CHAPTER 2

ALGORITHM ANALYSIS

[Definition] An algorithm is a finite set of instructions that, if followed, accomplishes a particular task. In addition, all algorithms must satisfy the following criteria:

- (1) Input There are zero or more quantities that are externally supplied.
- (2) Output At least one quantity is produced.
- (3) **Definiteness** Each instruction is clear and unambiguous.
- (4) Finiteness If we trace out the instructions of an algorithm, then for all cases, the algorithm terminates after finite number of steps.
- (5) **Effectiveness** Every instruction must be basic enough to be carried out, in principle, by a person using only pencil and paper. It is not enough that each operation be definite as in(3); it also must be feasible.

Note: A program is written in some programming language, and does not have to be finite (e.g. an operation system).

An algorithm can be described by human languages, flow charts, some programming languages, or pseudocode.

[Example] Selection Sort: Sort a set of $n \ge 1$ integers in increasing order.

for (i = 0; i < n; i++) {

Where?

Examine list[i] to list[n-1] and suppose that the smallest integer is at list[min];

Interchange list[i] and list[min];

Prom those integers that are currently unsorted, find the smallest.

Where and how are they stored?

Algorithm in pseudo-code

Sort = Find the smallest integer + Interchange it with list[i].

§ 1 What to Analyze

➤ Machine & compiler-dependent run times.

Time & space complexities: machine & compiler-independent.

- Assumptions:
- ① instructions are executed sequentially
- 2 each instruction is simple, and takes exactly one time unit
- 3 integer size is fixed and we have infinite memory
- Typically the following two functions are analyzed:

 $T_{\text{avg}}(N)$ & $T_{\text{worst}}(N)$ -- the average and worst case time complexities, rectively, as functions of input size N.

If there is more than one input, these functions may have more than one argument.

[Example] Matrix addition

```
void add ( int a[ ][ MAX_SIZE ],
           int b[][MAX_SIZE],
                                           A: Exchange
           int c[][MAX_SIZE],
                                           rows and cols.
           int rows, int cols)
  int i, j;
  for (i = 0; i < rows; i++) /* rows + 1 */
     for (j = 0; j < cols; j++) /* rows(cols+1)
         c[i][j] = a[i][j] + b[i][j]; /* rows \cdot cols */
          T(rows, cols) = 2 rows \cdot cols + (2rows) + 1
```

[Example] Iterative function for summing a list of numbers

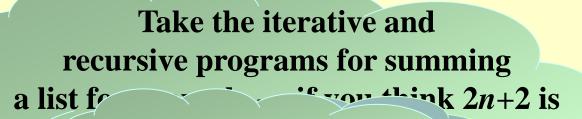
```
T_{sum}(n)=2n+3
```

[Example] Recursive function for summing a list of numbers

$$T_{rsum}(n)=2n+2$$

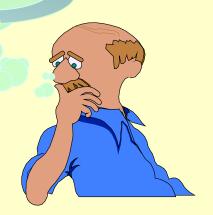
But it takes more time to compute each step.

```
float rsum ( float list[ ], int n )
{ /* add a list of numbers */
   if ( n ) /* count ++ */
     return rsum(list, n-1) + list[n - 1];
     /* count ++ */
   return 0; /* count ++ */
}
```



Good question! Let's ask the students ...





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§ 2 Asymptotic Notation (O, Ω, Θ, o)



The point of counting the steps is to predict the growth in run time as the N change, and thereby compare the time complexities of two programs. So what we really want to know is the asymptotic behavior of T_p .

Suppose $T_{p1}(N) = c_1N^2 + c_2N$ and $T_{p2}(N) = c_3N$. Which one is faster?

No matter what c_1, c_2 , and c_3 are, there will be an n_0 such that $T_{p1}(N) > T_{p2}(N)$ for all $N > n_0$.



I see! So as long as I know that T_{p1} is about N^2 and T_{p2} is about N, then for sufficiently large N, P2 will be faster!

