INF102 Algorithms, Data Structures and Programming

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INF102, practical stuff

- Lecturer: Marc Bezem; Team: see homepage
- ► Homepage: INF102 (hyperlinks in red)
- ► Also: GitHub (recommended); Dropbox: slides, schedule
- Textbook: Algorithms, 4th edition
- ▶ Prerequisites: INF100 + 101 (\approx Ch. 1.1 + 1.2)
- Syllabus (pensum): Ch. 1.3 − 1.5, Ch. 2 − 4
- Exam: three compulsory exercises and a written exam
- ▶ Old exams: 2004–2013, 2014
- Table of Contents of these slides

Resources

- Good textbook, USA-style: many pages, exercises etc.
- Average speed must be ca 50 pages p/w
- Lectures (ca 24) focus on the essentials
- ▶ Slides (ca 120, dense!) summarize the lectures
- Prepare yourself by reading in advance
- Workshops: selected exercises
- ► Test yourself by trying some exercises in advance
- ▶ If you can do the exercises (incl. compulsory), you are fine
- Review of exercises on Friday morning

Generic Bags, Queues and Stacks

- Generic programming in Java, example: PolyPair.java
- ▶ Bag, Queue and Stack are generic, iterable collections
- Queue and Stack: Ch. 9 in textbook INF100/1
- ► APIs include: boolean isEmpty() and int size()
- ▶ All three support adding an element
- Queue and Stack support removing an element (if any)
- ► FIFO Queue (en/dequeue), LIFO Stack (push/pop)
- ► Dijkstra's Two-Stack Expression Evaluation Movie
- ► Example: (1+((2+3)*(4*5)))

Implementations

- ResizingArray_Stack.java
- Arrays give direct access, but have fixed size
- Resizing takes time and space proportional to size
- LinkedList_Stack.java
- No fixed size, but indirect access
- ▶ Pointers take space and dereferencing takes time
- Programming with pointers: make a picture
- LinkedList_Queue.java

Computation time and memory space

- ► Two central questions:
 - How long will my program take?
 - ▶ Will there be enough memory?
- Example: ThreeSum.java
- ▶ Inner loop (here a[i]+a[j]+a[k]==0) is important
- Sorting helps: ThreeSumOptimized.java
- ▶ Run some experiments: 1Kints.txt, 2Kints.txt, ...

Methods of Analysis

Empirical:

- ▶ Run program with randomized inputs, measuring time & space
- Run program repeatedly, doubling the input size
- Measuring time: StopWatch
- ► Plot, or log-log plot and linear regression

Theoretical:

- Define a cost model by abstraction (e.g., array accesses, comparisons, operations)
- Try to count/estimate/average this cost as function of the input (size)
- ▶ Use O(f(n)) and $f(n) \sim g(n)$

ThreeSum, empirically

- ▶ Input sizes 1K, 2K, 4K, 8K take time 0.1, 0.8, 6.4 ,51.1 sec
- ► The log's are 3, 3.3, 3.6, 3.9 and -1, -0.1, 0.8, 1.71
- Basis of the logarithm should be the same for both
- ▶ Linear regression gives $y \approx 3x 10$
- ▶ $\log(f(n)) = 3\log(n) 10$ iff

$$f(n) = 10^{\log(f(n))} = 10^{3\log(n)-10} = n^3 * 10^{-10}$$

- ▶ Conclusion: cubic in the input size, with constant $\approx 10^{-10}$
- Strong dependence on input can be a problem
- ightharpoonup Constant 10^{-10} depends on computer, exponent 3 does not

ThreeSum, theoretically

- ▶ Number of different picks of triples: g(n) = n(n-1)(n-2)/6
- ▶ Inner loop a[i]+a[j]+a[k]==0 executed g(n) times
- $g(n) = n^3/6 n^2/2 + n/3$
- ▶ Cubic term $n^3/6$ wins for large n
- ► Computational model # array accesses: $3 * n^3/6 = n^3/2$
- ► Cost array access t sec: time $t * n^3/2$ sec
- Cost models are abstractions! (NB cache)

