

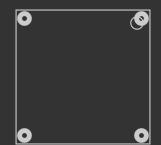
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# The Octadecayotton (3 Dimensions)

who'll be there when i'm gone?

By default 9 dimensions is used, but multiple Octadecayottons or mod settings can change it.

The 8 spheres will start moving, resembling the rotations of a 3-dimensional cube. 3 rotations are shown, followed by a brief pause before starting over.



### Identifying Dimensions

- There are 3 dimensions: X, Y, and Z. Each axis can either be positive, or negative.
- Any positive axis points to the right (+X), up (+Z), and/or towards (+Y) the viewer when viewed from the front.
- Any negative axis points to the left (-X), down (-Z), and/or away (-Y) the viewer when viewed from the front.
- Any given sphere has 3 neighbours, which are all 1 of each of the 3 axes, either positively or negatively.
- To the diagram to the right shows on example of a sphere's 3 neighbours as seen from the front. The unfilled spheres are neighbours of the filled sphere.
- In reading order (left-to-right then top-to-bottom), the spheres are Z, Y (stacked on top of the filled sphere), and X.
- In this example, going from the filled sphere to any unfilled is a positive axis, while going from an unfilled sphere to the filled sphere is a negative axis.



### Identifying Rotations

- Look at 2 spheres that are neighbours (note down their initial axis that connects them together) and watch them transform.
- If these 2 spheres are now neighboured from a different axis, that implies a rotation. Record the new axis that they transformed into, and repeat this process starting with the new axis until the first initial axis is reached.
- For any negative initial axis, invert both the initial and new axis.
  (positive -> negative, negative -> positive)

## Identifying Rotations (...continued)

- When the first initial axis has been reached, start from the bottom of the list, and working your way up; append all the new axes to a separate list.
- The resulting list is called a subrotation. In a given rotation there can be multiple simulatenous subrotations happening at the same time.

# Primary Values

- All rotations and subrotations have a primary value. Within each subrotation, create a list of every possible pair of axes from itself and the next axis. (including the last and first axis as a pair\*)
- If the subrotation contains exactly 1 axis, ignore the above rule and make only 1 pair, consisting of the axis repeated twice.
- For each pair, get the value from the table, using the first letter as the row and the second letter as the column.
- If 1 of the 2 axes are negative, multiply the pair's result with -1.

<sup>\*</sup> Even with 2 axes, this rule still applies. For example, subrotation +R-T gives +R-T and -T+R.

	X	Y	Z	
X	1	2	5	X
Y	2	3	6	Y
Z	9	1	4	Z
	X	Y	Z	

#### Primary Values (...continued)

• The absolute sum of all pairs on all subrotations modulo 8 is the primary value of that rotation. Later in this manual, whenever  $p_1$ ,  $p_2$ , or  $p_3$  is mentioned, it refers to the primary value of the  $1^{st}$ ,  $2^{nd}$ , and  $3^{rd}$  rotation respectively.

#### The Anchor Sphere

- Create 4 codes, named  $a_0$ ,  $a_1$ ,  $a_2$ , and  $a_3$ , each starting with the value "000".  $a_{1-3}$  represent rotations 1-3.
- Subtract the largest number equal or less than  $p_1$  found in "Decimal <-> Binary" from it, then set  $a_1$ 's Xth digit from the left to 1, where X is the position obtained from that same number that was subtracted with. Keep subtracting and setting digits to 1 until  $p_1$  is 0.
- Repeat the above step using  $p_2$  and  $a_2$ , as well as  $p_3$  and  $a_3$ .

Decimal <-> Binary						
Subtract	4	2	1			
Position	1 <sup>st</sup>	2 <sup>nd</sup>	3 <sup>rd</sup>			

- Look at  $a_1$  and its rotation, for each axis, invert the number's position (0 -> 1, 1 -> 0) according to this the table below.
- Repeat this for  $a_2$  and  $a_3$ , then set  $a_0$  based on these conditions.
  - o If the 2<sup>nd</sup> digit of a<sub>1</sub> is 1, set the 1<sup>st</sup> digit of a<sub>0</sub> to 1.
  - $\circ$  If the 2<sup>nd</sup> digit of  $a_2$  is 1, set the 2<sup>nd</sup> digit of  $a_0$  to 1.
  - $\circ$  If the 2<sup>nd</sup> digit of  $a_3$  is 1, set the 3<sup>rd</sup> digit of  $a_0$  to 1.

Axis <-> Position						
+Axis	+X	+Y	+Z			
-Axis	-Z	<b>-Y</b>	-х			
Position	1 <sup>st</sup>	2 <sup>nd</sup>	3 <sup>rd</sup>			

<sup>\*</sup> Modulo is to add/subtract the right number until the left is non-negative, and less than the right.

#### The Anchor Sphere (...continued)

- $a_{1-3}$  is now gray code, convert each one to binary:
  - 1. The first binary digit will match the first digit of the gray code.
  - 2. The next digit is a 1 if the sum of the previous digit of the binary code and the current position's gray code is exactly 1. Otherwise it's 0.
  - 3. Repeat step 2 until 3 digits are obtained. This is the binary code.
- Starting from  $a_1$ , add the current a with the previous  $a_1$ , and then refer to the next  $a_1$ . Don't carry (1+1  $\neq$  10) and replace 2's with 0's on each step.
- Replace every 0 with and every 1 with +. This is now the <u>anchor sequence</u>. Whenever the anchor sphere is mentioned, it refers to the only 1 sphere that matches all positive/negative attributes of the anchor sequence's axes. The position of each character represents what axis they belong to, with the order being "XYZ".

#### Pausing

- Interact anywhere on the module to pause it. The rotations will stop, and a sound cue is played to indicate that it is ready to be interacted with.
- Each time the module is paused, a random sphere is chosen. This is called the <u>starting sphere</u>. The starting sphere is white.
- The goal is to get the starting sphere to be on the same location as the anchor sphere.

## <u>Navigation</u>

- When the module is interacted with during the last digit being 0-2, an axis is queued. Each submission from 0-2 represents an axis, though order is random.
- 1 axis need to be queued for a valid input. When the timer's last digit is a 9, it will try submitting the 1 axis. The queue is cleared if any other number of axes are queued.
- The starting sphere goes to the other side of all 1 axis that were submitted.
- During this submission, all axes can only be submitted up to 3 times.
  - $_{\circ}$  This rule can be violated up to four times. The  $5^{th}$  time causes a strike.
- When the starting sphere is in the same position as the anchor sphere, submit all 3 axes. The module will strike or solve accordingly.
- Striking the module will unpause the module.