

PJ : Cold Brew Machine

조원 : 홍기화

[프로젝트 목적]

Cold Brew Coffee Automation System

주 목적

←---- optional
← mandatory

1 Ground Coffee Analysis

DSP(OpenCV)

Camera USB 3.0 1920 x 1280

Data 1 : Color(RGB)

Data 2 : Size(mm²)

Under Dark Room and LED light

Under Dark Room and LED light

Filter all but the ground coffee
-> Average the color of the dots

Brightness normalization ->
DFT -> range -> size

2 Sensor Data Processing(Digital Filter)

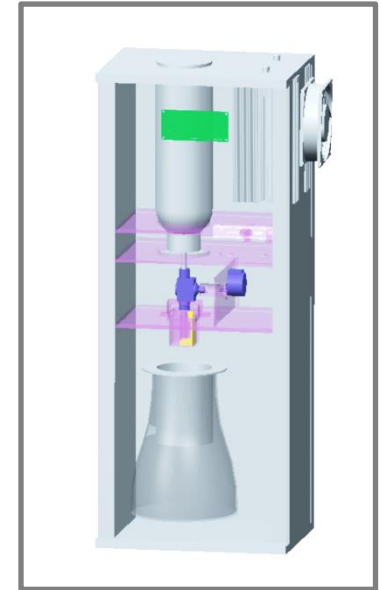
Weight Sensor Data -> ADC(<=3mV Change)

Temperature Sensor Data -> ADC

ADC -> Digital Filter(LPF)

Where 1 : Weight Sensor

Where 2 : Temperature Sensor



[프로젝트 목적]

Cold Brew Coffee Automation System

주 목적

←---- optional
← mandatory

3 Drop Display On Web

WebGL

Water Drop Visualization

Display Data

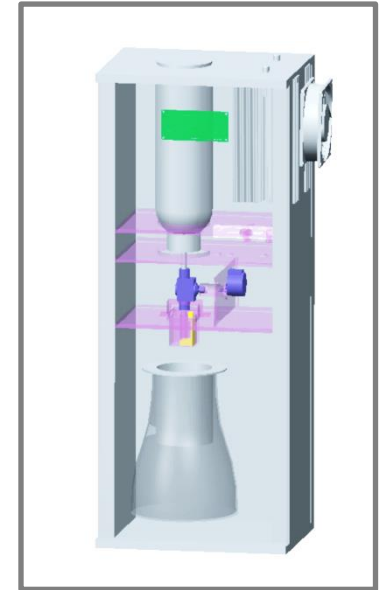
IR Remote -> Web

Ground coffee (size)

Display data

Ground coffee (color)

