# Minimisation du regret vs. Exploration pure: Deux critères de performance pour des algorithmes de bandit

Emilie Kaufmann (Telecom ParisTech) joint work with Olivier Cappé, Aurélien Garivier and Shivaram Kalyanakrishnan (Yahoo Labs)



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## Bandit model

## A multi-armed bandit model is a set of K arms where

- lacksquare Arm a is an unknown probability distribution  $u_a$  with mean  $\mu_a$
- $\blacksquare$  Drawing arm a is observing a realization of  $\nu_a$
- Arms are assumed to be independent

## In a **bandit game**, at round t, an agent

- chooses arm  $A_t$  to draw based on past observations, according to its sampling strategy (or bandit algorithm)
- lacksquare observes a sample  $X_t \sim 
  u_{A_t}$

## The agent wants to learn which arm(s) have highest means

$$a^* = \operatorname{argmax}_a \mu_a$$



## Bernoulli bandit model

### A multi-armed bandit model is a set of K arms where

- Arm a is a Bernoulli distribution  $\mathcal{B}(\mu_a)$  (with unknown mean  $\mu_a$ )
- Drawing arm a is observing a realization of  $\mathcal{B}(\mu_a)$  (0 or 1)
- Arms are assumed to be independent

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- $\blacksquare$  chooses arm  $A_t$  to draw based on past observations, according to its sampling strategy (or bandit algorithm)
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# The (classical) bandit problem: regret minimization

Samples are seens as rewards (as in reinforcement learning)

The forecaster wants to maximize the reward accumulated during learning or equivalentely minimize its regret:

$$R_n = n\mu_{a^*} - \mathbb{E}\left[\sum_{t=1}^n X_t\right]$$

He has to find a sampling strategy (or bandit algorithm) that

realizes a tradeoff between exploration and exploitation



## Best arm identification (or pure exploration)

The forecaster has to **find the best arm(s)**, and does not suffer a loss when drawing 'bad arms'.

He has to find a sampling strategy that

optimaly explores the environnement,

together with a stopping criterion, and then recommand a set S of marms such that

 $\mathbb{P}(\mathcal{S} \text{ is the set of } m \text{ best arms}) \geq 1 - \delta.$ 

# Zoom on an application: Medical trials

A doctor can choose between K different treatments for a given symptom.

- treatment number a has unknown probability of sucess  $\mu_a$
- **Unknown** best treatment  $a^* = \operatorname{argmax}_a \mu_a$
- If treatment a is given to patient t, he is cured with probability  $p_a$

#### The doctor:

- $\blacksquare$  chooses treatment  $A_t$  to give to patient t
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The doctor can ajust his strategy  $(A_t)$  so as to

Regret minimization	Pure exploration
Maximize the number of patient healed	Identify the best treatment
during a study involving $n$ patients	with probability at least $1-\delta$
	(and always give this one later)

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# Asymptotically optimal algorithms

 $N_a(t)$  be the number of draws of arm a up to time t

$$R_T = \sum_{a=1}^{K} (\mu^* - \mu_a) \mathbb{E}[N_a(T)]$$

■ [Lai and Robbins,1985]: every consistent policy satisfies

$$\mu_a < \mu^* \Rightarrow \liminf_{T \to \infty} \frac{\mathbb{E}[N_a(T)]}{\log T} \ge \frac{1}{\mathsf{KL}(\mathcal{B}(\mu_a), \mathcal{B}(\mu_{a^*}))}$$

A bandit algorithm is **asymptotically optimal** if

$$\mu_a < \mu^* \Rightarrow \limsup_{n \to \infty} \frac{\mathbb{E}[N_a(T)]}{\log T} \le \frac{1}{\mathsf{KL}(\mathcal{B}(\mu_a), \mathcal{B}(\mu_{a^*}))}$$

# Algorithms: a family of optimistic index policies

■ For each arm a, compute a confidence interval on  $\mu_a$ :

$$\mu_a \le UCB_a(t) \ w.h.p$$

Act as if the best possible model was the true model (optimism-in-face-of-uncertainty):

$$A_t = \underset{a}{\operatorname{arg\,max}} \ UCB_a(t)$$

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**Example** UCB1 [Auer et al. 02] uses Hoeffding bounds:

$$UCB_a(t) = \frac{S_a(t)}{N_a(t)} + \sqrt{\frac{\alpha \log(t)}{2N_a(t)}}.$$

 $S_a(t)$ : sum of the rewards collected from arm a up to time t.

