memory region. Enabling the caching of memory can improve debugger performance. Memory regions that can be modified by external sources should not be cached by the debugger. For example volatile peripherals.

`nocache` is the default.

`verify | noverify`

Controls whether or not a write operation must verify the value written by reading the value back and comparing it to the value written. The `verify` option also requires the `rw` attribute to be specified so that the verify operation to be performed. Arm recommends that you mark areas of memory containing peripherals as `noverify`, because some peripheral registers are volatile such that reading their value changes their contents as a side-effect.

`verify` is the default.

`unwind | nounwind`

Controls whether the debugger should read from this area of memory when unwinding the stack.

By default, when unwinding the stack, the debugger accesses any area of memory marked as readable.

Examples

```
memory 0x1000 0x2FFF cache     # specify RW region 0x1000-0x2FFF (cache)
memory 0x3000 0x7FFF ro 8      # specify 8-bit RO region 0x3000-0x7FFF (nocache)
memory 0x8000 0x0              # specify RW region 0x8000-0xFFFF (nocache)
memory 0 0xFFFFFFFF ro nobp    # specify RO region 0-0xFFFFFFFF no breakpoints
```

Related references

1.2.9 Memory group on page 1-31
1.3.60 info memory on page 1-88
1.3.24 disable memory on page 1-68
1.3.33 enable memory on page 1-73
1.3.21 delete memory on page 1-67

1.3.87 memory auto

Resets the memory regions to the default target settings and discards all user-defined regions.

Syntax

`memory auto`

Examples

```
memory auto     # reset default memory regions
```

Related references

1.2.9 Memory group on page 1-31

1.3.88 memory debug-cache

Controls the caching by the debugger for all memory regions. You can use `info mem` to display the caching attributes.

Syntax

`memory debug-cache <option>`

Where:

`<option>`

Specifies additional options:

`off`

Globally disables debugger caching of memory regions. All memory accesses are performed directly on the target.

`on`

Globally enables debugger caching of memory regions. When caching is globally enabled the debugger might cache the results of read operations from memory regions that allow caching. This is the default.

`invalidate`

Invalidates all the caches, so that the next subsequent read from memory is performed on the target and not the cache.

Examples

```
memory debug-cache off                      # Disable caching
memory debug-cache invalidate               # Invalidates all caches
```

Related references

1.2.9 Memory group on page 1-31

1.3.89 memory fill

Writes a specific pattern of bytes to memory.

Syntax

`memory fill [<verify=flag>:]<start_address> {<end_address> | +<offset>} <fill_size> <pattern>`

Where:

`verify`

Qualifies the address with a flag to specify whether the operation must perform a verify action or not. The values for flag are:

0

There is no need to verify whether the operation executed correctly.

1

The operation must verify whether it executed correctly. This is the default.

<start_address>

Specifies the start address for the region. This can be either an address or an expression that evaluates to an address.

For example:

```
memory fill EL1N<verify=0>:0x0 0xFFFFFFFF 4 0x12345678
```

If there is only one (anonymous) address space, then use:

```
memory fill <verify=0>:0x00xFFFFFFFF 4 0x12345678
```

<end_address>

Specifies the inclusive end address for the region. This can be either an address or an expression that evaluates to an address.

+<offset>

Specifies the length of the region in bytes.

<fill_size>

Specifies the size of the fill pattern in bytes.

<pattern>

Specifies an expression that defines the fill pattern. If the pattern does not fit exactly into the specified region, then the remaining bytes are filled with partial bytes from the pattern.

Examples

```
memory fill 0x0 0xFFFFFFFF 4 0x12345678   # Fill 0x0 to 0xFFFFFFFF inclusive with int
                                          # value 0x12345678 using default access width
memory fill main (main+15) 1 (char)0x0    # Fill 16 bytes from symbol main with byte
                                          # value 0x0
```

Related references

1.2.9 Memory group on page 1-31

1.3.90 memory set

Writes to memory.

Syntax

```
memory set [<verify=flag>:]<address> <width> <expression>
```

Where:

verify

Qualifies the address with a flag to specify whether the operation must perform a verify action or not. The values for flag are:

0

There is no need to verify whether the operation executed correctly.

1

The operation must verify whether it executed correctly. This is the default.

<address>

Specifies an address at which to write the first value. The address must be correctly aligned for the type of the specified expression.

For example:

```
memory set EL1N<verify=0>:0x8000 32 0x1234
```

If there is only one (anonymous) address space, then use:

```
memory set <verify=0>:0x8000 32 0x1234
```

<width>

Specifies the access width (bits) to use when writing to memory. If the width is narrower than the value being written then more than one access is used to write the value. For example:

0

enables the debugger to determine the access width

8

8-bit

16

16-bit

32

32-bit

64

64-bit.

Widths depend on the target, address region, and address alignment. Some access sizes might not be supported.

<expression>

Specifies either a single expression or an aggregate of expressions with the same size enclosed in curly braces. If there is more than one expression, then the values are written to memory sequentially with the addresses determined by the width of the type of the values.

Note

This command sets a default address variable to the value of the memory address. Some commands, such as `x`, use this default value if no address is specified.

Examples

```
memory set 0x8000 0 "Hello"  # Writes a string to memory
memory set 0x1000 0 {(char)0x10,(char)0xFF,(char)1,(char)2,(char)3,(char)42}
                              # Is equivalent to the following commands:
                                    # set variable *(char*)0x1000 = (char)0x10
                                    # set variable *(char*)0x1001 = (char)0xFF
                                    # set variable *(char*)0x1002 = (char)1
                                    # set variable *(char*)0x1003 = (char)2
                                    # set variable *(char*)0x1004 = (char)3
                                    # set variable *(char*)0x1005 = (char)42
memory set 0x1008 0 0x1234   # Equivalent to set variable *(int*)0x1008 = 0x1234
memory set 0x1008 8 0x1234   # Same effect but forces use of 4 writes of one byte each
```

Related references

1.2.9 Memory group on page 1-31

1.3.91 memory set_typed

Writes a list of values to memory.

Syntax

`memory set_typed <address> <type> <expressions>`

Where:

`<address>`

Specifies an address at which to write the first value. The address must be correctly aligned for the specified `<type>`.

`<type>`

Specifies the data type to which each of the series of expressions is converted and the width of each value in memory. For example, long.

`<expressions>`

Specifies a space separated list of expressions. If an expression contains spaces it must be enclosed in parentheses. The expressions are evaluated, converted to the specified type, and then written to memory sequentially.

Note

This command sets a default address variable to the value of the memory address. Some commands, such as `x`, use this default value if no address is specified.

Examples

```
memory set_typed 0x8000 (long long) 0x100 0x200
                 # Is equivalent to the following commands:
                     # set variable *((long long*)0x8000) = (long long)0x100
                     # set variable *((long long*)0x8008) = (long long)0x200
```

Related references

1.2.9 Memory group on page 1-31

1.3.92 mmu list memory-maps, mpu list memory-maps

Lists the available memory maps and their associated parameters.

Syntax

```
mmu list memory-maps
```

```
mpu list memory-maps
```

Examples

```
mmu list memory-maps
Available memory maps:
  PL1S_S1
    parameters: S_SCTLR, S_TTBCR, S_TTBR0, S_TTBR1
  PL1N_S1
    parameters: N_TTBR1, N_TTBCR, N_SCTLR, N_TTBR0

mpu list memory-maps
Available memory maps:
  MPU
```

Related references

1.2.12 mmu on page 1-33
1.2.14 mpu on page 1-35
1.2.15 mpu list on page 1-35

1.3.93 mmu list tables, mpu list tables

Lists the available translation tables and their associated parameters.

Syntax

```
mmu list tables

mpu list tables
```

Examples

```
mmu list tables
Available translation tables:
  PL1S_S1_TTBR0
    parameters: S_TTBCR, S_TTBR0, S_SCTLR
  PL1S_S1_TTBR1
    parameters: S_TTBCR, S_TTBR1, S_SCTLR
  PL1N_S1_TTBR0
    parameters: N_TTBCR, N_TTBR0, N_SCTLR
  PL1N_S1_TTBR1
    parameters: N_TTBCR, N_TTBR1, N_SCTLR

mpu list tables
Available translation tables:
  MPU_MPU_S
  MPU_MPU_NS
  MPU_SAU
  MPU_IDAU
```

Related references

1.2.12 mmu on page 1-33

1.2.14 mpu on page 1-35

1.2.15 mpu list on page 1-35

1.3.94 mmu list translations

Lists the available translations and their associated parameters.

Syntax

```
mmu list translations
```

Examples

```
mmu list translations
Available address translations:
  PL1S_S1
    parameters: S_SCTLR, S_TTBCR, S_TTBR0, S_TTBR1
  PL1N_S1
    parameters: N_TTBR1, N_TTBCR, N_SCTLR, N_TTBR0
```

Related references

1.2.12 mmu on page 1-33

1.3.95 mmu memory-map, mpu memory-map

Prints the memory map.

Syntax

```
mmu memory-map [<memory-map>] [<param1>=<value1>]...

mpu memory-map [<memory-map>] [<param1>=<value1>]...
```

Where:

<memory-map>

Specifies the memory map to print. If you do not specify a memory map, then the command prints the most relevant memory map.

<param1>=<value1>

Specifies a parameter and its value to govern the interpretation of the memory map. If you do not specify a required parameter, then it is determined from the current target state.

Examples

```
mmu memory-map PL1S_S1 S_TTBR1=0x80000404A
Virtual Range         | Physical Range        | Type   | AP | C     | S    | X
-------------------------------------------------------------------------------
0x00000000-0x00007FFF | <unmapped>
0x00008000-0x00008FFF | 0x8DC4B000-0x8DC4BFFF | Normal | RO | True  | True | True
0x00009000-0x00009FFF | 0x8DC4D000-0x8DC4DFFF | Normal | RO | True  | True | True
0x0000A000-0x0000AFFF | 0x8DC69000-0x8DC69FFF | Normal | RO | True  | True | True
0x0000B000-0x0000BFFF | 0x8DC6B000-0x8DC6BFFF | Normal | RO | True  | True | True
0x0000C000-0x0000CFFF | 0x8DE2B000-0x8DE2BFFF | Normal | RO | True  | True | True
0x0000D000-0x0000DFFF | 0x8DC9E000-0x8DC9EFFF | Normal | RO | True  | True | True
0x0000E000-0x0000EFFF | 0x80EB0000-0x80EB0FFF | Normal | RO | True  | True | True

mpu memory-map
Virtual Range         | Physical Range        | Type          | SA     | AP (Priv) | AP
(Unpriv) | X     | C     | S
-------------------------------------------------------------------------------------------------------
--------------------------
0x00000000-0x1FFFFFFF | 0x00000000-0x1FFFFFFF | Normal        | SECURE | RW        |
RW          | True  | True  | False
0x20000000-0x3FFFFFFF | 0x20000000-0x3FFFFFFF | Normal        | SECURE | RW        |
RW          | True  | False | False
0x40000000-0x5FFFFFFF | 0x40000000-0x5FFFFFFF | Device-nGnRE  | SECURE | RW        |
RW          | False | False | True
0x60000000-0x7FFFFFFF | 0x60000000-0x7FFFFFFF | Normal        | SECURE | RW        |
RW          | True  | False | False
0x80000000-0x9FFFFFFF | 0x80000000-0x9FFFFFFF | Normal        | SECURE | RW        |
RW          | True  | True  | False
0xA0000000-0xDFFFFFFF | 0xA0000000-0xDFFFFFFF | Device-nGnRE  | SECURE | RW        |
RW          | False | False | True
0xE0000000-0xE00FFFFF | 0xE0000000-0xE00FFFFF | Device-nGnRnE | SECURE | RW        |
RW          | False | False | True
0xE0100000-0xFFFFFFFF | 0xE0100000-0xFFFFFFFF | Device-nGnRE  | SECURE | RW        |
RW          | False | False | True
```

Related references

1.2.12 mmu on page 1-33
1.2.14 mpu on page 1-35

1.3.96 mmu print, mpu print

Prints the contents of a translation table.

Printing translation tables might be slow on some targets because it might involve a full traversal of the translation tables on the target.

Syntax

`mmu print [<table>] [<param1>=<value1>]...`

`mpu print [<table>] [<param1>=<value1>]...`

Where:

<table>

Specifies the translation table to print. If you do not specify a table, the command prints all tables for the current translation regime.

<param1>=<value1>

Specifies a parameter and its value to govern the interpretation of the table. If you do not specify a required parameter, then it is determined from the current target state.

Examples

```
mmu print PL1S_S1_TTBR0
SP:0x80F15000
```

```
Input Address | Type          | Next Level      | Output Address   | Properties
-------------------------------------------------------------------------------
+ 0x00000000  | TTBR0         | SP:0x0080500000 |                  |
 - 0x00000000 | Fault (x704)  |                 |                  |
 - 0x2C000000 | Section       |                 | SP:0x002C000000  | NS=0, nG=0, S=0
 - 0x2C100000 | Fault (x1343) |                 |                  |
 - 0x80000000 | Section       |                 | SP:0x0080000000  | NS=0, nG=0, S=1
 - 0x80100000 | Fault (x2047) |                 |                  |
+ 0xFFFFFFFF  | TTBR1         | SP:0x009082C300 |                  |

mpu print
Base                 | Limit       | Type    | Properties
-----------------------------------------------------------------------------------------------
--------
+ MPU (Secure)       |             |         | ENABLE=0, HFNMIENA=0, PRIVDEFENA=0, MAIR 0=0x0,
MAIR 1=0x0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
+ MPU (Non-Secure)   |             |         | ENABLE=0, HFNMIENA=0, PRIVDEFENA=0, MAIR 0=0x0,
MAIR 1=0x0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
 - 0x00000000        | 0x00000000  | Region  | SH=0, AP=0, XN=0, AttrIndex=0, EN=0
+ SAU                |             |         | ALLNS=0, ENABLE=0
 - 0x00000000        | 0x00000000  | Region  | NSC=0, ENABLE=0
 - 0x00000000        | 0x00000000  | Region  | NSC=0, ENABLE=0
 - 0x00000000        | 0x00000000  | Region  | NSC=0, ENABLE=0
 - 0x00000000        | 0x00000000  | Region  | NSC=0, ENABLE=0
 - 0x00000000        | 0x00000000  | Region  | NSC=0, ENABLE=0
 - 0x00000000        | 0x00000000  | Region  | NSC=0, ENABLE=0
+ IDAU               |             |         | [Not Configured]
```

Related references

1.2.12 mmu on page 1-33
1.2.14 mpu on page 1-35

1.3.97 mmu translate

Performs translations between virtual and physical addresses.

It translates either:
- From a virtual address to a physical address.
- From a physical address to one or more virtual addresses.

Physical to virtual address translation might be slow on some targets because it might involve a full traversal of the translation tables on the target.

Syntax

```
mmu translate <address> [<translation>][<param1>=<value1>]...
```

Where:

`<address>`

Specifies the address to translate. If this is a virtual address then a virtual to physical address translation is performed. If this is a physical address then a physical to virtual address translation is performed.

`<translation>`

Specifies the translation to perform.

`<param1>=<value1>`

Specifies a parameter and its value to govern the interpretation of the table. If you do not specify a required parameter, then it is determined from the current target state.

Examples

```
mmu translate 0x00008000 PL1S_S1 S_TTBR1=0x80000404A

SP:0x80F15000

mmu translate SP:0x80F15000
Address SP:0x80F15000 maps to
0x00008000
0x80F15000
```

Related references

1.2.12 mmu on page 1-33

1.3.98 newvar

Declares and initializes a new debugger convenience variable.

Syntax

`newvar [global] $<name>[=<initial_value>]`

Where:

`global`

Specifies that the variable has global scope. If global is not specified, then the variable is only accessible within its enclosing lexical scope.

`<name>`

Specifies the name of the new variable. The name must be a valid C identifier but prefixed with $.

`<initial_value>`

Specifies the initial value of the variable. If an initial value is not specified, then by default, the variable is of integer type with value 0.

