

```
//Hannah, Emma, Lindsey
//graph class
```

```
#include "vertex.h"
#include "list.h"
#include "pq.h"
#include <string>
#include <iostream>
#include <fstream>
#include <sstream>
```

```
using namespace std;
```

```
class Graph
```

```
{
public:
    Graph          (string filename);
    Graph          (const Graph& g);
    ~Graph         (void);
    Graph operator= (const Graph& g);
    void dfs       (void);
    bool cycle     (void);
    void Prim      (int root);
```

```
private:
```

```
    List<Vertex>  graph;
    List<Edge>    edges;
    bool          BALLS = false;

    void dfs_visit (Vertex &u, int timee);
    bool pqHelp    (Vertex s, MinPriorityQueue<Vertex> pq);
    int findEdge   (Vertex u, Vertex v);
```

```
};
//=====
```

```
//=====
//default constructor
//Pre-Condition:
// -file with matrix representation of a graph
//Post-Condition:
// -a graph
//=====
```

```
Graph::Graph (string filename)
```

```
{
    ifstream file;
    file.open(filename); //open file
    string line;
    getline(file, line);
    istringstream buffer(line); //read in number of
    int num_vert; //vertices
    buffer >> num_vert;
    for (int i = 0; i < num_vert; i++)
    {
        Vertex *v = new Vertex(i);
        graph.append(v); //append all vertices to graph
    }
    for (int j = 0; j < num_vert; j++) //iterates rows
    {
        int srch_pt = 0;
        getline(file, line);
        for (int k = 0; k < num_vert; k++)
```

```

{
    int space = line.find(" ", srch_pt);          //read in connections
    int weight;
    istream buffer (line.substr(srch_pt, space-srch_pt));
    buffer >> weight;
    srch_pt = space+1;

    if (weight != 0)
    {
        Edge *e = new Edge();                    //creates edges
        e->u = graph[j]->id;
        e->v = graph[k]->id;
        e->weight = weight;
        edges.append(e);
        graph[j]->adj_list.append(graph[k]);
    }
}
}
//cout << graph;
file.close();
}

//=====
//copy constructor
//Pre-Conditions
// -graph
//Post-Conditions
// -copied graph
//=====
Graph::Graph (const Graph& g)
{
    graph = g.graph;
}

//=====
//destructor
//Pre-Conditions
// - graph
//Post-Conditions
// -no graph
//=====
Graph::~~Graph (void)
{
    //delete this;
}

//=====
//assignment operator
//Pre-Conditions
// -two different graphs
//Post-Conditions
// -two same graphs
//=====
Graph Graph::operator= (const Graph& g)
{
    delete this;          //destructor
    graph = g.graph;      //copy
    edges = g.edges;
    return *this;
}

//=====
//dfs - depth first search

```

```

//Pre-Conditions
// -graph
//Post-Conditions
// -traversed graph
//=====
void Graph::dfs (void)
{
    if (graph.length()==0)                //throw error if empty
        throw EmptyError();
    for (int i = 0; i < graph.length(); i++)
    {
        graph[i]->color = 'w';            //set all to white
    }
    int timee = 0;
    //cout << timee << endl;
    for (int i = 0; i < graph.length(); i++)
    {
        if (graph[i]->color == 'w')
        {
            dfs_visit(*(graph[i]), timee);    //visit vertex
        }
    }
}
//=====
//dfs_visit - depth first search
//=====
void Graph::dfs_visit (Vertex& u, int timee)
{
    timee += 1;
    u.disc = timee;
    u.color = 'g';                        //discover
    cout << "Visiting: " <<u << endl;
    for (int i = 0; i < u.adj_list.length(); i++)
    {
        if (u.adj_list[i]->color == 'g')
        {
            BALLS = true;
        }
        if (u.adj_list[i]->color == 'w')
        {
            u.adj_list[i]->pred = &u;        //set predecessor
            dfs_visit(*u.adj_list[i], timee); //visit adjacent vertices
        }
    }
    u.color = 'b';                        //all adjacent vertices visited
    timee += 1;
    u.fin = timee;
}
//=====
//cycle
//Pre-Conditions
// -graph
//Post-Conditions
// -indication if graph contains cycle
//=====
bool Graph::cycle (void)
{
    dfs();
    return BALLS;
}
//=====