Big Oh, and \sim

- Q: 'wins for large n' uhh???
- lacktriangle A: Big Oh, and \sim will clear this up
- ▶ Costs are positive quantities, so $f, g, ... : \mathbb{N} \to \mathbb{R}^+$
- ▶ MNF130: f(n) is O(g(n)) if there exist $c \in \mathbb{R}^+$, $N \in \mathbb{N}$ such that $f(n) \le cg(n)$ for all $n \ge N$ (that is,, for n large enough)
- ► Example: n^2 and even $99n^3$ are $O(n^3)$, but n^3 is not $O(n^{2.9})$
- ▶ INF102: $f(n) \sim g(n)$ if $1 = \lim f(n)/g(n)$
- ▶ If $f(n) \sim g(n)$, then f(n) is O(g(n)) and g(n) is O(f(n))
- ▶ Big Oh and ~ aim to capture 'order of growth'
- ightharpoonup Big Oh abstracts from constant factors, \sim does not
- Large constant factors are important!

Important orders of growth

- ▶ constant: c, f(n) = c for all n
- ▶ linear: n (compare all for n = 20 sec)
- ▶ linearithmetic: n log n
- ▶ quadratic: n²
- ightharpoonup cubic: n^3
- exponential: 2ⁿ
- general form: $an^b(\log n)^c$

Logarithms and Exponents

- ▶ Definition: $\log_x z = y$ iff $x^y = z$ for x > 0
- ▶ Inverses: $x^{\log_x y} = y$ and $\log_x x^y = y$
- Exponent: $x^{(y+z)} = x^y x^z$, $x^{(yz)} = (x^y)^z$
- ► Logarithm: $\log_x(yz) = \log_x y + \log_x z$, $\log_x z = \log_x y \log_y z$
- ▶ Base of logarithm: the x in log_x
- ▶ Various bases: $log_2 = lg$, $log_e = ln$, $log_{10} = log$
- ▶ Double exponent: e.g. $2^{(2^n)}$ (not used in INF102)
- ▶ Double logarithm: log(log n) (not used in INF102)

Examples

- Worst case: guaranteed, independent of input
- ► Average case: not guaranteed, dependent of input *distribution*
- Linked list implementations of Stack, Queue and Bag: all operations take constant time in the worst case
- Resizing array implementations of Stack, Queue and Bag: adding and deleting take linear time in the worst case (easy)
- ▶ Amortized: worst-case cost *per operation*. E.g., each 10-th operation has cost ≤ 21 , all others cost 1, amortized ≤ 3 p/o.
- Resizing arrays: adding and deleting take constant time per operation in the worst case (proof is difficult)
- ▶ Special case of resizing array that is only growing: $1(2)2(4)34(8)5678(16)9 \dots 16(32) \dots$, with (n) the new size. Risizing to (n) costs 2n array accesses, so in total $(1+4)+(1+8)+(2+16)+(4+32)+(8+64) \dots$, so 9 p/push.

Staying Connected

- ▶ MNF130: relation $E \subseteq V \times V$ is an equivalence if
 - ▶ *E* is reflexive: $\forall x \in V$. E(x,x)
 - ▶ *E* is *symmetic*: $\forall x, y \in V$. $E(x, y) \rightarrow E(y, x)$
 - ▶ *E* is transitive: $\forall x, y, z \in V$. $E(x, y) \land E(y, z) \rightarrow E(x, z)$
- We assume connectedness to be an equivalence
- Dynamic connectivity means that R can grow and shrink
- ► Example: if the 'Bergensbanen' is broken, Oslo and Bergen are no longer connected by rail
- We want efficient algorithms and datastructures for testing whether two objects are connected
- Clear relationship with paths in graphs, (connected) components (MNF130)
- We take $V = \{0, ..., N-1\}$.

Union Find

- ▶ UF, idea: every component has an identifier ('hub'), which has edges ('spokes') to the elements of its component
- ► API: UF
- ▶ Implementations with int[] id containing the identifiers
 - SlowUF.java
 - ► FastUF.java
 - WeightedUF.java
- WeightedUF: log depth of tree (Proposition X)