- Debugger scripts and the top-level interactive interpreter are considered separate lexical scopes where non-global convenience variables are not visible to any child or parent debugger script
- The if, else, and while commands define new lexical scopes that inherit parent lexical scopes up to the level of a script, top-level interpreter, or user-defined command.
- Any non-global convenience variables, declared within a lexical scope, are destroyed at the end of the lexical scope.

Examples

```
define advance_hw    # This defines a new command that runs
                     # to an address using a hardware breakpoint.
  hbreak $arg0       # Set a hardware breakpoint at the value of the first parameter.
  newvar $bp_num = $ # Save the number of the breakpoint in a new variable.
  continue
  wait
  delete $bp_num     # Delete the hardware breakpoint.
end
advance_hw 0x00008000
```

Related references

1.2.4 Scripts on page 1-25

1.3.99 next

Steps through an application at the source level stopping at the first instruction of each source line but stepping over all function calls. You must compile your code with debug information to use this command successfully.

Syntax

`next [<count>]`

Where:

<count>
Specifies the number of source lines to execute.

Note

Execution stops immediately if a breakpoint is reached, even if fewer than <count> source lines are executed.

Examples

```
next                                    # Execute one source line
next 5                                  # Execute five source lines
```

Related references

1.3.190 step on page 1-157
1.3.191 stepi on page 1-158
1.3.192 steps on page 1-159
1.3.100 nexti on page 1-111
1.3.101 nexts on page 1-111
1.2.2 Execution control on page 1-22

1.3.100 nexti

Steps through an application at the instruction level but stepping over all function calls.

Syntax

nexti [<count>]

Where:

<count>
Specifies the number of instructions to execute.

Note

Execution stops immediately if a breakpoint is reached, even if fewer than <count> instructions are executed.

Examples

```
nexti                                    # Execute one instruction
nexti 5                                  # Execute five instructions
```

Related references

1.3.190 step on page 1-157
1.3.191 stepi on page 1-158
1.3.192 steps on page 1-159
1.3.99 next on page 1-110
1.3.101 nexts on page 1-111
1.2.2 Execution control on page 1-22

1.3.101 nexts

Steps through an application at the source level stopping at the first instruction of each source statement but stepping over all function calls. You must compile your code with debug information to use this command successfully.

Syntax

`nexts [<count>]`

Where:

`<count>`

Specifies the number of source statements to execute.

Note

Execution stops immediately if a breakpoint is reached, even if fewer than `<count>` source statements are executed.

Examples

```
nexts                                   # Execute one source statement
nexts 5                                 # Execute five source statements
```

Related references

1.3.190 step on page 1-157
1.3.191 stepi on page 1-158
1.3.192 steps on page 1-159
1.3.99 next on page 1-110
1.3.100 nexti on page 1-111
1.2.2 Execution control on page 1-22

1.3.102 nosharedlibrary

Discards all loaded shared library symbols.

Note

You must launch the debugger with `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

`nosharedlibrary`

Examples

```
nosharedlibrary     # Discards loaded shared library symbols
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.3.103 output

Displays only the result of an expression. This is similar to the **print** command but it does not record the results in a debugger variable.

Syntax

`output [/<flag>] <expression>`

Where:

`<flag>`

Specifies the output format:

x

Hexadecimal (casts the value to an unsigned integer prior to printing in hexadecimal)

d

Signed decimal. This is the default.

u

Unsigned decimal

o

Octal

t

Binary

a

Absolute hexadecimal address

c

Character

f

Floating-point

s

Default format from the expression.

<expression>

Specifies an expression that is evaluated and the result is returned.

Note

If your expression accesses memory then a default address variable is set to the location after the last accessed address. Some commands, such as x, use this default value if no address is specified.

Examples

```
output (int*)8                  # Cast a number as a pointer
output 4+4                      # Display result of expression in decimal
output "initializing..."        # Display progress information
output /x $PC                   # Display address in PC register (hexadecimal)
```

Related references

1.2.16 Display on page 1-35

1.3.104 pause

Pauses the execution of a script for a specified period of time.

Syntax

```
pause <number> [ms|s]
```

Where:

<number>

Specifies the period of time.

ms

Specifies the time in milliseconds. This is the default.

s

Specifies the time in seconds.

Examples

```
pause 1000                                  # Pause for 1 second
pause 0.5s                                  # Pause for half a second
```

Related references

1.2.24 Support on page 1-46

1.3.105 preprocess

Displays the preprocessed expression, not the evaluated expression.

Syntax

```
preprocess [<expression>]
```

Note

This functionality is dependent on the compiler generating accurate macro debug information.

Examples

If your application contained the following code:

```
#define BASE_ADDRESS (0x1000)
#define REG_ADDRESS  (BASE_ADDRESS + 0x10)

int main () {
    return REG_ADDRESS;
}
```

During a debug session, you can display the REG_ADDRESS by using:

```
>preprocess REG_ADDRESS
((0x1000) + 0x10)
```

This compares with the expression value as output by the print command:

```
>print/x REG_ADDRESS
0x1010
```

Related references

1.2.24 Support on page 1-46

1.3.106 print, inspect

Displays the output of an expression (128 character limit) and also records the result in a new debugger variable, `$<n>`, where `<n>` is a number. Results from the `print` command can be used successively in expressions using the `$` character. If you do not want the results recorded in a debugger variable, use the `output` command instead.

Syntax

`print [/<flag>] [<expression>]`

`inspect [/<flag>] [<expression>]`

Where:

<flag>

Specifies the output format:

x

Hexadecimal (casts the value to an unsigned integer prior to printing in hexadecimal)

d

Signed decimal. This is the default.

u

Unsigned decimal

o

Octal

t

Binary

a

Absolute hexadecimal address

c

Character

f

Floating-point

s

Default format from the expression.

<expression>

Specifies an expression that is evaluated and the result is returned. If no <expression> is specified then the last expression is repeated.

Note

If your expression accesses memory then a default address variable is set to the location after the last accessed address. Some commands, such as x, use this default value if no address is specified.

Examples

```
print (int*)8                   # Cast a number as a pointer
print 4+4                       # Display result of expression in decimal
print "initializing..."         # Display progress information
print /x $PC                    # Display address in PC register (hexadecimal)
```

Related references

1.2.16 Display on page 1-35

1.3.107 pwd

Displays the current working directory.

Syntax

pwd

Examples

```
pwd      # Display current working directory
```

Related references

1.2.7 Files on page 1-29

1.3.108 quit, exit

Quits the debugger session.

Syntax

`quit`

`exit`

Examples

```
quit     # Quit debugger session
```

Related references

1.2.24 Support on page 1-46

1.3.109 reload-symbol-file

Reloads debug information from an already loaded image into the debugger using the same settings as the original load operation. For example, you can use this command to reload debug information into the debugger after you have rebuilt your image.

Note

The PC register is not set with this command.

Syntax

`reload-symbol-file [<filename>]`

Where:

`<filename>`

Specifies the image to reload. If it is not already loaded then an error is generated.

Examples

```
reload-symbol-file "myFile.axf"     # Reload debug information
```

Related references

1.2.7 Files on page 1-29

1.3.110 reset

Performs a reset on the target. The exact behavior of the `reset` command depends on the debug agent and the target.

For example:

- A debug agent can be configured to reset the target in different ways.
- The position of the switches on the target.
- A `gdbserver` connection can be configured to restart gdbserver and run scripts.

For more information, see the documentation for your target or debug agent.

Note

`reset` does not affect the symbols loaded in the debugger. Registers and memory might contain different values after a reset.

Syntax

`reset [<key>]`

Where:

<key>

Specifies the reset key. The reset capabilities are target dependent and might not all be enabled. You can use `info capabilities` to display a list of capability settings for the target device that is currently connected to the debugger.

Possible options for the reset key are:

app

Application restart.

bus

Bus reset.

jtag

JTAG reset, applied to the nTRST signal.

system

General hardware reset that is not specific to a bus or processor.

If no `key` is specified, then the first enabled reset capability is performed.

Examples

```
reset                           # Performs the first enabled reset capability
reset app                       # Performs an application restart
reset system                    # Performs a general hardware reset
reset bus                       # Performs a bus reset
reset jtag                      # Performs a JTAG (nTRST) reset
```

Related references

1.2.2 Execution control on page 1-22

1.3.111 resolve

Re-evaluates the specified breakpoints or watchpoints and those with addresses that can be resolved are set. Unresolved addresses remain pending.

Syntax

`resolve [<number>] ...`

Where:

<number>

Specifies the breakpoint or watchpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

If no `<number>` is specified, then all breakpoints and watchpoints are re-evaluated.

Examples

```
resolve 1                     # Resolve breakpoint/watchpoint number 1
resolve 1 2                   # Resolve breakpoints/watchpoint number 1 and 2
resolve                       # Resolve all breakpoints/watchpoints
resolve $                     # Resolve the breakpoint/watchpoint whose number is in the
                              # most recently created debugger variable
```

Related references

1.3.6 break on page 1-58
1.3.41 hbreak on page 1-78
1.3.193 tbreak on page 1-159
1.3.194 thbreak on page 1-161
1.3.15 clear on page 1-63
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.112 restore

Reads data from a file and writes it to memory.

Syntax

`restore <filename> [binary] [<offset> [<start_address> [<end_address>|+<size>]]]`

Where:

`<filename>`

Specifies the file.

`binary`

Specifies binary format. The file format is only required for binary files. All other files are automatically recognized by the debugger. See the `append` command for a list of the file formats supported by the debugger.

`<offset>`

Specifies an offset that is added to all addresses in the image prior to writing to memory. Some image formats do not contain embedded addresses and in this case the offset is the absolute address where the image is restored.

`<start_address>`

Specifies the minimum address that can be written to. Any data prior to this address is not written. If no `<start_address>` is given then the default is address zero.

`<end_address>`

Specifies the maximum address that can be written to. Any data after this address is not written. If no `<end_address>` is given then the default is the end of the address space.

`<size>`

Specifies the size of the region.

Examples

```
restore myFile.bin binary 0x200        # Restore content of binary file
                                       # myFile.bin starting at 0x200
restore myFile.m32 0x100 0x8000 0x8FFF # Add 0x100 to addresses in Motorola
                                       # 32-bit (S-records) file and restore
                                       # content between 0x8000-0x8FFF
```

Related references

1.2.7 Files on page 1-29
1.2.9 Memory group on page 1-31

1.3.113 run

Starts running the target.

Bare-metal

This command sets the PC register to the entry point address previously recorded by the `load`, `loadfile`, or `file` command and starts running the target. Subsequent `run` commands also reload the executable image if it follows a previous load operation.

Linux application

This command sends a request to the server to restart the application and then start running it.

Note

Control is returned as soon as the target is running. You can use the `wait` command to block the debugger from returning control until either the application completes or a breakpoint is hit.

Syntax

`run [<args>]`

Where:

`<args>`

Specifies the command-line arguments that are passed to the `main()` function in the application using the `argv` parameter. The name of the image is always implicitly passed in `argv[0]` and it is not necessary to pass this as an argument to the run command.

Examples

```
run      # Start running the device
```

1.3.114 rwatch

Sets a watchpoint for a data symbol. The debugger stops the target when the memory at the specified address is read.

This command records the ID of the watchpoint in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the watchpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Watchpoints are only supported on scalar values.

The availability of watchpoints depends on your target. In the case of Linux application debug using *gdbserver*, the availability of watchpoints also depends on the Linux kernel version and configuration.

The address of the instruction that triggers the watchpoint might not be the address shown in the PC register. This is because of pipelining effects.

Syntax

`rwatch [-d] [-p] [-w <width>] [<filename>:]<symbol> | <*address> [vmid <number>] [if <condition>]`

Where:

`-d`

Creates the watchpoint disabled.

`-p`

Specifies whether or not the resolution of an unrecognized watchpoint location results in a pending watchpoint being created.

-w <width>

Specifies the width to watch at the given address, in bits. Accepted values are: 8, 16, 32, and 64 if supported by the target. This parameter is optional.

The width defaults to:

- 32 bits for an address.
- The width corresponding to the type of the symbol or expression, if entered.

<filename>

Specifies the file.

<symbol>

Specifies a global/static data symbol. For arrays or structs you must specify the element or member.

<address>

Specifies the address. This can be either an address or an expression that evaluates to an address.

vmid <number>

Specifies the Virtual Machine ID (VMID) to apply the watchpoint to. This can be either an integer or an expression that evaluates to an integer. Applicable only on targets which support hypervisor / virtual machine debugging.

if <condition>

Specifies the condition which must evaluate to true at the time the watchpoint is triggered for the target to stop. You can create several conditional watchpoints, but when a conditional watchpoint is enabled, no other watchpoints (regardless of whether they are conditional) can be enabled.

Examples

```
rwatch myVar1                        # Set read watchpoint on myVar1
rwatch *0x80D4                       # Set read watchpoint on address 0x80D4
rwatch myVar1 if myVar1 == 2         # Set read watchpoint on myVar1 which
                                     # will only be hit if myVar1 evaluates to 2
rwatch myVar1 if $LR & 0xFF == 0x12 # Set read watchpoint on myVar1 which
                                     # will only be hit if ($LR & 0xFF) evaluates
                                     # to 0x12 when myVar1 is accessed
```

Related references

1.3.212 watch on page 1-175
1.3.16 clearwatch on page 1-64
1.3.5 awatch on page 1-57
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.115 select-frame

Moves the current frame pointer in the call stack.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

```
select-frame <number>
```

Where:

<number>

Specifies the frame number.

Examples

```
select-frame 1      # Move to stack frame 1
```

Related references

1.2.5 Call stack on page 1-26

1.3.116 set arm

Controls the behavior of the debugger when selecting the instruction set for disassembly and setting breakpoints.

Note

Available instruction sets depend on the target that the debugger is connected to.

Syntax

`set arm <option>`

Where:

<option>

Specifies additional options:

force-mode

Controls the default debugger behavior overriding the `fallback-mode` setting.

a32|arm

Forces the debugger to use the A32 instruction set.

a64

Forces the debugger to use the A64 instruction set.

t32|thumb

Forces the debugger to use the T32 instruction set.

auto

Forces the debugger to use debug information when available or the `fallback-mode` if this is not available. This is the default.

fallback-mode

Controls the default debugger behavior when `force-mode` is set to auto and debug information is not available.

a32|arm

Forces the debugger to use the A32 instruction set when debug information is not available.

a64

Forces the debugger to use the A64 instruction set when debug information is not available.

t32|thumb

Forces the debugger to use the T32 instruction set when debug information is not available.

auto

Forces the debugger to use the current instruction set of the target. This is the default.

Examples

```
set arm force-mode t32                    # Force the use of T32
set arm fallback-mode a32                 # When force-mode is auto, use A32
                                          # if no debug information is available
```

Related references

1.2.19 Set on page 1-39

1.2.24 Support on page 1-46

1.3.117 set auto-solib-add

Controls the automatic loading of shared library symbols.

Note

You must launch the debugger with the `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
set auto-solib-add {off|on}
```

Where:

off

No automatic loading. When automatic loading is off you must explicitly load shared library symbols using the `sharedlibrary` command.

on

Loads shared library symbols automatically. This is the default.