Terminal T(N) = O(f(N)) if there are positive constants c and n_0 such that $T(N) \le c \cdot f(N)$ for all $N \ge n_0$.

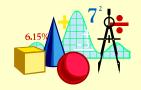
[Definition] $T(N) = \Omega(g(N))$ if there are positive constants c and n_0 such that $T(N) \ge c \cdot g(N)$ for all $N \ge n_0$.

Terminal $T(N) = \Theta(h(N))$ if and only if T(N) = O(h(N)) and $T(N) = \Omega(h(N))$.

Definition T(N) = o(p(N)) if T(N) = O(p(N)) and $T(N) \neq O(p(N))$.

Note:

- > $2N + 3 = O(N) = O(N^{k \ge 1}) = O(2^N) = \cdots$ We shall always take the smallest f(N).
- \geq $2^N + N^2 = \Omega(2^N) = \Omega(N^2) = \Omega(N) = \Omega(1) = \cdots$ We shall always take the largest g(N).



Rules of Asymptotic Notation

- If $T_1(N) = O(f(N))$ and $T_2(N) = O(g(N))$, then (a) $T_1(N) + T_2(N) = \max(O(f(N)), O(g(N)))$, (b) $T_1(N) * T_2(N) = O(f(N) * g(N))$.
- If T(N) is a polynomial of degree k, then $T(N) = \Theta(N^k)$.
- $\log^k N = O(N)$ for any constant k. This tells us that logarithms grow very slowly.

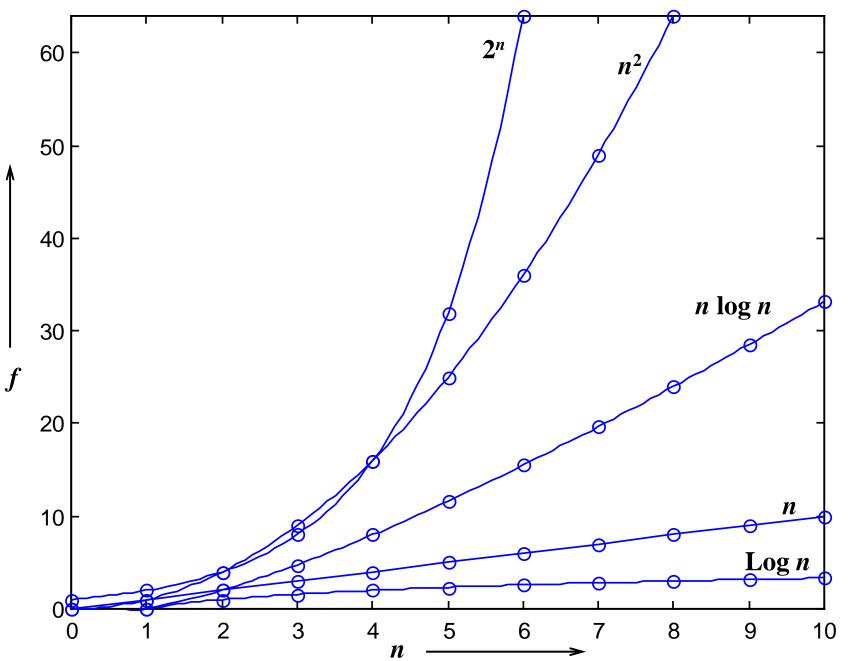
Note: When compare the complexities of two programs asymptotically, make sure that N is sufficiently large.

For example, suppose that $T_{p1}(N) = 10^6 N$ and $T_{p2}(N) = N^2$. Although it seems that $\Theta(N^2)$ grows faster than $\Theta(N)$, but if $N < 10^6$, P2 is still faster than P1.

