

# Emilio A. Magaña

+1 (541) 2501487 • Portland, OR • [magana.emil.a@gmail.com](mailto:magana.emil.a@gmail.com)

## EDUCATION

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**Oregon State University** | Bachelor of Science in Electrical and Computer Engineering Graduated June 2021  
❖ GPA: 3.52/4.0  
❖ [Minor in Computer Science](#)  
❖ *Related Coursework:* Power Electronics, Digital Logic Design, VLSI, CMOS, Computer Architecture, Signal and Systems

## EXPERIENCE

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**Product Engineer** Oct. 2021 - Jan. 2024  
[Lattice Semiconductor](#) | Hillsboro, OR

- My main role consisted of being in charge of validating and characterizing IP associated with our product. This included:
  - Wrote documentation of methodology for validation and characterization.
  - Worked Closely with all aspects of FPGA IPs but mainly on: I/O, PLL's, OSC's.
  - Development of behavioral patterns using Verilog through our in-house design software: Radiant.
  - Bringup, maintenance, and automatization (Python) of bench.
  - Created detailed statistical visuals between spec and performance of product using R.
  - Interpreted Chip and PCB layouts for testing.
- As part of the PDE team, Worked with Customer issues/JIRA (internal and external) in providing solutions and data.

**Teacher's Assistant/Head TA** Jan. 2019 - Mar. 2019  
[OSU, ECE Department](#) | Corvallis, OR

- Coordinated lab sessions for ECE 112: Introduction to Electrical and Computer Engineering. Made sure that students were on task in doing their lab work, along with creating weekly quizzes and holding office hours.

## PROJECTS

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**HV Peripherals** Oct. 2020 - Mar. 2021  
[Global Formula Racing](#) | Corvallis, OR

- As part of my capstone, I joined the Global Formula Racing team at Oregon state. The Global formula racing team is a joint effort between OSU and DHBW Ravensburg, and competes every year by building a race car to compete in FS and FSAE competitions. I contributed to the following aspects of the project:
  - The High voltage peripherals for the ePowertrain sub-team within GFR, which included updating the cars DC-Link board and Brake System Plausibility Device (BSPD).
    - The DCL board was able to discharge the maximum system current **2627% faster** than the allotted maximum given time under FS regulations and **50% faster** under FSAE regulations (max. time for both rule sets is 15s).
    - The BSPD was able to **"restart the car" 11.6s** after no implausibility being present under FS rules (min. time being 10s) and remained indefinitely turned off under FSAE rules.

**SCARA Robot Arm** Jan. 2020 - Mar. 2020  
[Junior Design](#) | Corvallis, OR

- Programmed a SCARA Robot Arm, with three other classmates, capable of drawing a 10-inch straight line within 2.5 seconds and being able to sort a single layer of US coins into their proper slots of the enclosure using an Arduino, a Jetson Nano, and a custom made PCB.
- My contribution lay in the coding of the SCARA's motion, using Python and Arduino Ide.

## SKILLS & LANGUAGES

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**Languages:** Python, Verilog, R, C/C++, Bash, LaTeX, Tcl

**Lab Equipment Proficiency:** DTG, Oscilloscope, Voltage Supply, Thermal Oven/Stream, DMM

**EDA tools:** Eagle CAD, LtSpice, Cadence

**Conversational Languages:** Spanish (fluent, Oregon Seal Of Bilingual), German (Conversational)