```

```

//Prim's algorithm -- we tried but it's not happening
//Pre-Conditions
// -undirected weighted graph
//Post-Conditions
// -MST of graph
//=====
void Graph::Prim (int root)
{
    MinPriorityQueue<Vertex> pq; //create min pq
    for (int i = 0; i < graph.length(); i++)
    {
        if (graph[i]->id != graph[root]->id)
        {
            graph[i]->key = INT_MAX;
            graph[i]->pred = NULL;
            pq.insert(graph[i]); //insert vertices into pq
        }
    }
    graph[root]->key = 0;
    pq.insert(graph[root]); //insert root into pq
    cout << pq << endl;
    //cout << "SHIT" << endl;
    while (!pq.empty())
    {
        Vertex *u = pq.extractMin(); //find minimum weight
        cout << "MIN: " << u->id << endl;
        for (int j = 0; j < u->adj_list.length(); j++) //visit adjacent vertices
        {
            Vertex *v = u->adj_list[j];
            //cout << "weight of " << *v << " " << v->key << endl;
            if (v->key > u->key && findEdge(u,v) < v->key)
            {
                //cout << "what to heck" << endl;
                v->pred = u; //update pred and key
                v->key = findEdge(u,v);
                //cout << "reset key of " << v->id << "to " << v->key << endl;
            }
        }
    }
    for (int k = 0; k < graph.length(); k++)
    {
        cout << k << " weight: " << graph[k]->key << graph[k]->pred << endl;
    }
}

//=====
//pqHelp
// this method verifies if an element is present in the pq
//=====
bool Graph::pqHelp(Vertex s, MinPriorityQueue<Vertex> pq)
{
    while (!pq.empty())
    {
        Vertex v = pq.extractMin();
        if (v.id == s.id )
            return true;
    }
    return false;
}

//=====
//findEdge
// this method finds the edges and returns the weight given two vertices
//=====

```

```
int Graph::findEdge (Vertex u, Vertex v)
{
    for (int i = 0; i < edges.length(); i++)
    {
        if (edges[i]->u == u.id && edges[i]->v == v.id)
        {
            return edges[i]->weight;
        }
    }
    return 0;
}
```

```
//Hannah, Emma, Lindsey
//Vertex class

#include "list.h"
#include <climits>
using namespace std;

class Vertex
{
public:
    int id;
    Vertex* pred;
    List<Vertex> adj_list;
    char color;
    int disc;
    int fin;
    int key;

    bool operator< (const Vertex &x) {return this->key <= x.key;}
    bool operator> (const Vertex &x) {return this->key > x.key;}
    bool operator== (const Vertex &x) {return this->id == x.id;}

    Vertex& operator= (const Vertex& v);

    Vertex (int name);
    Vertex (Vertex* v);
    ~Vertex (void);

private:
    friend ostream& operator<< (ostream& os, const Vertex& v)
    {
        os << "Vertex ID: " << v.id << endl;
        return os;
    }
};

Vertex::Vertex(int name)
{
    id = name;
    pred = NULL;
    color = 'w';
    disc = INT_MAX;
    fin = 0;
    key = INT_MAX;
}

Vertex::Vertex(Vertex* v)
{
    id = v->id;
    pred = v->pred;
    adj_list = v->adj_list;
    color = v->color;
    disc = v->disc;
    fin = v->fin;
}

Vertex::~~Vertex ()
{
}

Vertex& Vertex::operator= (const Vertex& v)
{
    this->id = v.id;
    this->pred = v.pred;
```

```
this->adj_list = v.adj_list;
this->color = v.color;
this->disc = v.disc;
this->fin = v.fin;

return *this;
}

class Edge
{
public:
    int u;    //start Vertex
    int v;    //end Vertex
    int weight;    //weight (u,v)

    Edge()
    {
        u = -1;
        v = -1;
        weight = 0;
    }

    ~Edge()
    {
    }
};
```

```
/*
 * testin dis graph bish
 */

#include <iostream>
#include "graph.h"
using namespace std;

void test1 (void)
{
    cout << "testing grap.txt" << endl;
    Graph g1("grap.txt");
    //g1.dfs();
    cout << boolalpha << g1.cycle() << endl;
}

void test2 (void)
{
    cout << "testing grap2.txt" << endl;
    Graph g2("grap2.txt");
    //g2.dfs();
    cout << boolalpha << g2.cycle() << endl;
}

void test3 (void)
{
    cout << "testing grap3.txt" << endl;
    Graph g3("grap3.txt");
    // g3.dfs();
    cout << boolalpha << g3.cycle() << endl;
}

void test4 (void)
{
    cout << "testing grap4.txt" << endl;
    Graph g4("grap4.txt");
    //g4.dfs();
    cout << boolalpha << g4.cycle() << endl;
}

int main (void)
{
    test1();
    test2();
    test3();
    test4();
}
```