UCB1 is not asymptotically optimal, but one can show that

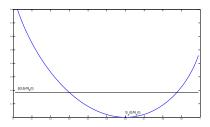
$$\mathbb{E}[N_a(T)] \leq \frac{K_1}{2(\mu_a - \mu^*)^2} \ln T + K_2, \quad \text{with } K_1 > 1.$$

# KL-UCB: and asymptotically optimal frequentist algorithm

■ KL-UCB [Cappé et al. 2013] uses the index:

$$\begin{split} u_a(t) &= \operatorname*{argmax}_{x > \frac{S_a(t)}{N_a(t)}} \left\{ d\left(\frac{S_a(t)}{N_a(t)}, x\right) \leq \frac{\ln(t) + c \ln \ln(t)}{N_a(t)} \right\} \\ \text{with } d(p,q) &= \operatorname{KL}\left(\mathcal{B}(p), \mathcal{B}(q)\right) = p \log \left(\frac{p}{q}\right) + (1-p) \log \left(\frac{1-p}{1-q}\right). \end{split}$$

with 
$$d(p,q) = \mathsf{KL}\left(\mathcal{B}(p),\mathcal{B}(q)\right) = p\log\left(\frac{p}{q}\right) + (1-p)\log\left(\frac{1-p}{1-q}\right)$$



$$\mathbb{E}[N_a(T)] \le \frac{1}{d(\mu_a, \mu^*)} \ln T + C$$

# Regret minimization: Summary

An (asymptotic) lower bound on the regret of any good algorithm

$$\liminf_{T \to \infty} \frac{R_T}{\log T} \ge \sum_{a: \mu_a < \mu^*} \frac{\mu^* - \mu_a}{\mathsf{KL}(\mathcal{B}(\mu_a), \mathcal{B}(\mu^*))}$$

An algorithm based on confidence intervals matching this lower bound: KI-UCB

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- An algorithm based on confidence intervals matching this lower bound: KI-UCB
- A Bayesian approach of the MAB problem can also lead to asymptotically optimal algorithms (Thompson Sampling, Bayes-UCB)



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## m best arms identification

Assume  $\mu_1 \geq \cdots \geq \mu_m > \mu_{m+1} \geq \dots \mu_K$ .

#### Parameters and notations

- m the number of arms to find
- $\delta \in ]0,1[$  a risk parameter
- $\mathcal{S}_m^* = \{1, \dots, m\}$  the set of m optimal arms

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#### The forecaster

- chooses at time t one (or several) arms to draw
- $lue{}$  decides to stop after a (possibly random) total number of samples from the arms au
- $\blacksquare$  recommends a set  $\mathcal{S}$  of m arms



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## His goal

 $\blacksquare \mathbb{P}(S = S_m^*) \ge 1 - \delta$ , and  $\mathbb{E}[\tau]$  is small (fixed-confidence setting)

# Generic algorithms based on confidence intervals

#### Generic notations:

confidence interval on the mean of arm a at round t:

$$\mathcal{I}_a(t) = [L_a(t), U_a(t)]$$

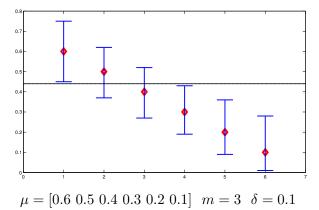
- J(t) the set of estimated m best arms at round t (m empirical best)
- $u_t \in J(t)^c$  and  $l_t \in J(t)$  two 'critical' arms (likely to be misclassified)

$$u_t = \operatorname*{argmax}_{a \notin J(t)} U_a(t) \quad \text{and} \quad l_t = \operatorname*{argmin}_{a \in J(t)} L_a(t).$$

# (KL)-Racing: uniform sampling and eliminations

The algorithm maintains a set of remaining arms R and at round t:

- lacksquare draw all the arms in  $\mathcal{R}$  (uniform sampling)
- possibly accept the empirical best or discard the empirical worst

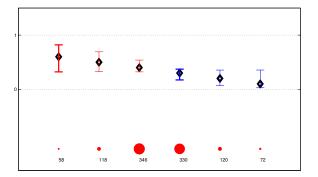


In this situation, arm 1 is selected

# (KL)-LUCB algorithm: adaptive sampling

## At round t, the algorithm:

- lacktriangle draw only two well-chosen arms:  $u_t$  and  $l_t$  (adaptive sampling)
- lacksquare stops when CI for arms in J(t) and  $J(t)^c$  are separated



Set J(t), arm  $l_t$  in bold Set  $J(t)^c$ , arm  $u_t$  in bold



# Two $\delta$ -PAC algorithms

$$L_a(t) = \min \{ q \in [0, \hat{\mu}_a(t)] : N_a(t) d(\hat{\mu}_a(t), q) \le \beta(t, \delta) \},$$
  

$$U_a(t) = \max \{ q \in [\hat{\mu}_a(t), 1] : N_a(t) d(\hat{\mu}_a(t), q) \le \beta(t, \delta) \}.$$

for  $\beta(t, \delta)$  some exploration rate.

