Actuators

Team: Los simuladores

Types of comercial actuators



Development

- 1. Use the following list of comercial electric actuators models for the development of the activity based on the instructions requested by the advisor.
 - Double axis gear motor
 - Unipolar stepper motor
 - Bipolar stepper motor
 - SG90 model servo motor
- 2. Wait for the advisor to indicate the type of sensor that your team will develop and once you have it mark the sensor within the previous point.
- 3. Once you know the topic to be developed, research and write following points within this document:



Engineering in Computer Systems, Information and Communication Technologies and Computing

Subject: SCC-1023/SC7A Programmable Systems

Team Members

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• Introduction

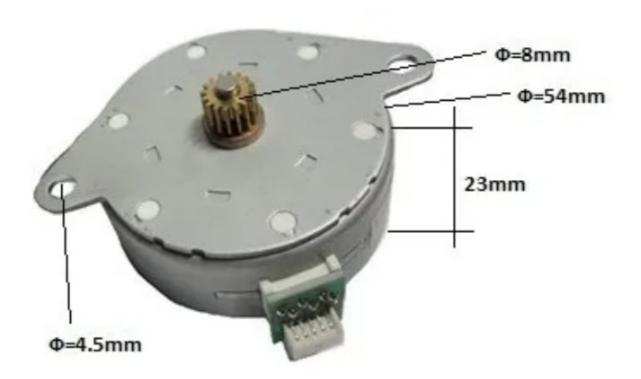
Stepper motors are very useful motors since they allow to control very precisely the movement of the motor and the number of degrees that it moves. making it of great importance in jobs that require greater precision, on this occasion we will talk about its simplest model, the unipolar stepper motor that stands out for maintaining that high precision of the stepper motors but also being easier to use that other motors of this type

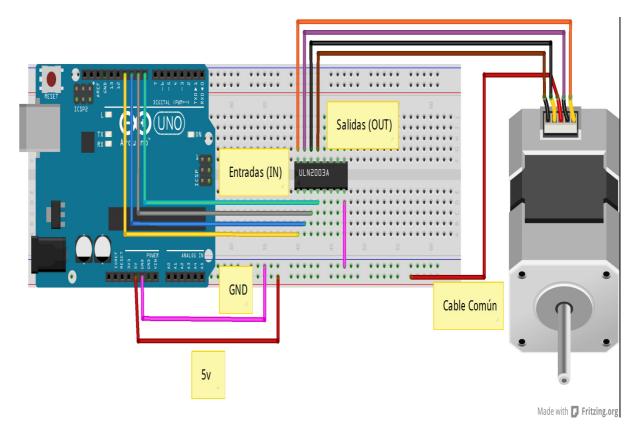
Development

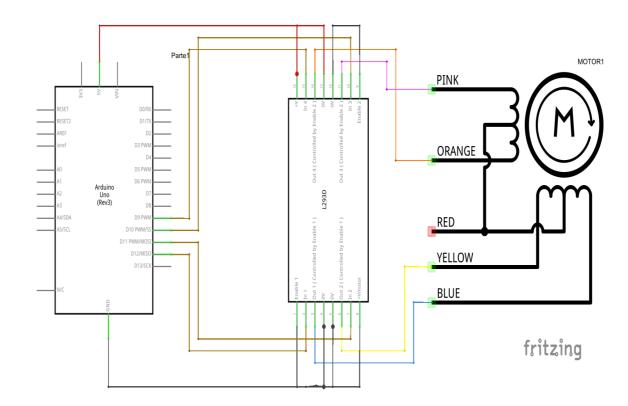
- Definition. The unipolar stepper motor is a stepper type motor, which means that when a
 voltage is applied to it, this one moves a certain number of angles transforming electrical
 impulses into controlled rotational movements.
 - This specific type of motor is the unipolar one that is easier to control and only allows current to pass in one direction
- **Images** from the actuator.











• Physical properties.

