Bayesian Statistics |

Lecture 4 - Regression, Prediction and Decisions

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Lecture overview

- Normal model with conjugate prior
- The linear regression model
- Prediction
- Decision making

Linear regression

The linear regression model in matrix form

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}_{(\mathbf{n} \times \mathbf{1})} + \boldsymbol{\varepsilon}_{(\mathbf{n} \times \mathbf{1})}$$

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}, \beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_k \end{pmatrix}, \varepsilon = \begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{pmatrix}$$

$$X = \begin{pmatrix} x'_1 \\ \vdots \\ x'_n \end{pmatrix} = \begin{pmatrix} x_{11} & \cdots & x_{1k} \\ \vdots & \ddots & \vdots \\ x_{n1} & \cdots & x_{nk} \end{pmatrix}$$

- Usually $x_{i1} = 1$, for all i. β_1 is the intercept.
- Likelihood

$$y|\beta, \sigma^2, X \sim N(X\beta, \sigma^2 I_n)$$

Linear regression - uniform prior

Standard non-informative prior: uniform on $(β, log σ^2)$

$$p(\beta, \sigma^2) \propto \sigma^{-2}$$

Joint posterior of β and σ^2 :

$$\beta | \sigma^2, y \sim N [\hat{\beta}, \sigma^2(X'X)^{-1}]$$

 $\sigma^2 | y \sim Inv - \chi^2 (n - k, s^2)$

where $\hat{\beta} = (X'X)^{-1}X'y$ and $s^2 = \frac{1}{n-k}(y - X\hat{\beta})'(y - X\hat{\beta})$.

- Simulate from the joint posterior by simulating from
 - $ightharpoonup p(\sigma^2|y)$
 - $ightharpoonup p(\beta|\sigma^2,y)$
- **Marginal posterior** of β :

$$\beta | \mathbf{y} \sim t_{n-k} \left[\hat{\beta}, s^2 (X'X)^{-1} \right]$$

Linear regression - conjugate prior

Joint prior for β and σ^2

$$eta | \sigma^2 \sim N\left(\mu_0, \sigma^2 \Omega_0^{-1}
ight) \ \sigma^2 \sim \mathit{Inv} - \chi^2\left(\nu_0, \sigma_0^2
ight)$$

Posterior

$$\begin{split} \beta | \sigma^2, \mathbf{y} &\sim \textit{N}\left[\mu_\textit{n}, \sigma^2 \Omega_\textit{n}^{-1}\right] \\ \sigma^2 | \mathbf{y} &\sim \text{Inv} - \chi^2\left(\nu_\textit{n}, \sigma_\textit{n}^2\right) \end{split}$$

$$\begin{split} \mu_n &= \left(\mathsf{X}'\mathsf{X} + \Omega_0\right)^{-1} \left(\mathsf{X}'\mathsf{X}\hat{\beta} + \Omega_0\mu_0\right) \\ \Omega_n &= \mathsf{X}'\mathsf{X} + \Omega_0 \\ \nu_n &= \nu_0 + n \\ \nu_n\sigma_n^2 &= \nu_0\sigma_0^2 + \left(\mathsf{y}'\mathsf{y} + \mu_0'\Omega_0\mu_0 - \mu_n'\Omega_n\mu_n\right) \end{split}$$

Polynomial regression

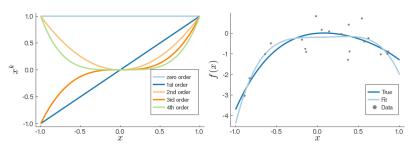
Polynomial regression

$$f(x_i) = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \dots + \beta_k x_i^k.$$

$$y = X_P \beta + \varepsilon,$$

where

$$X_P = (1, x, x^2, ..., x^k).$$



Priors for regularization (ridge, lasso etc) in Lecture 6.

Prediction/Forecasting

Posterior predictive density for future \tilde{y} given observed y

$$p(\tilde{y}|y) = \int_{\theta} p(\tilde{y}|\theta, y) p(\theta|y) d\theta$$

IID data:

$$p(\tilde{y}|y) = \int_{\theta} p(\tilde{y}|\theta) p(\theta|y) d\theta$$

Parameter uncertainty in $p(\tilde{y}|y)$ by averaging over $p(\theta|y)$.