Examples

```
set auto-solib-add off      # No automatic loading of shared library symbols
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.19 Set on page 1-39

1.3.118 set backtrace

Controls the default behavior when using the `info stack` command.

Syntax

```
set backtrace <option>
```

Where:

<option>

Specifies additional options:

limit <n>

Specifies the maximum limit when displaying the call stack. You can specify zero as the maximum limit to display the entire call stack.

The default call stack limit is 100.

Examples

```
set backtrace limit 10          # Limit the call stack display to 10 frames
set backtrace limit 0           # No limit, display the entire call stack
```

Related references

1.2.5 Call stack on page 1-26

1.2.19 Set on page 1-39

1.3.119 set blocking-run-control

Controls whether run control operations such as stepping and running are blocked until the target stops or released immediately.

Syntax

`set blocking-run-control {off|on|script-only}`

Where:

off

Specifies asynchronous, control is returned before the target stops.

on

Specifies synchronous, run control operations are blocked until the target stops. This has the same effect as issuing a wait command after each run control operation.

script-only

Specifies that run control operations block only when executed as commands from within a script.

This is the default.

Examples

```
set blocking-run-control on     # Block run control operations until target stops
```

Related references

1.2.2 Execution control on page 1-22

1.2.19 Set on page 1-39

1.3.120 set breakpoint

Controls the automatic behavior of breakpoints and watchpoints.

Syntax

`set breakpoint [<option>]`

Where:

<option>

Specifies additional options:

auto-hw

Controls the automatic breakpoint selection when using the `break` command:

off

Disables automatic breakpoint selection.

on

Uses the memory map attributes to decide if hardware or software breakpoints must be used. This is the default.

auto-remove

Controls the automatic removal of breakpoints and watchpoints when disconnecting from the target:

off

Disables automatic removal.

on

Enables automatic removal. This is the default.

Note

If the target is running, the debugger temporarily stops the target before removing breakpoints and watchpoints.

skipmode

Controls whether to skip all breakpoints and watchpoints:

off

Disables skip mode. This is the default.

on

Enables skip mode.

Examples

```
set breakpoint auto-hw off        # No automatic breakpoint selection
set breakpoint skipmode on        # Skip all breakpoints and watchpoints
set breakpoint auto-remove off    # No automatic removal of breakpoints and watchpoints
```

Related references

1.3.23 disable breakpoints on page 1-68
1.3.20 delete breakpoints on page 1-66
1.3.47 info breakpoints on page 1-83
1.3.78 info watchpoints on page 1-96
1.3.49 info capabilities on page 1-84
1.3.48 info breakpoints capabilities on page 1-83
1.3.79 info watchpoints capabilities on page 1-97
1.2.1 Breakpoints and watchpoints on page 1-20
1.2.19 Set on page 1-39

1.3.121 set case-insensitive-source-matching

Controls the case sensitivity of debugger file matching operations.

Syntax

```
set case-insensitive-source-matching [off|on]
```

Where:

off

Specifies case sensitive file matching. This is the default.

on

Specifies case insensitive file matching. This is useful if the file paths or filenames in the debug data have a different case to those in the filesystem.

Examples

```
# By default the debugger performs case sensitive file matching.
# Assume that the debug data contains the filename main.c.
break -p "C:/example/Main.c":2              # This fails because Main.c does not match
main.c.
WARNING(CMD452-COR167):
! Breakpoint 8 has been pended
! No compilation unit matching "C:/example/Main.c" was found.

set case-insensitive-source-matching on     # case insensitive matching.
break -p "C:/EXAmple/Main.c"                # This file matching operation succeeds.
Breakpoint 9 at S:0x000080A8
    on file main.c, line 2
```

Related references

1.2.19 Set on page 1-39

1.3.122 set cde-coprocessors

Specify the coprocessors that are associated with the Arm Custom Datapath Extension (CDE).

Default

By default, coprocessors are associated with the General CoProcessor (GCP) encoding.

Syntax

```
set cde-coprocessors <coprocessor>=<type>[, <coprocessor>=<type>[, ...]]
```

Where:

<coprocessor>

Specifies the coprocessor. Valid values are `P0` to `P7`.

<type>

Specifies the encoding pattern the coprocessor supports. The types are:

CDE

Support the CDE encoding pattern.

GCP

Support the GCP encoding pattern.

Note

You can provide multiple coprocessor associations in a single command, separated by commas.

Example: specify a single coprocessor association

```
set cde-coprocessors p1=cde                 # Associates coprocessor P1 with the CDE.
                                            # All other coprocessors default to the
                                            # general coprocessor encoding.
```

Example: specify multiple coprocessor associations

```
set cde-coprocessors p1=cde, p4=gcp, p5=cde  # Associates coprocessor P1 and P5 with
                                             # the CDE.
```

Related references

1.3.159 show cde-coprocessors on page 1-145

1.3.123 set debug-agent

Sets an internal configuration parameter for the debug agent. The available parameters depend on the debug agent, such as the DSTREAM family of devices or gdbserver.

Syntax

```
set debug-agent <name> <value>
```

Where:

<name>

Specifies the name of the parameter to set.

<value>

Specifies the value of the parameter. Values depend on the parameter being set. An error is reported if the value is not valid.

Examples

```
set debug-agent UserOut_P1 1

# Set value of USER OUT pin1 to 1.
# This parameter is available for DSTREAM connections.
```

Related references

1.2.19 Set on page 1-39

1.3.124 set debug-from

Specifies the address of the temporary breakpoint for subsequent use by the `start` command. If you do not specify this command then the default value used by the `start` command is the address of the global function `main()`.

Syntax

```
set debug-from <expression>
```

Where:

<expression>

Specifies an expression that evaluates to an address. The expression is only evaluated when the `start` command is processed, therefore, you can refer to symbols that might not exist yet but might be made available in the future. You can use the debugger variable `$entrypoint` to refer to the entry point for the currently loaded image.

Examples

```
set debug-from *0x8000          # Set start-at setting to address 0x8000
set debug-from *$entrypoint     # Set start-at setting to address of $entrypoint
set debug-from main+8           # Set start-at setting to address of main+8
set debug-from function1        # Set start-at setting to address of function1
```

Related references

1.2.2 Execution control on page 1-22

1.2.19 Set on page 1-39

1.3.125 set dtsl-options

Sets a parameter in the DTSL configuration.

Syntax

```
set dtsl-options <name> <value>
```

Where:

<name>

Specifies a name of the parameter to set.

<value>

Specifies the value of the parameter. Values depend on the parameter being set. An error is reported if the value is not valid.

Examples

```
set dtsl-options options.cortexA9.coreTrace.cycleAccurate False

# Set DTSL configuration cycle Accurate parameter to false
```

Related references

1.2.19 Set on page 1-39

1.3.126 set dtsl-temporary-directory

Specifies the path for the temporary directory to store trace data.

Syntax

```
set dtsl-temporary-directory <path>
```

Where:

<path>

Specifies the location of your temporary directory, for example, `C:my_temp_dir`.

———— **Note** ————

This command can only set the path to an existing directory location. You must create the directory before using this command.

————————————

To clear the setting and revert to the default system directory, enter `set dtsl-temporary-directory ""`.

You can also use the **Arm DS Preferences** dialog box to set trace data temporary directory. To do this:

1. From the Arm DS menu, select **Window** > **Preferences**.
2. Browse to **Arm DS** > **Debugger** > **Trace**.
3. Select the **Use custom directory for temporary trace data files** option.
4. Enter or **Browse** the path to your temporary directory.

Examples

```
set dtsl-temporary-directory C:\my_temp_dir      # Set DTSL temporary directory path as
C:\my_temp_dir.
```

Related references

1.2.19 Set on page 1-39

1.3.127 set elf cache-uninitialized-sections

Controls whether the debugger caches uninitialized sections.

After the symbols for an image are loaded, the debugger by default marks regions corresponding to ELF sections as cacheable if:

- The section has `sht_type` that is set to one of:
  - `SHT_PROGBITS`
  - `SHT_INIT_ARRAY`
  - `SHT_FINI_ARRAY`
  - `SHT_PREINIT_ARRAY`
  - `SHT_NOBITS`.
- The `SHF_ALLOC` flag in `sh_flags` is set for the section.

This can result in uninitialized sections, or volatile regions of the address space, for example peripherals, being set to cacheable by default. To overcome this problem, you can use `set elf cache-uninitialized-sections off` to disable the debugger from caching such ELF sections.

Syntax

```
set elf cache-uninitialized-sections {off|on}
```

Where:

`off`

Disables caching of uninitialized sections.

`on`

Enables caching of uninitialized sections. This is the default.

Examples

```
set elf cache-uninitialized-sections off      # Disable caching of uninitialized sections
```

Related references

1.2.19 Set on page 1-39

1.3.128 set elf load-segments-at-p_paddr

Enables loading to the specified load offset + `p_paddr` when loading segments of ELF images to the target.

When loading segments of ELF images to the target, by default, the debugger loads to the specified load offset `+ p_vaddr` . If you want the debugger to load to the specified load offset `+ p_paddr` then enable `elf load-segments-at-p_addr`. (as specified in the ELF Program Header for that segment).

Note

The ELF Program Header for the corresponding segment specifies the `p_vaddr`.

Syntax

```
set elf load-segments-at-p_paddr {off|on}
```

Where:

`off`

Loads to the specified load offset + `p_vaddr`. This is the default.

`on`

Loads to the specified load offset + `p_paddr`.

Examples

```
set elf load-segments-at-p_paddr on      # Loads to the specified load offset + p_paddr
```

Related references

1.2.19 Set on page 1-39

1.3.129 set elf zero-extra-segment-bytes

Enables zeroing of bytes from `p_filesz` to `p_memsz` when loading segments of ELF images to the target.

When loading segments of ELF images to the target, by default, the debugger only writes `p_filesz` bytes to the target. If `p_filesz` is less than `p_memsz`, and you want the debugger to pad the region from `p_filesz` to `p_memsz` with zero then enable `elf zero-extra-segment-bytes`.

Note

The ELF Program Header for the corresponding segment specifies the `p_filesz`.

Syntax

```
set elf zero-extra-segment-bytes {off|on}
```

Where:

`off`

Disables zeroing. This is the default.

`on`

Enables zeroing the region from `p_filesz`

Examples

```
set elf zero-extra-segment-bytes on      # Enable zeroing from p_filesz to p_memsz
```

Related references

1.2.19 Set on page 1-39

1.3.130 set endian

Specifies the byte order for use by the debugger. The endianness of the target is not modified by this command.

Syntax

```
set endian {auto|be8|big|little}
```

Where:

`auto`

Uses the same byte order as the image where possible, otherwise it uses the current endianness of the target. This is the default.

`be8`

Specifies Byte Invariant Addressing big-endian mode introduced in the Armv6 architecture (data is big endian and code is little endian).

`big`

Specifies big endian mode.

`little`

Specifies little endian mode.

Examples

```
set endian little      # Debug using little endian
```

Related references

1.2.19 Set on page 1-39

1.2.24 Support on page 1-46

1.3.131 set escape-strings

Controls how special characters in strings are printed on the debugger command-line.

Syntax

```
set escape-strings {off|on}
```

Where:

off

Specifies that any backslash characters in strings are treated as escape sequences. For example, if the string contains "`\t`" then this is printed as a tab character.

This is the default.

on

Specifies that any backslashes in strings are not treated as escape sequences and are instead output literally. For example, if the string contains "`\t`" then this is printed as a "`\`" character followed by a "`t`" character.

Examples

```
set escape-strings on
output "Say \"hello\""
"Say \"hello\""
set escape-strings off
output "Say \"hello\""
"Say "hello""
```

Related references

1.2.19 Set on page 1-39

1.3.132 set escapes-in-filenames

Controls the use of special characters in paths.

Syntax

```
set escapes-in-filenames {off|on}
```

Where:

off

Specifies that a backslash in a path is treated as a directory separator (with the exception that it can be used to escape spaces). For example:

```
C:\test\file.c
```

The first backslash is treated as a separator followed by a t, not an escape sequence representing the tab character. The second backslash escapes the space.

This is the default.

on

Specifies that a backslash is to be treated as part of an escape sequence to indicate that the character following is a special character. For example:

```
C:\\test\\file.c
```

The backslash in this example is a directory separator and must be identified as a special character.

Examples

```
set escapes-in-filenames on      # Use backslash as an escape character in paths
```

Related references

1.2.19 Set on page 1-39

1.3.133 set idau-region

Specifies the Implementation Defined Attribution Unit (IDAU) region parameters for each memory range. Targets with Armv8-M Security Extension can provide an IDAU which constrains security attribution for an address in an IMPLEMENTATION DEFINED manner. To instruct Arm Debugger to take the IDAU into consideration, you must specify the IDAU region using the `set idau-region` command.

Syntax

```
set idau-region <region_number> <base_address> <limit_address> <region_type>
```

Where:

<region_number>

Specifies the number of the IDAU region.

To delete an existing IDAU region, specify the region number without any additional parameters.

<base_address>

Specifies the base address of the IDAU region.

<limit_address>

Specifies the last address of the IDAU region.

<region_type>

Specifies the type of security attribution that is provided by the IDAU region. The types are:

EXEMPT

Specifies if the region is exempt from security attribution.

SECURE

Specifies if the region is a secure region.

SECURE_NSC

Specifies if the region is a Non-secure Callable (NSC) memory region.

NON_SECURE

Specifies if the region is a Non-secure memory region.

Examples

```
set idau-region 10 0x80000000 0x8000ffff SECURE  # Set IDAU region 10,with base address
                                                 # 0x80000000, limit address 0x8000ffff,
```

```
                                                # and specify the region as SECURE.
set idau-region 10                              # Delete IDAU region 10
```

1.3.134 set listsize

Modifies the default number of source lines that the `list` command displays.

Syntax

```
set listsize <n>
```

Where:

`<n>`

Specifies the number of source lines.

Examples

```
set listsize 20      # Set listing size for list command
```

Related references

1.2.19 Set on page 1-39

1.3.135 set mmu use-cache-for-phys-reads

Instructs the debugger to, where possible, ensure that the translation table entries it reads from physical memory are coherent with the contents of data caches.

Syntax

```
set mmu use-cache-for-phys-reads {off|on}
```

Where:

`off`

Does not ensure coherency between physical memory reads and data caches. This is the default.

`on`

Ensures coherency between physical memory reads and data caches.

Examples

```
set mmu use-cache-for-phys-reads on      # Ensure coherent physical memory reads
```

Related references

1.2.12 mmu on page 1-33

1.2.19 Set on page 1-39

Related information

About debugging MMUs

1.3.136 set os

Controls operating system (OS) settings in the debugger. An OS-aware connection must be established before you can use this command.

Syntax

```
set os <option>
```

Where:

`<option>`

Specifies additional options:

enabled

Controls OS support:

auto

Automatically stops the target and enables OS support when an OS image is loaded into the debugger. For example, Linux kernel images are detected by reading the members for the structure returned by the expression `init_nsproxy.uts_ns->name`. Unloading the image disables OS support.

This is the default for Linux kernel connections.

deferred

Automatically enables OS support when an OS image is loaded into the debugger, but only when the target next stops. Unloading the image disables OS support.

This is the default for Real-Time Operating System (RTOS) aware connections.

off

Disables OS support.

on

Enables OS support. Use this option when the OS image is already loaded into the debugger and the target is stopped.

kernel-stack-size <bytes>

Specifies the number of bytes to use for the stack size.

log-capture

Controls logging to the console:

off

Disables OS log capture and printing of Linux kernel `dmesg` logs to the console. This is the default.

on

Enables OS log capture and printing to the console.

Note

This option automatically checks the connection state and, if required, stops the target before changing this setting.

physical-address

Specifies the physical address of where the kernel is loaded.

read-all-threads-on-stop

Controls the OS reading of threads:

off

Disables OS reading of threads when the target is stopped. This is the default.

on

Enables OS reading of threads when the target is stopped.

Examples

```
set os log-capture on              # Enable OS log capture and printing to the console
set os enabled off                 # Disable OS support in the debugger
set os physical-address 0x80080000 # Specifies the physical address
                                   # of where the kernel is loaded as 0x80080000.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.19 Set on page 1-39

1.3.137 set overlays enabled

Enables or disables overlay support. The default setting is auto.

Syntax

`set overlays enabled [on | off | auto]`

Where:

`on`

Enables overlay support.

`off`

Disables overlay support.

`auto`

If the required symbols are present in an image during load time, automatically enables overlay support. This is the default.

Examples

```
set overlays enabled on       # Enable overlay support
set overlays enabled off      # Disable overlay support
set overlays enabled auto     # Enable overlay support if overlay symbols are detected
```

1.3.138 set print

Controls the current debugger print settings.

Syntax

`set print <option>`

Where:

`<option>`

Specifies additional options:

`library-not-found-warnings`

Controls the printing of "unable to find library…" messages.

