

Sheath equations

1 Equations describing plasma-wall interaction

Boltzmann-Poisson system The `sheath` executable solves the following Boltzmann-Poisson system

$$\partial_t f_a + v \partial_x f_a + \frac{q_a E}{m_a} \partial_v f_a = \mathcal{C}(f_a) + \mathcal{S}(f_a), \quad (1)$$

$$-\partial_x^2 \phi = \rho / \varepsilon_0 \quad \text{with} \quad \rho = \sum_{\text{species}} q_a n_a. \quad (2)$$

Where we use the x variable to specify the position. The v variable expresses the velocity of the considered particle. $f_a(v, x, t)$ is the distribution function of species a , which expresses the density of particles at time t and at point (x, v) of phase space. The subscript a denotes the species the quantity refers to:—e for electrons, i for ions. The mass of any particle of species a is written m_a , and its charge is q_a . ε_0 is the dielectric permittivity of vacuum. The electric field is written E , and we have $E = -\partial_x \phi$. We also introduced the local density n_a of species a , which is a function of time and space. It is defined as the integral over the velocity space $n_a = \int dv f_a$. The $\mathcal{C}(f_a)$ term accounts for collisions, and the $\mathcal{S}(f_a)$ operator represents sources and sinks. Depending on the simulation parameters, these operators can be a combination of the terms described in the following. For more detail about each operator, see the corresponding documentation.

The Boltzmann-Poisson system is normalized using a reference density n_0 and temperature T_0 . Time is normalized to the inverse of the electron plasma frequency $\omega_{pe0} = \sqrt{n_0 e^2 / m_e \varepsilon_0}$. The space variable x is normalized to the length scale relevant for plasma-wall interaction studies, i.e. the Debye length $\lambda_{D0} = \sqrt{\varepsilon_0 T_0 / n_0 e^2}$. The electrostatic potential is normalized to T_0 / e . The phase space velocity variable v is normalized to the thermal velocity of each species v_{T0a} as $v_a = v / v_{T0a}$, with the thermal velocity of species a written as $v_{T0a} = \sqrt{T_0 / m_a}$. Particles distribution functions are normalized to the reference particle density in phase space n_0 / v_{T0a} . We use the notation $A_a = m_e / m_a$ to express the mass ratio between electrons and species a (in particular $A_e = 1$). The normalized charge of species a is written as $Z_a = q_a / e$. The normalized Boltzmann-Poisson system then reads as follows

$$\partial_t f_a + \sqrt{A_a} (v_a \partial_x f_a - Z_a \partial_x \phi \partial_{v_a} f_a) = \mathcal{C}(f_a) + \mathcal{S}(f_a), \quad (3)$$

$$-\partial_x^2 \phi = \rho \quad \text{with} \quad \rho = \sum_{\text{species}} Z_a n_a. \quad (4)$$

In all the following each quantity of interest is normalized. If a reference to some dimensional quantities is needed, it will be explicitly pointed out.

Sources and sinks The source term $\mathcal{S}(f_a)$ can be composed of the following operators.

1. A Bhatnagar-Gross-Krook operator [1] of the form

$$\mathcal{S}(f_a) = -\nu_a \mathcal{M}(x) (f_a - g), \quad (5)$$

that relaxes the distribution function f_a towards a target function g . Depending on the characteristics of the target function this operator can inject or absorb particles. The $\mathcal{M}(x)$ term is a function of space that defines the simulation region where the operator becomes active. Typically this function has a hyperbolic tangent shape and transitions smoothly between a region where it is equal to zero—therefore where the BGK operator is not active—and another region where it is equal to one. ν_a is a coefficient that sets the operator magnitude. This coefficient can be either a constant, or can be adapted at each spatial position and each timestep to ensure that this BGK term conserves the charge locally.

2. A source term [2, Appendix A] defined by

$$S(f_a) = s_k \frac{\mathcal{M}(x)}{\int_0^{L_x} \mathcal{M}(x) dx} S_v(v), \quad (6)$$

where the mask function \mathcal{M} defines the spatial extent of the source, similarly to its counterpart of Eq. 5. L_x stands for the simulation box length. The S_v term is written as

$$S_v(v) = \left\{ s_0 \left(\frac{3}{2} - \frac{v^2}{2T_s} \right) + s_2 \left(-\frac{1}{2} + \frac{v^2}{2T_s} \right) \right\} \frac{1}{\sqrt{2\pi T_s}} e^{-\frac{v^2}{2T_s}} \quad (7)$$

The T_s is a constant parameter that defines the source temperature. The s_0 , s_2 and s_k parameters are numerical inputs of the code that define the properties of the source. In particular when using $s_0 = s_2 = 1$, the source adopts a Maxwellian shape whose magnitude is defined by the s_k parameter:

$$S(f_a) = s_k \frac{\mathcal{M}(x)}{\int_0^{L_x} \mathcal{M}(x) dx} \frac{1}{\sqrt{2\pi T_s}} e^{-\frac{v^2}{2T_s}}. \quad (8)$$

Collisions The collisions term $\mathcal{C}(f_a)$ accounts for both intra and inter species collisions.

An extensive description of the source, sink and collision operators described above can be found in the `src/geometryXVx/rhs/doc` folder.

References

- [1] P L Bhatnagar, E P Gross, and M Krook. “A Model for Collision Processes in Gases. I. Small Amplitude Processes in Charged and Neutral One-Component Systems”. In: *Physical Review* 94.3 (May 1954). Publisher: American Physical Society, pp. 511–525. DOI: 10.1103/PhysRev.94.511. URL: <https://link.aps.org/doi/10.1103/PhysRev.94.511>.
- [2] Y Sarazin et al. “Predictions on heat transport and plasma rotation from global gyrokinetic simulations”. In: *Nuclear Fusion* 51.10 (2011). Publisher: IOP Publishing, p. 103023. ISSN: 0029-5515. DOI: 10.1088/0029-5515/51/10/103023. URL: <http://dx.doi.org/10.1088/0029-5515/51/10/103023>.