Select settings



4 Interrupt List(Priority)

1. Remote Control

2. Drop Count

3. Weight Sensor




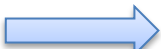



4. LCD Display

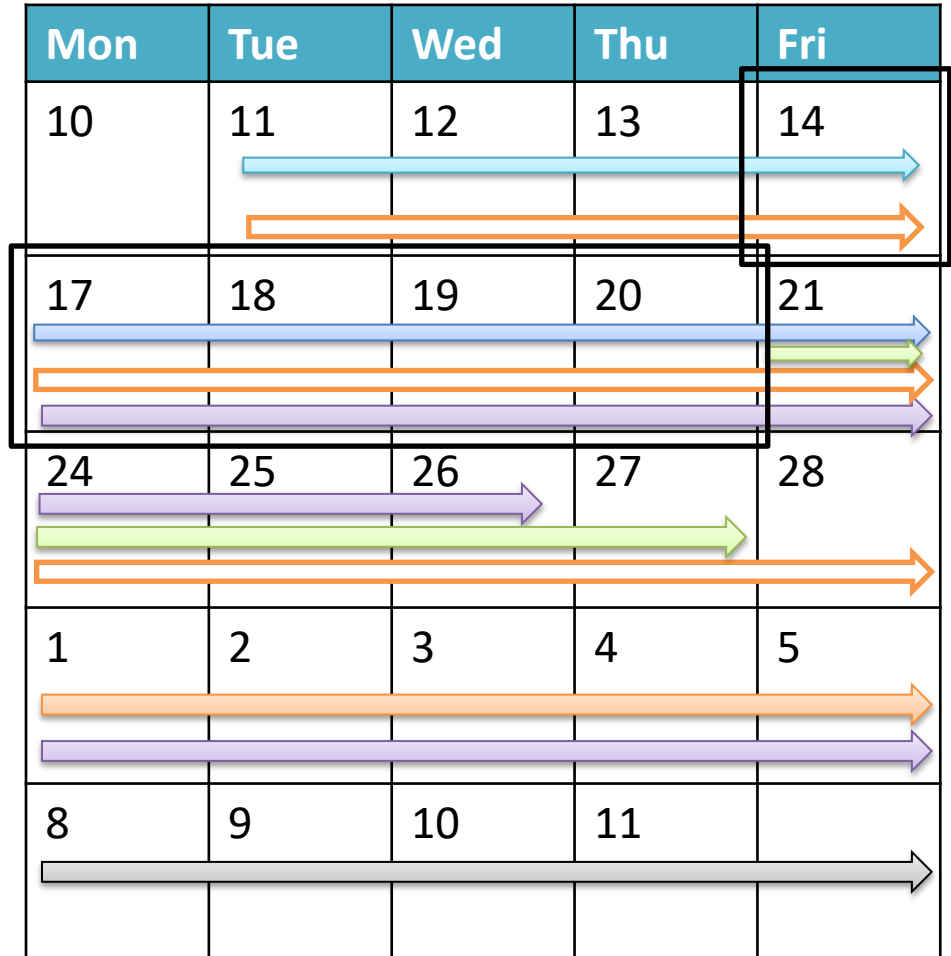
[PJ CBM : BOM]

대분류	소분류	품명	수량(ea)	단위가격(원)	총액(원)
electronic parts	MCU	TI tms570 launchpad	1	37570	37570
	LCD	LC1621 LCD	1	7700	7700
	Weight Sensor	Load cell BND-611N 1kg	2	25300	50600
	Weight Sensor	Load cell BND-611N 2kg	1	14500	14500
	Weight sensor adc IC	HX711 Module (24bit AD)	1	1540	1540
	Drop Sensor	photo interrupter	1	1760	1760
	Temperature sensor	ETH-01DV	1	8910	8910
	UV-LED	uv-c 4545 smd led 5mW	3	5000	15000
	IR receiver + control board	(chinese)	1	2000	2000
	step motor controller	ULN2003 Module	1	1300	1300
	step motor for valve control	28BYJ-48	1	1200	1200
	FAN		1	17500	17500
	TEC Module	TEC-12705	2	5400	10800
	Relay		2	2000	4000
	Camera	usb3.0	1	75000	75000
Mechanical parts	door switch	ramps 1.4 limit switch	3	2400	7200
	펄티어 단열스폰지	펄티어 단열스폰지	1	600	600
	Peltier heatsink	Peltier-Heatsink-Set(협신전자)	1	16500	16500
	LED PCB	smd led 기판	1	1800	1800
	투명 튜브	에어호스 6mm	1	800	800
	electric wire	0.35Q x 12C 10color 1m	1	1300	1300
	wire mold	wire duct PVC 사각몰드 밤색 1호	3	300	900
	문 경첩	경첩	2	1000	2000
	문고리	문고리	1	1000	1000
	문자석	문 자석	1	1200	1200
	case	플라베니아 5T 회색	1	4950	4950
	단열재	압축스티로폼 20mm	1	2000	2000
	물병	물병 티보틀	1	5000	5000
	실리콘마개	SL.Sto6105 (싸이랩코리아)	1	4500	4500
	Water valve	FSC0600 호스6mm 미세조절	1	2600	2600
	Water tank	daiso 1001333	2	1760	3520
	Li-po 2800mAh 35C	Li-po 2800mAh 35C	1	51900	51900
	3D Printer	Ender 3	1	230000	230000
	3d print 필라멘트	PLA 필라멘트 1kg	2	17500	35000
	볼트너트	m3,m4,m5 볼트 너트 와셔 세트(은색)	1	6100	6100
	더치기구	더치기구	1	19500	19500
합계 총액					647,750

