

How to Run the Kinect Demo Scenes

1. Download and install Kinect v2 SDK as described in the next section.
2. Download and import this package.
3. If you want to utilize the included shaders instead of CPU image processing, make sure that Direct3D11 is the first option in the 'Graphics API'-list, in Player Settings / Other Settings / Rendering.
4. If you want to utilize the Kinect speech recognition, download and install the Speech Platform Runtime or SDK, as well as the needed language packs, as described in the next section.
5. Open and run a demo scene of your choice:
 - KinectAvatarsDemo1, located in KinectDemos/AvatarsDemo-folder. Move around to see how the avatars and the cube-man reflect your movements. Try one or more of the suggested gestures.
 - KinectAvatarsDemo2, located in the same folder. See how the first-person avatar (and the cube-man) reflects your movements. Try to see your arms and legs.
 - KinectBackgroundRemoval1, located in KinectDemos/BackgroundRemovalDemo-folder. See how the cut-out user's image is mixed with the background texture.
 - KinectBackgroundRemoval2, located in the same folder. Check how to set the cut-out user's image as a 2nd background layer and put 3d-objects behind it (the halo), or in front of it (the cubes).
 - KinectBackgroundRemoval3, located in the same folder. Check how to use a separate layer and camera, in order to display images, objects and image effects behind the user's silhouette.
 - ColorColliderDemo, located in KinectDemos/ColliderDemo-folder. Touch any of the creatures with your hands to make them jump, as a result of the collision event between them and your hand.
 - DepthColliderDemo, located in the same folder. Move around to bounce the falling eggs.
 - KinectFaceTrackingDemo1, located in KinectDemos/FaceTrackingDemo-folder. See how the Kinect-generated face model overlays your face on the screen. The model can be textured or not.
 - KinectFaceTrackingDemo2, located in the same folder. See how the hat moves along with your head.
 - KinectFaceTrackingDemo3, located in the same folder. See how the user face can be tracked along.
 - KinectFaceTrackingDemo4, located in the same folder. See how the model follows you and face expressions (animation units) affect the rigged face expression.
 - KinectFittingRoom1, located in KinectDemos/FittingRoomDemo-folder. Stand in T-pose for calibration. See how the selected clothing model overlays your body on the screen.
 - KinectFittingRoom2, located in the same folder. Stand in T-pose for calibration. See how the humanoid model overlays your body on the screen. You can replace it with your model, for testing.
 - KinectGesturesDemo1, located in KinectDemos/GesturesDemo-folder. Swipe left, right or up turn the presentation cube left, right or up. You can also check the 'Seated' visual (VGB) gesture here.
 - KinectGesturesDemo2, located in the same folder. Use the Wheel-gesture to turn the model left or right, or Zoom-in / Zoom-out gestures, to scale the model. Lower your hands between the gestures.
 - KinectInteractionDemo1, located in KinectDemos/InteractionDemo-folder. Use your left or right hand to control the hand-cursor on the screen. Grip an object to drag it around. Open your hand to release it. Try to interact with the GUI components, too.
 - KinectInteractionDemo2, located in the same folder. Grip the cube with your left or right hand. Then turn it in all directions, to see it from all sides.
 - Scene0-StartupScene, located in KinectDemos/MultiSceneDemo-folder. Add Scene0, Scene1 and Scene2 to the 'Scenes in Build'-list in 'File / Build Settings'. Then run the startup scene. You will see how to use the Kinect-related managers across multiple scenes in a game.
 - KinectOverlayDemo1, located in KinectDemos/OverlayDemo-folder. Move your hands. See how the green ball follows the position of your right hand on the screen.

- KinectOverlayDemo2, located in the same folder. See how the spheres overlay all tracked joints in your body, and the lines represent the bones between them.
- KinectOverlayDemo3, located in the same folder. This is a simple 'draw-in-the-air' application. Close your right hand to start drawing. Open it to stop. Press 'U' to undo the last curve.
- KinectRecorderDemo, located in KinectDemos/RecorderDemo-folder. Say 'Record' to start recording your body movements, 'Stop' to stop it, or 'Play' to replay the previously saved movements.
- KinectSpeechRecognition, located in KinectDemos/SpeechRecognitionDemo-folder. Say clearly one of the listed commands to control the robot. Repeat it, if needed. Then open the xml-grammar file 'SpeechGrammar.grxml', located in the Assets/Resources folder of the Unity project, and modify the commands, according to your needs. Save the grammar file and run the scene again to try them.
- KinectPoseDetector, located in KinectDemos/VariousDemos-folder. See how the differences in bone angles are calculated and summed up to provide pose matching info.
- KinectSceneVisualizer, located in KinectDemos/VariousDemos-folder. Check how the real environment within predefined depth and left/right limits can be mixed with the virtual objects.
- KinectUserVisualizer, located in KinectDemos/VariousDemos-folder. See how the user's 3d mesh-model can be added to the virtual scene, and how it can interact with virtual objects in the scene.

