```
Configuration: Default
     Coordinate system: -- default --
Mass = 130.49 grams
Volume = 222376.77 cubic millimeters
Surface area = 179319.94 square millimeters
Center of mass: ( millimeters )
        X = 68.62
        Y = -0.44
        Z = 8.14
Principal axes of inertia and principal moments of inertia: ( grams * square millimeters )
Taken at the center of mass.
         Ix = (0.99, 0.10, -0.01)
                                          Px = 385919.47
         Iy = (-0.10, 0.98, 0.16)

Iz = (0.02, -0.16, 0.99)
                                          Py = 7100526.69
                                          Pz = 7466085.70
Moments of inertia: ( grams * square millimeters )
Taken at the center of mass and aligned with the output coordinate system. (Using positive tensor nota
        Lxx = 456293.00 Lxy = 682424.77 Lxz = -57126.87
        Lyx = 682424.77 Lyy = 7039520.56
                                                  Lyz = 51058.43
        Lzx = -57126.87 Lzy = 51058.43 Lzz = 7456718.29
Moments of inertia: ( grams * square millimeters )
Taken at the output coordinate system. (Using positive tensor notation.)
        Ixx = 464968.20 Ixy = 678446.51 Ixz = 15776.96
        Iyx = 678446.51 Iyy = 7662656.45 Iyz = 50 Izx = 15776.96 Izy = 50586.45 Izz = 8071230.49
                                                  Iyz = 50586.45
One or more components have overridden mass properties:
        DmMc_Wing_type6<2><Default>
        DmMc Centriod type6 D30mm<1><Default>
        DmMc BetaFPV 300mah2s<1><Default>
        DmMc_BetaFPV_300mah2s<2><Default>
        DmMc_ESP32S3WROOM1_type6<1><Default>
        DmMc_F35Aesc_type6<1><Default>
DmMc_RM3100compass_type6<1><Default>
        DmMc D24V22F5_type6<1><Default>
```

Mass properties of DmMc_Interfaceplate_type6_Full