Sorting

- Sorting: putting objects in a certain order
- ▶ MNF130: relation $R \subseteq V \times V$ is a *total order(ing)* if
 - 1. *R* is reflexive: $\forall x \in V$. R(x,x)
 - 2. R is transitive: $\forall x, y, z \in V$. $R(x, y) \land R(y, z) \rightarrow R(x, z)$
 - 3. R is antisymmetric: $\forall x, y \in V$. $R(x, y) \land R(y, x) \rightarrow x = y$
 - 4. R is total: $\forall x, y \in V$. $R(x, y) \vee R(y, x)$
- Natural orderings:
 - ▶ Numbers of any type: ordinary \leq and \geq
 - ► Strings: lexicographic
 - ► Objects of a Comparable type: v.compareTo(w) < 0

Sorting (ctnd)

- Bubble sort: ExampleSort.java
- Certification: assert isSorted(a) in main()
- No guarantee against modifying the array (but exch() is safe)
- Costmodel 1: number of exch()'s and less()'s
- Costmodel 2: number of array accesses
- ► Pitfalls: cache misses, expensive v.compareTo(w) < 0
- Why studying sorting? (java.util.Arrays.sort())
- Comparing sorting algorithms: CompareSort.java

Selection Sort

- ▶ Bubble sort: $\sim n^2/2$ compares, 0 . . $\sim n^2/2$ exchanges
- Selection sort:
 - Find index of a minimal value a[1..n], exchange with a[1]
 - ▶ Find index of a minimal value a[2..n], exchange with a[2]
 - ▶ ... until n-1
- ▶ Selection sort: $\sim n^2/2$ compares, n-1 exchanges

```
public static void sort(Comparable[] a) {
  int N = a.length;
  for (int i=0; i<N-1; i++){
    int min=i;
    for (int j=i+1; j<N; j++) if less(a[j],a[min])) min=j;
    exch(a,i,min);
}</pre>
```

Insertion sort

- Insertion sort:
 - Insert a[2] on its correct place in (sorted) a[1..1]
 - Insert a[3] on its correct place in (sorted) a[1..2]
 - ... until a[n]
- Very good for partially sorted arrays, costs:
 - ▶ Best case: n-1 compares and 0 exchanges
 - Worst case: $\sim n^2/2$ compares and exchanges
 - ▶ Average case: $\sim n^2/4$ compares and exchanges (distinct keys)

```
public static void sort(Comparable[] a) {
  int N = a.length;
  for (int i=1; i<N; i++){
    for (int j=i; j>0 && less(a[j],a[j-1]); j--)
      exch(a,j,j-1);
  }
}
```

Shell sort

- Insertion sort:
 - Very good for partially sorted arrays
 - Slow in transport: step by step exch(a,j,j-1)
- ▶ Idea: h-sort, a[i],a[i+h],a[i+2h],... sorted (any i)

```
public static void hsort(int h, Comparable[] a) {
  int N = a.length;
  for (int i=h; i<N; i++)
   for (int j=i; j-h>=0 && less(a[j],a[j-h]); j-=h)
      exch(a,j,j-h);
}
```

- ▶ Insertion sort: hsort(1,a)
- Shell sort: e.g., hsort(10,a); hsort(1,a)

Shell sort (ctnd)

- ▶ hsort(10,a); hsort(1,a) faster than just hsort(1,a)!
- Q: How is this possible?
- ► A: hsort(10,a) transports items in steps of 10, which would be done by hsort(1,a) in 10 steps of 1
- ▶ What about hsort(100,a); hsort(10,a); hsort(1,a)?
- ▶ To be expected: depends on the length N of the array
- ▶ Book:

Mergesort

- ► Top-down (recursive) algorithm:
 - Mergesort left half, mergesort right half
 - Merge the results
- Using an auxiliary array: TopDownMergeSort.java, Movie
- ▶ Bottom-up algorithm:
 - Merge a[0],a[1], a[2],a[3], a[4],a[5], ...
 - ► Mergea[0..1],a[2..3], a[4..5],a[6..7], ...
 - ► Mergea[0..3],a[4..7], a[8..11],a[12..15], ...
- Also using an auxiliary array: BottomUpMergeSort.java

The complexity of sorting

- ▶ Mergesort uses between $\sim (n/2) \lg n$ and $\sim n \lg n$ compares
- ▶ Mergesort uses between $\sim 6n \lg n$ array accesses
- ▶ Mergesort uses $\sim 2n$ space (plus some var's)
- Q: How fast can compare-based sorting be?
- ► Book:

Quicksort

- Top-down (recursive) algorithm:
 - ► Choose a (pivot value) *v* in the array
 - ▶ Partition the array in non-empty parts $\leq v$ and $\geq v$
 - Quicksort the two parts
- ▶ Pros: in-place, average computation time $O(n \log n)$
- ▶ Cons: stack space for the recursion, worst-case $O(n^2)$
- Implementation: QuickSort.java

Quicksort, details

- Subtleties in partition:
 - ▶ Invariants 1<=h in the two inner loops
 - Postcondition after the two inner loops
 - Invariant of the for(;;) loop
 - Termination of the for(;;) loop
- Termination of recursive quicksort

Quicksort, performance

- ► Compare Quicksort to other sorting methods $(n = 10^2, 10^3, ...)$
- Quicksort runs in quadratic time if pivot is always smallest (largest)
- Randomization is important (choose pivot randomly, or shuffle array)
- ▶ If all keys are distinct and randomization is perfect, then quicksort uses on average $\sim 2n \ln n$ compares (proof on blackboard)
- Similar result for exchanges holds (proof is complicated)
- Relevant improvements:
 - ▶ Cutoff to insertion sort for sizes ≤ M
 - ► Median-of-three pivot
 - Taking advantage of duplicate keys (3-way partitioning)
- Quicksort is generally very good, ... bucketsort

Priority Queues

- Assume collecting and processing items having keys
- Examples of keys: time-stamp, price-tag, priority-tag
- Assume: keys can be ordered
- Reasonable: processing currently highest (or lowest)
- Seen this before? Yes, when items are time-stamped when added:
 - Queue: dequeue currently oldest (lowest time-stamp)
 - Stack: pop currently newest (highest time-stamp)
- Priority queue generalizes this
- Examples: highest priority, largest transaction, lowest price
- Distinction between 'item' and 'key' inessential

Priority Queues

```
► Good info: Wikipedia; API (the essentials):

public class ArrayListPQ<Key extends Comparable<Key>>

void insert(Key v) // insert a key
Key delMax() // delete the largest key, if any
boolean isEmpty()
int size()
```

Heaps

- MNF130: A binary tree is complete if all levels are filled. So, a complete binary tree of depth d has 2^d-1 nodes (picture).
- NF102: A binary tree is (left-)complete if all levels < h are filled, the level h may be partially be empty on the right. So, a (left-)complete binary tree of n nodes has height ⌊lg n⌋.</p>
- A binary tree is heap-ordered if the key in each node is ≥ the keys in its children (if any). So, the root has a maximal key.
- ► Array representation of heap-ordered binary tree: picture
- ▶ The methods swim and sink

Purpose of Sorting

- Sorting makes the following easier and more efficient:
 - ► Searching (binary search, example: ThreeSumOptimized
 - ▶ Searching and looking up, e.g., the pagenumber in an index
 - Removing duplicates
 - Finding the median, quartiles etc.
- Our sorting algorithms are generic: sort(Comparable[] a), for any user-defined data type with a compareTo() method
- ▶ We do *pointer sorting*, manipulating refs to objects.
 - ▶ Pro: not moving full objects
 - Cons: pointer dereferencing, no sort(int[] a)
- More flexibility: pass a Comparator object to sort()

Comparator object

- API: public static void sort(Object[] a, Comparator c)
- Call: Insertion.sort(a, new Transaction.WhenOrder())
- Call: Insertion.sort(a, new Transaction.SizeOrder())
- ▶ Obs: import java.util.Comparator
- Obs: public static boolean less(Object o1, Object o2, Comparator c)
- ▶ Priority queues also with Comparator

More

- Stability: relative order of equal keys is preserved
- ▶ Important in multi-key applications (e.g., timestamp and size)
- Which sorting algorithm to use?
 - Quicksort is a good general purpose choice
 - ► Don't forget: java.util.Arrays.sort()
 - Special care: sorting arrays of primitive type
 - Special care: many duplicate keys
- ► Consider sorting first to make other problems easier

Applications of Sorting

- Commercial computing
- Search for information
- Job scheduling heuristic: longest processing time first
- Combinatorial search in AI
- ► To come: Prim's and Dijkstra's algorithms
- Data compressions
- Cryptology and genomics (e.g., longest repeating substring)

ToC and topics of general interest

- ► Table of Contents on next slide (all items clickable)
- Practical stuff: slide 2

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