Prediction - Normal data, known variance

Under the uniform prior $p(\theta) \propto c$, then

$$p(\tilde{y}|y) = \int_{\theta} p(\tilde{y}|\theta) p(\theta|y) d\theta$$
$$\theta|y \sim N(\bar{y}, \sigma^{2}/n)$$
$$\tilde{y}|\theta \sim N(\theta, \sigma^{2})$$

Simulation algorithm:

- **I** Generate a **posterior draw** of θ ($\theta^{(1)}$) from $N(\bar{y}, \sigma^2/n)$
- **2** Generate a **predictive draw** of \tilde{y} ($\tilde{y}^{(1)}$) from $N(\theta^{(1)}, \sigma^2)$
- 3 Repeat Steps 1 and 2 N times to output:
 - ▶ Sequence of posterior draws: $\theta^{(1)}$,, $\theta^{(N)}$
 - ▶ Sequence of predictive draws: $\tilde{y}^{(1)}$, ..., $\tilde{y}^{(N)}$.

Predictive distribution - Normal model

- $\theta^{(1)} = \bar{y} + \varepsilon^{(1)}$, where $\varepsilon^{(1)} \sim N(0, \sigma^2/n)$. (Step 1).
- $ilde{\mathbf{y}}^{(1)} = heta^{(1)} + v^{(1)}$, where $v^{(1)} \sim \mathit{N}(0, \sigma^2)$. (Step 2).
- $\tilde{\mathbf{y}}^{(1)} = \bar{\mathbf{y}} + \varepsilon^{(1)} + v^{(1)}$.
- lacksquare $arepsilon^{(1)}$ and $v^{(1)}$ are independent.
- The sum of two normal random variables is normal so

$$\begin{split} E(\tilde{y}|\mathbf{y}) &= \bar{y} \\ V(\tilde{y}|\mathbf{y}) &= \frac{\sigma^2}{n} + \sigma^2 = \sigma^2 \left(1 + \frac{1}{n} \right) \\ \tilde{y}|\mathbf{y} \sim N \left[\bar{y}, \sigma^2 \left(1 + \frac{1}{n} \right) \right] \end{split}$$

Iteration laws

Expectation with respect to what? Explicit:

$$\mathbb{E}_{\theta|\mathsf{y}}(\theta) \equiv \int \theta p(\theta|\mathsf{y}) d\theta$$

Law of iterated expectation and Law of total variance.

Iteration laws

Law of iterated expectation:

$$\mathbb{E}_X(X) = \mathbb{E}_Y \big(\mathbb{E}_{X|Y}(X) \big)$$

Law of total variance:

$$V_X(X) = \mathbb{E}_Y (V_{X|Y}(X)) + V_Y (\mathbb{E}_{X|Y}(X))$$

Iteration laws for Bayes

Marginal posterior mean:

$$\mathbb{E}_{\boldsymbol{\theta}_1|\mathbf{y}}(\boldsymbol{\theta}_1) = \mathbb{E}_{\boldsymbol{\theta}_2|\mathbf{y}}\big(\mathbb{E}_{\boldsymbol{\theta}_1|\boldsymbol{\theta}_2,\mathbf{y}}(\boldsymbol{\theta}_1)\big)$$

Marginal posterior variance:

$$\begin{split} \mathbb{V}_{\theta_1}(\theta_1) &= \mathbb{E}_{\theta_2 | \mathbf{y}} \big(\mathbb{V}_{\theta_1 | \theta_2, \mathbf{y}}(\theta_1) \big) \\ &+ \mathbb{V}_{\theta_2 | \mathbf{y}} \big(\mathbb{E}_{\theta_1 | \theta_2, \mathbf{y}}(\theta_1) \big) \end{split}$$

Predictive distribution - Normal model and prior

- Predictive distribution still normal (sum of normals is normal).
- Predictive mean conditional on θ is trivial:

$$E_{\tilde{y}|\theta}(\tilde{y}) = \theta$$

 \blacksquare "Remove the conditioning" on θ by averaging over posterior:

$$E(\tilde{y}|y) = E_{\theta|y}(\theta) = \mu_n$$
 (Posterior mean of θ).