`off`

Disables these messages. This is the default.

`on`

Enables these messages.

`full-source-path`

Controls the printing of source file names in messages.

off

Disables printing the full path. This is the default.

on

Enables printing the full path.

stop-info

Controls the printing of event messages when the target stops.

off

Disables printing of event messages. This setting takes precedence over the `silence` and `unsilence` commands.

on

Enables printing of event messages. This is the default.

current-vmid

Controls the printing of current VMID messages when the target stops.

off

Disables printing of VMID messages. This is the default.

on

Enables printing of VMID messages.

double-format <format>

Controls the formatting of double precision floating-point values. `<format>` is a `printf()` style format string. The default is "`%,.16g`".

float-format <format>

Controls the formatting of single precision floating-point values. `<format>` is a `printf()` style format string. The default is "`%,.6g`".

Examples

```
set print library-not-found-warnings off  # Disable unfound library messages
set print full-source-path on             # Display full source path in messages
set print double-format %+g               # Print decimal scientific notation with sign
set print float-format %08.4e             # Print decimal scientific notation, zero-pad
                                          # min 8 characters, 4 digit precision
```

Related references

1.2.16 Display on page 1-35

1.2.19 Set on page 1-39

1.1.3 Expressions within Arm Development Studio on page 1-10

1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.139 set semihosting

Controls the semihosting settings in the debugger. Semihosting is used to communicate input/output requests from application code to the host workstation running the debugger.

Note

These settings only apply if the target supports semihosting and they cannot be changed while the target is running.

Syntax

`set semihosting <option>`

Where:

`<option>`

Specifies additional options:

`args <arguments>`

Specifies the command-line arguments that are passed to the `main()` function in the application using the `argv` parameter. The name of the image is always implicitly passed in `argv[0]` and it is not necessary to pass this as an argument.

`file-base <directory>`

Specifies the base directory where the files that the application opens are relative to.

`stderr "stderr "|<filename>`

Specifies either console streams or a file to write `stderr` for semihosting operations.

`stdin "stdin "|<filename>`

Specifies either console streams or a file to read `stdin` for semihosting operations.

`stdout "stdout "|<filename>`

Specifies either console streams or a file to write `stdout` for semihosting operations.

`top-of-memory <address>`

Specifies the top of memory.

`<stack_heap_options>`

Specifies finer controls to manually configure the base address and limits for the stack and heap. If you use `<stack_heap_options>`, then these settings take precedence over the top-of-memory and all of the following options must be specified:

`stack-base <address>`

The base address of the stack.

`stack-limit <address>`

The end address of the stack.

`heap-base <address>`

The base address of the heap.

`heap-limit <address>`

The end address of the heap.

`enabled`

Controls semihosting operations:

`auto`

Automatically enables semihosting operations if appropriate when an image is loaded. This is the default.

`off`

Disables all semihosting operations.

on

Enables all semihosting operations.

You might have to configure semihosting addresses before you enable semihosting. For example:

```
set semihosting top-of-memory address
set semihosting enabled on
```

vector

Allows you to specify the semihosting trap mechanism to use on your target.

ADDR <trap_address>

Specifies a breakpoint address for the vector catch. This instructs the debugger to set a breakpoint at the specified address. When the breakpoint is hit, the debugger takes control to perform the semihosting operation.

SVC

Uses `SVC` vector catch to trap semihosting operations.

UNDEF

Uses `UNDEF` vector catch to trap semihosting operations.

SVC+UNDEF

Uses `SVC+UNDEF` vector catch to trap semihosting operations.

Note

- On M-Profile targets, this command produces an error since semihosting is implemented using a compiled in software breakpoint (BKPT) on these targets.
- On Armv7 A or R profiles and classic Arm targets, you can use `SVC`, `UNDEF`, `SVC+UNDEF`, or the `ADDR <trap_address>` options to switch between vector catch operations.
- On Armv8-A targets, use `ADDR <trap_address>` to enable instruction breakpoint based semihosting.

Examples

```
set semihosting args 500                  # Set 500 as command-line argument
set semihosting stdout output.log         # Write stdout to output.log
set semihosting enabled on                # Enable semihosting operations
set semihosting vector svc                # Set the semihosting vector catch to SVC
set semihosting vector ADDR 0x800         # Set the semihosting vector catch to 0x00000800
```

Related references

1.2.19 Set on page 1-39

1.2.24 Support on page 1-46

Related information

Using semihosting to access resources on the host computer

1.3.140 set solib-absolute-prefix

Specifies the system root directory to search for shared library symbols.

The debugger uses this directory to search for a copy of the debug versions of target shared libraries. The system root on the host workstation must contain an exact representation of the libraries on the target root filesystem.

Note

You must launch the debugger with the `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
set solib-absolute-prefix <path>
```

Where:

`<path>`

Specifies the system root directory.

Examples

```
set solib-absolute-prefix "/mySystem"      # Set system root directory "/mySystem"
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.19 Set on page 1-39

1.3.177 show solib-absolute-prefix on page 1-152

1.3.141 set solib-search-path

Specifies additional directories to search for shared library symbols. If you use this command without an argument then any additional search directories, previously added using this command, are removed. You can use `show solib-search-path` command to display the current settings.

Note

You must launch the debugger with `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
set solib-search-path [<path>]...
```

Where:

`<path>`

Specifies an additional directory to search for shared libraries. The debugger uses the system root directory first, then it searches the additional directories specified with this command. You can use `set sysroot` to specify the system root directory.

Multiple directories can be specified but must be separated with either:

- a colon (Unix)
- a semi-colon (Windows).

Examples

```
set solib-search-path "\usr\lib"         # Specify search directory
set solib-search-path "/lib":"/My Lib"   # Specify two search directories(Unix)
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.19 Set on page 1-39

1.3.142 set step-mode

Controls the default behavior of the `step` and `steps` commands.

Syntax

```
setstep-mode {step-over|stop|step-until-source}
```

Where:

`step-over`

If the instruction is a function call then the debugger performs a step-over. Otherwise, it stops. This is the default.

`stop`

The debugger stops when execution reaches an address with no source.

`step-until-source`

The debugger performs steps until it reaches source. To speed up the execution, the debugger might use abstract interpretation and break or run until the line of source is reached.

Examples

```
set step-mode step-over             # Step over a function call and stop.
                                    # Otherwise stop
```

Related references

1.2.2 Execution control on page 1-22

1.2.19 Set on page 1-39

1.3.143 set stop-on-solib-events

Controls whether the debugger stops execution when a shared object is loaded or unloaded.

Note

You must launch the debugger with the `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
set stop-on-solib-events {off|on}
```

Where:

`off`

Ignore event. This is the default.

`on`

Stop execution. Use this option only when you want the debugger to stop execution. For example, you might want to set a breakpoint in a shared library prior to use or perhaps you might want to check the initialization of global variables.

Examples

```
set stop-on-solib-events on     # Stop execution when event occurs
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.19 Set on page 1-39

1.3.144 set substitute-path

Modifies the search paths used by the debugger when it executes any of the commands that look up and display source code. This command is useful when the source files have moved from the original location used during compilation.

Subsequent use of the `set substitute-path` command appends rules to the current list.

Syntax

```
set substitute-path <path1> <path2>
```

Where:

<path1>

Specifies the existing search path.

<path2>

Specifies the replacement search path.

Examples

```
set substitute-path "\src" "\My Src"    # Substitute "\src" with "\My Src"
```

Related references

1.2.7 Files on page 1-29

1.2.19 Set on page 1-39

1.3.145 set sysroot

Specifies the system root directory to search for shared library symbols.

The debugger uses this directory to search for a copy of the debug versions of target shared libraries. The system root on the host workstation must contain an exact representation of the libraries on the target root filesystem.

Note

You must launch the debugger with the `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
set sysroot <path>
```

Where:

<path>

Specifies the system root directory.

Examples

```
set sysroot "/mySystem"      # Set system root directory "/mySystem"
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.19 Set on page 1-39

1.3.146 set trust-ro-sections-for-opcodes

Controls whether the debugger can read opcodes from read-only sections of images on the host workstation rather than from the target itself.

Syntax

```
set trust-ro-sections-for-opcodes {off|on}
```

Where:

off

Disables this behavior. Use this option to trace self-modifying code or when the code on the target is modified before being loaded to the target.

Note

The Linux kernel often contains self-modifying code.

on

Enables reading opcodes from read-only sections of images on the host machine. Reading opcodes from the host workstation is usually faster than reading them from the target. This is the default.

Examples

```
set trust-ro-sections-for-opcodes on     # Enable reading opcodes from host
```

Related references

1.2.19 Set on page 1-39

1.3.147 set variable

Evaluates an expression and assigns the result to a variable, register, or memory address.

Syntax

```
set [variable] <expression>
```

Where:

<expression>

Specifies an expression and assigns the result to a variable, register, or memory address.

Examples

```
set variable myVar=10                              # Assign 10 to variable myVar
set variable $PC=0x8000                            # Assign address 0x8000 to
                                                   # PC register
set variable $CPSR.N=0                             # Clear N bit
set variable (*(int*)0x8000)=1                     # Assign 1 to address 0x8000
set variable *0x8000=1                             # Assign 1 to address 0x8000
set variable strcpy((char*)0x8000,"My String")     # Assign string to address 0x8000
set variable memcpy(void*)0x8000,{10,20,30,40},4)  # Assign array to address 0x8000
```

Related references

1.2.19 Set on page 1-39

1.3.61 info memory-parameters on page 1-89

Related information

Arm Architecture Reference Manual

1.3.148 set wildcard-style

Specifies the type of wildcard pattern matching you can use for examining the contents of strings.

Syntax

```
set wildcard-style glob|regex
```

Where:

glob

Specifies a simpler style of pattern matching using glob expressions to refine your search. For example, you can use `m*` to search for strings starting with `m`.

This is the default.

regex

Specifies a more complex style of pattern matching using regular expressions to refine your search. For example, you can use `my_lib[0-9]+` to search for strings starting with `my_lib` followed by an integer.

Examples

```
set wildcard-style regex     # Use regular expression pattern matching
```

Related references

1.2.19 Set on page 1-39

1.3.149 sharedlibrary

Loads symbols from shared libraries. It can only load symbols for shared libraries that are already loaded by the application.

Note

You must launch the debugger with `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

`sharedlibrary [<expression>]`

Where:

<expression>

Specifies a library path or a wildcard expression. You can use wildcard expressions to enhance your pattern matching.

If no `<expression>` is specified then the symbols from all shared libraries are loaded.

Examples

```
sharedlibrary                 # Load symbols from all shared libraries.
sharedlibrary m*              # Load symbols matching path starting with m
                              # (use when set wildcard-style=glob).
sharedlibrary .*my_lib[0-9]+  # Load symbols matching path that ends with my_lib
                              # followed by a number(use when set wildcard-style=regex).
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.3.150 shell

Runs a shell command within the debug session. The command is launched in the working directory. You can use to display the working directory.

Syntax

`shell <cmd>`

Where:

<cmd>

Specifies the command and associated arguments.

Examples

```
shell dir                   # On Windows, list files in directory.
shell cat my_script.ds      # On Linux, list contents of my_script.ds file.
```

Related references

1.2.24 Support on page 1-46

1.3.151 show

Displays the debugger settings.

Syntax

`show`

Examples

```
show         # Display debugger settings.
```

Related references

1.2.21 show group on page 1-42

1.3.152 show architecture

Displays the architecture of the target.

Syntax

`show architecture`

Examples

```
show architecture     # Display target architecture.
```

Related references

1.2.21 show group on page 1-42
1.2.24 Support on page 1-46

1.3.153 show arm

Displays the instruction set settings in use by the debugger for disassembly and setting breakpoints.

Syntax

`show arm <option>`

Where:

<option>

Specifies additional options:

force-mode

Display the current force-mode behavior.

fallback-mode

Display the current fallback-mode behavior.

Examples

```
show arm                        # Display the instruction set settings.
show arm force-mode             # Display the force-mode setting.
```

Related references

1.2.21 show group on page 1-42

1.2.24 Support on page 1-46

1.3.154 show auto-solib-add

Displays the automatic setting for use when loading shared library symbols. You can use the `set auto-solib-add` command to modify this setting.

Note

You must launch the debugger with the `target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
show auto-solib-add
```

Examples

```
show auto-solib-add          # Display automatic setting for loading
                             # shared library symbols.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.21 show group on page 1-42

1.3.155 show backtrace

Displays the behavior settings for use with the `info stack` command. You can use the `set backtrace` commands to modify these settings.

Syntax

```
show backtrace <option>
```

Where:

`<option>`

Specifies additional options:

`limit`

Displays the limit when listing the call stack.

Examples

```
show backtrace limit      # Display current call stack limit.
```

Related references

1.2.5 Call stack on page 1-26

1.2.21 show group on page 1-42

1.3.156 show blocking-run-control

Displays the setting for blocking run control operations such as stepping and running. You can use the `set blocking-run-control` command to modify this setting.

Syntax

```
show blocking-run-control
```

Examples

```
show blocking-run-control      # Display run control setting.
```

Related references

1.2.2 Execution control on page 1-22

1.2.21 show group on page 1-42

1.3.157 show breakpoint

Displays the breakpoint and watchpoint behavior settings. You can use the `set breakpoint` commands to modify these settings.

Syntax

```
show breakpoint <option>
```

Where:

`<option>`

Specifies additional options:

`auto-hw`

Displays the automatic breakpoint selection setting. This sets the type of breakpoint to use for the `break` command.

`skipmode`

Displays the breakpoint and watchpoint skipmode setting.

Examples

```
show breakpoint auto-hw      # Display automatic breakpoint selection setting.
show breakpoint skipmode     # Display breakpoint and watchpoint skipmode setting.
```

Related references

1.2.21 show group on page 1-42

1.3.158 show case-insensitive-source-matching

Displays the case sensitivity setting for the debugger file matching operations. You can use the `set case-insensitive-source-matching` command to modify this setting.

Syntax

```
show case-insensitive-source-matching
```

Examples

```
show case-insensitive-source-matching     # Display case sensitivity setting.
```

Related references

1.2.21 show group on page 1-42

1.3.159 show cde-coprocessors

Displays the encoding associated with each coprocessor.

Coprocessors are associated with either the General CoProcessor (GCP) encoding, or the Custom Datapath Extension (CDE) encoding.

Syntax

```
show cde-coprocessors
```

Examples

```
show cde-coprocessors      # Display the coprocessor encodings

> P0 = CDE, P1 = GCP, P2 = GCP, P3 = GCP, P4 = GCP, P5 = GCP, P6 = GCP,
P7 = GCP                   # Outputs the coprocessor encodings.
                           # Here, only the P0 coprocessor is associated
                           # with the CDE encoding. The other coprocessors
                           # are associated with the GCP encoding.
```

Related references

1.2.21 show group on page 1-42
1.3.122 set cde-coprocessors on page 1-125

1.3.160 show debug-agent

Displays the value of an internal configuration parameter for the debug agent. You can use the `set debug-agent` command to modify this setting. The available parameters depend on the debug agent, such as DSTREAM or `gdbserver`.

Syntax

```
show debug-agent [<name>]
```

Where:

<name>

Specifies the parameter to display.

Examples

```
show debug-agent     # Display all debug agent configuration parameters.
```

Related references

1.2.21 show group on page 1-42

1.3.161 show debug-from

Displays the setting for the expression that is used by the `start` command to set a temporary breakpoint. You can use the `set debug-from` command to modify this setting.

Syntax

```
show debug-from
```

Examples

```
show debug-from     # Display expression used by start command.
```

Related references

1.2.2 Execution control on page 1-22
1.2.21 show group on page 1-42

1.3.162 show directories

Displays the list of directories to search for source files. You can use the `directory` command to modify this list.

Syntax