6
0 2 0 4 0 0
2 0 1 7 9 5
0 1 0 0 0 0
4 7 0 0 0 0
0 9 0 0 0 0
0 5 0 0 0 0

4

0 5 1 0

3 0 2 2

4 1 0 1

3 3 3 0

4

0 1 0 0

0 0 0 1

0 0 0 0

0 0 1 0

```
5
0 0 0 0 1
1 0 1 0 0
0 0 0 1 0
0 0 0 0 1
0 0 0 0 0
```

```

// pq.h
// This MinPriorityQueue template class assumes that the class KeyType has
// overloaded the < operator and the << stream operator.

#ifndef PQ_H
#define PQ_H

#include <iostream>
#include "heap.h"

template <class KeyType>
class MinPriorityQueue : public MinHeap<KeyType>
{
public:
    MinPriorityQueue();           // default constructor
    MinPriorityQueue(int n);       // construct an empty MPQ with capacity n
    MinPriorityQueue(const MinPriorityQueue<KeyType>& pq); // copy constructor

    KeyType* minimum() const;     // return the minimum element
    KeyType* extractMin();         // delete the minimum element and return it
    void decreaseKey(int index, KeyType* key); // decrease the value of an element
    void insert(KeyType* key);     // insert a new element
    bool empty() const;           // return whether the MPQ is empty
    int length() const;           // return the number of keys
    std::string toString() const; // return a string representation of the MPQ
    //int findIndex (KeyType * k);

    // Specify that MPQ will be referring to the following members of MinHeap<KeyType>.

    using MinHeap<KeyType>::A;
    using MinHeap<KeyType>::heapSize;
    using MinHeap<KeyType>::capacity;
    using MinHeap<KeyType>::parent;
    using MinHeap<KeyType>::swap;
    using MinHeap<KeyType>::heapify;

    /* The using statements are necessary to resolve ambiguity because
       these members do not refer to KeyType. Alternatively, you could
       use this->heapify(0) or MinHeap<KeyType>::heapify(0).
    */
};

template <class KeyType>
std::ostream& operator<<(std::ostream& stream, const MinPriorityQueue<KeyType>& pq);

class FullError { }; // MinPriorityQueue full exception
class EmptyError { }; // MinPriorityQueue empty exception
class KeyError { }; // MinPriorityQueue key exception

#include "pq.cpp"

#endif

```

```

#include <sstream>
#include <string>
#include <iostream>
#include <exception>

/*
 * notes
 * minimum method to return the minimum element, but the function header makes it return a pointer. it works but it's returning the address and not the int value of the smallest element
 */

/*-----
 * default constructor
 * uses minHeap default constructor
-----*/
template <class KeyType>
MinPriorityQueue<KeyType>::MinPriorityQueue() :MinHeap<KeyType>()
{
}

/*-----
 * construct an empty MinPriorityQueue with capacity n
 * uses minHeap constructor to construct an empty heap with capacity n
-----*/
template <class KeyType>
MinPriorityQueue<KeyType>::MinPriorityQueue(int n) :MinHeap<KeyType>(n)
{
}

/*-----
 * copy constructor
 * uses minHeap copy constructor
-----*/
template <class KeyType>
MinPriorityQueue<KeyType>::MinPriorityQueue(const MinPriorityQueue<KeyType>& pq) :MinHeap<KeyType>(pq)
{
}

//=====
//=====
/*-----
 * minimum()
 * return smallest element in MinPriorityQueue
 * parameters: void
 * return value: KeyType*
 * precondition: MPQ is not empty (exception to handle this case)
 * postcondition: MPQ is unchanged
-----*/
template <class KeyType>
KeyType* MinPriorityQueue<KeyType>::minimum( void ) const //note: fix exceptions
{
    if (empty())
    {
        throw EmptyError();
    }
    else
    {
        return A[0];
    }
}