#### Theorem

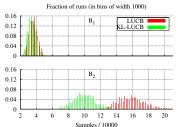
The KL-Racing algorithm and KL-LUCB algorithm using

$$\beta(t,\delta) = \log\left(\frac{k_1 K t^{\alpha}}{\delta}\right),\tag{1}$$

with  $\alpha > 1$  and  $k_1 > 1 + \frac{1}{\alpha-1}$  satisfy  $\mathbb{P}(\mathcal{S} = \mathcal{S}_m^*) \geq 1 - \delta$ .

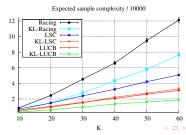
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## Confidence intervals based on KL are always better



$$B_1: K = 15; \mu_1 = \frac{1}{2}; \mu_a = \frac{1}{2} - \frac{1}{40} \text{ for } a = 2, 3, \dots, K. \ B_2 = \frac{1}{2}B_1$$

## Adaptive Sampling seems to do better than Uniform Sampling



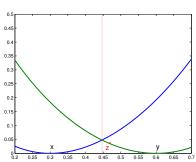
# Sample complexity analysis

## ■ A new informational quantity: Chernoff information

$$d^*(x,y) := d(z^*,x) = d(z^*,y),$$

where  $z^*$  is defined by the equality

$$d(z^*, x) = d(z^*, y).$$



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# Sample Complexity analysis

KL-LUCB with  $\beta(t,\delta)=\log\left(\frac{k_1Kt^{\alpha}}{\delta}\right)$  is  $\delta$ -PAC and satisfies, for  $\alpha>2$ ,

$$\mathbb{E}[\tau] \le 4\alpha H^* \left[ \log \left( \frac{k_1 K(H^*)^{\alpha}}{\delta} \right) + \log \log \left( \frac{k_1 K(H^*)^{\alpha}}{\delta} \right) \right] + C_{\alpha},$$

with

$$H^* = \min_{c \in [\mu_{m+1}; \mu_m]} \sum_{a=1}^K \frac{1}{d^*(\mu_a, c)}.$$



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## Lower bound on the number of sample used complexity

For KL-LUCB, 
$$\mathbb{E}[\tau] = O\left(H^* \log \frac{1}{\delta}\right)$$
.

#### Theorem

Any algorithm that is  $\delta$ -PAC on every bandit model such that  $\mu_m > \mu_{m+1}$  satisfies, for  $\delta \leq 0.15$ ,

$$\mathbb{E}[\tau] \ge \left(\sum_{t=1}^{m} \frac{1}{d(\mu_a, \mu_{m+1})} + \sum_{t=m+1}^{K} \frac{1}{d(\mu_a, \mu_m)}\right) \log \frac{1}{2\delta}$$

## The informational complexity of m best arm identification

For a bandit model  $\nu$ , one can introduce the complexity term

$$\kappa_C(\nu) = \inf_{\substack{\mathcal{A} \text{ } \delta - \mathsf{PAC} \\ \mathsf{algorithm}}} \limsup_{\delta \to 0} \frac{\mathbb{E}_{\nu}[\tau]}{\log \frac{1}{\delta}}.$$

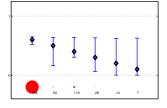
Our results rewrite

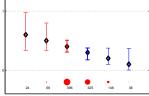
$$\sum_{t=1}^{m} \frac{1}{d(\mu_a, \mu_{m+1})} + \sum_{t=m+1}^{K} \frac{1}{d(\mu_a, \mu_m)} \le \kappa_C(\nu) \le 4 \min_{c \in [\mu_{m+1}; \mu_m]} \sum_{a=1}^{K} \frac{1}{d^*(\mu_a, c)}$$

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## Regret minimization versus Best arms Identification

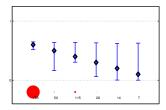
■ KL-based confidence intervals are useful in both settings, altough KL-UCB and KL-LUCB draw the arms in a different fashion

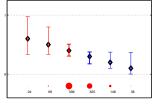




## Regret minimization versus Best arms Identification

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Do the complexity of these two problems feature the same information-theoretic quantities?

$$\inf_{\substack{\text{constistent}\\ \text{algorithms}}} \limsup_{T \to \infty} \frac{R_T}{\log T} = \sum_{a=2}^K \frac{\mu_1 - \mu_a}{d(\mu_a, \mu_1)}$$

$$\inf_{\substack{\delta-PAC\\\text{algorithms}}}\limsup_{\delta\to\infty}\frac{\mathbb{E}[\tau]}{\log(1/\delta)} \geq \sum_{a=1}^K\frac{1}{d(\mu_a,\mu_{m+1})} + \sum_{\substack{a=m+1\\ a \neq m+1}}^K\frac{1}{d(\mu_a,\mu_m)}$$