```
show directories
```

Examples

```
show directories     # Display list of search paths.
```

Related references

1.2.7 Files on page 1-29

1.2.21 show group on page 1-42

1.3.163 show dtsl-options

Displays the value of a parameter in the DTSL configuration. You can use the `set dtsl-options` command to modify this setting.

Syntax

`show dtsl-options[<name>]`

Where:

`<name>`

Specifies the parameter to display.

Examples

```
show dtsl-options     # Display all DTSL configuration parameters.
```

Related references

1.2.21 show group on page 1-42

1.3.164 show dtsl-temporary-directory

Displays the current path for the temporary directory which stores trace data. You can modify the temporary directory path using the `set dtsl-temporary-directory` command.

Syntax

`show dtsl-temporary-directory`

Examples

```
show dtsl-temporary-directory      # Shows the current trace data temporary directory path.
```

Related references

1.2.21 show group on page 1-42

1.3.165 show elf cache-uninitialized-sections

Displays the debugger setting that controls whether uninitialized sections are cached.

Syntax

`show elf cache-uninitialized-sections`

Examples

```
show elf cache-uninitialized-sections     #Display whether uninitialized sections are cached
```

Related references

1.2.21 show group on page 1-42

1.3.166 show elf load-segments-at-p_paddr

Displays the debugger setting that controls the location for loading segments of ELF images.

Syntax

```
show elf load-segments-at-p_paddr
```

Examples

```
show elf load-segments-at-p_paddr     # Displays whether the load location is
                                      # the specified load offset + p_paddr.
```

Related references

1.2.21 show group on page 1-42

1.3.167 show elf zero-extra-segment-bytes

Displays the debugger setting that controls zeroing of bytes when loading segments of ELF images to the target.

Syntax

```
show elf zero-extra-segment-bytes
```

Examples

```
set elf zero-extra-segment-bytes      # Display whether the debugger writes zeros
                                      # if p_filesz is smaller than p_memsz.
```

Related references

1.2.21 show group on page 1-42

1.3.168 show endian

Displays the byte order setting in use by the debugger. You can use the `set endian` command to modify this setting.

Syntax

```
show endian
```

Examples

```
show endian      # Display byte order setting.
```

Related references

1.2.21 show group on page 1-42
1.2.24 Support on page 1-46

1.3.169 show escape-strings

Displays the setting for controlling how special characters in strings are printed on the debugger command line. You can use the `set escape-strings` command to modify this setting.

Syntax

```
show escape-strings
```

Examples

```
show escape-strings           # Display setting for controlling how
                              # special characters in strings are printed.
```

Related references

1.2.21 show group on page 1-42

1.3.170 show escapes-in-filenames

Displays the setting for controlling the use of special characters in paths. You can use the `set escapes-in-filenames` command to modify this setting.

Syntax

```
show escapes-in-filenames
```

Examples

```
show escapes-in-filenames            # Display setting for controlling the use of
                                     # special characters in paths.
```

Related references

1.2.21 show group on page 1-42

1.3.171 show idau-region

Displays the currently specified Implementation Defined Attribution Unit (IDAU) region parameters.

Syntax

```
show idau-region
```

Examples

```
show idau-region      # Display the currently specified IDAU region parameters.
```

1.3.172 show listsize

Displays the number of source lines that the `list` command displays. You can use the `set listsize` command to modify the display size.

Syntax

```
show listsize
```

Examples

```
show listsize     # Display listing size for list command.
```

Related references

1.2.21 show group on page 1-42

1.3.173 show mmu use-cache-for-phys-reads

Displays the MMU setting that controls the coherency between translation table memory reads and cache data.

Syntax

```
show mmu use-cache-for-phys-reads
```

Examples

```
show mmu use-cache-for-phys-reads     # Displays the MMU coherency setting.
```

Related references

1.2.12 mmu on page 1-33
1.2.21 show group on page 1-42

Related information

About debugging MMUs

1.3.174 show os

Displays the Operating System (OS) control settings. You can use the `set os` command to modify these settings.

Note

An OS aware connection must be established before you can use this command.

Syntax

```
show os <option>
```

Where:

`<option>`

Specifies additional options:

`enabled`

Displays the setting for controlling OS support.

`kernel-stack-size`

Displays the stack size of the kernel.

`log-capture`

Displays the setting for controlling the capturing and printing of OS logging messages.

`read-all-threads-on-stop`

Displays the setting for the reading of threads when the target is stopped.

Examples

```
show os log-capture            # Display setting for controlling os log capture.
show os enabled                # Display OS enabled setting.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.21 show group on page 1-42

1.3.175 show print

Displays the debugger print settings. You can use the `set print` commands to modify these settings.

Syntax

```
show print <option>
```

Where:

`<option>`

Specifies additional options:

`library-not-found-warnings`

Displays the print settings for "unable to find library…" messages.

`full-source-path`

Displays the print settings for source paths in messages.

`stop-info`

Displays the print settings for event messages when the target stops.

current-vmid

Displays the print settings for VMID messages when the target stops.

double-format

Displays the print settings that controls the `printf()` style formatting of double values.

float-format

Displays the print settings that controls the `printf()` style formatting of floating-point values.

Examples

```
show print library-not-found-warnings   # Display print settings for unfound
                                        # library messages.
show print full-source-path             # Display print settings for
                                        # source paths in messages.
```

Related references

1.2.16 Display on page 1-35

1.2.21 show group on page 1-42

1.1.3 Expressions within Arm Development Studio on page 1-10

1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.176 show semihosting

Displays the semihosting settings in the debugger. You can use the `set semihosting` commands to modify these settings.

Syntax

`show semihosting <option>`

Where:

<option>

Specifies additional options:

args

Displays the command-line arguments that are passed to the `main()` function in the application.

enabled

Displays the semihosting enabled setting.

file-base

Displays the setting for the `file-base` directory.

stdin

Displays the `stdin` settings.

stdout

Displays the `stdout` settings.

stderr

Displays the `stderr` settings.

top-of-memory

Displays the address for the top of memory.

stack-base

Displays the address for the stack base.

stack-limit

Displays the address for the stack limit.

heap-base

Displays the address for the heap base.

heap-limit

Displays the address for the heap limit.

vector

When using a semihosting breakpoint, the address is displayed otherwise a message is displayed indicating that a vector is in use.

Examples

```
show semihosting args                # Display command-line arguments.
show semihosting enabled             # Display semihosting enabled setting.
show semihosting top-of-memory       # Display the top of memory address.
```

Related references

1.2.21 show group on page 1-42

1.2.24 Support on page 1-46

1.3.177 show solib-absolute-prefix

Displays the system root directory in use by the debugger when searching for shared library symbols. You can use the `set sysroot` command to specify a system root directory on the host workstation.

The debugger uses this directory to search for a copy of the debug versions of target shared libraries. The system root on the host workstation must contain an exact representation of the libraries on the target root filesystem.

Note

You must launch the debugger with `target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
show solib-absolute-prefix
```

Examples

```
show solib-absolute-prefix     # Display system root directory.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.21 show group on page 1-42

1.3.182 show sysroot on page 1-154

1.3.140 set solib-absolute-prefix on page 1-137

1.3.178 show solib-search-path

Displays the search paths in use by the debugger when searching for shared libraries. You can use the `set sysroot` command to specify a system root directory on the host workstation and you can also use the `set solib-search-path` command to specify additional directories.

Note

You must launch the debugger with `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
show solib-search-path
```

Examples

```
show solib-search-path     # Display search path for shared libraries.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.21 show group on page 1-42

1.3.179 show step-mode

Displays the step setting for functions without debug information. You can use the `set step-mode` command to modify this setting.

Syntax

```
show step-mode
```

Examples

```
show step-mode     # Display step setting (function without debug).
```

Related references

1.2.2 Execution control on page 1-22

1.2.21 show group on page 1-42

1.3.180 show stop-on-solib-events

Displays the debugger setting that controls whether execution stops when shared library events occur. You can use the `set stop-on-solib-events` command to modify this setting.

Note

You must launch the debugger with `--target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
show stop-on-solib-events
```

Examples

```
show stop-on-solib-events      # Display stop setting for shared library events.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.21 show group on page 1-42

1.3.181 show substitute-path

Displays the search path substitution rules in use by the debugger when searching for source files. You can use the `set substitute-path` command to modify these substitution rules.

Syntax

```
show substitute-path
```

Examples

```
show substitute-path     # Display all substitution rules.
```

Related references

1.2.7 Files on page 1-29

1.2.21 show group on page 1-42

1.3.182 show sysroot

Displays the system root directory in use by the debugger when searching for shared library symbols. You can use the `set sysroot` command to specify a system root directory on the host workstation.

The debugger uses this directory to search for a copy of the debug versions of target shared libraries. The system root on the host workstation must contain an exact representation of the libraries on the target root filesystem.

Note

You must launch the debugger with `target_os` command-line option before you can use this feature. In Arm DS, this option is automatically selected when you connect to a target using `gdbserver`.

Syntax

```
show sysroot
```

Examples

```
show sysroot     # Display system root directory.
```

Related references

1.2.6 Operating System (OS) on page 1-27

1.2.21 show group on page 1-42

1.3.145 set sysroot on page 1-140

1.3.183 show trust-ro-sections-for-opcodes

Displays the debugger setting that controls whether the debugger can read opcodes from read-only sections of images on the host workstation rather than from the target itself.

Syntax

```
show trust-ro-sections-for-opcodes
```

Examples

```
show trust-ro-sections-for-opcodes     # Display trust-ro-sections-for-opcodes setting.
```

Related references

1.2.21 show group on page 1-42

1.3.184 show version

Displays the version number of the debugger.

Syntax

```
show version
```

Examples

```
show version      # Display debugger version number.
```

Related references

1.2.21 show group on page 1-42

1.2.24 Support on page 1-46

1.3.185 show wildcard-style

Displays the wildcard style for pattern matching. You can use the `set wildcard-style` command to modify this setting.

Syntax

`show wildcard-style`

Examples

```
show wildcard-style     # Display wildcard style.
```

Related references

1.2.21 show group on page 1-42

1.3.186 silence

Disables the printing of stop messages for a specific breakpoint.

Syntax

`silence[<number>]`

Where:

`<number>`

Specifies the breakpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

If no `<number>` is specified, then all stop messages are disabled.

Examples

```
silence 2   # Disable printing of stop messages for breakpoint 2.
silence $   # This applies to the breakpoint whose number is in
            # the most recently created debugger variable.
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.187 source

Loads and runs a script file to control and debug your target.

The following types of script are available:

Arm DS

Arm Debugger commands.

CMM

CMM is a scripting language supported by some third-party debuggers. Arm Development Studio supports a small subset of CMM-style commands, sufficient for running small target initialization scripts.

Jython

Jython is a Java implementation of the Python scripting language. It provides extensive support for data types, conditional execution, loops, and organization of code into functions, classes, and modules, as well as access to the standard Jython libraries. Jython is an ideal choice for larger or more complex scripts.

Note

Debugger views are not updated when commands issued in a script are executed.

Syntax

```
source [/v]<filename>[<args>]
```

Where:

v

specifies verbose output. Script commands are interleaved with the debugger output.

<filename>

specifies the script file. Use these file extensions to identify the script type:

.ds

for Arm Development Studio scripts.

.cmm, .t32

for CMM scripts.

.py

for Jython scripts.

<args>

specifies the number of arguments (zero or more) to pass to the script (only supported for Jython scripts).

Examples

```
source myScripts\myFile.ds        # Run Arm Debugger commands from myFile.ds.
source myScripts\myFile.cmm       # Run CMM-style commands from myFile.cmm.
source myScripts\myFile.t32       # Run CMM-style commands from myFile.t32.
source /v myFile.ds               # Run Arm Debugger commands from myFile.ds and
                                  # display commands interleaved with debugger output.
source myScripts\myFile.py        # Run a Jython script from file myFile.py.
```

Related references

1.2.4 Scripts on page 1-25

1.3.188 start

Sets a temporary breakpoint, calls the debugger `run` command, and then deletes the temporary breakpoint when it is hit. By default, the temporary breakpoint is set at the address of the global function `main()`.

You can use the `set debug-from` command to change the breakpoint location. If the breakpoint location cannot be found then the breakpoint is set at the image entry point.

This command records the ID of the breakpoint in a new debugger variable, `$<n>` , where `<n>` is a number. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Note

Control is returned as soon as the target is running. You can use the `wait` command to block the debugger from returning control until either the application completes or a breakpoint is hit.

Syntax

`start[<args>]`

Where:

`<args>`

Specifies the command-line arguments that are passed to the `main()` function in the application using the `argv` parameter. The name of the image is always implicitly passed in `argv[0]` and it is not necessary to pass this as an argument.

Examples

```
start                                   # Start running the target to the
                                        # temporary breakpoint.
```

Related references

1.2.2 Execution control on page 1-22

1.3.189 stdin

Specifies semihosting input requested by application code.

Note

This command is not required if you launch the debugger within Arm DS, or if you use a telnet session to interact directly with the application.

Syntax

`stdin [<input>]`

Where:

`<input>`

Specifies semihosting input requested by application code. This must be terminated by `\n` to tell the debugger that the input is complete.

You can use this command before the input is required by the application code. All input is buffered by the debugger until requested and then discarded when the semihosting operation finishes.

Examples

```
stdin 10000\n      # Pass the number 10000 to the application.
```

Related references

1.2.24 Support on page 1-46

1.3.190 step

Steps through an application at the source level stopping on the first instruction of each source line including stepping into all function calls. You must compile your code with debug information to use this command successfully.

You can modify the behavior of this command with the `set step-mode` command.

Syntax

`step [<count>]`

Where:

`<count>`

Specifies the number of source lines to execute.

Note

Execution stops immediately if a breakpoint is reached, even if fewer than `<count>` source lines are executed.

Examples

```
step                                    # Execute one source line.
step 5                                  # Execute five source lines.
```

Related references

1.3.191 stepi on page 1-158
1.3.192 steps on page 1-159
1.3.99 next on page 1-110
1.3.100 nexti on page 1-111
1.3.101 nexts on page 1-111
1.2.2 Execution control on page 1-22

1.3.191 stepi

Steps through an application at the instruction level including stepping into all function calls.

Syntax

`stepi [<count>]`

Where:

`<count>`

Specifies the number of instructions to execute.

Note

Execution stops immediately if a breakpoint is reached, even if fewer than `<count>` instructions are executed.

Examples

```
stepi                                    # Execute one instruction.
stepi 5                                  # Execute five instructions.
```

Related references

1.3.190 step on page 1-157
1.3.192 steps on page 1-159
1.3.99 next on page 1-110
1.3.100 nexti on page 1-111
1.3.101 nexts on page 1-111
1.2.2 Execution control on page 1-22

1.3.192 steps

Steps through an application at the source level stopping on the first instruction of each source statement (for example, statements in a `for()` loop) including stepping into all function calls. You must compile your code with debug information to use this command successfully.

Syntax

You can modify the behavior of this command with the `set step-mode` command.

`steps [<count>]`

Where:

`<count>`

Specifies the number of source statements to execute.

Note

Execution stops immediately if a breakpoint is reached, even if fewer than `<count>` source statements are executed.

Examples

```
steps                           # Execute one source statement.
steps 5                         # Execute five source statements.
```

Related references

1.3.190 step on page 1-157
1.3.191 stepi on page 1-158
1.3.99 next on page 1-110
1.3.100 nexti on page 1-111
1.3.101 nexts on page 1-111
1.2.2 Execution control on page 1-22

1.3.193 tbreak

Sets an execution breakpoint at a specific location and deletes the breakpoint when it is hit. You can also specify a conditional breakpoint by using an `if` statement that stops only when the conditional expression evaluates to `true`.

This command records the ID of the breakpoint in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the breakpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Note

Breakpoints that are set within a shared object or kernel module become pending when the shared object or kernel module is unloaded.

Use `set breakpoint` to control the automatic breakpoint behavior when using this command.

Syntax

`tbreak [-d] [-p] [[<filename>:]<location><address>] [[threadcore] <number>...] [if <expression>]`

Where:

`d`

disables the breakpoint immediately after creation.

p

specifies whether or not the resolution of an unrecognized breakpoint location results in a pending breakpoint being created.

<filename>

specifies the file.

<location>

specifies the location:

<line_num>

is a line number.

<function>

is a function name.

<label>

is a label name.

+<offset>|-<offset>

specifies the line offset from the current location.

<address>

specifies the address. This can be either an address or an expression that evaluates to an address.

<number>

specifies one or more threads or processors to apply the breakpoint to. You can use `$thread` to refer to the current thread. If `<number>` is not specified then all threads are affected.

<expression>

specifies an expression that is evaluated when the breakpoint is hit.

If no arguments are specified then a breakpoint is set at the PC.

Examples

