

Magnetism

Magnetism Equations

Point Charge

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{qv \sin(\theta)}{r^2}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q\vec{v} \times \hat{r}}{r^2}$$

$$1 \text{ Tesla} = N/Am$$

Infinite Wire

$$B = \frac{\mu_0}{2\pi} \frac{I}{r}$$

Current Loop

$$B = \frac{\mu_0}{2} \frac{NI}{R}$$

Solenoid

$$B = \mu_0 \frac{N}{L} I$$

Current Segment

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{I \Delta \vec{s} \times \hat{r}}{r^2}$$

Long, Straight Wire

$$B = \frac{\mu_0}{2\pi} \frac{I}{r}$$

Coil Center

$$B = \frac{\mu_0}{2} \frac{NI}{R}$$

Dipole

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{2\vec{\mu}}{z^3}$$

$$\vec{\mu} = AI$$

Current is in the direction of curled fingers.

Ampère's Law

$$\int_{surface} \vec{B} \cdot d\vec{s} = \mu_0 I_{through}$$

Positive currents are ones flowing in direction of thumb when curled with current.

Field Inside Current-Carrying Wire

$$B = \frac{\mu_0 I}{2\pi R^2} r$$

Solenoid

$$B = \frac{\mu_0 NI}{l} = \mu_0 nI$$

Magnetic Force

$$\vec{F} = q\vec{v} \times \vec{B}$$

Notice force is in the opposite direction if the charge is negative

This also implies cyclotron motion by showing that the force is perpendicular when initially traveling straight in a field.

Cyclotron

Radius

$$r_{cyc} = \frac{mv}{qB}$$

Frequency

$$f_{cyc} = \frac{qB}{2\pi m}$$

Hall Effect

Voltage

$$\Delta V_H = \frac{IB}{tne}$$

Forces Between Wires

$$\vec{F} = I\vec{l} \times \vec{B}$$

Parallel Wires

$$F = I_1 l B_2 = \frac{\mu_0 I I_1 I_2}{2\pi d}$$

d is distance between them.

Same direction attract. Different repel.

Torque

Current Loop

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

μ is the vector defined earlier.

Electromagnetic Wave Velocity

$$v = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

Transformer

Coil ratio:

$$V_2 = \frac{N_2}{N_1} V_1$$

Inductor

Henries

$$L_{solenoid} = \frac{\mu_0 N^2 A}{l}$$

Potential

$$\epsilon = L \left| \frac{dl}{dt} \right|$$

Potential across inductor is opposite of circuit polarity.

Energy

Stored

$$U_L = \frac{1}{2} L I^2$$

Density

$$u = \frac{1}{2 \mu_0} B^2$$

LC Circuits

Oscillation frequency:

$$\omega = \sqrt{\frac{1}{LC}}$$

$$f = \omega / 2\pi$$

or

$$I = I_{max} \sin(\omega t)$$

LR Circuits

Discharging

$$I = I_0 e^{-t/\tau}$$

$$\tau = L/R$$

Lenz's Law

The direction of induced current *opposes* the change in magnetic flux through a loop.

Faraday's Law

$$I = \frac{\epsilon}{R}$$

$$\epsilon = \left| \frac{d\Phi_m}{dt} \right|$$

$$\epsilon_{coil} = N \left| \frac{d\Phi_{per\ coil}}{dt} \right|$$

This can also be used to describe flux in a circuit by subbing in Φ for the flux equation and then realizing change in area is related to velocity of movement.

Induced Electric Fields

$$\int_{surface} \vec{E} \cdot d\vec{s} = A \left| \frac{dB}{dt} \right|$$

So $d\vec{s}$ is length of loop, then solve for \vec{E} .

$d\vec{s}$ also ensures that this vector is tangent to the curve.

Inside a solenoid

$$E = \frac{r}{2} \left| \frac{dB}{dt} \right|$$

Induced Currents

Motional EMF

$$\epsilon = v l B$$

Induced Current In Circuit

Current Created

$$I = \frac{\epsilon}{R} = \frac{v l B}{R}$$

Power Dissipated

$$P = I^2 R = \frac{v^2 l^2 B^2}{R}$$

Magnetic Flux

$$\Phi_m = \vec{A} \cdot \vec{B}$$

$$\Phi_m = AB \cos \theta$$

Units of weber: $1\ Tm^2$