```

```
/*-----
* extractMin()
* delete the minimum element of MinPriorityQueue and return it
* parameters: void
* return value: KeyType*
* precondition: non-empty MPQ (exception to handle this case)
* postcondition: MPQ no longer contains smallest value
-----*/
template <class KeyType>
KeyType* MinPriorityQueue<KeyType>::extractMin( void )
{
    //cout << "EXTRACT MIN!!!!!!!!!!!" << endl;
    if (empty())
    {
        throw EmptyError();
    }
    else
    {
        KeyType* temp = A[0];
        //cout << "temp 1: " << *temp << endl;
        A[0] = A[heapSize - 1];
        //cout << "temp 2: " << *temp << endl;
        heapSize -= 1;
        //cout << "temp 3: " << *temp << endl;
        heapify(0);
        //cout << "temp 4: " << *temp << endl;
        //cout << "END EXTRACT MIN!!!!!!!!!!!" << endl;
        return temp;
    }
}

/*-----
* decreaseKey()
* decrease the value of an element
* paramters: int index of value to decrease priority of, KeyType* value to decrease
* return value: void
* precondition: non-empty MPQ (exception)
* postcondition: given value has decreased in priority and its position has changed
-----*/
template <class KeyType>
void MinPriorityQueue<KeyType>::decreaseKey( int index, KeyType* key )
{
    if (empty())
    {
        throw EmptyError();
    }
    else
    {
        A[index] = *key;
        while (index > 0 and *(A[parent(index)]) > *(A[index]))
        {
            swap(index, parent(index));
            index = parent(index);
        }
    }
}

/*-----
* insert
* insert a new element
* parameters: KeyType* key to insert
* return value: void
```

```
* precondition: MPQ exists
* postcondition: MPQ now contains value passed to insert
-----*/
```

```
template <class KeyType>
void MinPriorityQueue<KeyType>::insert( KeyType* key )
{
    if (heapSize + 1 == capacity - 1)
    {
        throw FullError();
    }
    else
    {
        A[heapSize] = key;
        heapSize++;
        decreaseKey(heapSize-1, key);
    }
}
```

```
/*-----
* empty()
* return whether the MinPriorityQueue is empty
* parameters: void
* return value: bool
* precondition: MPQ exists
* postcondition: MPQ is unchanged
-----*/
```

```
template <class KeyType>
bool MinPriorityQueue<KeyType>::empty( void ) const
{
    return heapSize == 0;
}
```

```
/*-----
* length
* returns length of MinPriorityQueue
* parameters: void
* return value: int
* precondition: MPQ exists
* postcondition: unchanged MPQ
-----*/
```

```
template <class KeyType>
int MinPriorityQueue<KeyType>::length( void ) const
{
    return heapSize;
}
```

```
/*-----
* toString
* inserts MPQ contents into string
* parameters: none
* return value: string
-----*/
```

```
template <class KeyType>
std::string MinPriorityQueue<KeyType>::toString() const
{
    std::stringstream ss;

    if (heapSize == 0)
    {
        ss << "[ ]";
    }
    else
```



```
{
    ss << "[";
    for (int index = 0; index < heapSize - 1; index++)
        ss << *(A[index]) << ", ";
    ss << *(A[heapSize - 1]) << "]";
}
return ss.str();
}

/*-----
* overloaded cout operator
-----*/

template <class KeyType>
std::ostream& operator<<(std::ostream& stream, const MinPriorityQueue<KeyType>& pq)
{
    stream << pq.toString();
    return stream;
}

/*template <class KeyType>
int MinPriorityQueue<KeyType>::findIndex(KeyType * k)
{
    if (empty())
        throw EmptyError();

    else
    {
        for (int i = 0; i < length(); i++)
        {
            if (A[i] == *k)
                return i;
        }
        return -1;
    }
}
*/
```

```

#include <string>
#include <fstream>

const int DEFAULT_SIZE = 100;
using namespace std;
template <class KeyType>
class MinHeap
{
public:
    MinHeap(int n = DEFAULT_SIZE);           // default constructor
    MinHeap(KeyType* initA[], int n);         // construct heap from array
    MinHeap(const MinHeap<KeyType>& heap);     // copy constructor
    ~MinHeap();                               // destructor
    void heapSort(KeyType* sorted[]);         // heapsort, return result in sorted
    std::string toString() const;             // return string representation
    MinHeap<KeyType>& operator=(const MinHeap<KeyType>& heap); // assignment operator

protected:
    KeyType **A;                             // array containing the heap
    int heapSize;                             // size of the heap
    int capacity;                             // size of A
    void buildHeap();                         // build heap
    int leftChild(int index) { return 2 * index + 1; } // return index of left child
    int rightChild(int index) { return 2 * index + 2; } // return index of right child
    int parent(int index) { return (index - 1) / 2; } // return index of parent
    void swap(int index1, int index2);        // swap elements in A
    void copy(const MinHeap<KeyType>& heap);    // copy heap to this heap
    void heapify(int index);                  // heapify subheap rooted at index

    void destroy();                          // deallocate heap
};
#include "heap.cpp"