[프로젝트 일정]

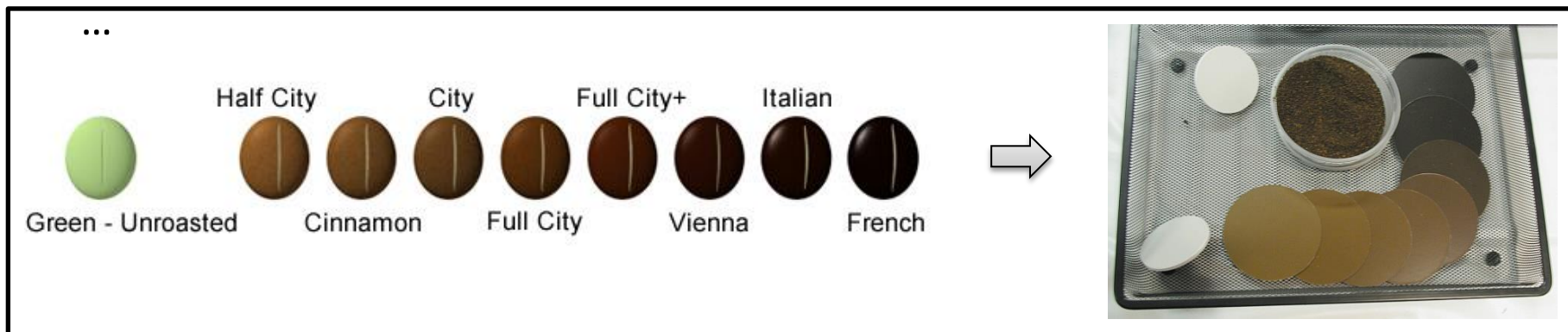
6/14~6/20




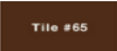
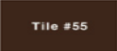


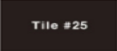
-  DSP(Camera)
-  Sensor fix(고장 수리)
-  DFT, LPF
-  WebGL
-  Interrupt Priority check
-  Debug
-  Communication(dsp<->mcu)



[PJ CBM : 진행 상황]

☐ Coffee Color Palette Standard (RGB) : SCAA, agtron m-basis roami



SCAA 분류법		SCAA
단계	색	R, G, B Value
Very Light	 Tile #95	122, 61, 26
Light	 Tile #85	108, 55, 25
Moderately Light	 Tile #75	96, 49, 32
Light Medium	 Tile #65	78, 44, 23
Medium	 Tile #55	61, 38, 26
Moderately Dark	 Tile #45	58, 43, 28
Dark	 Tile #35	58, 43, 28
Very Dark	 Tile #25	39, 30, 28



측정값 : R,G,B (144,105,82)

보정값 : R,G,B (-83,-67,-56)

측정값 + 보정값 = 사용할 Color Data

[PJ CBM : 진행 상황]

□ Brightness Upscale

Mat chk_color(Mat img, int radius)

```
{  
    int rows = img.rows;  
    int cols = img.cols;  
    int array = rows * cols;  
    int count_dots=0, black_dots=0, white_dots=0;  
    int i=0,j=0;  
    int total_r = 0, total_g = 0, total_b = 0;  
    int white_r = 0, white_g = 0, white_b = 0;
```