§ 2 Asymptotic Notation

Input size n												
Time	Name	1	2	4	8		16	32				
1	constant	1	1	1	1		1	1				
$\log n$	logarithmic	0	1	2	3		4	5				
n	linear	1	2	4	8		16	32				
$n \log n$	log linear	0	2	8	24		64	160				
n^2	quadratic	1	4	16	64		256	1024				
n^3	cubic	1	8	64	512	4	1096	32768				
2^n	exponential	2	4	16	256	65536		4294967296				
n!	factorial	1	2	24	40326	2092278988000		26313×10^{33}				

§ 2 Asymptotic Notation



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		Ti	Time for $f(n)$ instructions on a 10^9 instr/sec computer									
n		f(n)=n	$n \log_2 n$	n^2	n^3	n^4	n^{10}	2 ⁿ				
	10	0 .01μs	.03µs	.1μs	1μs	10µs	10sec	1µs				
	20	0 .02μs	.09µs	.4µs	8µs	160µs	2.84hr	1ms				
	30	0 .03μs	.15µs	.9µs	27μs	810µs	6.83d	1sec				
	40	0 .04μs	.21µs	1.6µs	64μs	2.56ms	121.36d	18.3min				
	50	0 .05μs	.28µs	2.5μs	125µs	6.25ms	3.1yr	13d				
	100	0 .10μs	.66µs	10 μs	1ms	100ms	3171yr	4*10 ¹³ yr				
	1,000	0 1.00μs	9.96µs	1ms	1sec	16.67min	3.17*10 ¹³ yr	32*10 ²⁸³ yr				
	10,000	0 10μs	130.03µs	100ms	16.67min	115.7d	3.17*10 ²³ yr					
	100,00	0 100μs	1.66ms	10sec	11.57d	3171yr	3.17*10 ³³ yr					
1,	000,00	0 1.0ms	19.92ms	16.67min	31.71yr	3.17*10 ⁷ yr	3.17*10 ⁴³ yr					

 $\mu s = microsecond = 10^{-6} seconds$ $ms = millisecond = 10^{-3} seconds$ sec = seconds

min = minutes hr = hours d = days

yr = years

[Example] Matrix addition

```
void add ( int a[ ][ MAX_SIZE ],
            int b[][MAX_SIZE],
            int c[][MAX_SIZE],
            int rows, int cols)
  int i, j;
  for (i = 0; i < rows; i++) /* \Theta (rows) */
      for (j = 0; j < cols; j++) /* \Theta (rows · cols ) */
          c[i][j] = a[i][j] + b[i][j]; /* \Theta (rows \cdot cols) */
```

 $T(rows, cols) = \Theta(rows \cdot cols)$



General Rules

- FOR LOOPS: The running time of a for loop is at most the running time of the statements inside the for loop (including tests) times the number of iterations.
- **NESTED FOR LOOPS:** The total running time of a statement inside a group of nested loops is the running time of the statements multiplied by the product of the sizes of all the for loops.
- **CONSECUTIVE STATEMENTS:** These just add (which means that the maximum is the one that counts).
- F / ELSE: For the fragment if (Condition) S1; else S2;

the running time is never more than the running time of the test plus the larger of the running time of S1 and S2.

PRECURSIONS:

[Example] Fibonacci number:

$$Fib(0) = Fib(1) = 1$$
, $Fib(n) = Fib(n-1) + Fib(n-2)$

```
long int Fib ( int N ) /* T(N) */
{
    if ( N <= 1 ) /* O(1) */
        return 1; /* O(1) */
    else
        return Fib( N - 1 ) + Fib( N - 2 );
} /*O(1)*/ /* T(N-1)*/ /* T(N-2)*/</pre>
```

$$T(N) = T(N-1) + T(N-2) + 2 \ge \text{Fib}(N)$$

$$\left(\frac{3}{2}\right)^{N} \le \text{Fib}(N) \le \left(\frac{5}{3}\right)^{N} \longrightarrow T(N) \text{ grows exponentially}$$

Proof by induction