```cpp
#include <Servo.h>




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Servo servoMotor;

void setup() {

  Serial.begin(9600);
  servoMotor.attach(9);
}

void loop() {


  servoMotor.write(0);
  delay(1000);

  servoMotor.write(90);
  delay(1000);
  servoMotor.write(180);
  delay(1000);
}
```