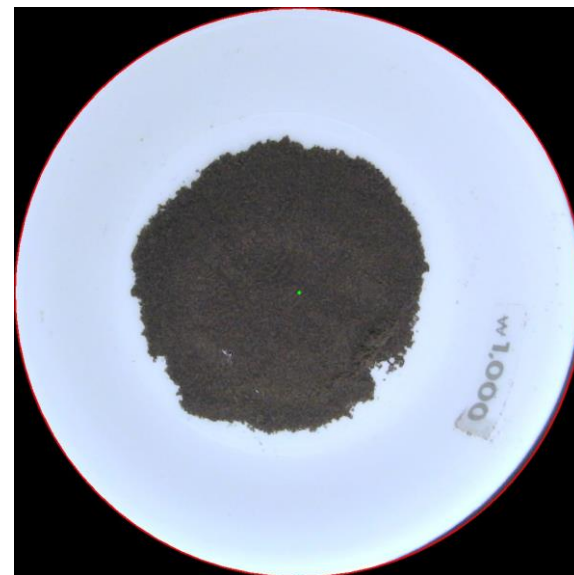
커피, 흰색, 검정색(배경) 구분

```
/*  
    src.at(i,j) is using (i,j) as (row,column)  
    but Point(x,y) is using (x,y) as (column,row)  
*/  
/* 680*480*256 = 83558400  
int limit = 2111111111;  
printf("limit = %d\n", limit);  
*/  
for(i=0; i<rows; i++){  
    for(j=0; j<cols; j++){  
        if((img.at<Vec3b>(i,j)[0] == 0) && (img.at<Vec3b>(i,j)[1] == 0) && (img.at<Vec3b>(i,j)[2] == 0))  
        {  
            black_dots++;  
            continue;  
        }  
  
        else if((img.at<Vec3b>(i,j)[0] >= 140) && (img.at<Vec3b>(i,j)[1] >= 140) && (img.at<Vec3b>(i,j)[2] >= 140)){  
            white_r += img.at<Vec3b>(i,j)[2];  
            white_g += img.at<Vec3b>(i,j)[1];  
            white_b += img.at<Vec3b>(i,j)[0];  
            white_dots++;  
            continue;  
        }  
  
        total_r += img.at<Vec3b>(i,j)[2];  
        total_g += img.at<Vec3b>(i,j)[1];  
        total_b += img.at<Vec3b>(i,j)[0];  
        count_dots++;  
    }  
}
```

흰색 기준으로 upscale

```
for(i=0; i<rows; i++){  
    for(j=0; j<cols; j++){  
        if((img.at<Vec3b>(i,j)[2]==0)&&(img.at<Vec3b>(i,j)[1]==0)&&(img.at<Vec3b>(i,j)[0]==0))  
            continue;  
        else{  
            if ((int)(img.at<Vec3b>(i,j)[2] + (255 - (white_r/white_dots)))>255)  
                img.at<Vec3b>(i,j)[2]=255;  
            else  
                img.at<Vec3b>(i,j)[2] += (255 - (white_r/white_dots));  
  
            if ((int)(img.at<Vec3b>(i,j)[1] + (255 - (white_g/white_dots)))>255)  
                img.at<Vec3b>(i,j)[1]=255;  
            else  
                img.at<Vec3b>(i,j)[1] += (255 - (white_g/white_dots));  
  
            if ((int)(img.at<Vec3b>(i,j)[0] + (255 - (white_b/white_dots)))>255)  
                img.at<Vec3b>(i,j)[0]=255;  
            else  
                img.at<Vec3b>(i,j)[0] += (255 - (white_b/white_dots));  
        }  
    }  
}
```

imwrite("a_colorcheck_img_brighter.jpg", img);



기
존
밝
기
수
준

수
정
후
밝
기
수
준

[PJ CBM : 진행 상황]

☐ Brightness Upscale -> DCT Test



mean : [-9.848960512195825]
stddev : [827.6144785028674]

mean : [-9.794771350184202]
stddev : [841.8923988885016]

mean : [-9.726895776497841]
stddev : [823.6670048330741]

mean : [-9.486053139658093]
stddev : [807.4953496042172]

mean : [-9.367362561205923]
stddev : [810.6738272124364]

[PJ CBM : 진행 상황]