Installation of Kinect v2 SDK

1. Download the Kinect for Windows SDK 2.0. Here is the download page: <http://www.microsoft.com/en-us/download/details.aspx?id=44561>
2. Run the installer. Installation of Kinect SDK/Runtime 2.0 is simple and straightforward.
3. Connect the Kinect v2 sensor. The needed drivers are installed automatically.
4. If you want to use the Kinect speech recognition, download and install the MS Speech Platform Runtime v11 (or Speech Platform SDK v11). Install both x86 and x64-packages, to be on the safe side. Here is the download page: <http://www.microsoft.com/en-us/download/details.aspx?id=27225>
5. For the Kinect speech recognition, you also need to download and install the respective language pack. Here is the download page: <https://www.microsoft.com/en-us/download/details.aspx?id=43662>

Why Are There Two Avatars in the Avatars-Demo1

The presence of the two avatars (humanoid characters) in the scene is to demonstrate different options of their AvatarController-components. These are the components that make these 3d-models copy players' movements.

First, you can have an avatar that mirrors your movements, and (in this case) moves around the main camera, the same way you move around the sensor. This is the right one, facing you in the Demo-1 scene. As you can see, its transform Y-rotation (rotation around Y-axis) is set to 180 degrees. The AvatarController-component, attached to this avatar's game object has its 'Mirrored Movement'-setting enabled. It also has 'Pos relative to camera' set to the MainCamera, in order to reproduce your movement around the Kinect.

The left avatar, the one that has turned his back at you, is not mirrored. It reproduces your movements as they are. Your left is his left and your right is his right. Its transform Y-rotation is set to 0 (in order to be in the same direction as you) and the 'Mirrored Movement'-parameter of its AvatarController is disabled. It also has 'Pos relative to camera' set to None, that's why it moves around its initial position, instead of around the camera.

Also note the 'Player index'-setting of both avatars. It specifies which avatar which player tracks - 0 means the 1st detected user, 1 – the 2nd one, etc. If you want any of the avatars to follow another user, just change the 'Player index' setting of its respective AvatarController-component.

How to Reuse the Kinect-related Scripts in Your Own Unity Project (Windows Builds)

1. Copy folder 'KinectScripts' from the Assets-folder of the example to the Assets-folder of your project. This folder contains all needed scripts, filters and interfaces.
2. Copy folder 'Resources' from the Assets-folder of the example to the Assets-folder of your project. This folder contains the needed libraries and resources. You may skip the libraries you don't want to use.
3. Copy folder 'Standard Assets' from the Assets-folder of this package to the Assets-folder of your project. It contains the wrapper classes for Kinect v2.
4. Wait until Unity detects, imports and compiles the newly detected resources and scripts.
5. In your scene, create a KinectController-object and add the 'KinectManager' as component to it.
6. Enable its 'Compute User Map'-setting, if you want to use the body texture or the user-depth texture. Enable 'Compute Color Map', if you want to utilize the color camera texture. The respective Display-settings may be used to display these textures on the screen.
7. Add the 'AvatarController'-component to each avatar (humanoid character) in the scene that you need to control with the Kinect-sensor. See the previous topic for more information regarding AvatarController.
8. You may use the public API of 'KinectManager', 'InteractionManager', 'FacetrackingManager', 'SpeechManager', etc. managers in your scripts. See the components and scripts in almost each demo-scene folder, if you need examples. Also make sure you don't miss this valuable source of information:
<http://rfilkov.com/2015/01/25/kinect-v2-tips-tricks-examples/>

Additional Reading

The following how-to tutorials are also located in the Assets/_Readme-folder of this Unity-package:

1. Howto-Use-Gestures-or-Create-Your-Own-Ones.pdf
2. Howto-Use-KinectManager-Across-Multiple-Scenes.pdf

More Information, Support and Feedback

Tip and Tricks: <http://rfilkov.com/2015/01/25/kinect-v2-tips-tricks-examples/>

Troubleshooting: <http://rfilkov.com/2014/08/01/kinect-v2-with-ms-sdk/#ki>

Web: <http://rfilkov.com>

Contact: <http://rfilkov.com/about/#contact>

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