```

```
#include <iostream>
#include <sstream>

using namespace std;

//=====
// Default Constructor for MinHeap
// Pre-conditions:
//     none
// post-conditions:
//     It's a heap with nothing in it,
//     capacity n, heapSize 0
// Notes:
//     Now go out into the world. Don't return
//     until you have done all that is required.
//=====
template<class KeyType>
    MinHeap<KeyType>::MinHeap(int n)
{
    A = new KeyType*[n];
    capacity = n;
    heapSize = 0;
}

//=====
// Array Initilazation Constructor for MinHeap
// Pre-Conditions:
//     n > 0
// Post-Conditions:
//     Congratulations! It's a MinHeap,
//     capacity n, heapSize n
// Notes:
//     Now go out into the world. Don't return
//     until you have done all that is required.
//=====
template<class KeyType>
    MinHeap<KeyType>::MinHeap(KeyType* initA[], int n)
{
    capacity = n;
    heapSize = n;
    A = new KeyType*[n];
    for(int i = 0; i < n; i++)
    {
        A[i] = initA[i];
    }
    buildHeap();
}

//=====
// Copy Constructor for MinHeap
// Pre-Conditions:
//     none
// Post-Conditions:
//     Congratulations! It's a MinHeap,
//     capacity heap.capacity,
//     heapSize heap.heapSize
// Notes:
//     Now go out into the world. Don't return
//     until you have done all that is required.
//=====
template<class KeyType>
    MinHeap<KeyType>::MinHeap(const MinHeap<KeyType>& heap)
```

```
{
    copy(heap);
}

//=====
// Destructor for MinHeap
// Pre-Conditions:
//     None
// Post-Conditions:
//     None
// Notes:
//     And when you do return, I am here. And I
//     will destroy you. It is all I know.
//=====
template<class KeyType>
MinHeap<KeyType>::~MinHeap()
{
    destroy();
}

//=====
// Sorting Algorithm: heapSort
// Pre-Conditions:
//     The heap must be a MinHeap
// Post-Conditions:
//     sorted is now sorted in ascending order
//=====
template<class KeyType>
void MinHeap<KeyType>::heapSort(KeyType* sorted[])
{
    sorted = new KeyType*[capacity];
    //buildHeap();
    for(int i = capacity - 1; i >= 0; i--)
    {
        sorted[i] = A[0];
        swap(0,i);
        heapSize--;
        heapify(0);
    }
    heapSize = capacity;
}

//=====
// Assignment operator
// Pre-Conditions:
//     none
// Post-Conditions:
//     returns a new heap just like the heap
//     which was passed in
//=====
template<class KeyType>
MinHeap<KeyType>& MinHeap<KeyType>::operator=(const MinHeap<KeyType>& heap)
{
    destroy();
    copy(heap);
    return *this;
}

//=====
// String converter
// Pre-Conditions:
//     none
// Post-Conditions:
```

```
//          returns a string of the array in which
//          the heap is stored
//=====
template<class KeyType>
string MinHeap<KeyType>::toString() const
{
    stringstream stm;
    stm << "{";
    for(int i = 0; i < heapSize - 1; i++)
    {
        stm << *(A[i]) << ", ";
    }
    if(heapSize != 0)
        stm << *(A[heapSize - 1]) << "}";
    else
        stm << "}";

    return stm.str();
}

//=====
// Makes a heap into a min heap
// Pre-Conditions:
//          Both children must be roots of a Min-Heap
// Post-Conditions:
//          The heap is a Min-Heap (if the
//          Pre-Condition is satisfied)
//=====
template<class KeyType>
void MinHeap<KeyType>::heapify(int index)
{
    int l = leftChild(index);
    int r = rightChild(index);
    int min;
    if(l < heapSize && *(A[index]) > *(A[l]))