The predictive variance of \tilde{y} by law of total variance

$$V(\tilde{y}|y) = E_{\theta|y}[V_{\tilde{y}|\theta}(\tilde{y})] + V_{\theta|y}[E_{\tilde{y}|\theta}(\tilde{y})]$$

$$= E_{\theta|y}(\sigma^{2}) + V_{\theta|y}(\theta)$$

$$= \sigma^{2} + \tau_{n}^{2}$$

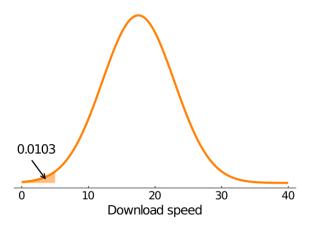
■ So, predictive distribution is

$$\tilde{\mathbf{y}}|\mathbf{y} \sim N(\mu_n, \sigma^2 + \tau_n^2).$$

Predictive distribution - Internet speed data

lacksquare My Netflix starts to buffer at speeds $< 5 \mathrm{Mbit}$.





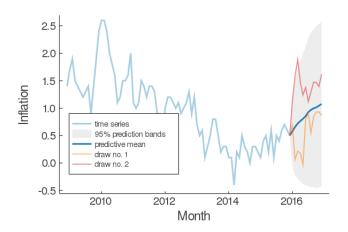
Bayesian prediction for time series

Autoregressive process

$$y_t = \mu + \phi_1(y_{t-1} - \mu) + ... + \phi_p(y_{t-p} - \mu) + \varepsilon_t, \ \varepsilon_t \stackrel{iid}{\sim} N(0, \sigma^2)$$

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Predictive distribution - AR process.
    Input: time series \mathbf{v}_{1:T} = (y_1, \dots, y_T)
                  number of predictive draws m.
                  forecast horizon h.
    for i in 1:m do
           \mu, \phi_1, \dots, \phi_p, \sigma \leftarrow \text{RPOSTERIORAR}(\mathbf{y}_{1:T}, \text{PriorSettings})
           \varepsilon_{T+1} \leftarrow \text{RNorm}(0, \sigma)
           \tilde{y}_{T+1} \leftarrow \mu + \phi_1(y_T - \mu) + \ldots + \phi_p(y_{T+1-p} - \mu) + \varepsilon_{T+1}
          \varepsilon_{T+2} \leftarrow \text{RNorm}(0,\sigma)
          \tilde{y}_{T+2} \leftarrow \mu + \phi_1(\tilde{y}_{T+1} - \mu) + \ldots + \phi_n(y_{T+2-n} - \mu) + \varepsilon_{T+2}
           \varepsilon_{T\perp h} \leftarrow \text{RNorm}(0,\sigma)
          \tilde{y}_{T+h} \leftarrow \mu + \phi_1(\tilde{y}_{T+h-1} - \mu) + \ldots + \phi_v(\tilde{y}_{T+h-v} - \mu) + \varepsilon_{T+h}
    end
    Output: m draws from the joint predictive density:
                     p(\tilde{y}_{T+1},\ldots,\tilde{y}_{T+h}|\mathbf{y}_{1:T}).
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Bayesian prediction of Swedish inflation



Predicting auction prices on eBay

- Problem: Predicting the final price in eBay coin auctions.
- Data: Bid from 1000 auctions on eBay. The highest bid is not observed (eBay proxy bidding).
- Covariates are auction-specific:
 - catalog value
 - seller's reservation price
 - quality
 - rating of seller etc
- Buyers are strategic.
 - \triangleright Bid \neq valuation.
 - ▶ Bid function, b = BidFunction(v), from Game theory.
 - Very complicated likelihood.

Simulating auction prices on eBay

Predictive distribution - auction price.

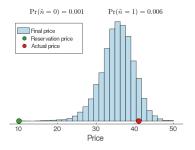
Input: training auction bids \mathbf{Y} training auction covariates \mathbf{X} . test auction covariates $\tilde{\mathbf{x}}$. number of predictive draws m.