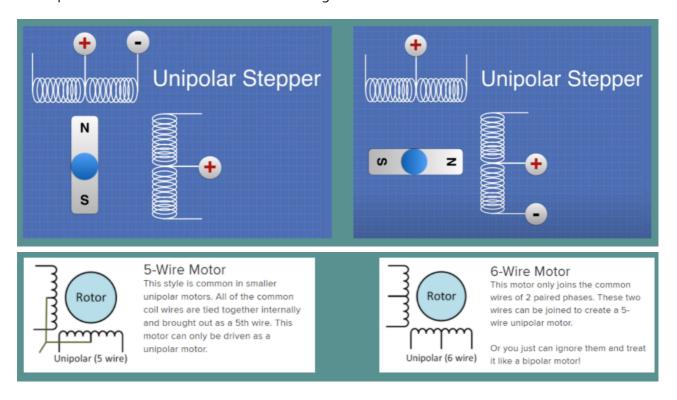
Property	Quantity
Steps per rotation	20, 24, 40, 48, 100, 200
Grades per step	18°, 15°, 9°, 7.5°, 3.6°, 1.8°
Plastic magnet	
Operating temperature	-10 to 50 C°
Storage temperature	-30 to 80 C°
Operating humedity	20% RH a 90% RH
Pines	5, 6 , 8
Internal coils	4

• **Electrical** properties.

Property	Quantity			
Average amperage	800 mA			
Voltage	5V to 28 V			
Insulation resistance	100 Mohms			
Coil resistance	30 ohms			
Dielectric strength	500V/1Min			

• Explain the principle of operation

The unipolar stepper motor operates with one winding with a center tap per phase. Each section of the winding is switched on for each direction of the magnetic field. Each winding is made relatively simple with the commutation circuit, this is donde since the arrangement has magnetic pole wich can be reversed without switching the direction of the current.



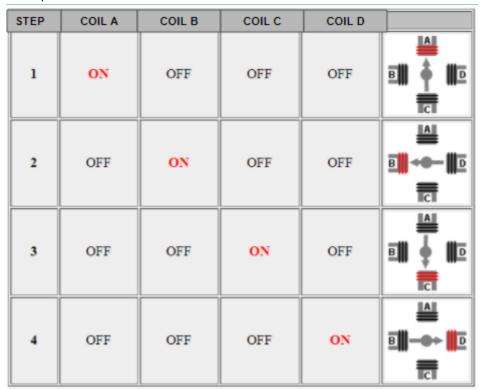
There are three possible sequences for this type of engines, which are detailed below. All sequences start again by step 1 after reaching the final step (4 or 8). To reverse the direction of rotation, simply run the sequences in reverse mode.

 Normal Sequence: This is the most used sequence and the one generally recommended by the manufacturer. With this sequence the engine advances one step at a time and because there are

always at least two coils activated, you get a high pitch and hold torque.

STEP	COIL A	COIL B	COIL C	COIL D	
1	ON	ON	OFF	OFF	B
2	OFF	ON	ON	OFF	
3	OFF	OFF	ON	ON	B D
4	ON	OFF	OFF	ON	B D

Wave drive sequence: In this sequence only one coil is activated at a time. In some engines this
provides smoother operation. The counterpart is that since only one coil is activated, the torque
of step and retention is less.