        min = l;
    else
        min = index;
    if(r < heapSize && *(A[min]) > *(A[r]))
        min = r;
    if(min != index)
    {
        swap(index, min);
        heapify(min);
    }
}

//=====
// Builds a MinHeap
// Pre-Conditions:
//          none
// Post-Conditions:
//          the heap is definitely a Min-Heap
//=====
template<class KeyType>
void MinHeap<KeyType>::buildHeap()
{
    heapSize = capacity;
    for(int i = heapSize / 2 - 1; i >= 0; i--)
    {
        heapify(i);
    }
}
```

```
//=====
// Swaps two items
// Pre-Conditions:
//             The indices are valid
// Post-Conditions:
//             The values at the indices
//             have been swapped
//=====
template<class KeyType>
void MinHeap<KeyType>::swap(int index1, int index2)
{
    KeyType* temp = A[index1];
    A[index1] = A[index2];
    A[index2] = temp;
}

//=====
// copies one heap into another
// Pre-Conditions:
//             none
// Post-Conditions:
//             This heap is just like the one passed in.
//             capacity heap.capacity,
//             heapSize heap.heapSize
//=====
template<class KeyType>
void MinHeap<KeyType>::copy(const MinHeap<KeyType>& heap)
{
    A = new KeyType*[heap.capacity];
    for(int i = 0; i < heap.capacity; i++)
        A[i] = heap.A[i];
    capacity = heap.capacity;
    heapSize = heap.heapSize;
}

//=====
// The End
// Pre-Conditions:
//             none
// Post-Conditions:
//             none
// Notes:
//             But don't feel betrayed or singled out.
//             I heed nothing. I leave nothing. All are
//             destroyed. Everything shall be deleted.
//=====
template<class KeyType>
void MinHeap<KeyType>::destroy()
{
    delete A;
}
```

```

// list.h
// Jessen Havill

#ifndef LIST_H
#define LIST_H

#include <cstdlib>
#include <iostream>

template <class T>
class Node
{
public:

    T *item;
    Node<T> *next;

    Node();
    Node(T *initItem);
    Node(T *initItem, Node<T> *initNext);
};

template <class T> class List;

template <class T>
std::ostream& operator<<(std::ostream& os, const List<T>& list);

template <class T>
class List
{
public:

    List(); // default constructor
    List(const List<T>& src); // copy constructor
    ~List(); // destructor

    void append(T *item); // append a new item to the end of the list
    int length() const; // return the number of items in the list
    int index(const T& item) const; // return index of value item, or -1 if not found
    T *get(const T& item) const; // return pointer to the item equal to parameter item
    void insert(int index, T *item); // insert item in position index
    T *pop(int index); // delete the item in position index and return it
    void remove(const T& item); // remove the first occurrence of the value item

    T *operator[](int index) const; // indexing operator
    List<T>& operator=(const List<T>& src); // assignment operator
    List<T>& operator+=(const List<T>& src); // concatenation operator

    std::string toString() const;

private:

    Node<T> *head; // head of the linked list
    int count; // number of items in the list

    void deepCopy(const List<T>& src);
    void deallocate(); // deallocate the list
    Node<T>* _find(int index) const; // return a pointer to the node in position index

    friend std::ostream& operator<< <T>(std::ostream& os, const List<T>& list);
};

class IndexError { };

