

Emilio A. Magaña

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EDUCATION

Bachelor of Science in Electrical and Computer Engineering

Graduated June 2021

[Oregon State University](#)

- ❖ GPA: 3.52/4.0
- ❖ Computer Science Minor
- ❖ *Related Coursework:* Digital Logic Design, VLSI, CMOS, Computer Architecture, Signal and Systems.

EXPERIENCE

Product Engineer

Oct. 2021 - Jan. 2024

[Lattice Semiconductor](#) | Hillsboro, OR | [Python](#), [SystemVerilog](#), [R](#)

- ❖ Main role consisted of validating and characterizing IP.
 - Wrote documentation of methodology for both validation and characterization.
 - Worked closely with all aspects of FPGA IP's, mainly on: I/O, PLL, OSC.
 - Developed behavioral patterns through our in-house design software.
 - In charge of bring-up, maintenance, and automatization of benches.
 - Created statistical visuals between specification and performance of IP.
- ❖ Worked with customer issues/JIRA (internal and external) in providing solutions and data.
- ❖ Small Projects involving: BSCAN/JTAG, Thermal Studies.

Teacher's Assistant/Head TA

Jan. 2019 - Mar. 2019

[OSU, ECE Department](#) | Corvallis, OR

- ❖ Coordinated lab sessions for ECE 112: Introduction to Electrical and Computer Engineering.

PROJECTS

Portfolio Website

[Personal Project](#) | [TypeScript](#), [React.js](#), [TailwindCSS](#), [Next.js](#)

- ❖ Designed a personal website to act as a root to all socials and future projects and give a self-introduction.
- ❖ Used Next.js for developing serverless functionality, when handling api calls.

High Voltage Peripherals

[Global Formula Racing](#) | [Eagle CAD](#), [LTspice](#)

- ❖ Capstone Project was done with the Global Formula Racing (GFR) Team at Oregon State, a International Formula Student team in conjunction with DHBW Ravensburg, as part of the ePowertrain sub-team.
- ❖ Designed and Functionally tested the DC-Link (DCL) and Brake System Plausibility Device (BSPD) for both FS and FSAE 2021 Competitions.
 - Under FS rules:
 - The DCL discharged the vehicle's current **2627% faster** than the allotted maximum given time.
 - The BSPD **rebooted the car 11.6s** after no implausibility being present (reboot must be > 10s).
 - Under FSAE rules:
 - The DCL discharged the vehicle's current **50% faster** than the allotted maximum given time.
 - The BSPD was not to be used.

SCARA Robot Arm

[Junior Design Project](#) | [Python](#), [Eagle CAD](#)

- ❖ Programmed a SCARA Robot Arm, with three other classmates, capable of drawing a 10-inch straight line within 2.5 seconds and being able to sort a single layer of coins using an Arduino, a Jetson Nano, and a custom made PCB.
- ❖ Contributed in the coding of the SCARA's motion, using Python and Arduino Ide.

TECHNICAL SKILLS

Languages: [TypeScript](#), [Python](#), [CSS](#), [Go](#), [SystemVerilog](#), [R](#)

Frameworks/Libraries: [React.js](#), [Next.js](#), [TailwindCSS](#), [Node.js](#)

Tools: Vite, Git, Supabase, [Eagle CAD](#), Cadence, [LTspice](#), Electrical Lab Equipment

Conversational Languages: [Spanish \(Fluent, Oregon Seal Of Bilingual\)](#), [German \(Conversational\)](#)