```
tbreak *0x8000                # Set breakpoint at address 0x8000.

tbreak *0x8000 thread $thread # Set breakpoint at address 0x8000 on
                              # current thread.
tbreak *0x8000 thread 1 3     # Set breakpoint at address 0x8000 on
                              # threads 1 and 3.
tbreak main                   # Set breakpoint at address of main().
tbreak SVC_Handler            # Set breakpoint at address of label SVC_Handler.
tbreak +1                     # Set breakpoint at address of next source line.
tbreak my_File.c:main         # Set breakpoint at address of main() in my_File.c.
tbreak my_File.c:8            # Set breakpoint at address of line 8 in my_File.c.
tbreak function1 if x>0       # Set conditional breakpoint that stops when x>0.
```

Related references

1.3.6 break on page 1-58
1.3.41 hbreak on page 1-78
1.3.194 thbreak on page 1-161
1.3.111 resolve on page 1-117
1.3.15 clear on page 1-63
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.194 thbreak

Sets a hardware execution breakpoint at a specific location and deletes the breakpoint when it is hit. You can also specify a conditional breakpoint by using an `if` statement that stops only when the conditional expression evaluates to `true`.

This command records the ID of the breakpoint in a new debugger variable, `$<n>` , where `<n>` is a number. You can use this variable, in a script, to delete or modify the breakpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Note

The number of hardware breakpoints are usually limited. If you run out of hardware breakpoints, then delete or disable one that you no longer use.

Note

Breakpoints that are set within a shared object or kernel module become pending when the shared object or kernel module is unloaded.

You can use `info breakpoints capabilities` to display a list of parameters that you can use with breakpoint commands for the current connection.

Syntax

```
thbreak [-d] [-p] [[<filename>:]<location>|*<address>] [[thread|core] <number>...]
[vmid <vmid>] [context <contextid>] [if <expression>]
```

Where:

`-d`

Disables the breakpoint immediately after creation.

`-p`

Specifies whether or not the resolution of an unrecognized breakpoint location results in a pending breakpoint being created.

`<filename>`

Specifies the file.

`<location>`

Specifies the location:

`<line_num>`

Is a line number.

`<function>`

Is a function name.

`<label>`

Is a label name.

`{+<offset>|-<offset>}`

Specifies the line offset from the current location.

`<number>`

Specifies one or more threads or processors to apply the breakpoint to. You can use `$thread` to refer to the current thread. If `<number>` is not specified then all threads are affected.

<address>

Specifies the address. This can be either an address or an expression that evaluates to an address.

<vmid>

Specifies the Virtual Machine ID (VMID) to apply the breakpoint to. This can be either an integer or an expression that evaluates to an integer.

<contextid>

Specifies the context ID to apply the breakpoint to. This can be either an integer or an expression that evaluates to an integer. You can only use the context parameter if your hardware supports it and your application makes use of the `CONTEXTIDR` register. For more information, see `CONTEXTIDR` in the *Arm Architecture Reference Manual*.

<expression>

Specifies an expression that is evaluated when the breakpoint is hit.

If no arguments are specified, then a hardware breakpoint is set at the next instruction.

Examples

```
thbreak *0x8000                # Set breakpoint at address 0x8000.
thbreak *0x8000 thread $thread # Set breakpoint at address 0x8000 on
                               # current thread
thbreak *0x8000 thread 1 3     # Set breakpoint at address 0x8000 on
                               # threads 1 and 3
thbreak main                   # Set breakpoint at address of main()
thbreak SVC_Handler            # Set breakpoint at address of label SVC_Handler
thbreak +1                     # Set breakpoint at address of next source line
thbreak my_File.c:main         # Set breakpoint at address of main(), my_File.c
thbreak my_File.c:8            # Set breakpoint at address of line 8, my_File.c
thbreak function1 if x>0       # Set conditional breakpoint that stops when x>0
thbreak context 257 0x80000000 # Set conditional breakpoint at address 0x80000000
                               # that stops when CONTEXTIDR=257
```

Related references

1.3.6 break on page 1-58
1.3.41 hbreak on page 1-78
1.3.193 tbreak on page 1-159
1.3.111 resolve on page 1-117
1.3.15 clear on page 1-63
1.2.1 Breakpoints and watchpoints on page 1-20

1.3.195 thread, core

Displays information about the current thread or processor.

It displays:

- The unique *id* number assigned by the debugger.
- The thread or processor state (for example stopped or running).
- The current stack frame, including function names and source line numbers.

Syntax

```
thread [<id>]
```

```
core [<id>]
```

Where:

<id>

Specifies the unique thread or processor number.

If <id> is not specified, then the debugger switches control to the current thread or processor before displaying information. You can use `infocores`, `info processes`, or `info threads` to display the <id> numbers.

If <id> is specified, then the debugger switches control to that thread or processor before displaying the information. Registers and call stacks are associated with a particular thread or processor. This means that switching context also switches the registers and call stack to those belonging to the current thread or processor.

Examples

```
thread 699                              # Set current thread to number 699.
core 2                                  # Set current processor to number 2.
```

Related references

1.2.2 Execution control on page 1-22
1.2.6 Operating System (OS) on page 1-27
1.1.3 Expressions within Arm Development Studio on page 1-10
1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11
1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

1.3.196 thread apply, core apply

Switches control to a specific thread or processor to execute a debugger command and then switches back to the original state.

If an error occurs then the debugger stops processing the command and switches back to the original state.

Syntax

`thread apply` *`all`*`|`*`<id>`* `<command>`

`core apply` *`all`*`|`*`<id>`* `<command>`

Where:

all

Specifies all threads or all processors.

<id>

Specifies the unique thread or processor number. You can use `infocores`, `info processes`, or `info threads` to display the <id> numbers.

<command>

Specifies the debugger command that you want to execute.

If `all` is specified then the command is executed on each thread or processor successively before switching back.

Examples

```
thread apply all print /x $pc           # Cycle through all threads and print address
                                        # in PC register (hexadecimal).
```

Related references

1.2.2 Execution control on page 1-22
1.2.6 Operating System (OS) on page 1-27

1.3.197 trace clear

Clears the trace on the specified trace capture device. If no device is specified, clears the trace on all connected trace capture devices.

Note

Trace capture devices do not support clearing while capture is active.

Syntax

```
trace clear [<trace_capture_device>]
```

Where:

<trace_capture_device>

Specifies the trace capture device.

If no `<trace_capture_device>` is specified, then all trace capture devices are cleared.

Examples

```
trace clear               # Clears all connected trace capture devices.
trace clear ETB           # Clears trace capture device named ETB.
```

Related references

1.2.3 Tracing on page 1-24

1.3.198 trace dump

Dumps raw trace data to a directory, along with target trace configuration metadata, from a trace capture device or a trace source.

Syntax

```
trace dump <output_path> [-<option>] [<trace_capture_device>|<trace_source>]...
```

Where:

<output_path>

Specifies the destination of the trace dump. It creates a directory named `<output_path>`. It creates the metadata and trace data within this directory. It generates an error if this directory already exists.

Note

If you specify a folder name only or a relative path, then it creates the output directory in, or relative to, the current working directory.

<option>

Is one of:

raw

Dumps raw data. Raw data is the captured trace data with trace device specific formatting. The raw option only applies to trace capture devices.

no_metadata

Suppresses the metadata.

no_tracedata

Suppresses the trace data.

split_file_size=<value>

Specifies the maximum file size (in bytes) of the trace data files generated by the `trace dump` command. If the size of the file exceeds this amount, a new trace data file is generated. Specify `-1` to keep trace data in a single file. Default value is `1073741824`. Minimum value is `65536`.

<trace_capture_device>

Specifies the trace capture device.

<trace_source>

Specifies a trace source.

- If no `<trace_capture_device>` or `<trace_source>` is specified, then all trace capture device buffers are dumped.
- If a trace capture device is specified and a trace source from that device is also specified then the trace data for that source will be dumped twice. Once within the complete buffer for the device and again as a dump of just the specified trace source.

Examples

```
trace dump TraceDump
   # Creates a directory named TraceDump. Dumps the buffers of all active
   # trace capture devices into TraceDump, along with the metadata
   # describing them.


trace dump TraceDump ETB
   # ETB is the name of a trace capture device. Dumps the contents of the
   # ETB buffer to TraceDump.


trace dump TraceDump DSTREAM -raw
   # DSTREAM is the name of a trace capture device. Dumps the contents of
   # the DSTREAM buffer to TraceDump in raw format.


trace dump TraceDump PTM_1
   # PTM_1 is the name of a trace source. Extracts the trace data for PTM_1
   # from the trace device buffer and dumps it to TraceDump.

trace dump TraceDump ETB -no_metadata
   # Dumps the contents of the ETB buffer to TraceDump, but does not write
   # the metadata.

trace dump TraceDump ETB -no_tracedata
   # Writes the metadata for ETB in TraceDump, but does not write the trace
   # data.

trace dump TraceDump ETB -no_tracedata -no_metadata
   # Creates an empty directory named TraceDump.
```

Related references

1.2.3 Tracing on page 1-24

1.3.199 trace info

Displays details about trace capture devices and trace sources.

Syntax

`traceinfo [-<option>] [<trace_capture_device>|<trace_source>]`

Where:

<trace_capture_device>

specifies the trace capture device.

<trace_source>

specifies the trace capture source.

If no <trace_capture_device> or <trace_source> is specified, then all trace capture devices and sources are displayed.

<option>

specifies how information is displayed:

show disabled

displays disabled devices and sources.

Examples

```
trace info
# Display all the enabled trace capture devices and trace sources.

trace info -showdisabled
# Display all trace capture devices and trace sources including disabled ones.

trace info ETB
# Display the trace capture device or trace source named ETB.
```

Related references

1.2.3 Tracing on page 1-24

1.3.164 show dtsl-temporary-directory on page 1-147

1.3.126 set dtsl-temporary-directory on page 1-127

1.3.200 trace list

Lists the trace capture devices and trace sources.

Syntax

```
trace list
```

Examples

```
trace list      # List all of the trace capture devices and trace sources
```

Related references

1.2.3 Tracing on page 1-24

1.3.201 trace report

Produces a trace report, containing the decoded trace data, for the currently selected core.

Syntax

```
trace report [<option> = <value>]...
```

Where:

<option>

Specifies the name of a trace report option to set.

<value>

Specifies the new value of the option.

The option names are not case sensitive. The options are:

OUTPUT_PATH

Specifies the directory to save the trace report files in. The default value is the current working directory.

FILE

Specifies the base file name of the trace report. If trace report generates multiple files, then each file will have a zero-padded number inserted before the file name extension. The default value is `Trace_Report.txt`.

SPLIT_FILE_SIZE

Specifies the maximum file size, in bytes, that trace report generates. If the file size is larger than `SPLIT_FILE_SIZE`, trace report generates a new report file. Specifying `-1` indicates that there is no maximum file size, so the trace report is not split into separate files. The default value is `1073741824`.

START

Specifies the position in the trace buffer to start decoding trace from. The default value is 0, which starts the decoding from the beginning of the buffer.

END

Specifies the position in the trace buffer to stop decoding trace. Specifying `-1` indicates that the trace report should decode to the end of the buffer. The default value is `-1`.

FORMAT

Specifies the format of the report. Valid values are `CSV` (Comma-Separated Values) and `TSV` (Tab Separated Values). The default value is `TSV`. Format values are not case sensitive.

SOURCE

Specifies the trace source to report. Execute the trace list command to view the list of available trace sources. The default is to dump the trace source associated with the current core.

CORE

Specifies the core to report. Execute the `info cores` command to view the list of cores available. This option is analogous to the SOURCE option, except that the source for the given core will be discovered automatically. You can specify either a SOURCE or CORE but not both.

CONFIG

Specifies a configuration file. This is used to specify decoding details for STM and ITM trace sources. The default configuration is to decode all Ports, Masters, and Channels as binary data. This file is created by exporting it from the `Event Viewer Settings` dialog box.

COLUMNS

Specifies a comma separated list of columns to include in the report. The column names are not case sensitive.

Valid values for instruction trace sources are:

RECORD_TYPE

The type of the record.

INDEX

The index of the instruction. Canceled instructions do not have an index.

ADDRESS

The address of the instruction.

OPCODE

The opcode of the instruction, in hexadecimal, with no prefix.

OPCODE_WITH_PREFIX

The opcode of the instruction, in hexadecimal, with a `0x` prefix.

CYCLES

The cycle count of the instruction.

DETAIL

For instruction records, this gives the disassembly of the instruction. For other record types, this gives various information.

FUNCTION

The function of the instruction.

BRANCH

This is true if the instruction is a branch. Otherwise, this is false.

For instruction trace sources, the default is `ADDRESS, OPCODE, DETAIL`.

Valid values for STM trace sources are:

MASTER

The master number can be 0 to 128.

CHANNEL

The channel number can be 0 to 65535.

TIMESTAMP

An approximate timestamp for each record, if available.

SIZE

Size of the row in bytes.

DATA

The row data.

For STM trace sources, the default is `MASTER, CHANNEL, DATA`.

Valid values for ITM trace sources are:

PORT

The port number can be 0 to 255.

TIMESTAMP

The global timestamp for the record, if available (M-profile only). This column name is synonymous with the global time stamp (GTS).

DATA

The row data.

LTS

The local timestamp for the record, if available.

GTS

The global timestamp for the record, if available (M-profile only).

COMP

For DWT data trace packets, the number of the matching DWT comparator (M-profile only). This column is only useful if the DWT option is specified as true.

For ITM trace sources, the default is `PORT,DATA`.

DWT

For M-profile ITM trace sources, specifies whether to include DWT packets in the report. The default value is false. To include DWT packets, specify true.

PORTS

For ITM trace sources, specifies a comma-separated list of stimulus ports to include. Output from stimulus ports not listed is suppressed from the report. If the option is not present, output from all stimulus ports is included.

DECODERS

For ITM trace sources, specifies a comma-separated list of decoder assignments. Each decoder assignment has the form `P<n>:<decoder_name>` where `<n>` is a stimulus port number, and `<decoder_name>` is one of the names available in the `Encoding` drop-down list in the *Event Viewer Settings* dialog box. The decoders available by default are `TAE`, `Text`, and `Binary`. If no decoder is assigned to a stimulus port, the default is `Binary`.

HEADERS

Specifies whether to include the column headers in the report. The default value is false. To include headers, specify true.

Examples

```
trace report
   # Produces a default trace report named "Trace_Report.txt" in the
   # current working directory.
   # Instruction trace for the current core is reported.

trace report FILE=MyReport.csv OUTPUT_PATH=C:/files/trace_reports FORMAT=CSV
   # Produces a comma-separated value trace report named "MyReport.csv"
   # in C:/files/trace_reports.

trace report COLUMNS=RECORD_TYPE,INDEX,ADDRESS,OPCODE_WITH_PREFIX,DETAIL HEADERS=true
   # Produces a trace report with alternate columns.
   # The first line of the report contains the column names.

trace report SOURCE=ITM COLUMNS=PORT,DATA HEADERS=true
   # Produces an ITM trace report with alternate columns.
   # The first line of the report contains the column names.

trace report SOURCE=ITM PORTS=1,2 DECODERS=P1:Text,P2:TAE HEADERS=true
   # Specifies custom decoders for stimulus ports 1 and 2, and suppresses
   # output from all other stimulus ports.
   # The first line of the report contains the column names.