```

```
class ValueError { };
```

```
#include "list.cpp"
```

```
#endif
```



```
// list.cpp
// Jessen Havill

#include <sstream>

template <class T>
Node<T>::Node()
{
    item = NULL;
    next = NULL;
}

template <class T>
Node<T>::Node(T *initItem)
{
    item = initItem;
    next = NULL;
}

template <class T>
Node<T>::Node(T *initItem, Node<T> *initNext)
{
    item = initItem;
    next = initNext;
}

template <class T>
List<T>::List()
{
    head = NULL;
    count = 0;
}

template <class T>
List<T>::List(const List<T>& src)
{
    deepCopy(src);
}

template <class T>
List<T>::~~List()
{
    deallocate();
}

template <class T>
List<T>& List<T>::operator=(const List<T>& src)
{
    deallocate();
    deepCopy(src);

    return *this;
}

template <class T>
int List<T>::length() const
{
    return count;
}

template <class T>
int List<T>::index(const T& item) const
{

```

```
int index = 0;
Node<T> *node = head;
while ((node != NULL) && (!(node->item) == item))
{
    node = node->next;
    index++;
}

if (node == NULL)
    return -1;
else
    return index;
}

template <class T>
T *List<T>::get(const T& item) const
{
    Node<T> *node = head;
    while ((node != NULL) && (!(node->item) == item))
        node = node->next;

    if (node == NULL)
        return NULL;
    else
        return node->item;
}

template <class T>
void List<T>::append(T *item)
{
    Node<T> *node,
            *newNode;

    newNode = new Node<T>(item);

    if (head != NULL)
    {
        node = _find(count - 1);
        node->next = newNode;
    }
    else
        head = newNode;

    count++;
}

template <class T>
void List<T>::insert(int index, T *item)
{
    if ((index < 0) || (index > count))
        throw IndexError();

    Node<T> *node;

    if (index == 0)
        head = new Node<T>(item, head);
    else
    {
        node = _find(index - 1);
        node->next = new Node<T>(item, node->next);
    }
    count++;
}
```

```
template <class T>
T *List<T>::pop(int index)
{
    if ((index < -1) || (index >= count))
        throw IndexError();

    if (index == -1)
        index = count - 1;

    Node<T> *node, *dnode;
    T *item;

    if (index == 0)
    {
        dnode = head;
        head = head->next;
        item = dnode->item;
        delete dnode;
    }
    else
    {
        node = _find(index - 1);
        if (node != NULL)
        {
            dnode = node->next;
            node->next = node->next->next;
            item = dnode->item;
            delete dnode;
        }
    }
    count --;
    return item;
}

template <class T>
T* List<T>::operator[](int index) const
{
    if ((index < 0) || (index >= count))
        throw IndexError();

    Node<T> *node = _find(index);
    return node->item;
}

template <class T>
void List<T>::deepCopy(const List<T>& src)
{
    Node<T> *snode, *node;

    snode = src.head;
    if (snode != NULL)
    {
        node = head = new Node<T>(snode->item);
        snode = snode->next;
    }
    while (snode != NULL)
    {
        node->next = new Node<T>(snode->item);
        node = node->next;
        snode = snode->next;
    }
}
```

```
        count = src.count;
    }

template <class T>
void List<T>::deallocate()
{
    Node<T> *node, *dnode;

    node = head;
    while (node != NULL)
    {
        dnode = node;
        node = node->next;
        delete dnode;
    }
}

template <class T>
void List<T>::remove(const T& item)
{
    if (head == NULL)
        return;

    Node<T> *toDelete;

    if (*(head->item) == item)
    {
        toDelete = head;
        head = head->next;
        delete toDelete;
        count--;
    }
    else
    {
        Node<T> *node = head;
        while ((node->next != NULL) && (*(node->next->item) == item))
            node = node->next;

        if (node->next != NULL)
        {
            toDelete = node->next;
            node->next = node->next->next;
            delete toDelete;
            count--;
        }
    }
}

template <class T>
Node<T>* List<T>::_find(int index) const // used by append, insert, [], pop
{
    if ((index < 0) || (index >= count))
        throw IndexError();

    Node<T> *node = head;
    for (int i = 0; i < index; i++)
        node = node->next;

    return node;
}

template <class T>
std::string List<T>::toString() const
```

```
{
    std::stringstream ss;
    Node<T> *node = head;

    while (node != NULL)
    {
        ss << *(node->item) << " ";
        node = node->next;
    }
    return ss.str();
}

template <class T>
std::ostream& operator<<(std::ostream& os, const List<T>& list)
{
    os << list.toString();

    return os;
}
```