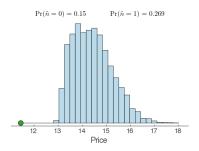
for *i* in 1:*m* **do**

$$\mu, \sigma, \lambda \leftarrow \text{RPOSTAUCTION}(\mathbf{Y}, \mathbf{X}, \tilde{\mathbf{x}}, \text{Prior}) \text{ # parameters}$$
 $\tilde{n} \leftarrow \text{RPOIS}(\lambda(\tilde{\mathbf{x}})) \text{ # number of bidders in test auction}$
 $\tilde{\mathbf{v}}_{1:\tilde{n}} \leftarrow \text{RNORM}(\mu(\tilde{\mathbf{x}}), \sigma(\tilde{\mathbf{x}})) \text{ # valuations for all } \tilde{n} \text{ bidders}$
 $b_{1:\tilde{n}} \leftarrow \text{BIDFUNCTION}(\tilde{\mathbf{v}}_{1:\tilde{n}}, \tilde{n}, \mu(\tilde{\mathbf{x}}), \sigma(\tilde{\mathbf{x}})) \text{ # bids}$
 $\tilde{p} \leftarrow \text{SecondLargest}(b_{1:\tilde{n}}) \text{ # final price}$
end

Output: *m* predictive draws of the final price \tilde{p} for an auction with covariates \tilde{x} .

Predicting auction prices on eBay





Decision Theory

- Let θ be an unknown quantity. State of nature. Examples: Future inflation, Global temperature, Disease.
- Let $a \in \mathcal{A}$ be an action. Ex: Interest rate, Energy tax, Surgery.
- Choosing action a when state of nature is θ gives utility

$$U(a, \theta)$$

Alternatively loss $L(a, \theta) = -U(a, \theta)$.

Decision Theory

- lacksquare Example loss functions when both a and heta are continuous:
 - ▶ Linear: $L(a, \theta) = |a \theta|$
 - **Quadratic**: $L(a, \theta) = (a \theta)^2$
 - Lin-Lin:

$$L(a,\theta) = \begin{cases} c_1 \cdot |a - \theta| & \text{if } a \le \theta \\ c_2 \cdot |a - \theta| & \text{if } a > \theta \end{cases}$$

- Example:
 - ightharpoonup heta is the number of items demanded of a product
 - a is the number of items in stock
 - Utility

$$U(a, \theta) = \begin{cases} p \cdot \theta - c_1(a - \theta) & \text{if } a > \theta \text{ [too much stock]} \\ p \cdot a - c_2(\theta - a)^2 & \text{if } a \leq \theta \text{ [too little stock]} \end{cases}$$

Optimal decision

- Ad hoc decision rules:
 - ▶ Minimax. Minimizes the maximum loss.
 - Minimax-regret ... bla bla bla ...
- Bayesian theory: maximize the posterior expected utility:

$$a_{bayes} = \operatorname{argmax}_{a \in \mathcal{A}} E_{p(\theta|y)}[U(a, \theta)],$$

where $E_{p(\theta|y)}$ denotes the posterior expectation.

Using simulated draws $\theta^{(1)}, \theta^{(2)}, ..., \theta^{(N)}$ from $p(\theta|y)$:

$$E_{p(\theta|y)}[U(a,\theta)] \approx N^{-1} \sum_{i=1}^{N} U(a,\theta^{(i)})$$

- Separation principle:
- **I** First obtain $p(\theta|y)$
- 2 then form $U(a, \theta)$ and finally
- 3 choose a that maximes $E_{p(\theta|y)}[U(a,\theta)]$.

Choosing a point estimate is a decision

- Choosing a point estimator is a decision problem.
- Which to choose: posterior median, mean or mode?
- It depends on your loss function:
 - ▶ Linear loss → Posterior median
 - ▶ Quadratic loss → Posterior mean
 - Zero-one loss → Posterior mode
 - ▶ Lin-Lin loss $\rightarrow c_2/(c_1+c_2)$ quantile of the posterior