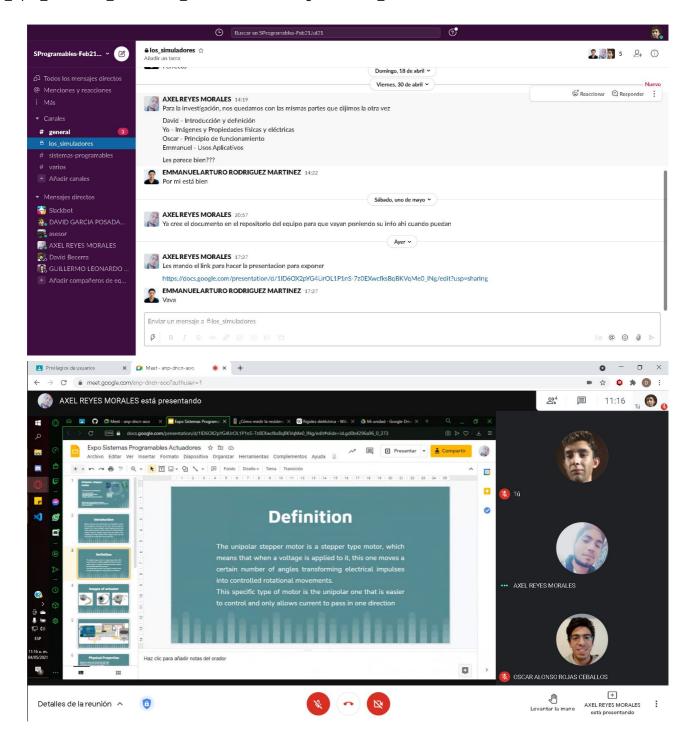
• Half-step sequence: In this sequence the coils are activated in such a way to provide a movement equal to half of the actual step. For this, 2 coils are activated first and then only 1 and so on. As we see in the table the entire sequence consists of 8 moves instead of 4.

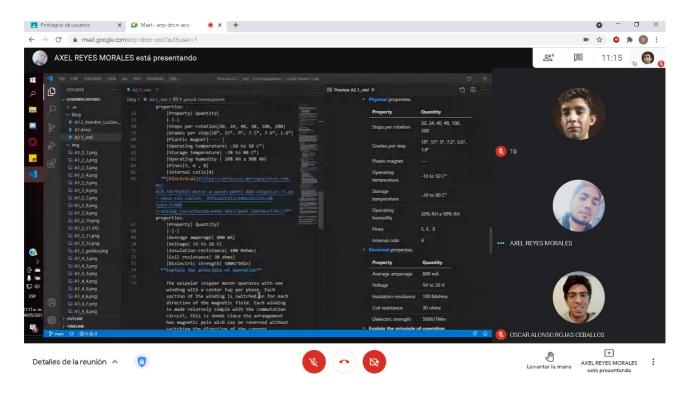
STEP	COIL A	COIL B	(COIL C	CC	OIL D						
1	ON	OFF		OFF		OFF		B				
2	ON	ON		OFF	(OFF	<u>B</u>		2			
3	OFF	ON		OFF	(OFF	8 4	<u> </u>	2			
4	OFF	ON		ON		OFF	B ,					
									A			
5	OFF	OFF		ON		OF	F	8	Į Ici	D		
									A			
6	OFF	OFF		ON		ON		ON		8	ici	D
7	OFF	OFF		OFF	,	ON		B III -	IAI	D		
8	ON	OFF	OFF		•	Ol	N	B.	IAI	D		

Aplicative uses.

They are mainly used in applications that require precise travel control, positioning devices, because it is easy to make the appropriate device and software using a computer and a controller. They are also widely used in biomedical appliances, computer disk drives, printers, scanners, smart lighting, to control camera lenses, the position of control elements in combustion engines, robotics, 3D printers and scanners, XY plotters, CNC machines. and other devices.

1. Insert images of evidence such as meetings of the team members held for the development of the activity.





2. Include the individual conclusions and results observed during the development of the activity.

David: The unipolar stepper motor is a great stepper motor to use when you are learning to use them for its great ease of use, mantaining almos all the advantages of the stepper motors with really only a few setbacks making it a grat options for begginers and experts alike

Axel: To conclude I can say that these types of engines help us in circumstances where we occupy the engine moving slowly, or occupy a slow motion of the engine

Emmanuel In conclusion, unipolar stepper motors work through magnets which make the motor rotate taking steps, this makes it possible to carry out jobs that need a lot of precision like that of a 3D printer.

Oscar Rojas The unipolar stepper is a great solution for small project it is easy to use, cheap and you can use it as a bipolar stepper.

Repositories

Axel Go to my repository

David Go to my repository

Emmanuel Go to my repository

Oscar Rojas Got to my repository