trace report SOURCE=CSITM DWT=true COLUMNS=PORT,COMP,DATA HEADERS=true
   # Produces an ITM trace report with DWT packets included, and DWT
   # comparator numbers for data trace packets.
   # The first line of the report contains the column names.
```

Related references

1.2.3 Tracing on page 1-24

1.3.202 trace start

Starts trace capture on the specified trace capture device. If no device is specified, starts trace capture on all connected trace capture devices.

Syntax

```
trace start [<trace_capture_device>]
```

Where:

<trace_capture_device>

Specifies the trace capture device.

If no <trace_capture_device> is specified, then all trace capture devices are started.

Examples

```
trace start               # starts all connected trace capture devices
trace start ETB           # starts trace capture device named ETB
```

Related references

1.2.3 Tracing on page 1-24

1.3.203 trace stop

Stops trace capture on the specified trace capture device. If no device is specified, stops trace capture on all connected trace capture devices.

Syntax

```
trace stop [<trace_capture_device>]
```

Where:

<trace_capture_device>

Specifies the trace capture device.

If no <trace_capture_device> is specified, then all trace capture devices are stopped.

Examples

```
trace stop                # stops all connected trace capture devices
trace stop ETB            # stops trace capture device named ETB
```

Related references

1.2.3 Tracing on page 1-24

1.3.204 unset

Modifies the current debugger settings.

Syntax

```
unset <option>
```

Where:

<option>

Specifies additional options:

substitute-path [<path>]

Deletes all the substituted source paths. If <path> is specified then only the substitution for <path> is deleted.

semihosting heap-base

Deletes the base address of the heap.

semihosting heap-limit

Deletes the end address of the heap.

semihosting stack-base

Deletes the base address of the stack.

semihosting stack-limit

Deletes the end address of the stack.

semihosting top-of-memory

Deletes the top of memory.

Examples

```
unset substitute-path      # Delete all substitution paths
```

Related references

1.2.24 Support on page 1-46

1.3.205 unsilence

Enables the printing of stop messages for a specific breakpoint.

Syntax

`unsilence [<number>]`

Where:

<number>

Specifies the breakpoint number. This is the number assigned by the debugger when it is set. You can use `info breakpoints` to display the number and status of all breakpoints and watchpoints.

If no `<number>` is specified, then all stop messages are enabled.

Examples

```
unsilence 2   # Enable printing of stop messages for breakpoint 2
unsilence $   # This applies to the breakpoint whose number is in
              # the most recently created debugger variable
```

Related references

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.206 up

Moves and displays the current frame pointer up the call stack towards the top frame. It also displays the function name and source line number for the specified frame.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

`up [<offset>]`

Where:

<offset>

Specifies a frame offset from the current frame pointer in the call stack. If no `offset` is specified, then the default is one.

Examples

```
up         # Move and display information 1 frame up from current frame pointer
up 2       # Move and display information 2 frames up from current frame pointer
```

Related references

1.2.5 Call stack on page 1-26

1.3.207 up-silently

Moves the current frame pointer up the call stack towards the top frame.

Note

Each frame is assigned a number that increases from the bottom frame (zero) through the call stack to the top frame that is the start of the application.

Syntax

`up-silently [<offset>]`

Where:

`<offset>`

Specifies a frame offset from the current frame pointer in the call stack. If no `offset` is specified, then the default is one.

Examples

```
up-silently                  # Move 1 frame up from current frame pointer
up-silently 2                # Move 2 frames up from current frame pointer
```

Related references

1.2.5 Call stack on page 1-26

1.3.208 usecase help

Displays help for a use case script.

The command prints information about the use case script and gives a list of options that can be provided when invoking the script.

Syntax

`usecase help [<flag>] <script_name> [<entry_point>]`

Where:

`<script_name>`

Name of the use case script to print help for.

`<flag>`

Specifies the location of the use case script. This can be one of:

`-p`

The directory associated with the current platform in the Development Studio Configuration databases.

`-s`

The `Scripts\usecase` directory in the Development Studio Configuration databases.

<entry_point>

Specifies a named entry point in the use case script. If there is only one entry point defined in the use case script, it is not necessary to specify the entry point on the command line. If the use case script contains more than one entry point, then you must specify which one to use, as a parameter to this command.

Examples

```
usecase help script.py
   # Print help for script.py from the current working directory

usecase help -p db_script.py
   # Print help for db_script.py from the current platform directory

usecase help multi_usecase.py mainOne
   # Print help for the mainOne entry point in multi_usecase.py

usecase help multi_usecase.py mainTwo
   # Print help for the mainTwo entry point in multi_usecase.py
```

Related references

1.2.4 Scripts on page 1-25

1.3.209 usecase list

Lists use case scripts.

By default, the command lists all the use case scripts in the current working directory.

Syntax

`usecase list [-p | -s | -a | <directory>]`

Where:

-p

Lists all the use case scripts associated with the current platform. The use case scripts must be in the same directory where the DTSL scripts and `.rvc` file for the current platform are stored in the Arm Development Studio Configuration databases.

-s

Lists all the use case scripts in the `Scripts\\usecase` directory in the Arm Development Studio Configuration databases.

-a

Lists all the use case scripts that are in any of these categories:

- In the current working directory.
- Associated with the current platform.
- In the `Scripts` directory in the Arm Development Studio Configuration databases.

<directory>

Lists all the use case scripts in the specified directory.

Examples

```
usecase list
   # Lists all the use case scripts in the current working directory

usecase list -p
   # Lists all the use case scripts for the current platform

usecase list -s
   # Lists all the use case scripts in the Scripts\usecase folder in the
   # Arm DS Configuration databases

usecase list c:\usecase\scripts
   # Lists all the use case scripts in c:\usecase\scripts
```

```
usecase list scripts
   # Lists all the use case scripts in the scripts folder in the current
   # working directory
```

Related references

1.2.4 Scripts on page 1-25

1.3.210 usecase run

Runs a use case script.

Syntax

```
usecase run [<flag>] <script_name> [<entry_point>][--<option> |
<positional_argument>]...
```

Where:

<script_name>

Name of the use case script to run.

<flag>

Specifies the location of the use case script. This can be one of:

-p

The directory associated with the current platform in the Development Studio Configuration databases.

-s

The `Scripts\usecase` directory in the Development Studio Configuration databases.

<entry_point>

Specifies a named entry point in the use case script. If there is only one entry point defined in the use case script, it is not necessary to specify the entry point on the command line. If the use case script contains more than one entry point, then you must specify which one to use, as a parameter to this command.

<option>

Specifies a named option defined in the use case script and its value. You can specify more than one `<option>`.

<positional_argument>

Specifies a positional argument to the entry point. You can specify more than one `<positional_argument>`.

Examples

```
usecase run myscript.py
   # Runs a script named myscript.py in the current directory

usecase run -p platform_script.py entry
   # Runs platform_script.py in the current platform directory in the
   # Arm DS Configuration database, with entry point set to entry

usecase run -s db_script.py --opts.x=1
   # Runs db_script.py in the Scripts\usecase directory in the Arm DS
   # Configuration database, with the option opt.x defined as 1

usecase run second_script.py main x y z
   # Runs second_script.py passing in x, y, and z as positional arguments
   # to the entry point main

usecase run -s myscript.py --cores=4 --target="run" t.txt
   # Runs myscript.py in the Scripts\usecase directory with options cores
   # and target and a positional argument t.txt
```

Related references

1.2.4 Scripts on page 1-25

1.3.211 wait

Instructs the debugger to wait until the target stops. For example, when the application completes or a breakpoint is hit. Arm recommends that you specify a time-out parameter to generate an error if the time-out value is reached.

Syntax

`wait [<time-out>[ms | s]]`

Where:

`<time-out>`

Specifies the period of time.

`ms`

Specifies the time in milliseconds. This is the default.

`s`

Specifies the time in seconds.

Examples

```
wait 1000                                # Wait or time-out after 1 second
wait 0.5s                                # Wait or time-out after half a second
```

Related references

1.2.2 Execution control on page 1-22

1.3.2 advance on page 1-52

1.3.212 watch

Sets a watchpoint for a data symbol. The debugger stops the target when the memory at the specified address is written.

This command records the ID of the watchpoint in a new debugger variable, `$<n>`, where `<n>` is a number. You can use this variable, in a script, to delete or modify the watchpoint behavior. If `$<n>` is the last or second-to-last debugger variable, then you can also access the ID using `$` or `$$`, respectively.

Watchpoints are only supported on scalar values.

The availability of watchpoints depends on your target. In the case of Linux application debug using *gdbserver*, the availability of watchpoints also depends on the Linux kernel version and configuration.

The address of the instruction that triggers the watchpoint might not be the address shown in the PC register. This is because of pipelining effects.

Syntax

`watch [-d][-p] [-w <width>] [{filename:}]<symbol> | *<address>} [vmid <number>] [if <condition>]`

Where:

`-d`

Creates the watchpoint disabled.

`-p`

Specifies whether or not the resolution of an unrecognized watchpoint location results in a pending watchpoint being created.

-w <width>

Specifies the width to watch at the given address, in bits. Accepted values are: 8, 16, 32, and 64 if supported by the target. This parameter is optional.

The width defaults to:

- 32 bits for an address.
- The width corresponding to the type of the symbol or expression, if entered.

<filename>

Specifies the file.

<symbol>

Specifies a global/static data symbol. For arrays or structs you must specify the element or member.

<address>

Specifies the address. This can be either an address or an expression that evaluates to an address.

vmid <number>

Specifies the Virtual Machine ID (VMID) to apply the watchpoint to. This can be either an integer or an expression that evaluates to an integer. Applicable only on targets which support hypervisor / virtual machine debugging.

if <condition>

Specifies the condition which must evaluate to true at the time the watchpoint is triggered for the target to stop. You can create several conditional watchpoints, but when a conditional watchpoint is enabled, no other watchpoints (regardless of whether they are conditional) can be enabled.

Examples

```
watch myVar1                          # Set read/write watchpoint on myVar1
watch *0x80D4                         # Set read/write watchpoint on address 0x80D4
watch myVar1 if myVar1 == 2           # Set read/write watchpoint on myVar1 which
                                      # will only be hit if myVar1 evaluates to 2
watch myVar1 if $LR & 0xFF == 0x12    # Set read/write watchpoint on myVar1 which
                                      # will only be hit if ($LR & 0xFF) evaluates
                                      # to 0x12 when myVar1 is accessed
```

Related references

1.3.114 rwatch on page 1-119

1.3.16 clearwatch on page 1-64

1.3.5 awatch on page 1-57

1.2.1 Breakpoints and watchpoints on page 1-20

1.3.213 watch-set-property

Updates the properties of an existing watchpoint.

Syntax

`watch-set-property<number><property>`

Where:

<number>

Specifies the watchpoint number. This is the number assigned by the debugger when it is set. You can use `info watchpoints` to display the number and status of all watchpoints.

<property>

Specifies the property to set. The valid properties are:

if[expression]

Specifies an expression that is evaluated when the watchpoint is hit. If the value of the expression evaluates to true, then the debugger stops the target, otherwise execution resumes. If no expression is specified then the watchpoint condition is deleted.

data-width[bits]

Specifies the width to watch at the given address, in bits. Accepted values are: 8, 16, 32, and 64 if supported by the target. This parameter is optional.

The width defaults to:

- 32 bits for an address.
- The width corresponding to the type of the symbol or expression, if entered.

Other target-dependent properties

This command supports other `<properties>` depending on your target. Use the `info watchpoints capabilities` command to display a list of `<properties>` that you can use for the current connection.

Examples

```
watch-set-property 4 if myVar1 == 2   # Update the 'if' property of watchpoint 4,
                                      # meaning the watchpoint will only be hit if
                                      # myVar1 evaluates to 2
```

1.3.214 whatis

Displays the data type of an expression.

Syntax

`whatis[<expression>]`

Where:

`<expression>`

Specifies an expression. If no `<expression>` is specified then the last expression is repeated.

Note

This command does not execute the expression.

Examples

```
whatis 4+4                          # Display data type of expression result
whatis myVar                        # Display data type of variable (myVar)
```

1.3.215 while

Enables you to write scripts with conditional loops that execute debugger commands.

Syntax

```
while <condition>

...

<optional_commands>

...

end
```

Where:

<condition>

Specifies a conditional expression. Follow the `while` statement with one or more debugger commands that execute repeatedly while `<condition>` evaluates to true.

<optional_commands>

Specifies optional commands that can also be used inside the `while` statement to change the loop behavior:

loop_break

Exit the loop.

loop_continue

Skip the remaining commands and return to the start of the loop.

Enter each debugger command on a new line and terminate the `while` command by using the `end` command.

Examples

```
# Define a while loop containing commands to conditionally execute

# myVar is a variable in the application code
while myVar<10
    step
    wait
    x
    set myVar++
end
```

Related references

1.2.4 Scripts on page 1-25

1.3.216 x

Displays the content of memory at a specific address.

Syntax

`x[/<flag>]...[/<flag>]...[<address>]`

Where:

<flag>

Specifies additional flags:

<count>

Specifies the number of values to display. If none specified, then the default is 1.

Size of memory:

b

1 byte

h

2 bytes

w

4 bytes (default)

g

8 bytes.

Note

If you specify either `x/b`, `x/h`, or `x/g`, and then in a later x command you remove the specified size, the debugger uses the previous size that you specified; it does not revert to the default size of `x/w`.

Output format:

x

hexadecimal (casts the value to an unsigned integer prior to printing in hexadecimal)

d

signed decimal

u

unsigned decimal

o

octal

t

binary

a

absolute hexadecimal address

c

character

f

floating-point

i

assembler instruction

Note

If no output format is specified then the initial default is x, unless preceded by another command using output format options in which case the same format is retained.

`<address>`

Specifies the address. This can be either an address, a symbol name, or an expression that evaluates to an address. If no `<address>` is specified then the default value is used. Some commands that access memory can set this default value. For example, `x`, `print`, `output`, and `info breakpoints`.

Note

This command sets a default address variable to the location after the last accessed address.

Examples

```
x 0x8000       # Display memory at address 0x8000
x/3wx 0x8000   # Display 3 words of memory from address 0x8000 (hexadecimal)
x/4b $SP       # Display 4 bytes of memory from address in SP register
x/4i $PC       # Display 4 instructions from address in PC register
x /h 0x8000    # Read a half-word from address 0x8000
```

Related references

1.2.9 Memory group on page 1-31

1.2.16 Display on page 1-35

1.1.3 Expressions within Arm Development Studio on page 1-10

1.1.4 Built-in functions within Arm Development Studio expressions on page 1-11

1.1.8 Usage of printf() style format string within Arm Development Studio on page 1-15

Chapter 2
CMM-style commands supported by the debugger

Describes how to use each of the commands with examples.

It contains the following sections:

2.1 Conformance and usage of CMM-style commands

CMM-style commands are a small subset of commands, sufficient for running target initialization scripts. CMM is a scripting language supported by some third-party debuggers.

To execute CMM-style commands you must create a debugger script file containing the CMM-style commands and then use the Arm Debugger **source** command to run the script.

Note

For full debug support, Arm recommends that you use the Arm Debugger commands. See *Arm Debugger Commands* on page 1-8 for more information.

Syntax of CMM-style commands

Many commands accept arguments and flags using the following syntax:

```
command [<argument>] [/<flag>]...
```

A flag acts as an optional switch and is introduced with a forward slash character. Where a command supports flags, the flags are described as part of the command syntax.

Note

Commands are not case sensitive. Abbreviations are underlined.

Usage of CMM-style commands

The commands you submit to the debugger must conform to the following rules:

- Each command line can contain only one debugger command.
- When referring to symbols, you must use the same case as the source code.

Many commands can be abbreviated. For example, **break.set** can be abbreviated to `b.s`. The syntax definition for each command shows how it can be abbreviated by underlining it, for example, `break.set`.

In the syntax definition of each command:

- Square brackets `[...]` enclose optional parameters.
- Braces `{...}` enclose required parameters.
- A vertical pipe `|` indicates alternatives from which you must choose one.
- Parameters that can be repeated are followed by an ellipsis `(...)`.

Do not type square brackets, braces, or the vertical pipe. Replace parameters in italics with the value you want. When you supply more than one parameter, use the separator as shown in the syntax definition for each command. If a parameter is a name that includes spaces, enclose it in double quotation marks.

Descriptive comments can be placed either at the end of a command or on a separate line. You can use either `//` or `;` to identify a descriptive comment.

Using expressions with CMM-style commands

Some commands accept expressions. In an expression, you can access the content of registers and variables by using a function-like notation, for example:

```
print "The result of my expression is: " v.value(myVar)+4+r(R0)
```

Where `v.value()` can be used to access the content of a variable and `r()` can be used to access the content of a register.

2.2 CMM-style commands groups: All

Displays all the CMM-style commands by group.

This section contains the following subsections:

2.2.1 Controlling breakpoints

List of CMM-style commands that enable you to control the starting and stopping of the debugger using breakpoints.

break.delete

Deletes a breakpoint at the specified address.

break.disable

Disables a breakpoint at the specified address.

break.enable

Enables a breakpoint at the specified address.

break.set

Sets a software breakpoint at the specified address.

Type `help` followed by a command name for more information on a specific command.

2.2.2 Controlling data and display settings

List of all the CMM-style commands that enable you to display specific output on the command-line.

data.dump

Displays data at a specific address or address range.

data.set

Writes data to memory.

print

Concatenates the results of one or more expressions.

register.set

Sets the value of a register.

var.global

Displays all global variables.

var.local

Displays all local variables in a function.

var.print

Concatenates the results of one or more expressions.

Type `help` followed by a command name for more information on a specific command.

2.2.3 Controlling images, symbols, and libraries

List of all the CMM-style commands that enable you to load files:

data.load.binary

Loads a binary image file.

data.load.elf

Arm Executable and Linking Format (ELF) file.

Type `help` followed by a command name for more information on a specific command.

2.2.4 Controlling target execution and connections

List of all the CMM-style commands that enable you to connect to a target:

break

Stops running the target.

go

Starts running the device.

system.down

Disconnects the debugger from the target.

system.up

Connects to the specified target.

Type `help` followed by a command name for more information on a specific command.

2.2.5 Displaying the call stack and associated variables

List of all the CMM-style commands that enable you to display stacks and variables:

var.frame

Displays the stack frame.

Type `help` followed by a command name for more information on a specific command.

2.2.6 Controlling the debugger and program information

List of all the CMM-style commands that enable you to control scripts:

var.new

Creates a new script variable and zero-initializes it. Script variables are for use at runtime only.

var.set

Sets and displays the value of an existing script variable.

Type `help` followed by a command name for more information on a specific command.

2.2.7 Supporting commands

List of all the miscellaneous CMM-style commands

help

Displays help information for a specific command or a group of commands listed according to specific debugging tasks.

wait

Pauses the execution of a script for a specified period of time.

Type `help` followed by a command name for more information on a specific command.

2.3 CMM-style commands listed in alphabetical order

Displays all the commands in alphabetical order.

This section contains the following subsections:

2.3.1 CMM-style commands: break

Stops running the target.

Syntax

`break`

Examples

```
break ; Stop running the target
```

2.3.2 CMM-style commands: break.delete

Deletes a breakpoint at the specified address.

Syntax

`break.delete <expression>`

Where:

`<expression>`

Specifies the breakpoint address. This can be either an address, a symbol name, or an expression that evaluates to an address. You can use the syntax `symbol\line` to refer to a specific source line offset from a symbol.

Examples

```
break.delete 0x8000  ; Delete breakpoint at address 0x8000
break.delete main    ; Delete breakpoint at address of main()
break.delete main+4  ; Delete breakpoint 4 bytes after address of main()
break.delete main\2  ; Delete breakpoint 2 source lines after address of main()
```

2.3.3 CMM-style commands: break.disable

Disables a breakpoint at the specified address.

Syntax

`break.disable <expression>`

Where:

`<expression>`

Specifies the breakpoint address. This can be either an address, a symbol name, or an expression that evaluates to an address. You can use the syntax `symbol\line` to refer to a specific source line offset from a symbol.

Examples

```
break.disable 0x8000 ; Disable breakpoint at address 0x8000
break.disable main   ; Disable breakpoint at address of main()
break.disable main+4 ; Disable breakpoint 4 bytes after address of main()
break.disable main\2 ; Disable breakpoint 2 source lines after address of main()
```

2.3.4 CMM-style commands: break.enable

Enables a breakpoint at the specified address.

Syntax

`break.enable.<expression>`

Where:

`<expression>`

Specifies the breakpoint address. This can be either an address, a symbol name, or an expression that evaluates to an address. You can use the syntax `symbol\line` to refer to a specific source line offset from a symbol.

Examples

```
break.enable 0x8000 ; Enable breakpoint at address 0x8000
break.enable main   ; Enable breakpoint at address of main()
break.enable main+4 ; Enable breakpoint 4 bytes after address of main()
break.enable main\2 ; Enable breakpoint 2 source lines after address of main()
```

2.3.5 CMM-style commands: break.set

Sets a software breakpoint at the specified address.

Syntax

`break.set <expression> [/<flag>]`

Where:

`<expression>`

Specifies the breakpoint address. This can be either an address, a symbol name, or an expression that evaluates to an address. You can use the syntax `symbol\line` to refer to a specific source line offset from a symbol.

`/<flag>`

Specifies an additional flag:

`disable`

Disables the breakpoint immediately after setting it.

Examples

```
break.set 0x8000      ; Set breakpoint at address 0x8000
break.set main        ; Set breakpoint at address of main()
break.set main+4      ; Set breakpoint 4 bytes after address of main()
break.set main\2      ; Set breakpoint 2 source lines after address of main()
```

2.3.6 CMM-style commands: data.dump

Displays data at a specific address or address range. By default, the display size is `0x20` bytes of data unless an address range is specified.

Syntax

`data.dump <expression> [/<flag>]'...`

Where:

`<expression>`

Specifies the address or address range. This can be either an address, an address range, or an expression that evaluates to an address. You can use `--` to specify an address range and `++` to specify an offset from an address.

`/<flag>`

Specifies additional flags:

`byte`

Formats the data as 1 byte

`word`

Formats the data as 2 bytes

`long`

Formats the data as 4 bytes

`quad`

Formats the data as 8 bytes

`width`

Specifies the number of columns

`nohex`

Suppresses the hexadecimal output

`noascii`

Suppresses the ASCII output

`le`

Formats the data as little endian

`be`

Formats the data big endian.

If no endianness is specified then the debugger looks for information at the start address of the loaded image otherwise little endian is used

Examples

```
data.dump 0x8000              ; Display 0x20 bytes (default) from address 0x8000
data.dump 0x8000--0x8170      ; Display data in address range 0x8000--0x8170
data.dump r(PC)++0x100        ; Display 0x100 bytes from address in PC register
```

2.3.7 CMM-style commands: data.load.binary

Loads a binary image file.

Note

Loading a binary image does not change the program counter or any symbols that are currently loaded.

Syntax

```
data.load.binary <filename> <expression>
```

Where:

<filename>

Specifies the image file.

<expression>

Specifies the load address. This can be either an address, a symbol name, or an expression that evaluates to an address. If none specified, then the default is `0x0`.

Examples

```
data.load.binary "myFile.bin"                    ; Load image at address 0x0
data.load.binary "../my directory/myFile.bin"    ; Load image at address 0x0
data.load.binary "myFile.bin" 0x8000             ; Load image at address 0x8000
```

2.3.8 CMM-style commands: data.load.elf

Arm Executable and Linking Format (ELF) file. This format is described in the Arm ELF specification and uses the `.axf` file extension.

Note

Loading an ELF image sets the program counter to the entry point of the image, if present.

Syntax

```
data.load.elf <filename> [/<flag>]...
```

Where:

<filename>

Specifies the image file.

/<flag>

Specifies additional flags:

nocode

Do not load code and data to the target.

nosymbol

Do not load symbols.

noclear

Symbol table is not cleared before loading the image.

noreg

Do not set register values, for example, PC and status registers.

Default

By default, this command loads code and data to the target, clears the existing symbol table before loading the new symbols into the symbol table, and sets the registers.

You must use additional flags if you want to modify the default options. For example, you must use `/noclear` if you want to load the symbols from multiple images.

Examples

```
data.load.elf "myFile.axf"                ; Load image and symbols
data.load.elf "../my directory/myFile.axf" ; Load image and symbols
data.load.elf "myFile.axf" /nosymbol       ; Load image without symbols
```

2.3.9 CMM-style commands: data.set

Writes data to memory.

Syntax

`data.set <address> [%<format>] <expression> [/<flag>]...`

Where:

<address>

Specifies the address or address range. This can be either an address, an address range, or an expression that evaluates to an address. You can use `--` to specify an address range.

<format>

Specifies additional formatting:

byte

Formats the data as 1 byte

word

Formats the data as 2 bytes

long

Formats the data as 4 bytes

quad

Formats the data as 8 bytes

float.ieee

Formats the data as a 4 byte floating-point.

float.ieeedbl

Formats the data as an 8 byte floating-point.

le

Formats the data as little endian

be

Formats the data big endian.

If no endianness is specified then the debugger searches for this information in the loaded image otherwise little endian is used.

<expression>

Specifies the data.

<flag>

Specifies additional flags:

verify

Verifies the write operation.

compare

Compares the data in memory but does not write to memory.

Examples

```
data.set r(PC) 0x10                      ; Write 0x10 to address in PC register
data.set 0x100--0x3ff 0x0                ; Zero initialize memory
data.set 0x8000--0x100 %w 0x2000 /compare ; Compare data in memory with 0x2000
data.set 0x100--0x3ff 0x0 /verify        ; Zero initialize memory and verify
```

2.3.10 CMM-style commands: go

Starts running the device.

Syntax

go

Examples

```
go ; Start running the device
```

2.3.11 CMM-style commands: help

Displays help information for a specific command or a group of commands listed according to specific debugging tasks.

Syntax

help [<command> | <group>]

Where:

<command>

Specifies an individual command.

<group>

Specifies a group name for specific debugging tasks:

all

Displays all the commands

breakpoints

Controlling breakpoints.

data

Controlling data and display settings.

files

Controlling images, symbols and libraries.

running

Controlling target execution and stepping.

stack

Displaying the call stack and associated variables.

status

Controlling the default settings and program status information.

support

Additional supporting commands.

Examples

```
help var.frame            # Display help information for var.frame command
help print                # Display help information for print command
help breakpoints          # Display group of breakpoint commands
help status               # Display group of status commands
```

2.3.12 CMM-style commands: print

Concatenates the results of one or more expressions.

Syntax

```
print [%<printing_format>] <expression>...
```

Where:

<printing_format>

Specifies one of [ascii | binary | decimal | hex]. If none specified, then the default is decimal format.

<expression>

Specifies an expression that is evaluated and the result is returned.

Examples

```
print %h r(R0)                ; Display R0 register in hexadecimal
print %d r(PC)                ; Display PC register in decimal
print 4+4                     ; Display result of expression in decimal
print "Result is " 4+4        ; Display string and result of expression
print "Value is: " myVar      ; Display string and variable value
print v.value(myVar)          ; Display variable value
```

2.3.13 CMM-style commands: register.set

Sets the value of a register.

Syntax

```
register.set <name> <expression>
```

Where:

<name>

Specifies the name of a register.

<expression>

Specifies an expression that is evaluated and the result assigned to a register.

Examples

```
register.set R0 15          ; Set value of R0 register to 15
register.set R0 (10*10)     ; Set value of R0 register to result of expression
register.set R0 r(R0)+1     ; Increment the value of R0 register
register.set PC main        ; Set value of PC register to address of main()
```

2.3.14 CMM-style commands: system.down

Disconnects the debugger from the target.

Syntax

system.down

Examples

```
system.down ; Disconnect from target
```

2.3.15 CMM-style commands: system.up

Connects to the specified target.

Syntax

system.up

Examples

```
system.up ; Connect to target
```

2.3.16 CMM-style commands: var.frame

Displays the stack frame.

Syntax

var.frame [%<printing_format>][/<flag>]'...

Where:

%<printing_format>

Specifies one of [ascii | binary | decimal | hex]. If none specified, then the default is decimal format.

/<flag>

Specifies additional flags:

novar

Disables the display of variables.

nocaller

Disables the display of function callers. This is the default.

args

Displays arguments. This is the default.

locals

Displays local variables.

caller

Displays function callers.

json

Specifies an output option to display messages in JSON format.

Examples

```
var.frame /locals /caller        ; Display variables and function callers
var.frame %hex /locals /caller   ; Display variables and callers in hexadecimal
```

```
var.frame /novar                ; Do not display any variables
var.frame /json                 ; Display stack frame in JSON format
```

2.3.17 CMM-style commands: var.global

Displays all global variables.

Syntax

`var.global [%<printing_format>] [/<flag>]`

Where:

%<printing_format>

Specifies one of [ascii | binary | decimal | hex]. If none specified, then the default is decimal format.

/<flag>

Specifies an additional flag:

json

Specifies an output option to display messages in JSON format.

Examples

```
var.global                  ; Display all global variables
var.global %h               ; Display all global variables in hexadecimal
```

2.3.18 CMM-style commands: var.local

Displays all local variables in a function.

Syntax

`var.local [%<printing_format>] [/<flag>]`

Where:

%<printing_format>

Specifies one of [ascii | binary | decimal | hex]. If none specified, then the default is decimal format.

/<flag>

Specifies an additional flag:

json

Specifies an output option to display messages in JSON format.

Examples

```
var.local                   ; Display all local variables
var.local %h                ; Display all local variables in hexadecimal
```

2.3.19 CMM-style commands: var.new

Creates a new script variable and zero-initializes it. Script variables are for use at runtime only.

Syntax

`var.new <name>`

Where:

<name>

Specifies the name of a script variable.

Examples

```
var.new \myVar ; Create new script variable
```

2.3.20 CMM-style commands: var.print

Concatenates the results of one or more expressions.

Syntax

```
var.print [%<printing_format>] <expression>'... [/<flag>]
```

Where:

%<printing_format>

Specifies one of [ascii | binary | decimal | hex]. If none specified, then the default is decimal format.

<expression>

Specifies an expression that is evaluated and the result is returned. You can use script variables in an expression by preceding the name with a backslash. Script variables are for use at runtime only.

/<flag>

Specifies an additional flag:

json

Specifies an output option to display messages in JSON format.

Examples

```
var.print "Value is: " myVar1       ; Display string and myVar1
var.print myVar1 " and " myVar2     ; Display concatenated string/variables
var.print %h myVar1                 ; Display myVar1 in hexadecimal
var.print \myVar                    ; Display value of script variable
```

2.3.21 CMM-style commands: var.set

Sets and displays the value of an existing script variable. It can also display the result of an expression. Script variables are for use at runtime only.

Syntax

```
var.set [<name>=]<expression>
```

Where:

<name>

Specifies the name of an existing script variable.

Note

If you specify the name of an existing script variable then you must use this command after the `var.new` command.

<expression>

Specifies an expression that is evaluated and the result is returned. If you specify an expression with the `name` option, then the value of that script variable is also updated with the result of the expression.

Examples

```
var.set \myVar               ; Display value of script variable
var.set \myVar=3+3           ; Set value of script variable and display result
var.set 3+3                  ; Display result
```

2.3.22 CMM-style commands: wait

Pauses the execution of a script for a specified period of time.

Syntax

```
wait <number>{m|s}
```

Where:

<number>

Specifies the period of time.

m

Specifies the time in milliseconds.

s

Specifies the time in seconds.

Examples

```
wait 1s                    ; Wait one second
wait 0.5s                  ; Wait half a second
wait 1000m                 ; Wait one thousand milliseconds
```

Chapter 3
GNU Free Documentation License Details

It contains the following sections:

3.1 GNU Free Documentation License

Version 1.2, November 2002

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