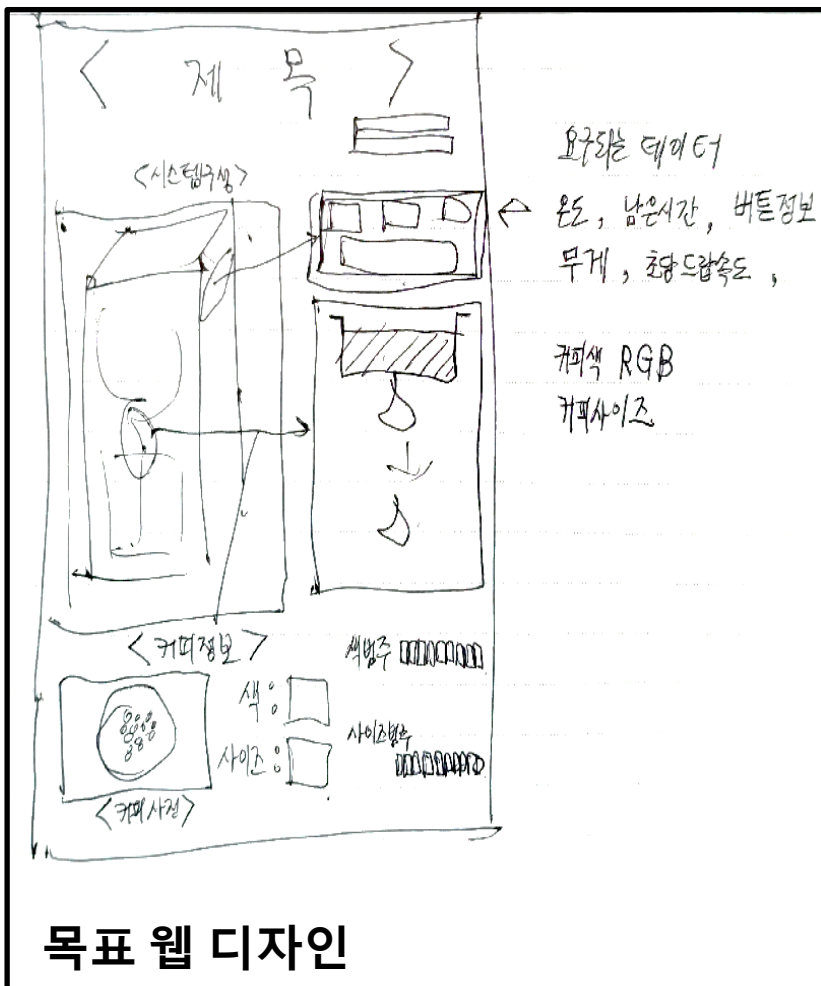
❑ DSP Multi thread

1.Web Server 2.communication

-> 완료

❑ Web design(html)

-> 진행중



DSP Multi thread

-> thread1: printf
thread2:server

```
root@am57xx-evm:~/gihwahong/web_physics# ./a.out
init done
Using Wayland-EGL
wlpvr: PVR Services Initialised
Serving HTTP on 0.0.0.0 port 5677 ...
192.168.0.128 - - [26/Mar/2018 16:00:24] "GET /freefall.html HTTP/1.1" 200 -
192.168.0.128 - - [26/Mar/2018 16:00:24] "GET /jsLibs/three.js HTTP/1.1" 200 -
192.168.0.128 - - [26/Mar/2018 16:00:24] "GET /jsLibs/stats.js HTTP/1.1" 200 -
192.168.0.128 - - [26/Mar/2018 16:00:24] "GET /favicon.ico HTTP/1.1" 404 -
thread1 print
thread1 print
thread2 print
^C '2 : ctrl + c' int initiated
(signal)status: 0x2
```

이미지, 텍스트 뿌리기




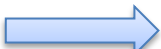



WebGL 구동



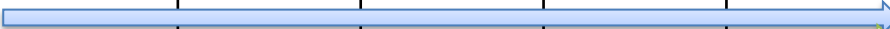







웹 시작 시 .txt 읽어 console 출력중

현재까지 진행 사항

[프로젝트 일정]

6/10~7/11

-  DSP(Camera)
-  Sensor fix(고장 수리)
-  DFT, LPF
-  WebGL
-  Interrupt Priority check
-  Debug
-  Communication(dsp<->mcu)

Mon	Tue	Wed	Thu	Fri
10	11	12	13	14
				
				
17	18	19	20	21
				
				
				
24	25	26	27	28
				
				
				
1	2	3	4	5
				
				
8	9	10	11	
